

$(\Omega, \mathcal{F}, \mathcal{F}, P)$ filtered prob. space

A r.v. τ on that space is called "stopping time" ST if one has — ①

$$\{\tau \leq t\} \in \mathcal{F}_t \text{ for each } t = 0, 1, 2, \dots$$

for an ST τ

$$\{\tau = t\} = \underbrace{\{\tau \leq t\}}_{\in \mathcal{F}_t} \cap \underbrace{\{\tau \leq t-1\}^c}_{\in \mathcal{F}_{t-1} \subset \mathcal{F}_t} \in \mathcal{F}_t \text{ — ②}$$

$$\{\tau \leq t\} = \bigcup_{s=0}^t \underbrace{\{\tau = s\}}_{\in \mathcal{F}_s \subset \mathcal{F}_t} \quad \text{since } ② \Rightarrow ①$$

About name.

τ (random) time when we decide to stop doing something (stop gambling or to sell a block of share at a stock exchange)

$\tau = t$, you act on the basis of you already know by that time $\therefore \{\tau = t\} \in \mathcal{F}_t$

Example (First hitting time)

adapted process $\{X_t\}$, a (boundary) fn $u_t, t=0, 1, 2, \dots$

Show that the first hitting (or crossing) time

$\tau := \inf \{t \geq 0 : X_t \geq u_t\}$ is a S.T.

Sol For any $t = 0, 1, 2, \dots$ — ③

$$\{\tau \leq t\} = \bigcup_{s=0}^t \{X_s \geq u_s\} \in \mathcal{F}_t$$

$$s \leq 0 \quad \sim \quad \in f_s \subset f_t$$

Note that we γ f_t rather than m_t in (X) , when $X_t \subset U_t \forall t$. The set of t -values appearing on $K \cup S$ of (X) is empty, since $m_t \phi = \infty$, we get $\tau = \infty$ then.

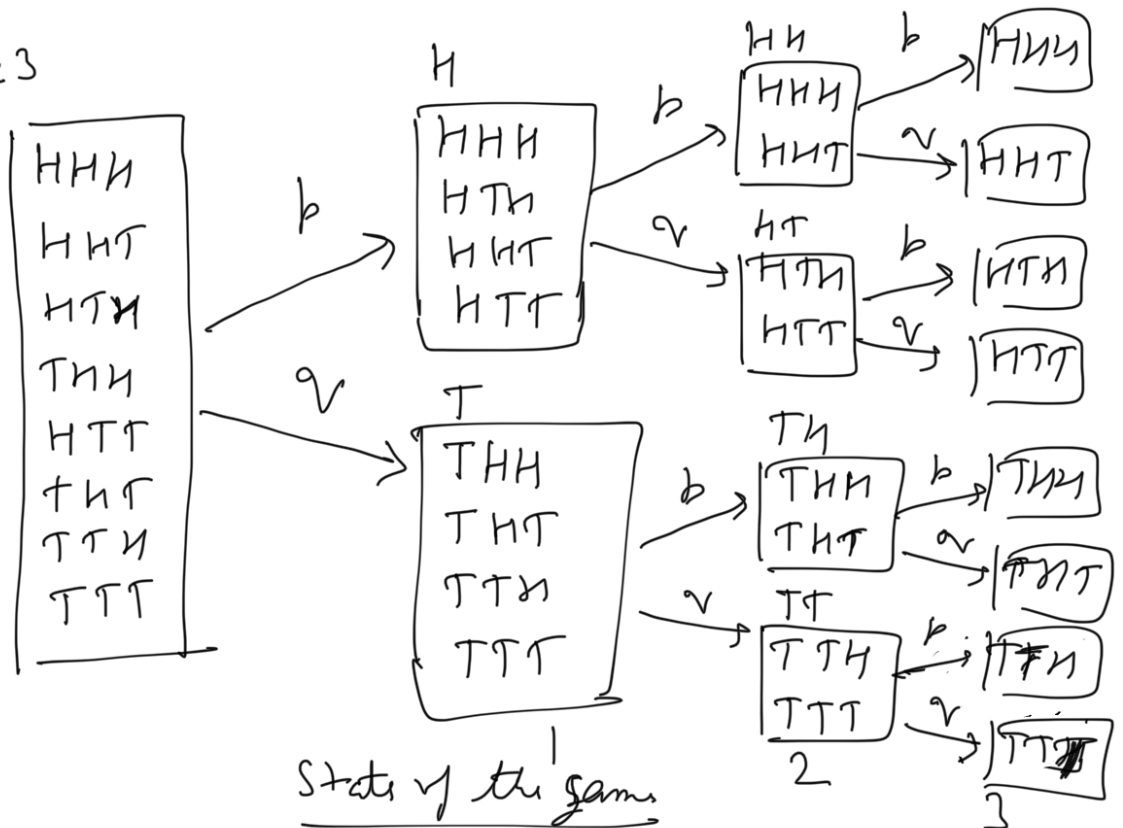
Example Coin tossing

$$t_0 < t_1 < \dots < t_N$$

$$\Omega_k = \{H, T\}^k$$

$$f_0 = [\phi, \Omega] ; f_1 = \sigma(A_H, A_T) ; f_2 = \sigma(A_{HH}, A_{HT}, A_{TH}, A_{TT})$$

eg $N=3$



Now let us suppose that for each head, a player wins \$1 and for each tails player loses \$1.

Let X_k be a r.v. on Ω that denote players winning in each round k .

for each $w \in J$,

$$X_k(\omega) = N_h([\omega_k]) - N_T([\omega_k])$$

$$|\gamma_n([w_k])| \text{ denote \# of heads in } [w_k]$$
$$N_T(\omega_1) \quad \therefore \quad \text{find } \kappa(\omega_k)$$
$$X_0, X_1, \dots, X_N \in SP$$
$$\{X_t\}_{t=0}^N \in \mathcal{SP}, \quad \text{when } X_0 = 0$$

X_k is F_k measurable, since X_t is adapted to filtration.

$$P(\omega) = p^{N_H(\omega)} q^{N_T(\omega)}$$

$\nearrow f(S_H)$

for each $\omega \in \Omega$
 $p+q=1$

$$\begin{array}{ccc} & & f(s_H) \\ f(s) & \nearrow & \\ \text{State} & & f(s_T) \end{array}$$

$$P(f_{k+1}(S_H) | f_k(S)) = p; \quad P(f_{k+1}(S_T) | f_k(S)) = q$$

$$p(f_k(s)) = p^{N_H(s)} q^{N_T(s)}$$

$$SP(X_t) \sim \underline{m_c}$$

$$\begin{aligned} E(X_{k+1} | \mathcal{F}_k(\delta)) &= X_k(\mathcal{F}_k(\delta)) \\ \Rightarrow \frac{E(X_{k+1} 1_{\mathcal{F}_k(\delta)})}{P(\mathcal{F}_k(\delta))} &= X_k(\mathcal{F}_k(\delta)) = N_q(\delta) - N_T(\delta) \\ &= W(\delta) \text{ say} \end{aligned}$$

$$\chi_{k+1}(\mathcal{L}_{k+1}(S_H)) = W(S) + 1$$

$$X_{k+1}(\mathcal{F}_{k+1}(\mathcal{S})) = W(\mathcal{S}) - 1$$

$$P(\mathcal{F}_{k+1}(\mathcal{S})) = p P(\mathcal{F}_k(\mathcal{S})) ; P(\mathcal{F}_{k+1}(\mathcal{S})) = q P(\mathcal{F}_k(\mathcal{S}))$$

$$\begin{aligned} E(X_{k+1} 1_{\mathcal{F}_k(\mathcal{S})}) &= \underbrace{E(X_{k+1} 1_{\mathcal{F}_k(\mathcal{S})} | \mathcal{F}_{k+1}(\mathcal{S}))}_{W(\mathcal{S}) - 1} P(\mathcal{F}_{k+1}(\mathcal{S})) \\ &\quad + \underbrace{E(X_{k+1} 1_{\mathcal{F}_k(\mathcal{S})} | \mathcal{F}_{k+1}(\mathcal{S}))}_{W(\mathcal{S}) - 1} P(\mathcal{F}_{k+1}(\mathcal{S})) \\ &= \underbrace{(W(\mathcal{S}) + 1)}_{p} P(\mathcal{F}_k(\mathcal{S})) + \underbrace{(W(\mathcal{S}) - 1)}_{q} P(\mathcal{F}_k(\mathcal{S})) \end{aligned}$$

$$\frac{E(X_{k+1} 1_{\mathcal{F}_k(\mathcal{S})})}{P(\mathcal{F}_k(\mathcal{S}))} = W(\mathcal{S}) + p - q$$

$$\begin{aligned} E(X_{k+1} | \mathcal{F}_k(\mathcal{S})) &= N_H(\mathcal{S}) - N_T(\mathcal{S}) + p - q \\ &= X_k(\mathcal{S}) + p - q \end{aligned}$$

$$(X_t) \text{ is MG iff } p = q = \frac{1}{2}$$

i.e. G.M. is fair

Thm $(X_t)_{t \geq 0}$ MG, τ S.T. on common filtered prob. space, then

$$Z_t := X_{t \wedge \tau}, \quad t = 0, 1, 2, \dots \text{ is MG on that space}$$

$$| a \wedge b = \min(a, b)$$

Sol

$$Z_0 = X_0$$

$$\text{For } t \geq 0 \quad Z_{t+1} = \sum_{k=0}^t X_k 1_{\tau=k} + X_{t+1} 1_{\tau > t}$$

$$1_A^{(n)} = \begin{cases} 1 & \text{if } n \in A \\ 0 & \text{if } n \notin A \end{cases}$$

$$E|Z_{t+1}| \leq E\left(\sum_{k=0}^{t+1} |X_k|\right) = \sum_{k=0}^{t+1} E|X_k| < \infty$$

$\therefore X_t$ M.G.

$$E(Z_{t+1} | \mathcal{F}_t) = E\left(\sum_{k=0}^t X_k 1_{\{\tau \geq k\}} + X_{t+1} 1_{\{\tau > t\}} \middle| \mathcal{F}_t\right)$$

$$= \sum_{k=0}^t X_k 1_{\{\tau \geq k\}} + \underbrace{E(X_{t+1} 1_{\{\tau > t\}} | \mathcal{F}_t)}$$

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$$1_{\{\tau > t\}} E(X_{t+1} | \mathcal{F}_t)$$

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$$1_{\{\tau > t\}} X_t$$

$$= \sum_{k=0}^t X_k 1_{\{\tau \geq k\}} + X_t 1_{\{\tau > t\}} \quad \left| \because X_t \text{ is M.G.} \right.$$

$$= Z_t$$

$\therefore [Z_t = X_{t \wedge \tau}]$ is M.G.

Thm: Optimal Stopping thm (martingale stopping thm)

(X_t) M.G., τ bounded S.T. (i.e. for a const $c < \infty$

one has $\tau < c$ a.s.)

$$\text{Th. } E[X_\tau] = E[X_0]$$

$$E(X_{t \wedge \tau}) = E(X_0) \quad \text{--- (1)}$$

(Thus, in a fair game, one cannot invent a rule for quitting the game that would "beat the system": the game will remain fair)

Sol $Z_t = X_{t \wedge \tau}$ is MG,

∵ MG has const mem

$$E(X_{t \wedge \tau}) = E(X_0)$$

setting $t := C$ yields (1).