

2019年05月18日

CSC421

2 a) Adam

RMSProp

$$v_t \leftarrow B_2 v_{t-1} + (1-B_2) g_t^2$$

$$v_t \leftarrow \gamma v_{t-1} + (1-\gamma) g_t^2$$

$$\theta_t \leftarrow \theta_{t-1} - \alpha_A m_t / (\sqrt{v_t} + \epsilon_A)$$

$$\theta_t \leftarrow \theta_{t-1} - \alpha_R g_t / (\sqrt{v_t} + \epsilon_R)$$

$$m_t \leftarrow B_1 m_{t-1} + (1-B_1) g_t$$

\therefore Set $B_2 = \gamma$.

$$B_1 = 0 \Rightarrow m_t = g_t$$

$$\alpha_A = \alpha_R$$

$$\epsilon_A = \epsilon_R$$

b) SGD w/momentum

$$p_t \leftarrow \mu p_{t-1} - (1-\mu) \nabla F(\theta_{t-1})$$

$$\theta_t \leftarrow \theta_{t-1} + \alpha_S p_t$$

$$\text{Want: } \alpha_S p_t \approx \alpha_A m_t / (\sqrt{v_t} + \epsilon_A)$$

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$$\text{Setting } B_2 = 1 \Rightarrow v_t \leftarrow v_{t-1} = 0 \quad \forall t$$

$$\text{Setting } \epsilon_A = 1, \alpha_A \neq -\alpha_S$$

$$\alpha_S p_t = -\alpha_S m_t$$

$$\text{Want: } p_t = -m_t$$

$$\text{Setting } B_1 = \mu \Rightarrow m_t = \mu m_{t-1} + (1-\mu) \nabla F(\theta_{t-1})$$

\rightarrow update eq's almost the same. m_t sums the gradient, p_t sums the neg.

Noting that $p_0 = m_0 = 0$, then:

$$p_1 = \mu p_0 - (1-\mu) \nabla F(\theta_0)$$

$$p_2 = -\mu(1-\mu) \nabla F(\theta_0) + (1-\mu) \nabla F(\theta_1)$$

$$p_3 = -\mu^2(1-\mu) \nabla F(\theta_0) - \mu(1-\mu) \nabla F(\theta_1) - (1-\mu) \nabla F(\theta_2)$$

$$p_T = \sum_{t=1}^T -\mu^{T-t} (1-\mu) \nabla F(\theta_{t-1})$$

$$\text{similarly: } m_T = \sum_{t=1}^T \mu^{T-t} (1-\mu) \nabla F(\theta_{t-1})$$

as required, $p_t = -m_t$

c) Suppose $\tilde{F} = C \cdot F$

$$\tilde{g}_t \leftarrow \nabla C \cdot F = C \cdot \nabla F = C \cdot g_t$$

$$\tilde{m}_t \leftarrow B_1 \tilde{m}_{t-1} + (1 - B_1) C g_t$$

$$\tilde{V}_t \leftarrow B_2 \tilde{V}_{t-1} + (1 - B_2) C^2 g_t^2$$

$$\tilde{\Theta}_t \leftarrow \tilde{\Theta}_{t-1} - \alpha_A \tilde{m}_t / \sqrt{\tilde{V}_t}$$

$$\text{Recall: } m_T = \sum_{t=1}^T B_1^{T-t} (1 - B_1) \nabla F(\Theta_{t-1})$$

$$\text{Clearly } \tilde{m}_T = C m_T \text{ since } \nabla \tilde{F} = C \nabla F.$$

By a very similar argument (e.g. let $\hat{g}_t = g_t^2$)

$$V_T = \sum_{t=1}^T B_2^{T-t} (1 - B_2) (\nabla F(\Theta_{t-1}))^2$$

$$\text{Again, noting } \nabla \tilde{F} = C \nabla F, \tilde{V}_T = C^2 V_T$$

$$\text{Then: } \tilde{\Theta}_t \leftarrow \tilde{\Theta}_{t-1} - \alpha_A C m_t / \sqrt{C^2 V_t}$$

$$\tilde{\Theta}_t \leftarrow \tilde{\Theta}_{t-1} - \alpha_A m_t / \sqrt{V_t}$$

P. Assuming $\tilde{\Theta}_{t-1} = \Theta_{t-1}$, this is the same recurrence.

$$\text{Base case: } \Theta_0 = 0 = \tilde{\Theta}_0.$$

\therefore If $C_A = 0$, then the trajectory is invariant to the scale of the loss fct.