# Application Assignment: Filter #114

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April 7, 2024

### 1 Introduction

We are supposed to design the equivalent FIR and IIR filter realizations for filter number 114. This is a bandpass filter whose specifications are available below.

# 2 Filter Specifications

The sampling rate for the filter has been specified as  $F_s = 48$  kHz. If the unnormalized discrete-time (natural) frequency is F, the corresponding normalized digital filter (angular) frequency is given by  $\omega = 2\pi \left(\frac{F}{F_s}\right)$ .

#### 2.1 The Digital Filter

- 1. Tolerances: The passband  $(\delta_1)$  and stopband  $(\delta_2)$  tolerances are given to be equal, so we let  $\delta_1 = \delta_2 = \delta = 0.15$ .
- 2. Passband: The passband of filter number j,j going from 109 to 135 is from  $\{3+0.6(j-109)\}$ kHz to  $\{3+0.6(j-107)\}$ kHz. Since our filter number is 114, substituting j=114 gives the passband range for our bandpass filter as 6 kHz 7.2 kHz. Hence, the un-normalized discrete time filter passband frequencies are  $F_{p1}=7.2$  kHz and  $F_{p2}=6.0$  kHz. The corresponding normalized digital filter passband frequencies are  $\omega_{p1}=2\pi\frac{F_{p1}}{F_s}=0.3\pi$  and  $\omega_{p2}=2\pi\frac{F_{p2}}{F_s}=0.25\pi$  kHz. The centre frequency is then given by  $\omega_c=\frac{\omega_{p1}+\omega_{p2}}{2}=0.275\pi$ .
- 3. Stopband: The transition band for bandpass filters is  $\Delta F = 0.3$  kHz on either side of the passband. Hence, the un-normalized stopband frequencies are  $F_{s1} = 7.2 + 0.3 = 7.5$  kHz and  $F_{s2} = 6.0 0.3 = 5.7$  kHz. The corresponding normalized frequencies are  $\omega_{s1} = 0.3125\pi$  and  $\omega_{s2} = 0.2375\pi$ .

#### 2.2 The Analog filter

In the bilinear transform, the analog filter frequency  $(\Omega)$  is related to the corresponding digital filter frequency  $(\omega)$  as  $\Omega = \tan \frac{\omega}{2}$ . Using this relation, we obtain the analog passband and stopband frequencies as  $\Omega_{p1} = 0.5095$ ,  $\Omega_{p2} = 0.4142$  and  $\Omega_{s1} = 0.5345$ ,  $\Omega_{s2} = 0.3914$  respectively.

# 3 The IIR Filter Design

Filter Type: We are supposed to design filters whose stopband is monotonic and passband equiripple. Hence, we use the *Chebyschev approximation* to design our bandpass IIR filter.

#### 3.1 The Analog Filter

1. Low Pass Filter Specifications: If  $H_{a,BP}(j\Omega)$  be the desired analog band pass filter, with the specifications provided in Section 2.2, and  $H_{a,LP}(j\Omega_L)$  be the equivalent low pass filter, then

$$\Omega_L = \frac{\Omega^2 - \Omega_0^2}{B\Omega} \tag{1}$$

where  $\Omega_0 = \sqrt{\Omega_{p1}\Omega_{p2}} = 0.4594$  and  $B = \Omega_{p1} - \Omega_{p2} = 0.0953$ . The low pass filter has the passband edge at  $\Omega_{Lp} = 1$  and stopband edges at  $\Omega_{Ls_1} = 1.4653$  and  $\Omega_{Ls_2} = -1.5511$ . We choose the stopband edge of the analog low pass filter as  $\Omega_{Ls} = \min(|\Omega_{Ls_1}|, |\Omega_{Ls_2}|) = 1.4653$ .

2. The Low Pass Chebyschev Filter Paramters: The magnitude squared of the Chebyschev low pass filter is given by

$$|H_{a,LP}(j\Omega_L)|^2 = \frac{1}{1 + \epsilon^2 c_N^2(\Omega_L/\Omega_{Lp})}$$
 (2)

where  $c_N(x) = \cosh(N \cosh^{-1} x)$  and the integer N, which is the order of the filter, and  $\epsilon$  are design paramters. Since  $\Omega_{Lp} = 1$ , (??) may be rewritten as

$$|H_{a,LP}(j\Omega_L)|^2 = \frac{1}{1 + \epsilon^2 c_N^2(\Omega_L)}$$
(3)

Also, the design paramters have the following constraints

$$\frac{\sqrt{D_2}}{c_N(\Omega_{Ls})} \le \epsilon \le \sqrt{D_1},$$

$$N \ge \left\lceil \frac{\cosh^{-1} \sqrt{D_2/D_1}}{\cosh^{-1} \Omega_{Ls}} \right\rceil,$$
(4)

where  $D_1 = \frac{1}{(1-\delta)^2} - 1$  and  $D_2 = \frac{1}{\delta^2} - 1$ . After appropriate substitutions, we obtain  $N \ge 4$  and  $0.3184 \le \epsilon \le 0.6197$ . In Figure 1, we plot  $|H(j\Omega)|$ 

for a range of values of  $\epsilon$ , for N=4. We find that for larger values of  $\epsilon$ ,  $|H(j\Omega)|$  decreases in the transition band. We choose  $\epsilon=0.4$  for our IIR filter design.

3. The Low Pass Chebyschev Filter: Thus, we obtain

$$|H_{a,LP}(j\Omega_L)|^2 = \frac{1}{1 + 0.16c_4^2(\Omega_L)}$$
 (5)

where

$$c_4(x) = 8x^4 + 8x^2 + 1. (6)$$

The poles of the frequency response in (??) lying in the left half plane are in general obtained as  $r_1 \cos \phi_k + jr_2 \sin \phi_k$ , where

$$\phi_k = \frac{\pi}{2} + \frac{(2k+1)\pi}{2N}, k = 0, 1, \dots, N-1$$

$$r_1 = \frac{\beta^2 - 1}{2\beta}, r_2 = \frac{\beta^2 + 1}{2\beta}, \beta = \left[\frac{\sqrt{1 + \epsilon^2} + 1}{\epsilon}\right]^{\frac{1}{N}}$$
(7)

Thus, for N even, the low-pass stable Chebyschev filter, with a gain G has the form

$$H_{a,LP}(s_L) = \frac{G_{LP}}{\prod_{k=1}^{\frac{N}{2}-1} (s_L^2 - 2r_1 \cos \phi_k s_L + r_1^2 \cos^2 \phi_k + r_2^2 \sin^2 \phi_k)}$$
(8)

Substituting  $N=4,\,\epsilon=0.5$  and  $H_{a,LP}(j)=\frac{1}{\sqrt{1+\epsilon^2}},$  from (??) and (??), we obtain

$$H_{a,LP}(s_L) = \frac{0.3125}{s_L^4 + 1.1068s_L^3 + 1.6125s_L^2 + 0.9140s_L + 0.3366}$$
(9)

In Figure 2 we plot  $|H(j\Omega)|$  using (??) and (??), thereby verifying that our low-pass Chebyschev filter design meets the specifications.

4. The Band Pass Chebyschev Filter: The analog bandpass filter is obtained from (??) by substituting  $s_L = \frac{s^2 + \Omega_0^2}{Bs}$ . Hence

$$H_{a,BP}(s) = G_{BP}H_{a,LP}(s_L)|_{\substack{s_L = \frac{s^2 + \Omega_0^2}{Bs}}},$$
 (10)

where  $G_{BP}$  is the gain of the bandpass filter. After appropriate substitutions, and evaluating the gain such that  $H_{a,BP}(j\Omega_{p1}) = 1$ , we obtain

$$H_{a,BP}(s) = \frac{2.7776 \times 10^{-5} s^4}{s^8 + 0.1055 s^7 + 0.8589 s^6 + 0.0676 s^5 + 0.2735 s^4 + 0.0143 s^3 + 0.0383 s^2 + 0.001 s + 0.002} \tag{11}$$

In Figure 3, we plot  $|H_{a,BP}(j\Omega)|$  as a function of  $\Omega$  for both positive as well as negative frequencies. We find that the passband and stopband frequencies in the figure match well with those obtained analytically through the bilinear transformation.

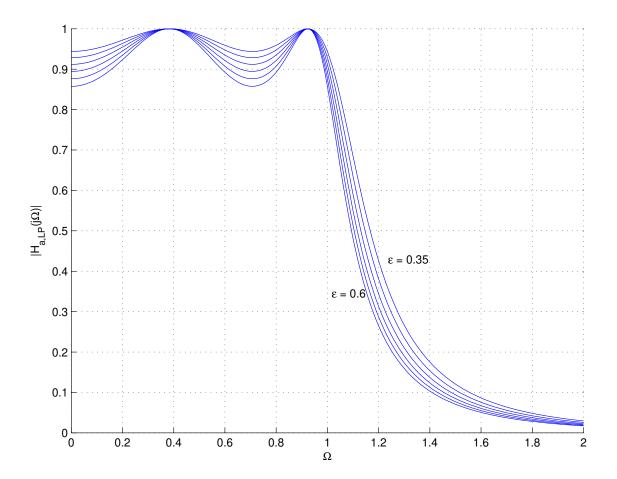


Figure 1: The Analog Low-Pass Frequency Response for  $0.35 \leq \epsilon \leq 0.6$ 

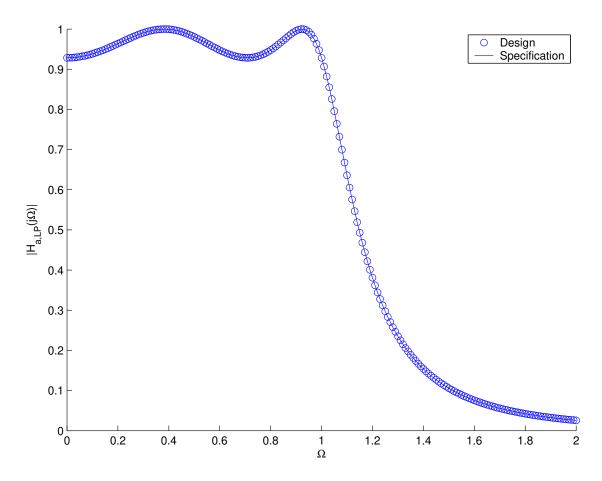


Figure 2: The magnitude response plots from the specifications in Equation ?? and the design in Equation ??

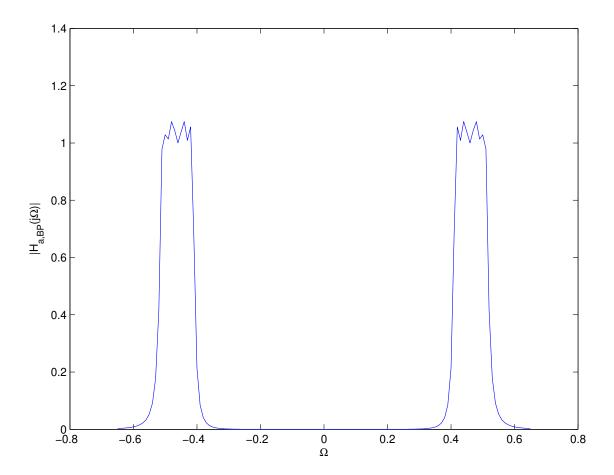


Figure 3: The analog bandpass magnitude response plot from Equation ??

## 3.2 The Digital Filter

From the bilinear transformation, we obtain the digital bandpass filter from the corresponding analog filter as

$$H_{d,BP}(z) = GH_{a,BP}(s)|_{s=\frac{1-z^{-1}}{1+z^{-1}}}$$
 (12)

where G is the gain of the digital filter. From (??) and (??), we obtain

$$H_{d,BP}(z) = G\frac{N(z)}{D(z)} \tag{13}$$

where  $G = 2.7776 \times 10^{-5}$ ,

$$N(z) = 1 - 4z^{-2} + 6z^{-4} - 4z^{-6} + z^{-8}$$
(14)

and

$$D(z) = 2.3609 - 12.0002z^{-1} + 31.8772z^{-2} - 53.7495z^{-3} + 62.8086z^{-4} -51.4634z^{-5} + 29.2231z^{-6} - 10.5329z^{-7} + 1.9842z^{-8}$$
 (15)

The plot of  $|H_{d,BP}(z)|$  with respect to the normalized angular frequency (normalizing factor  $\pi$ ) is available in Figure 4. Again we find that the passband and stopband frequencies meet the specifications well enough.

#### 4 The FIR Filter

We design the FIR filter by first obtaining the (non-causal) lowpass equivalent using the Kaiser window and then converting it to a causal bandpass filter.

#### 4.1 The Equivalent Lowpass Filter

The lowpass filter has a passband frequency  $\omega_l$  and transition band  $\Delta\omega = 2\pi \frac{\Delta F}{F_s} = 0.0125\pi$ . The stopband tolerance is  $\delta$ .

- 1. The passband frequency  $\omega_l$  is defined as  $\omega_l = \frac{\omega_{p1} \omega_{p2}}{2}$ . Substituting the values of  $\omega_{p1}$  and  $\omega_{p2}$  from section 2.1, we obtain  $\omega_l = 0.025\pi$ .
- 2. The impulse response  $h_{lp}(n)$  of the desired lowpass filter with cutoff frequency  $\omega_l$  is given by

$$h_l(n) = \frac{\sin(n\omega_l)}{n\pi} w(n), \tag{16}$$

where w(n) is the Kaiser window obtained from the design specifications.

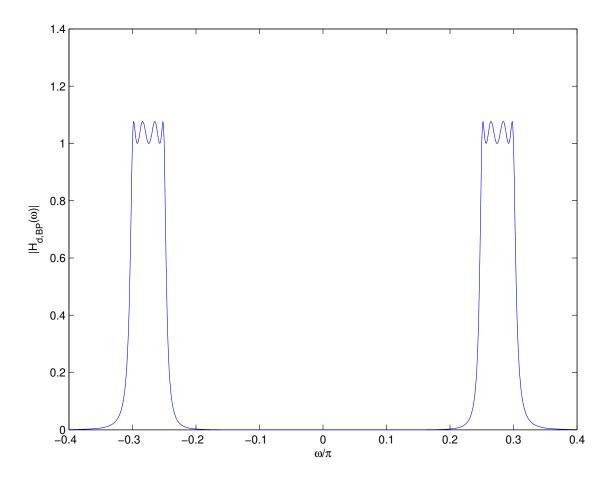


Figure 4: The magnitude response of the bandpass digital filter designed to meet the given specifications

## 4.2 The Kaiser Window

The Kaiser window is defined as

$$w(n) = \frac{I_0 \left[\beta N \sqrt{1 - \left(\frac{n}{N}\right)^2}\right]}{I_0(\beta N)}, \quad -N \le n \le N, \quad \beta > 0$$

$$= 0 \quad \text{otherwise}, \quad (17)$$

where  $I_0(x)$  is the modified Bessel function of the first kind of order zero in x and  $\beta$  and N are the window shaping factors. In the following, we find  $\beta$  and N using the design parameters in section 2.1.

1. N is chosen according to

$$N \ge \frac{A - 8}{4.57\Delta\omega},\tag{18}$$

where  $A = -20 \log_{10} \delta$ . Substituting the appropriate values from the design specifications, we obtain A = 16.4782 and  $N \ge 48$ .

2.  $\beta$  is chosen according to

$$\beta N = \begin{cases} 0.1102(A - 8.7) & A > 50\\ 0.5849(A - 21)^{0.4} + 0.07886(A - 21) & 21 \le A \le 50\\ 0 & A < 21 \end{cases}$$
(19)

In our design, we have A=16.4782<21. Hence, from (??) we obtain  $\beta=0$ .

3. We choose N = 100, to ensure the desired low pass filter response. Substituting in  $(\ref{eq:state})$  gives us the rectangular window

$$w(n) = 1, -100 \le n \le 100$$
  
= 0 otherwise (20)

From (??) and (??), we obtain the desired lowpass filter impulse response

$$h_{lp}(n) = \frac{\sin(\frac{n\pi}{40})}{n\pi} - 100 \le n \le 100$$

$$= 0, \quad \text{otherwise}$$
(21)

The magnitude response of the filter in (??) is shown in Figure 5.

#### 4.3 The FIR Bandpass Filter

The centre of the passband of the desired bandpass filter was found to be  $\omega_c = 0.275\pi$  in Section 2.1. The impulse response of the desired bandpass filter is obtained from the impulse response of the corresponding lowpass filter as

$$h_{bp}(n) = 2h_{lp}(n)cos(n\omega_c)$$
(22)

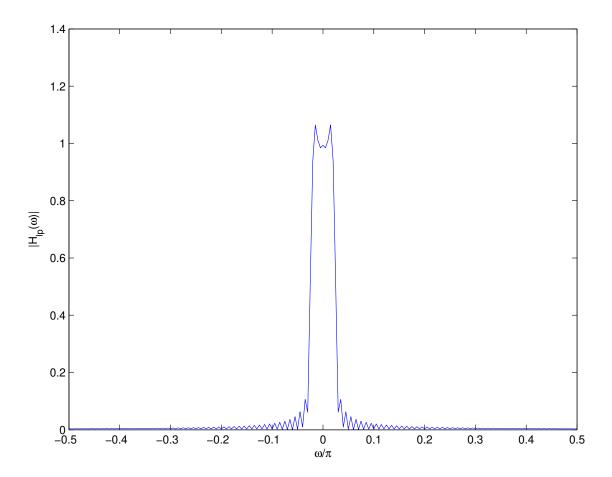


Figure 5: The magnitude response of the FIR lowpass digital filter designed to meet the given specifications  $\,$ 

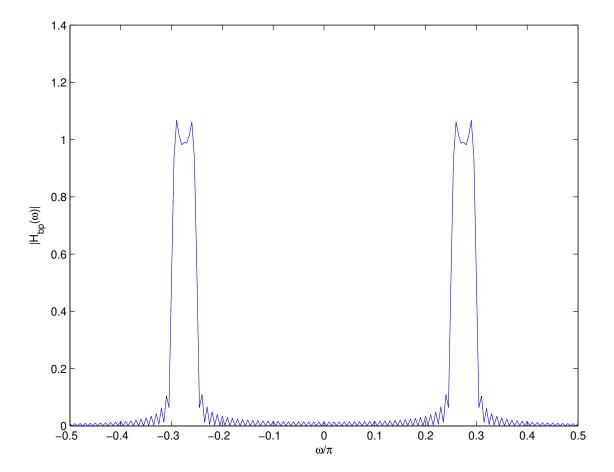


Figure 6: The magnitude response of the FIR bandpass digital filter designed to meet the given specifications

Thus, from (??), we obtain

$$h_{bp}(n) = \frac{2\sin(\frac{n\pi}{40})\cos(\frac{11n\pi}{40})}{n\pi} - 100 \le n \le 100$$

$$= 0, \qquad \text{otherwise}$$
(23)

The magnitude response of the FIR bandpass filter designed to meet the given specifications is plotted in Figure 6.