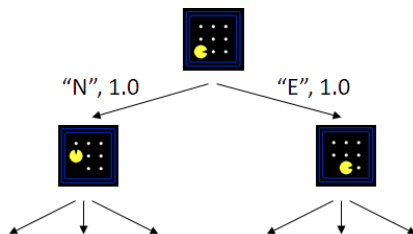


Problem Formulation

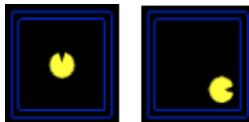
1-Initial State:



2-Successor Function:



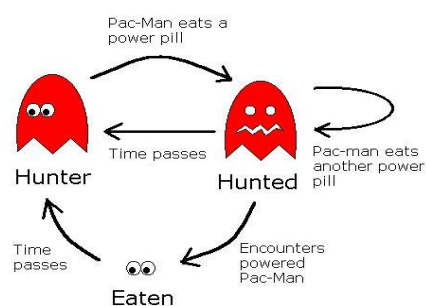
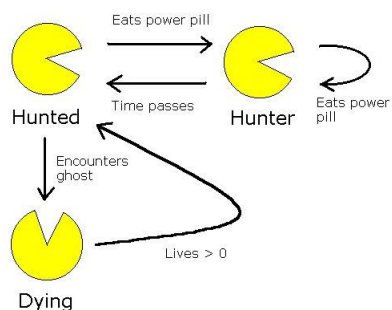
3-Goal Test:



4-Path Cost:

One for each step.

State Space



Search Tree

