

Totally Integrated Automation Portal

4R_Veloce_05_June / PLC [CPU 1214C DC/DC/DC] / Program blocks

Operation_cycle [FB24]

Operation_cycle Properties

General

Name	Operation_cycle	Number	24	Type	FB	Language	LAD
Numbering	Automatic						

Information

Title		Author		Comment		Family	
Version	0.1	User-defined ID					

Operation_cycle

Name	Data type	Default value	Retain	Accessible from HMI/OPC UA	Writ-able from HMI/OPC UA	Visible in HMI engi-neering	Setpoint	Supervi-sion	Comment
▼ Input									
Input_cmd_moc	Int	0	Non-retain	True	True	True	False		
RACK	Bool	false	Non-retain	True	True	True	False		
RACK_EXT	Bool	false	Non-retain	True	True	True	False		
BIN_DETECT	Bool	false	Non-retain	True	True	True	False		
TELESH1	Bool	false	Non-retain	True	True	True	False		
TELESH2	Bool	false	Non-retain	True	True	True	False		
BINC1	Bool	false	Non-retain	True	True	True	False		
BINC2	Bool	false	Non-retain	True	True	True	False		
Lift_reached	Bool	false	Non-retain	True	True	True	False		
Turntable_reached	Bool	false	Non-retain	True	True	True	False		
telescope_reached	Bool	false	Non-retain	True	True	True	False		
fork_reached	Bool	false	Non-retain	True	True	True	False		
Turn Act pos	DInt	0	Non-retain	True	True	True	False		
tele Act pos	DInt	0	Non-retain	True	True	True	False		
TUrntable_correction	DInt	0	Non-retain	True	True	True	False		
reset	Bool	false	Non-retain	True	True	True	False		
STO	Bool	false	Non-retain	True	True	True	False		
Turn_complete_sensor	Bool	false	Non-retain	True	True	True	False		
forks_down	Bool	false	Non-retain	True	True	True	False		
forks_up	Bool	false	Non-retain	True	True	True	False		
TelePick_intdeep1_mm	DInt	0	Non-retain	True	True	True	False		
TelePlace_intdeep1_mm	DInt	0	Non-retain	True	True	True	False		
turn_act_deg	DInt	0	Non-retain	True	True	True	False		
Lateral_offset	DInt	0	Non-retain	True	True	True	False		
TURNATEXT	Bool	false	Non-retain	True	True	True	False		
telepick_exedeeep1_extension	DInt	0	Non-retain	True	True	True	False		
telepick_exedeeep2_extension	DInt	0	Non-retain	True	True	True	False		
teleplace_exedeeep1_exten-sion	DInt	0	Non-retain	True	True	True	False		
teleplace_exedeeep2_exten-sion	DInt	0	Non-retain	True	True	True	False		
tele_joglimit_exten-sion_deep1	DInt	0	Non-retain	True	True	True	False		
tele_joglimit_exten-sion_deep2	DInt	0	Non-retain	True	True	True	False		
Tele_cmd_pos	DInt	0	Non-retain	True	True	True	False		
Jog_vel_Operation	DInt	0	Non-retain	True	True	True	False		
Lift_Barcode_pick_offset	Int	0	Non-retain	True	True	True	False		
Lift_Rack_IN_Offset	Int	0	Non-retain	True	True	True	False		
turn_offset	DInt	0	Non-retain	True	True	True	False		
▼ Output									
mOVE_TURN_TARGET	Bool	false	Non-retain	True	True	True	False		
Lift_Rack_offset	Int	0	Non-retain	True	True	True	False		
Lift Position	Int	0	Non-retain	True	True	True	False		
Tele_Pos_reached	Bool	false	Non-retain	True	True	True	False		
Turn_pos_reached	Bool	false	Non-retain	True	True	True	False		
Lift_pick_offset	Int	0	Non-retain	True	True	True	False		
tele_mode	Byte	16#0	Non-retain	True	True	True	False		
Turn_mode	Byte	16#0	Non-retain	True	True	True	False		
Jog_velocity	DInt	0	Non-retain	True	True	True	False		
tURN_CMD_POS	DInt	0	Non-retain	True	True	True	False		
telescope position	DInt	0	Non-retain	True	True	True	False		
Lift_execute	Bool	false	Non-retain	True	True	True	False		
Turntable_execute	Bool	false	Non-retain	True	True	True	False		
Telescope_execute	Bool	false	Non-retain	True	True	True	False		
fork	Int	0	Non-retain	True	True	True	False		
Lift_exePick	Bool	false	Non-retain	True	True	True	False		
lift_exe_picko1	Bool	false	Non-retain	True	True	True	False		
Lift_exePlace	Bool	false	Non-retain	True	True	True	False		
forkuppick	Int	0	Non-retain	True	True	True	False		
forkdownpick	Int	0	Non-retain	True	True	True	False		

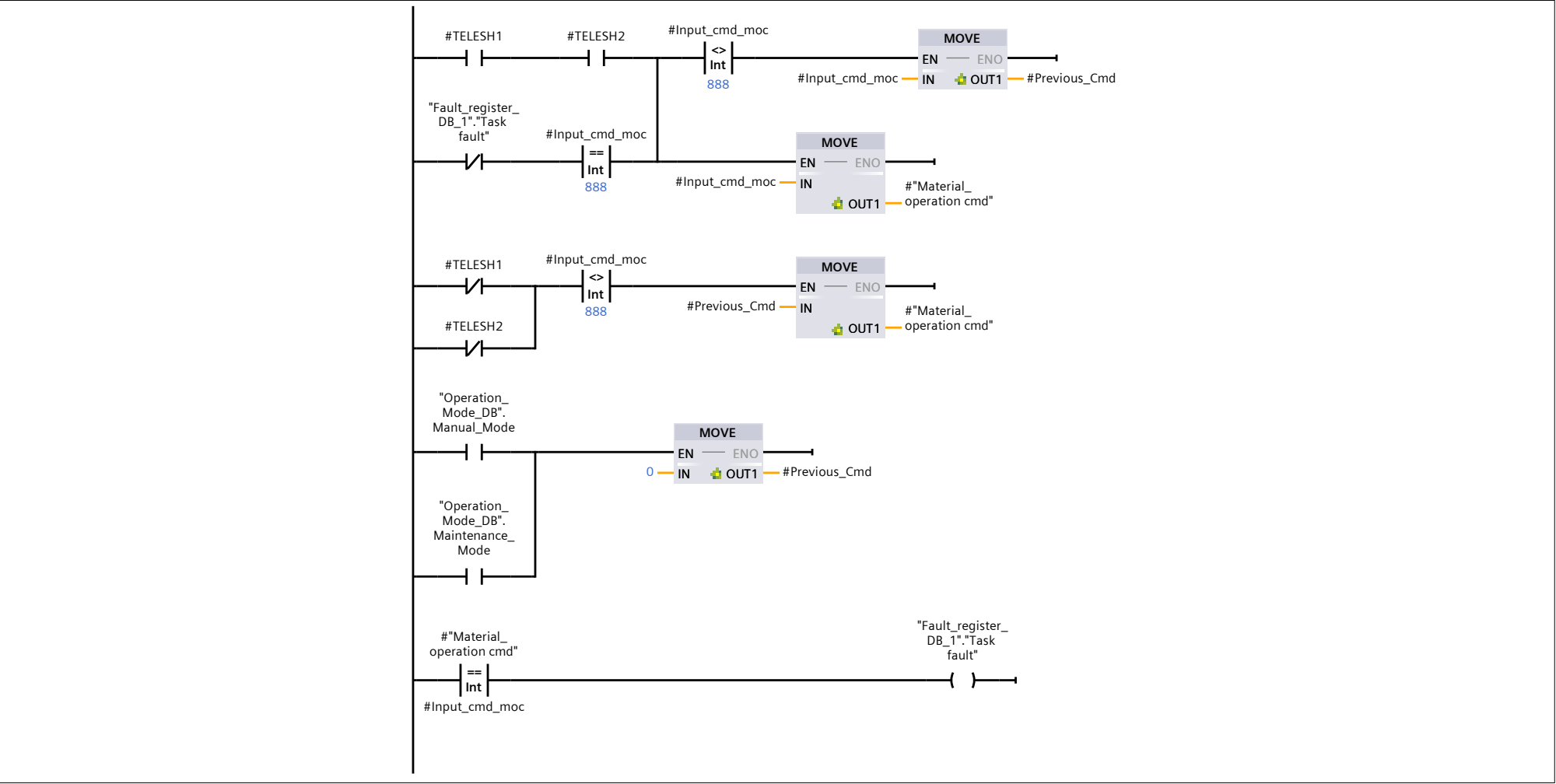
Totally Integrated Automation Portal									
Name	Data type	Default value	Retain	Accessible from HMI/OPC UA	Writ-able from HMI/OPC UA	Visible in HMI engi-neering	Setpoint	Supervi-sion	Comment
t6	Bool	false	Non-retain	False	False	False	False		
t7	Bool	false	Non-retain	False	False	False	False		
t8	Bool	false	Non-retain	False	False	False	False		
picked	Bool	false	Non-retain	True	True	True	False		
Deep	Int	0	Non-retain	True	True	True	False		
forkupplace	Int	0	Non-retain	True	True	True	False		
forkdownplace	Int	0	Non-retain	True	True	True	False		
Lif_temp	Int	0	Non-retain	True	True	True	False		
turntable pos	DInt	0	Non-retain	True	True	True	False		
POSITION	DInt	0	Non-retain	True	True	True	False		
Mov_turn_pos	Int	0	Non-retain	True	True	True	False		
jog_count	Int	0	Non-retain	True	True	True	False		
Material_op_temp	Int	0	Non-retain	True	True	True	False		
Ext_Lift_offset	Int	0	Non-retain	True	True	True	False		
Material_operation cmd	Int	0	Non-retain	True	True	True	False		
Static_1	Int	0	Non-retain	True	True	True	False		
Previous_Cmd	Int	0	Non-retain	True	True	True	False		
Lateral_extension_mm	DInt	0	Non-retain	True	True	True	False		
TelePick_extdeep1_mm	DInt	0	Non-retain	True	True	True	False		
TelePick_extdeep2_mm	DInt	0	Non-retain	True	True	True	False		
TelePlace_extdeep1_mm	DInt	0	Non-retain	True	True	True	False		
TelePlace_extdeep2_mm	DInt	0	Non-retain	True	True	True	False		
Telepick_Joglimit_deep2_mm	DInt	0	Non-retain	True	True	True	False		
Telepick_Joglimit_deep1_mm	DInt	0	Non-retain	True	True	True	False		
lateral_shift_doubledeep	DInt	0	Non-retain	True	True	True	False		
Tele_stalled_oper_pick	Bool	false	Non-retain	True	True	True	False		
Tele_fork_contact_pos	DInt	0	Non-retain	True	True	True	False		
tele_exeplace7	Bool	false	Non-retain	True	True	True	False		
tele_exePick8	Bool	false	Non-retain	True	True	True	False		
turn_exePick_1	Bool	false	Non-retain	True	True	True	False		
RACK_CYCLE	Int	0	Non-retain	False	False	False	False		
Rack_Place_Cycle	Int	0	Non-retain	False	False	False	False		
Turn_Corr_Step	Int	0	Non-retain	True	True	True	False		
tele_execute_4	Bool	false	Non-retain	False	False	False	False		
turn_table_offset	DInt	0	Non-retain	True	True	True	False		
turn_offset1	DInt	0	Non-retain	True	True	True	False		
turn_exePlace_1	Bool	false	Non-retain	True	True	True	False		
error_factor	Int	0	Non-retain	True	True	True	False		
Temp									
Constant									

Network 2:

```
0001 IF #Lateral_offset > 40 AND #Deep=1 THEN
0002     #Lateral_extension_mm := 40;
0003 ELSE
0004     IF #Lateral_offset < 0 THEN
0005         #Lateral_extension_mm := 0;
0006         ;
0007
0008     ELSE
0009         IF #Lateral_offset > 0 AND #Lateral_offset < 40 THEN
0010             #Lateral_extension_mm := #Lateral_offset;
0011             ;
0012             END_IF;
0013         END_IF;
0014     END_IF;
0015 IF #Lateral_offset > 30 AND #Deep = 2 THEN
0016     #lateral_shift_doubledeep := 30;
0017 ELSE
0018     IF #Lateral_offset < 0 THEN
0019         #lateral_shift_doubledeep := 0;
0020         ;
0021
0022     ELSE
0023         IF #Lateral_offset > 0 AND #Lateral_offset < 30 THEN
0024             #lateral_shift_doubledeep := #Lateral_offset;
0025             ;
0026             END_IF;
0027         END_IF;
0028     END_IF;
0029 #TelePick_extdeep1_mm := #telepick_exedeep1_extension + #Lateral_extension_mm - 20;
0030 #TelePick_extdeep2_mm := #telepick_exedeep2_extension + #lateral_shift_doubledeep- 20;
0031 #TelePlace_extdeep1_mm := #teleplace_exedeep1_extension + #Lateral_extension_mm- 20;
0032 #TelePlace_extdeep2_mm := #teleplace_exedeep2_extension + #lateral_shift_doubledeep- 20;
0033 #Telepick_Joglimit_deep1_mm := #tele_joglimit_extension_deep1 + #Lateral_extension_mm - 20;
0034 //#Telepick_Joglimit_deep2_mm := #tele_joglimit_extension_deep2 + #lateral_shift_doubledeep - 20;
```

```
0035
0036 #Telepick_Joglimit_deep2_mm := 1400;
0037 IF #Telepick_Joglimit_deep1_mm >= 800 THEN
0038     #Telepick_Joglimit_deep1_mm := 800;
0039 ;
0040 END_IF;
0041
0042 IF #TelePlace_extdeep2_mm >= 1400 THEN
0043     #TelePlace_extdeep2_mm := 1400;
0044 ;
0045 END_IF;
0046 IF #TelePick_extdeep2_mm >= 1400 THEN
0047     #TelePick_extdeep2_mm := 1400;
0048 ;
0049 END_IF;
0050 IF #Input_cmd_moc = 888 THEN
0051     #Lift_double_place_offset := 0;
0052 ;
0053 END_IF;
```

Network 3:



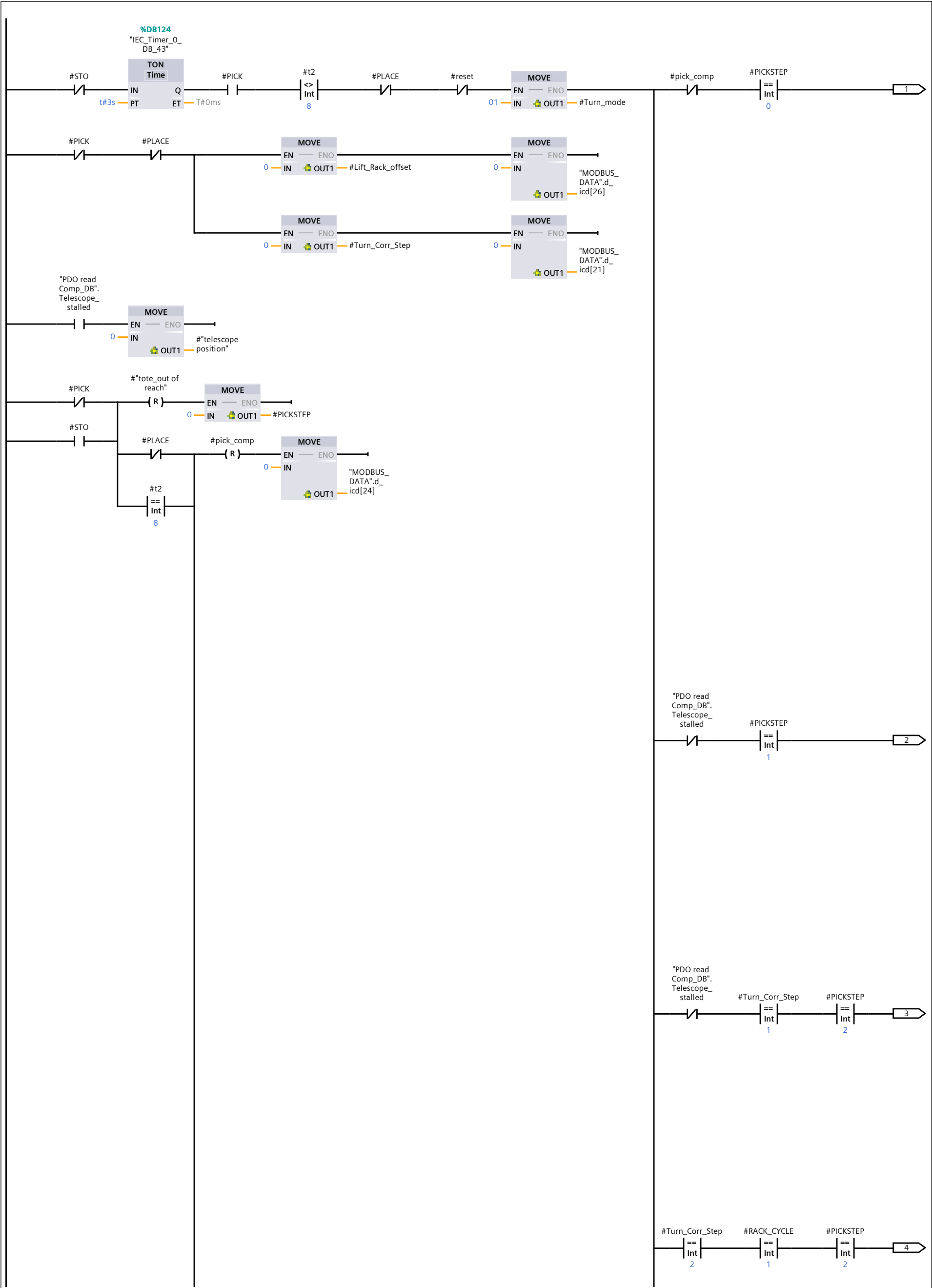
Network 4:

```
0001 #Lif_temp := #Material_op_temp MOD 10;
0002 IF #PICK OR #PLACE THEN
0003     #"Lift Position" := #Lif_temp;
0004 END_IF;
0005 IF #t2 = 8 THEN
0006     #"Lift Position" := 1;
0007 ;
0008 END_IF;
0009 #Deep := #"Material_operation cmd" / 1000;
0010
0011 #Material_op_temp := #"Material_operation cmd" MOD 1000;
0012
0013 #t1:=#Material_op_temp / 10;
0014 #turntable_dir := #t1 MOD 10;
0015
0016 #t2:= #t1/10;
0017 IF (#t2 = 1) THEN
0018     #PICK := 1;
0019
0020 END_IF;
0021 IF (#t2 <>1) THEN
0022     #PICK := 0;
0023 END_IF;
0024 IF (#t2 = 2) THEN
0025     #PLACE := 1;
0026 END_IF;
0027 IF (#t2 <> 2) THEN
0028     #PLACE := 0;
0029 END_IF;
```

Totally Integrated Automation Portal		
<pre>0030 IF #Material_op_temp=0 THEN 0031 #Mov_turn_pos := 0; 0032 ; 0033 END_IF; 0034 0035 0036 IF #turntable_dir=1 AND #Material_op_temp>0 THEN 0037 #"turntable pos" := -90; 0038 #Mov_turn_pos := 1; 0039 0040 ; 0041 END_IF; 0042 0043 IF #turntable_dir = 2 AND #Material_op_temp>0 THEN 0044 #"turntable pos" := 90; 0045 #Mov_turn_pos := 2; 0046 0047 ; 0048 END_IF; 0049 IF (#turntable_dir = 0 AND #"Lift Position" <> 9) OR ((#t2 = 8)) THEN 0050 #"turntable pos" := 0; 0051 #Mov_turn_pos := 3; 0052 ; 0053 END_IF; 0054 (*IF #Mov_turn_pos >0 AND #Mov_turn_pos <4 AND #"Material_operation cmd">0 THEN 0055 #mOVE_TURN_TARGET := 1; 0056 ELSE 0057 #mOVE_TURN_TARGET := 0; 0058 ; 0059 END_IF; 0060 *) 0061 IF #PICK AND #PICKSTEP < 1 THEN 0062 #turn_offset := 2000; 0063 END_IF; 0064 IF #turntable_dir = 0 OR (#t2 = 8) THEN 0065 #turn_offset := 2000; 0066 END_IF; 0067 IF #PLACE AND #PLACESTEP < 1 THEN 0068 #turn_offset := 2000; 0069 END_IF; 0070 0071 IF #Turn_Corr_Step < 2 THEN 0072 IF #turn_offset <> 2000 THEN 0073 IF #turn_offset1 >= 1000 THEN 0074 #turn_offset1 := 1000; 0075 ; 0076 END_IF; 0077 0078 IF #turn_offset1 <= 0 THEN 0079 #turn_offset1 := 0; 0080 ; 0081 END_IF; 0082 0083 IF #turn_offset <= 1000 AND #turn_offset >= 0 THEN 0084 #turn_offset1 := #turn_offset; 0085 ; 0086 END_IF; 0087 ELSE 0088 #turn_offset1 := 500; 0089 END_IF; 0090 END_IF; 0091 0092 #turn_table_offset := (#turn_offset1 - 500) * (86231578/10000) /100; // (x-500)/100 becomes int 0093 0094 #POSITION := #"turntable pos" * (86231578/10000) + #turn_table_offset; //7957.0193// 7680.185; //408.8888 // 0095 IF #POSITION > 819200 THEN 0096 #tURN_CMD_POS := 819200; 0097 0098 ; 0099 END_IF; 0100 IF #POSITION < -819200 THEN 0101 #tURN_CMD_POS := -819200; 0102 ; 0103 END_IF; 0104 IF #POSITION >= -819200 AND #POSITION <= 819200 THEN 0105 #tURN_CMD_POS := #POSITION; 0106 ; 0107 END_IF; 0108 #tURN_fb_DEGREE := ABS(#"Turn Act pos" / (86231578/10000)); 0109 0110 #error_factor := 20; // Error_factor value in error = 1 degree 0111 0112 #"turn error":=ABS(((#"Turn Act pos"*10)/(86231578/10000))-#"turntable pos"*10-((#turn_table_offset*10)/ (86231578/10000))); //Scaling error to turn error 10 factor means 10 = 1 degree error 0113 #"tele error" := ABS(#"tele Act pos" - #"telescope position"); 0114 IF #PICK = 1 AND #turntable_dir <> 0 THEN 0115 #pick_ext := 1; 0116 #mpv := 0;</pre>		

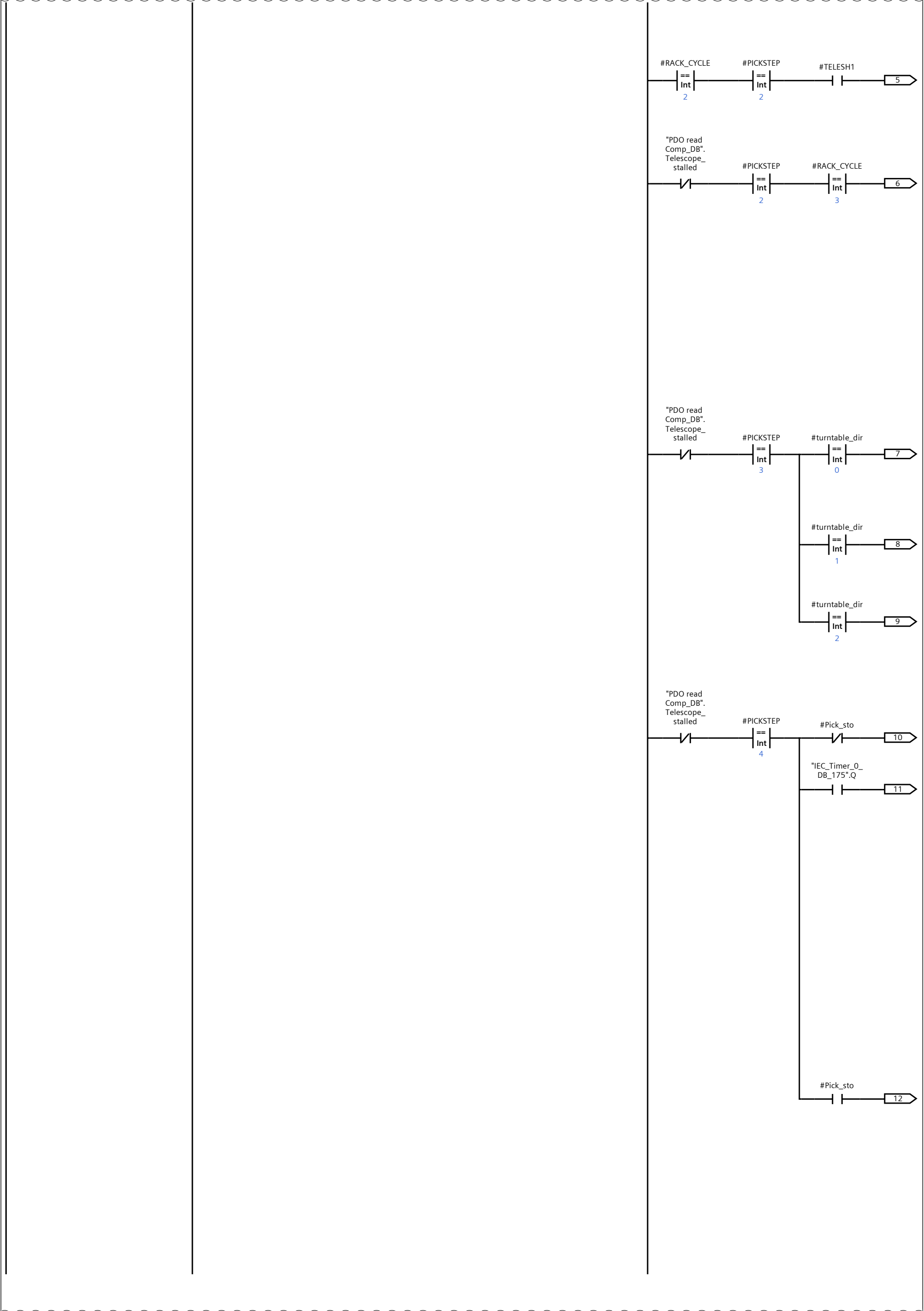
Totally Integrated Automation Portal		
<pre>0117 #place_ext := 0; 0118 0119 ; 0120 END_IF; 0121 IF #PLACE = 1 AND #turntable_dir <> 0 THEN 0122 #place_ext := 1; 0123 #pick_ext := 0; 0124 #mpv := 0; 0125 0126 ; 0127 ; 0128 END_IF; 0129 IF (#PLACE = 1 OR #PICK=1 OR #t2 = 8) AND (#turntable_dir =8 OR #turntable_dir =0) THEN 0130 #place_ext := 0; 0131 #pick_ext := 0; 0132 #mpv := 1; 0133 ; 0134 END_IF; 0135 "MODBUS_DATA".d_icd[25] := 1; 0136 ; 0137 "MODBUS_DATA".d_icd[18] := #PICKSTEP; 0138 "MODBUS_DATA".d_icd[19] := #PLACESTEP; 0139 #Tele_cmd_pos := (1426253 / 1000) * #"telescope position"; 0140 0141 IF #Lift_Barcode_pick_offset >= 250 THEN 0142 #Lift_Barcode_pick_offset := 250; 0143 ; 0144 END_IF; 0145 0146 IF #Lift_Barcode_pick_offset <= 0 THEN 0147 #Lift_Barcode_pick_offset := 0; 0148 ; 0149 END_IF; 0150 0151 IF #Lift_Rack_IN_Offset >= 200 THEN 0152 #Lift_Rack_IN_Offset := 200; 0153 ; 0154 END_IF; 0155 0156 IF #Lift_Rack_IN_Offset <= 0 THEN 0157 #Lift_Rack_IN_Offset := 0; 0158 ; 0159 END_IF;</pre> <p>Network 5: pick cycle</p>		

Network 5: pick cycle (1.1 / 13.1)

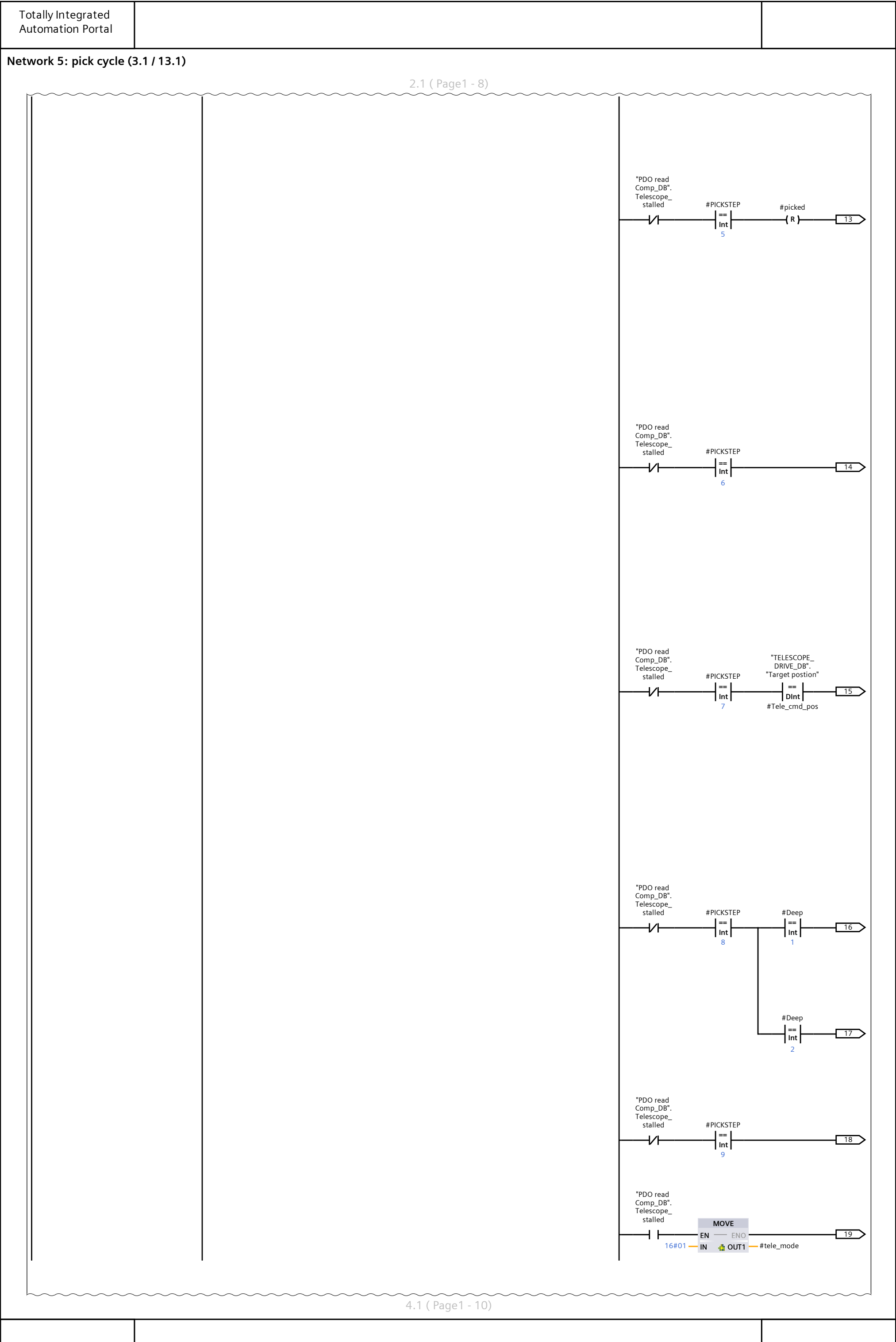


Network 5: pick cycle (2.1 / 13.1)

1.1 (Page1 - 7)

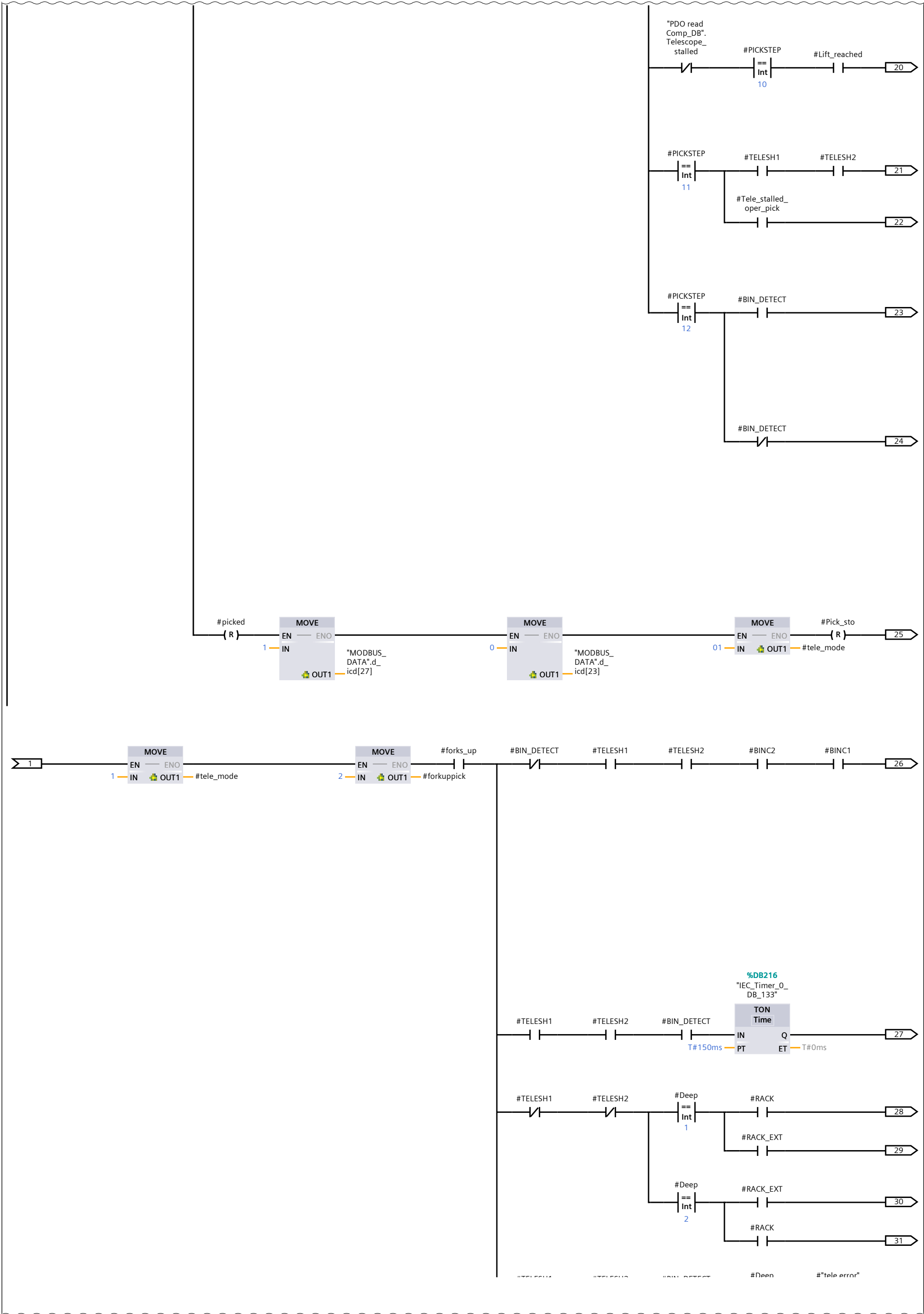


3.1 (Page1 - 9)



Network 5: pick cycle (4.1 / 13.1)

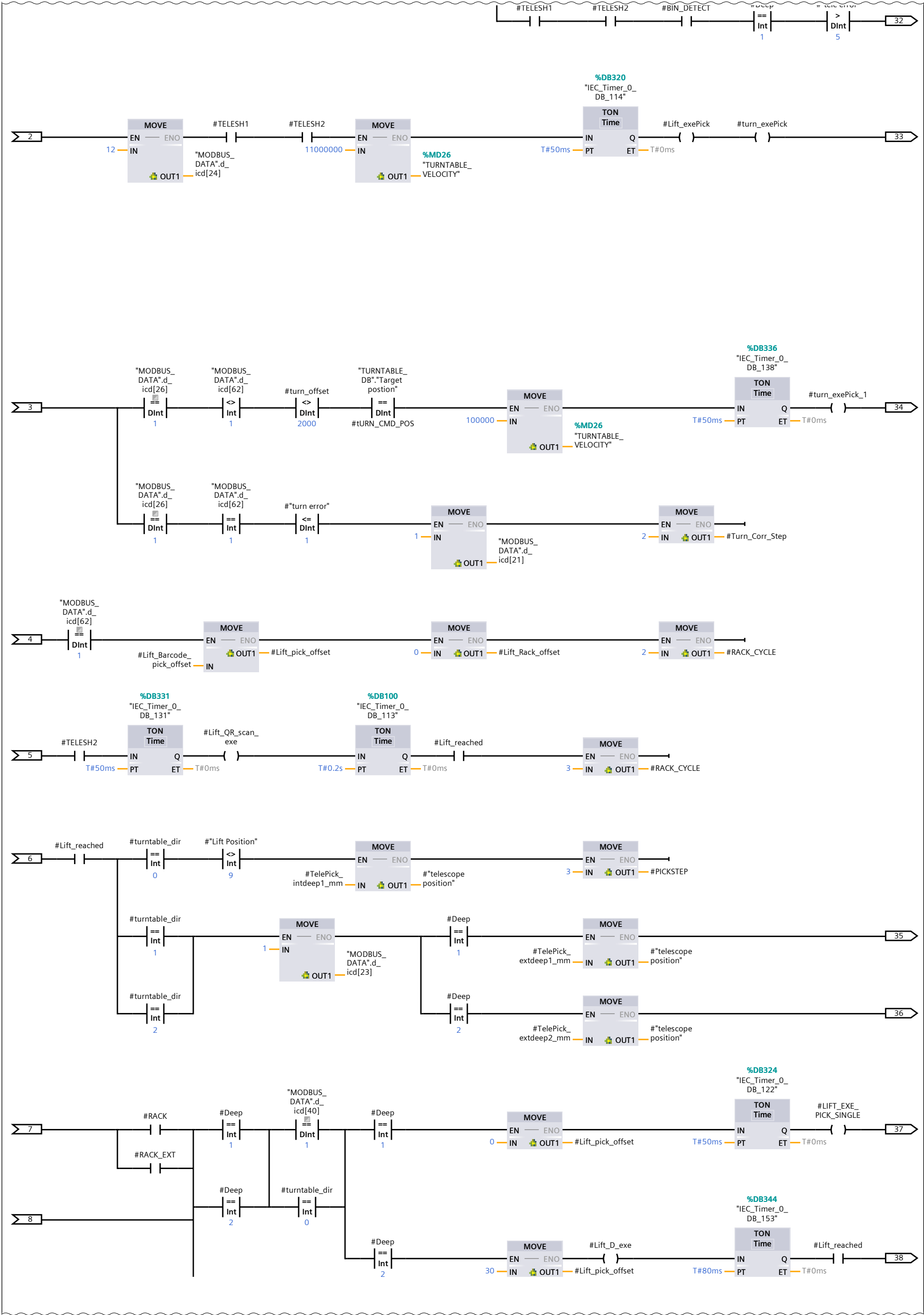
3.1 (Page1 - 9)



5.1 (Page1 - 11)

Network 5: pick cycle (5.1 / 13.1)

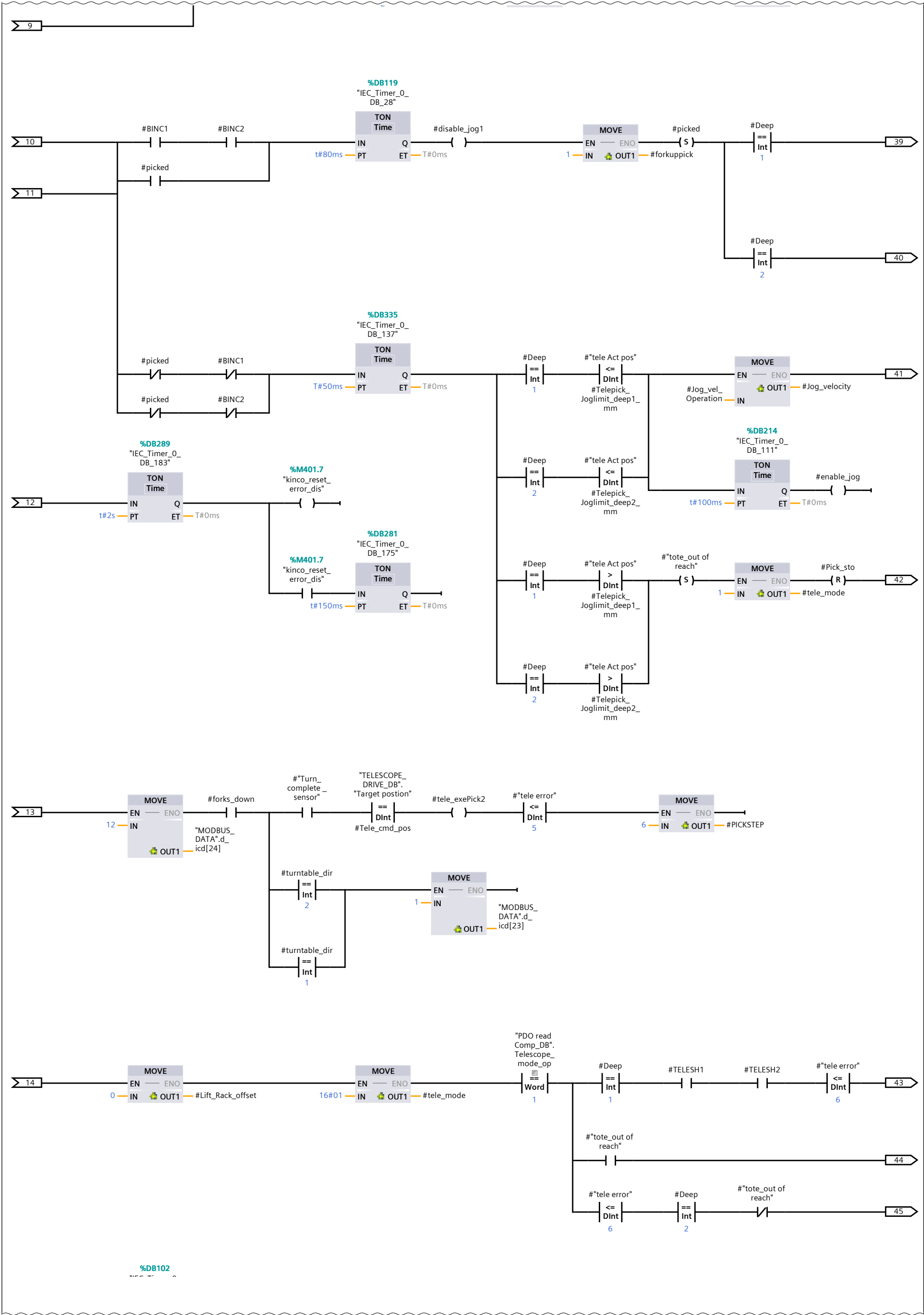
4.1 (Page1 - 10)



6.1 (Page1 - 12)

Network 5: pick cycle (6.1 / 13.1)

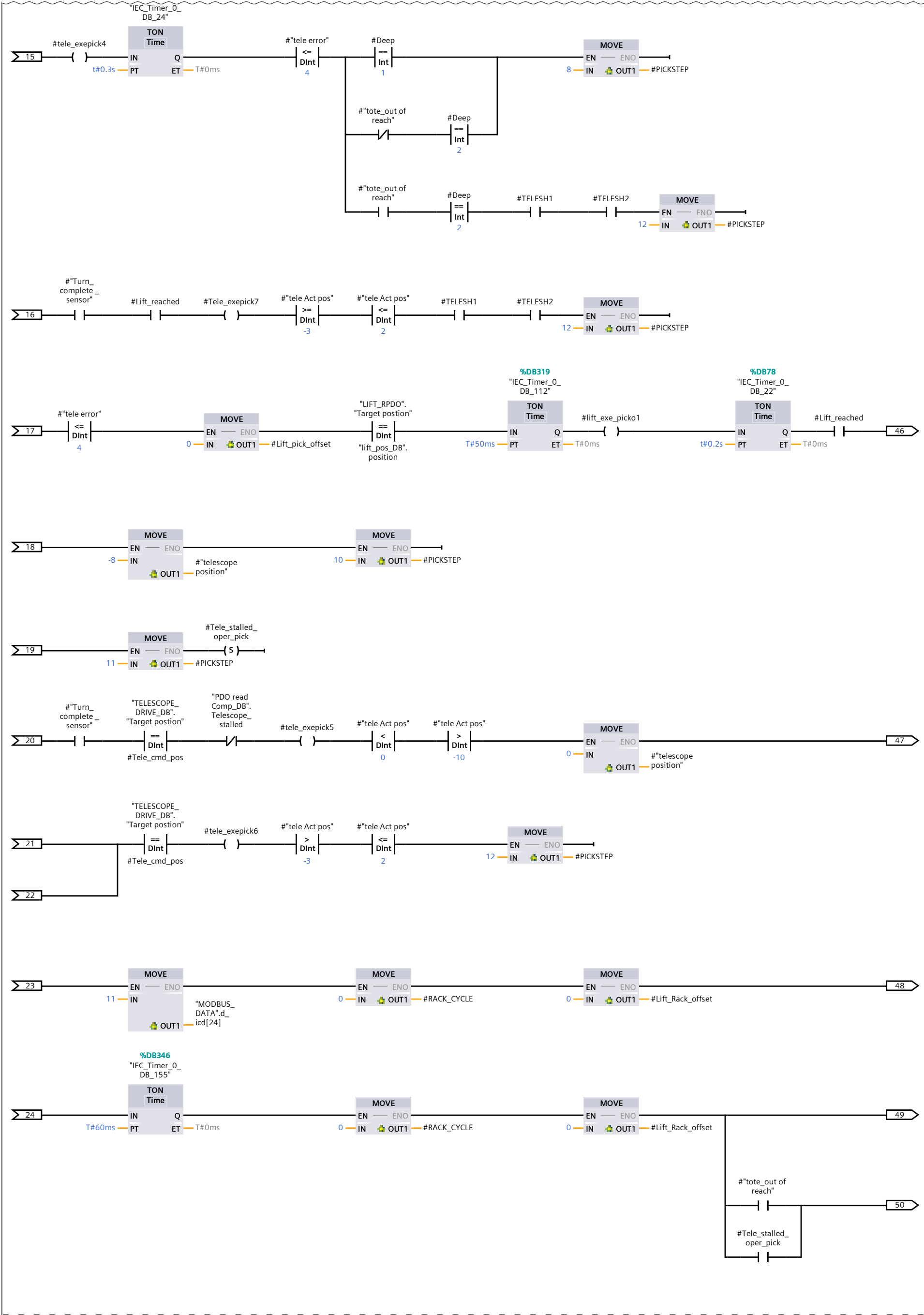
5.1 (Page1 - 11)



7.1 (Page1 - 13)

Network 5: pick cycle (7.1 / 13.1)

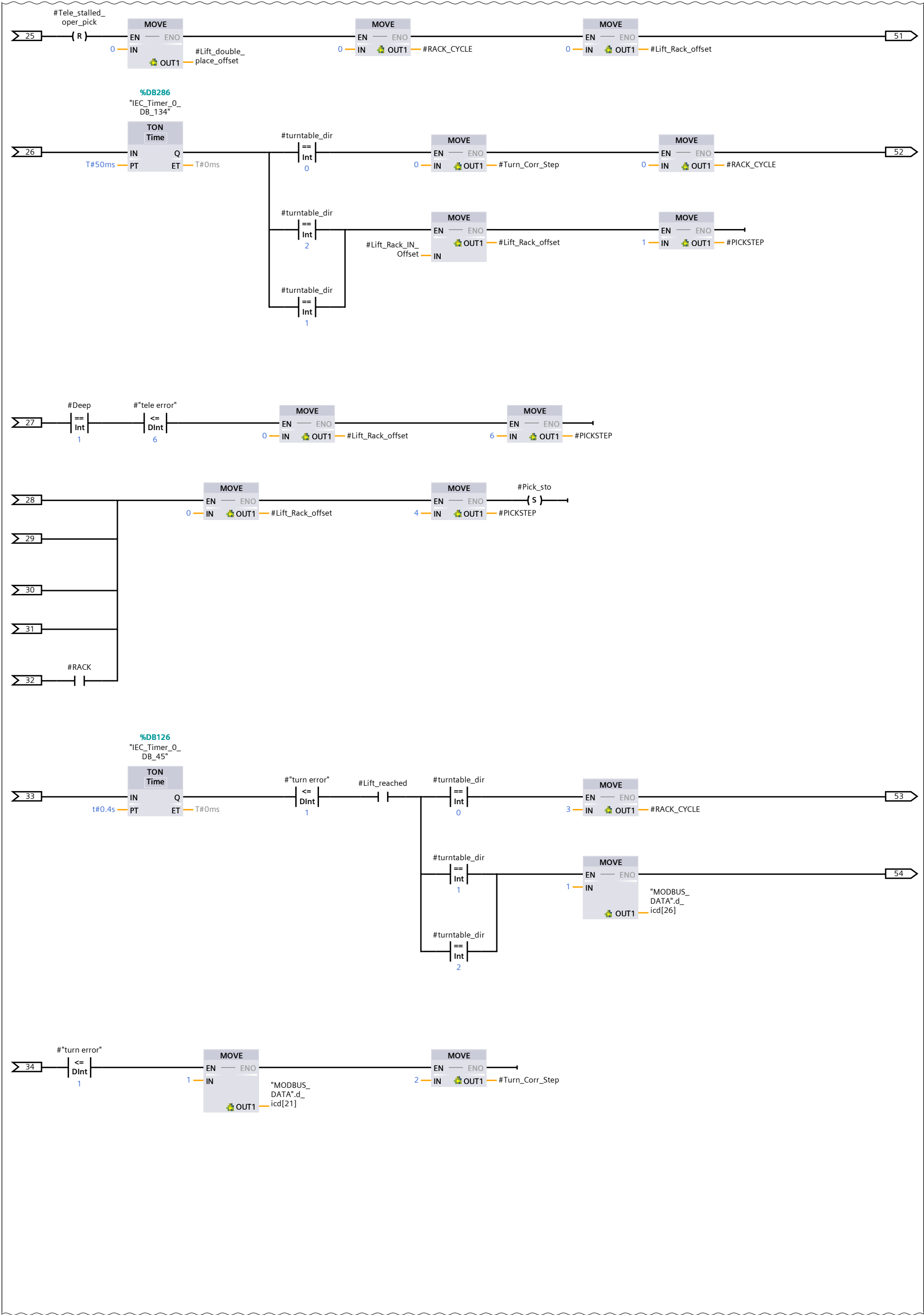
6.1 (Page1 - 12)



8.1 (Page1 - 14)

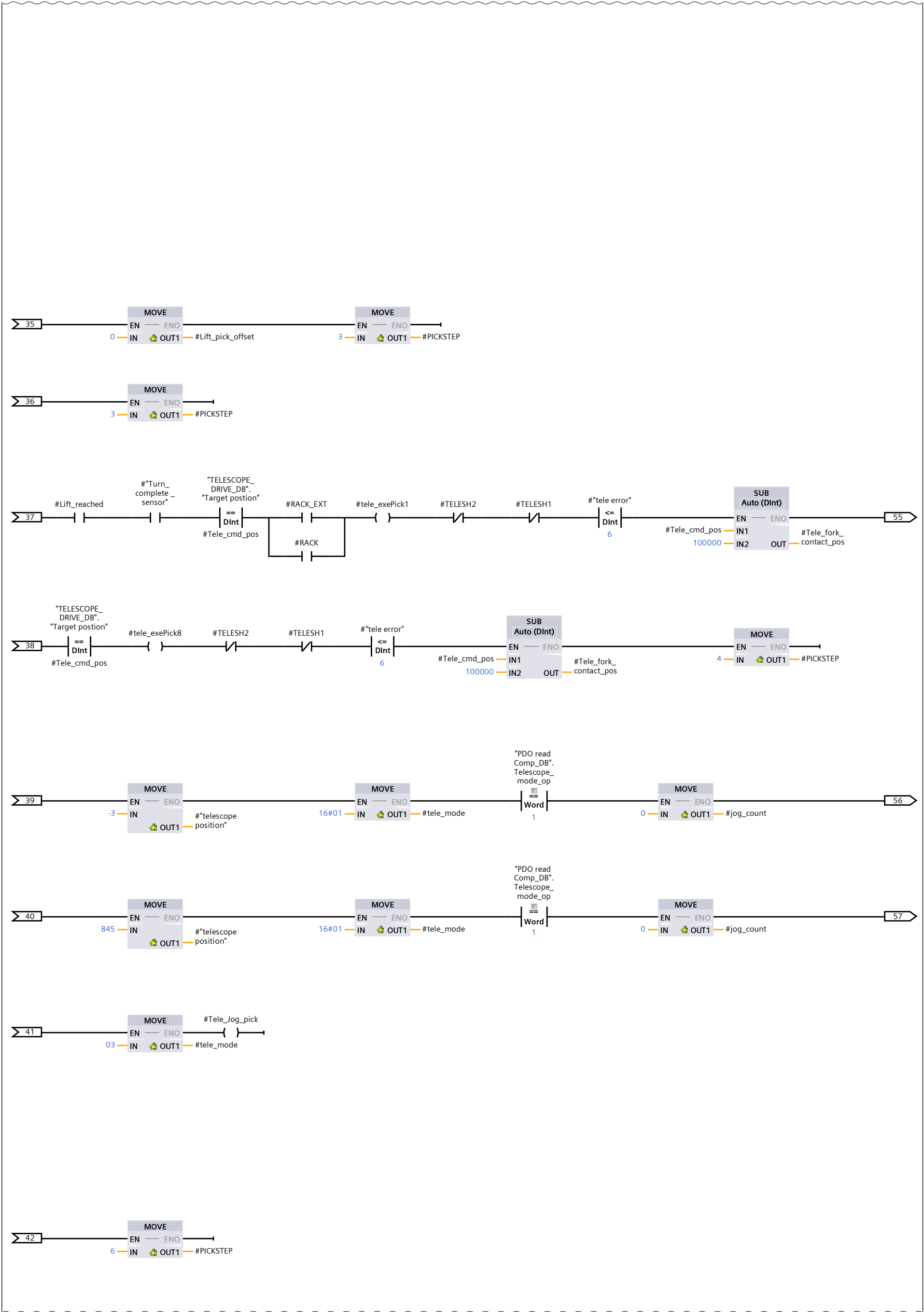
Network 5: pick cycle (8.1 / 13.1)

7.1 (Page1 - 13)



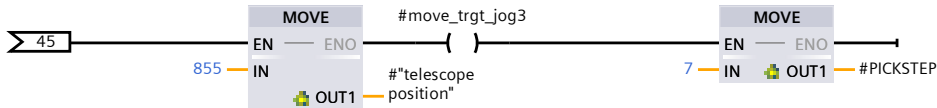
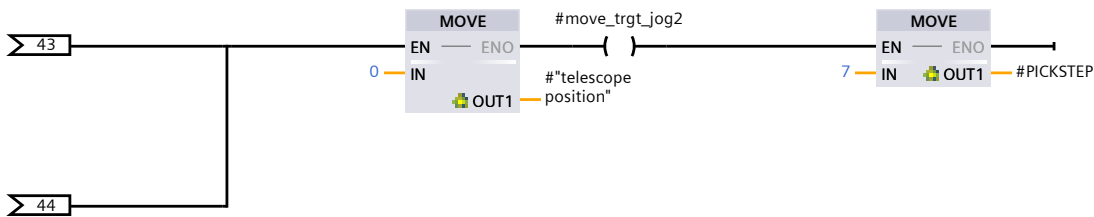
9.1 (Page1 - 15)

Network 5: pick cycle (9.1 / 13.1)



Network 5: pick cycle (10.1 / 13.1)

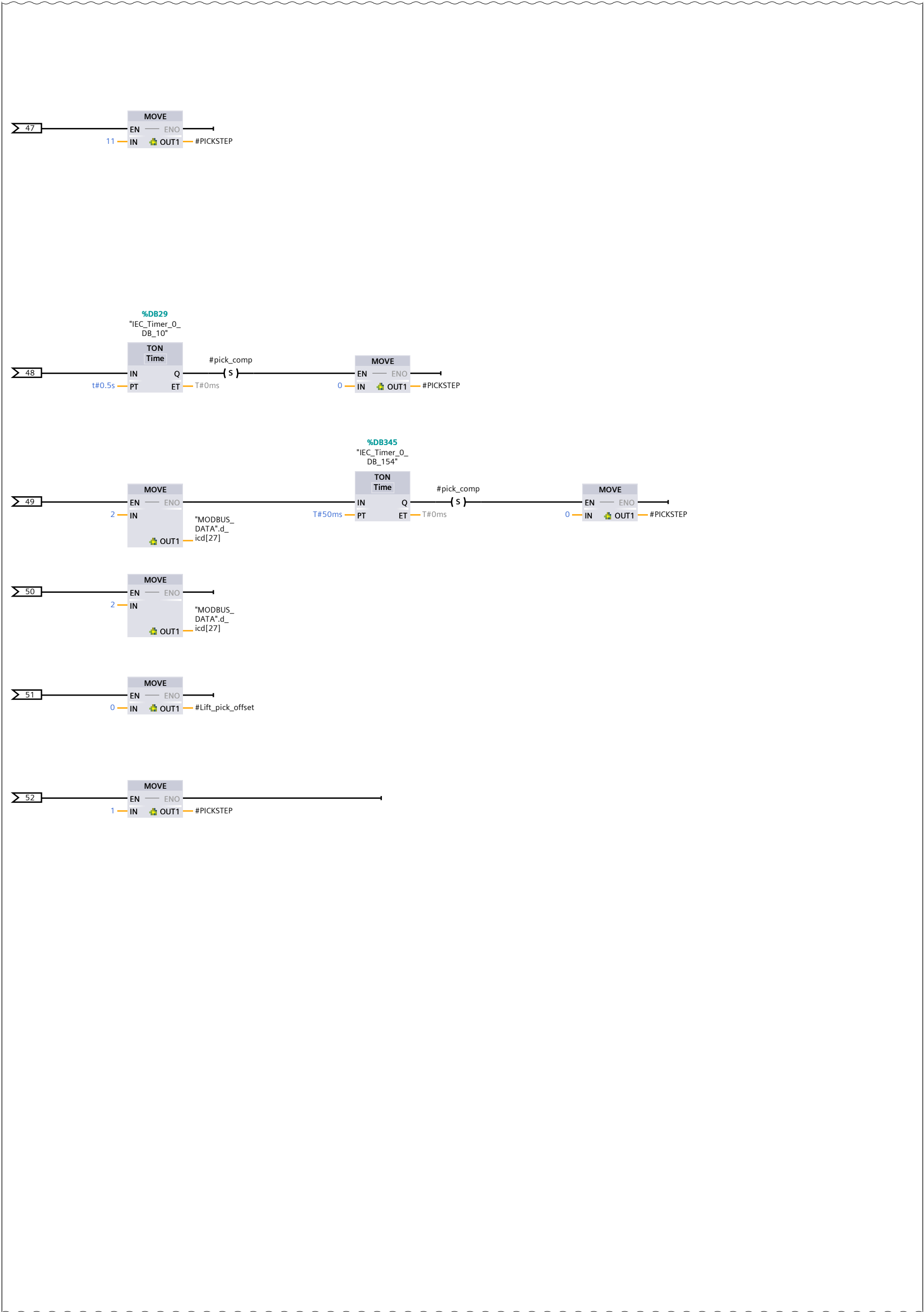
9.1 (Page1 - 15)



11.1 (Page1 - 17)

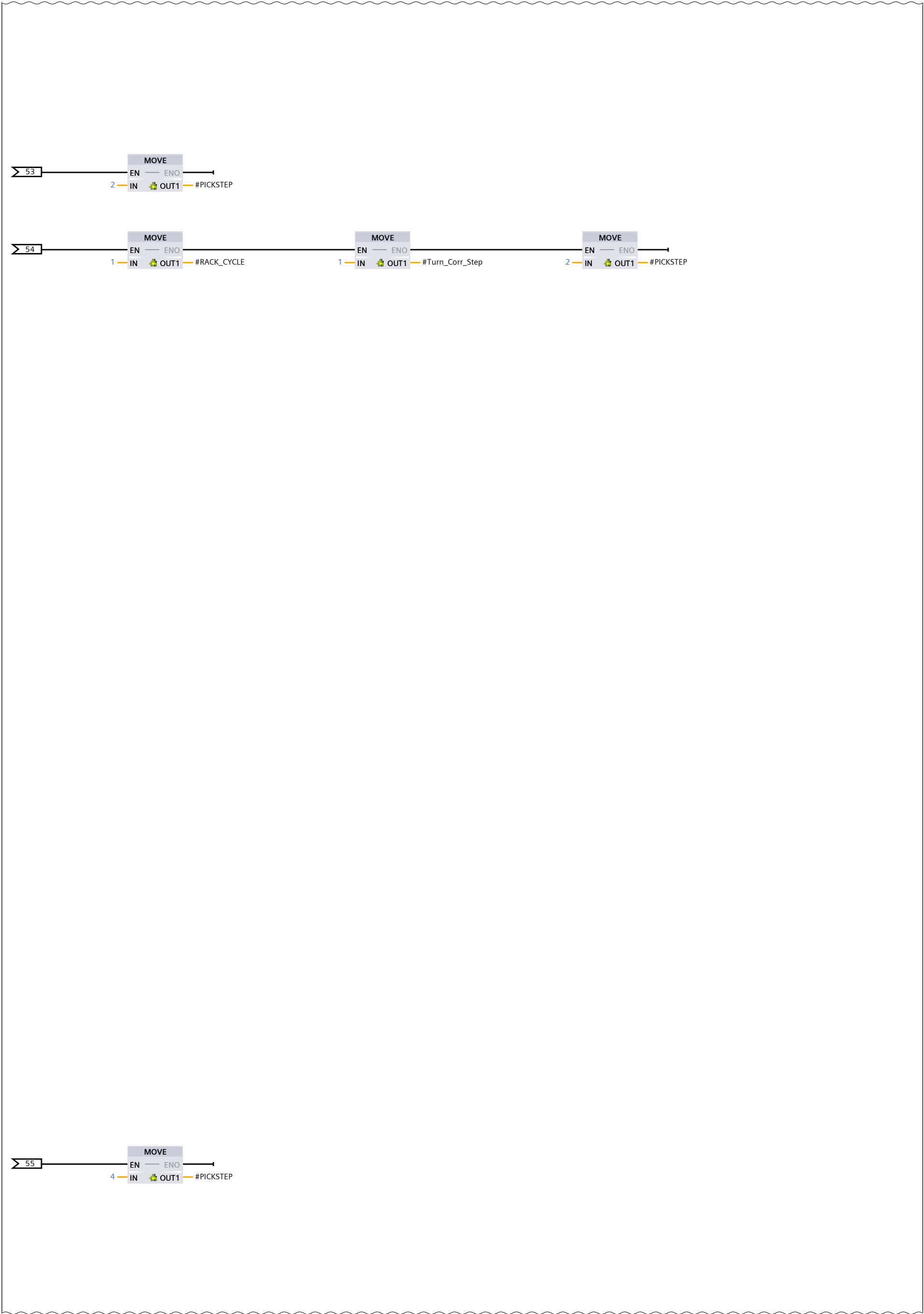
Network 5: pick cycle (11.1 / 13.1)

10.1 (Page1 - 16)



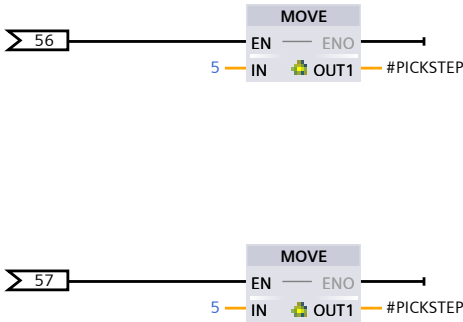
12.1 (Page1 - 18)

Network 5: pick cycle (12.1 / 13.1)



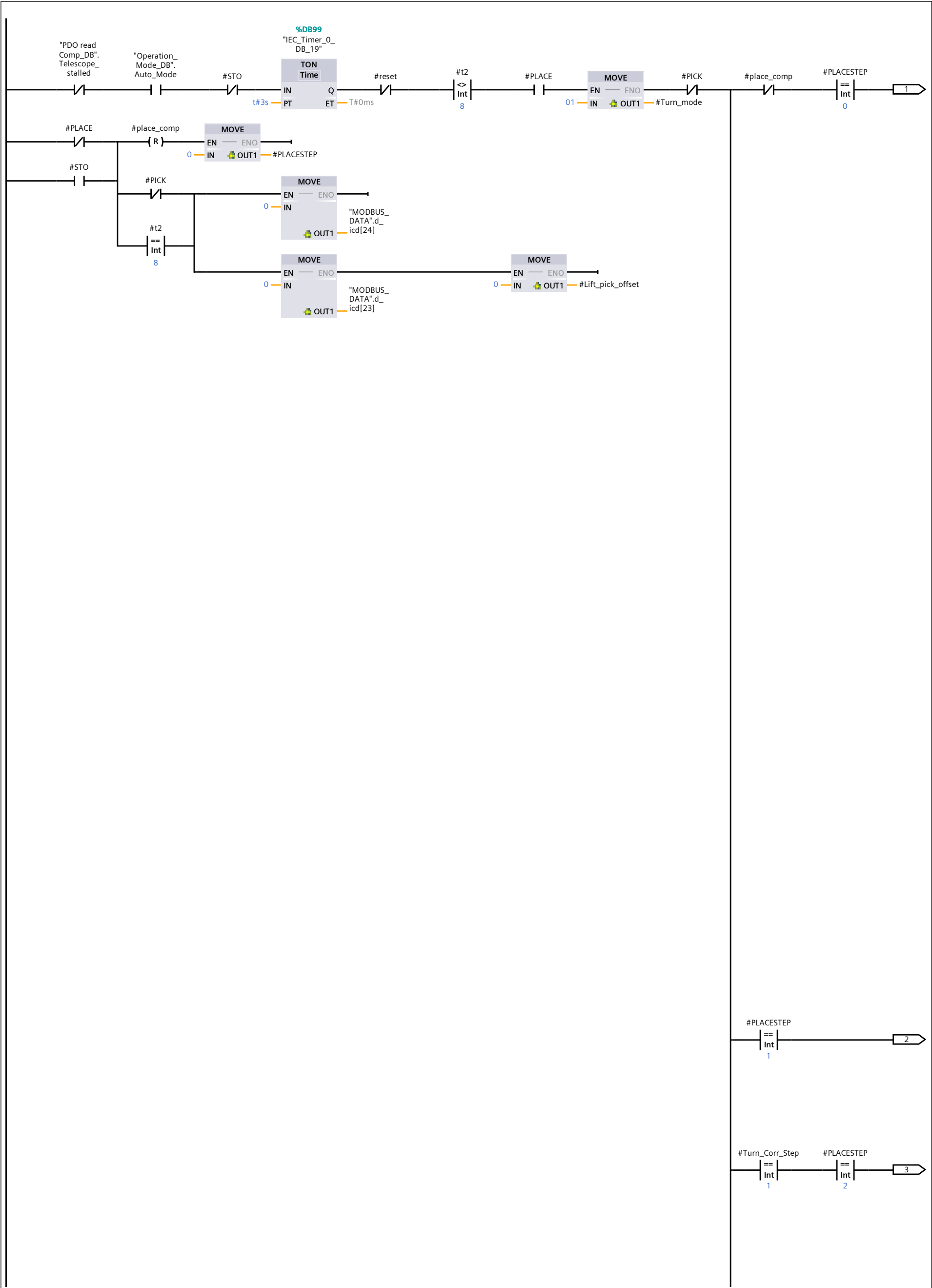
Network 5: pick cycle (13.1 / 13.1)

12.1 (Page1 - 18)



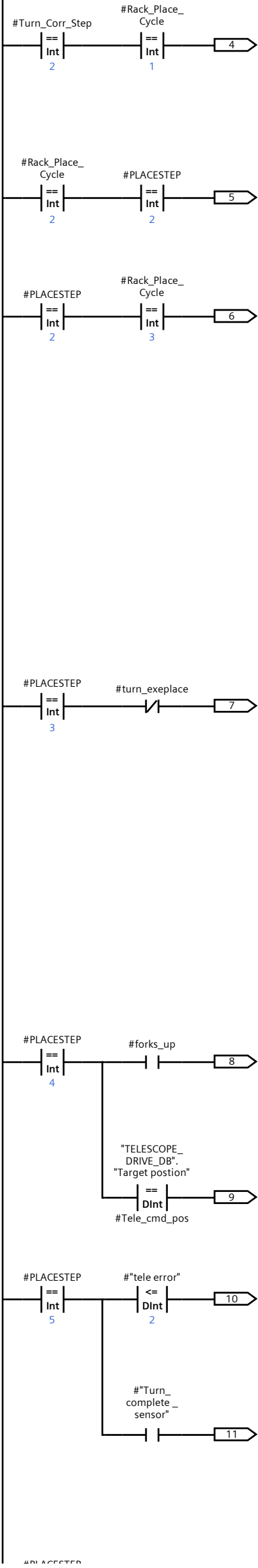
Totally Integrated Automation Portal		
Network 6: place cycle		

Network 6: place cycle (1.1 / 9.1)



Network 6: place cycle (2.1 / 9.1)

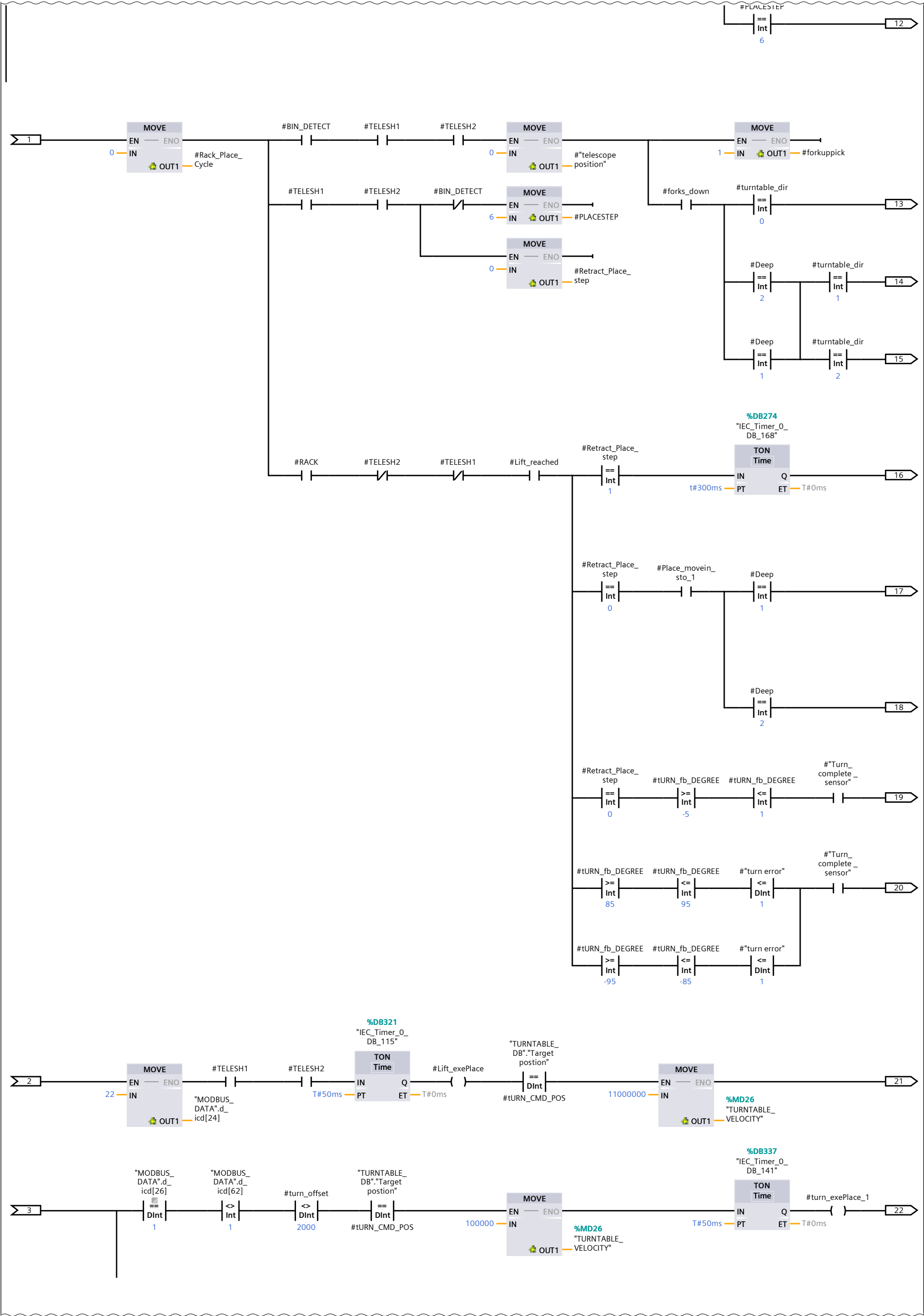
1.1 (Page1 - 21)



3.1 (Page1 - 23)

Network 6: place cycle (3.1 / 9.1)

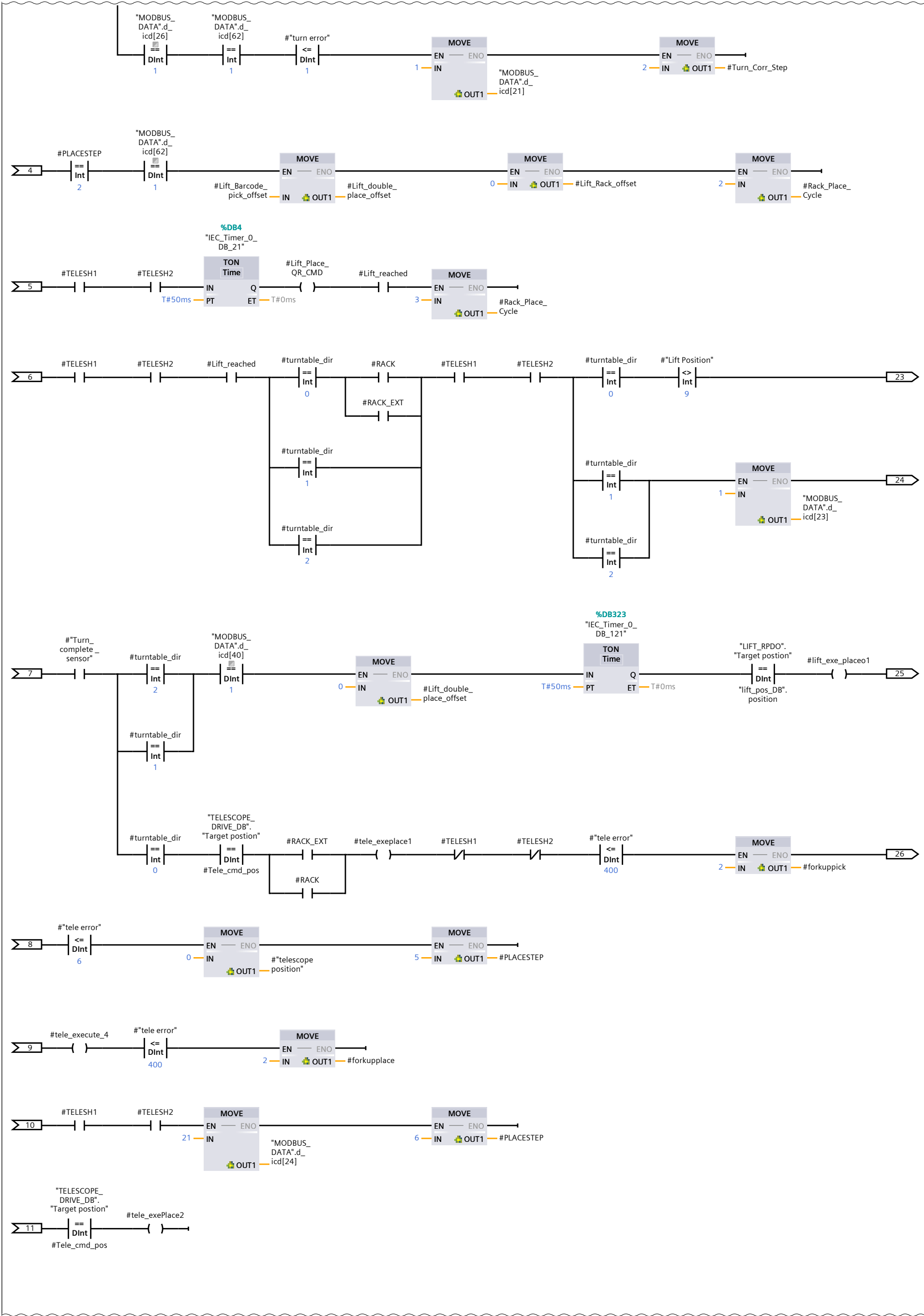
2.1 (Page1 - 22)



4.1 (Page1 - 24)

Network 6: place cycle (4.1 / 9.1)

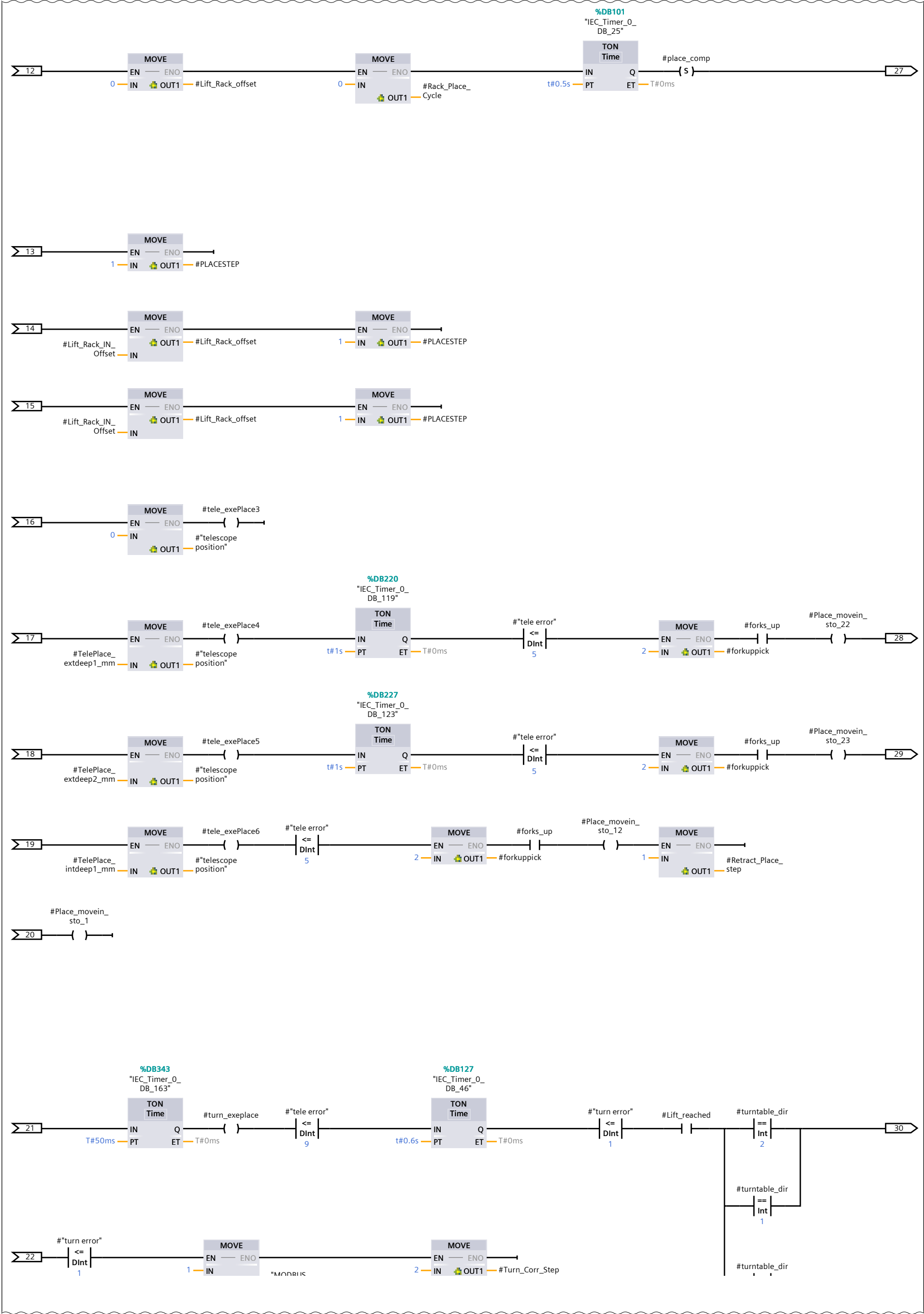
3.1 (Page1 - 23)



5.1 (Page1 - 25)

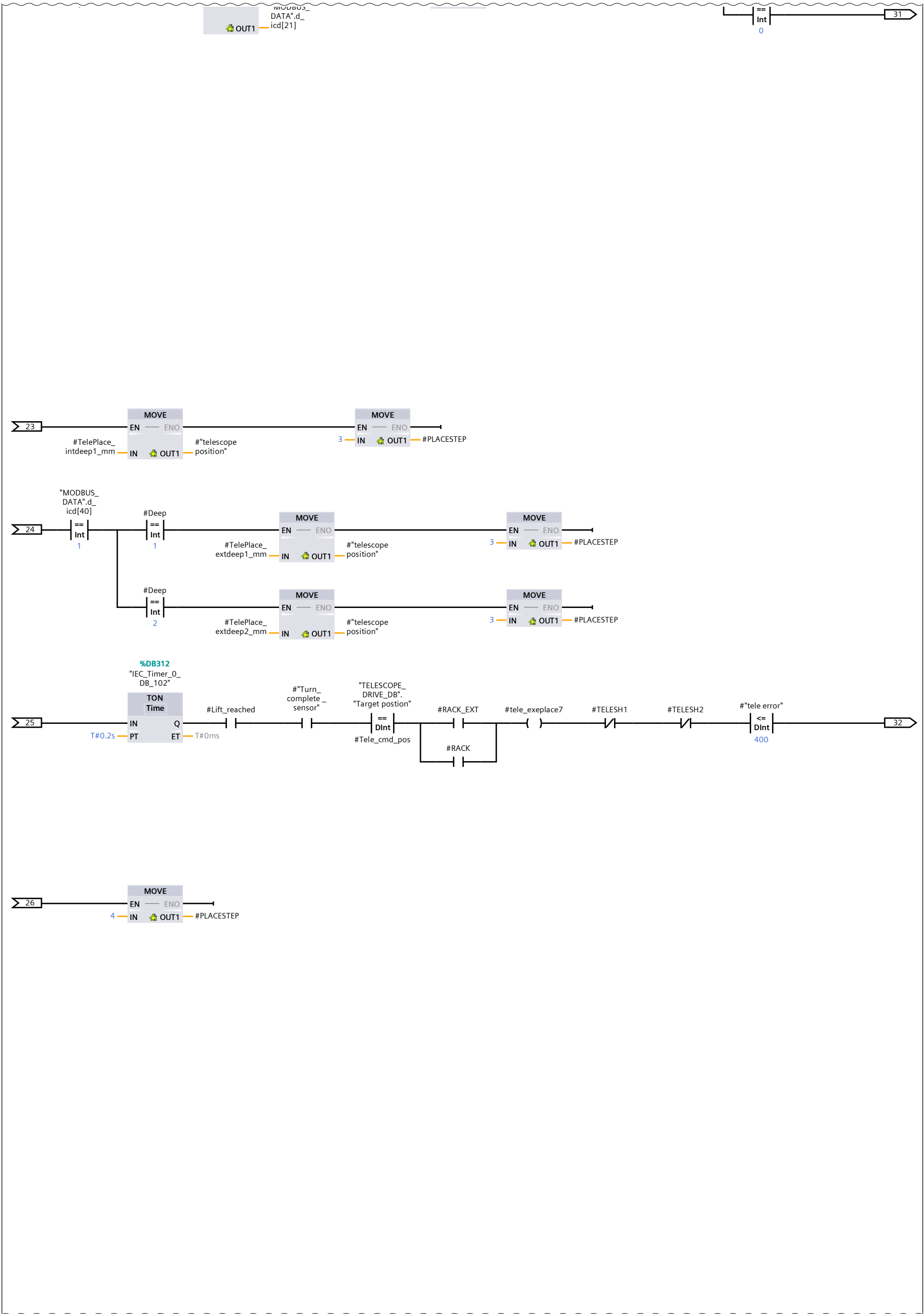
Network 6: place cycle (5.1 / 9.1)

4.1 (Page1 - 24)

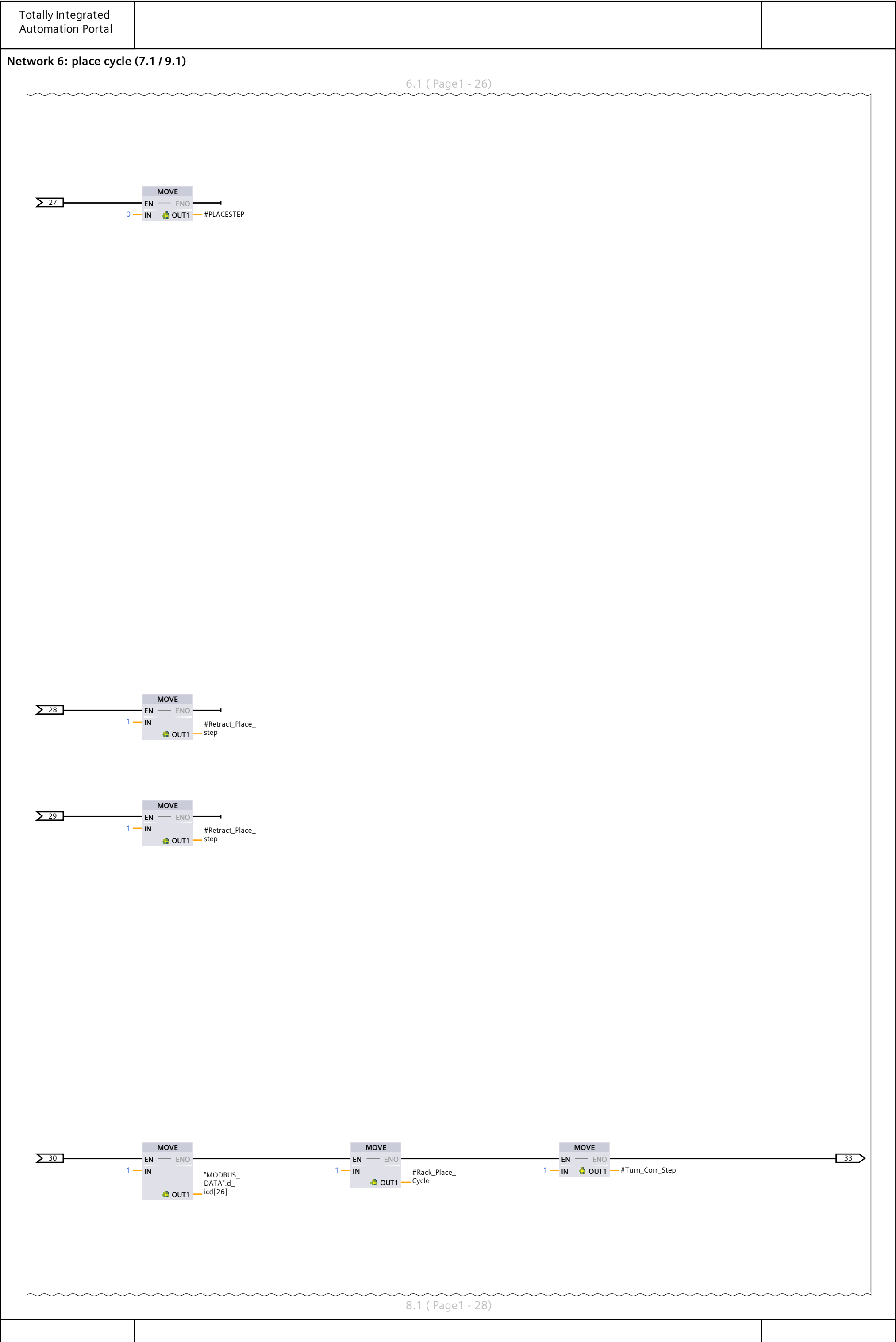


Network 6: place cycle (6.1 / 9.1)

5.1 (Page1 - 25)

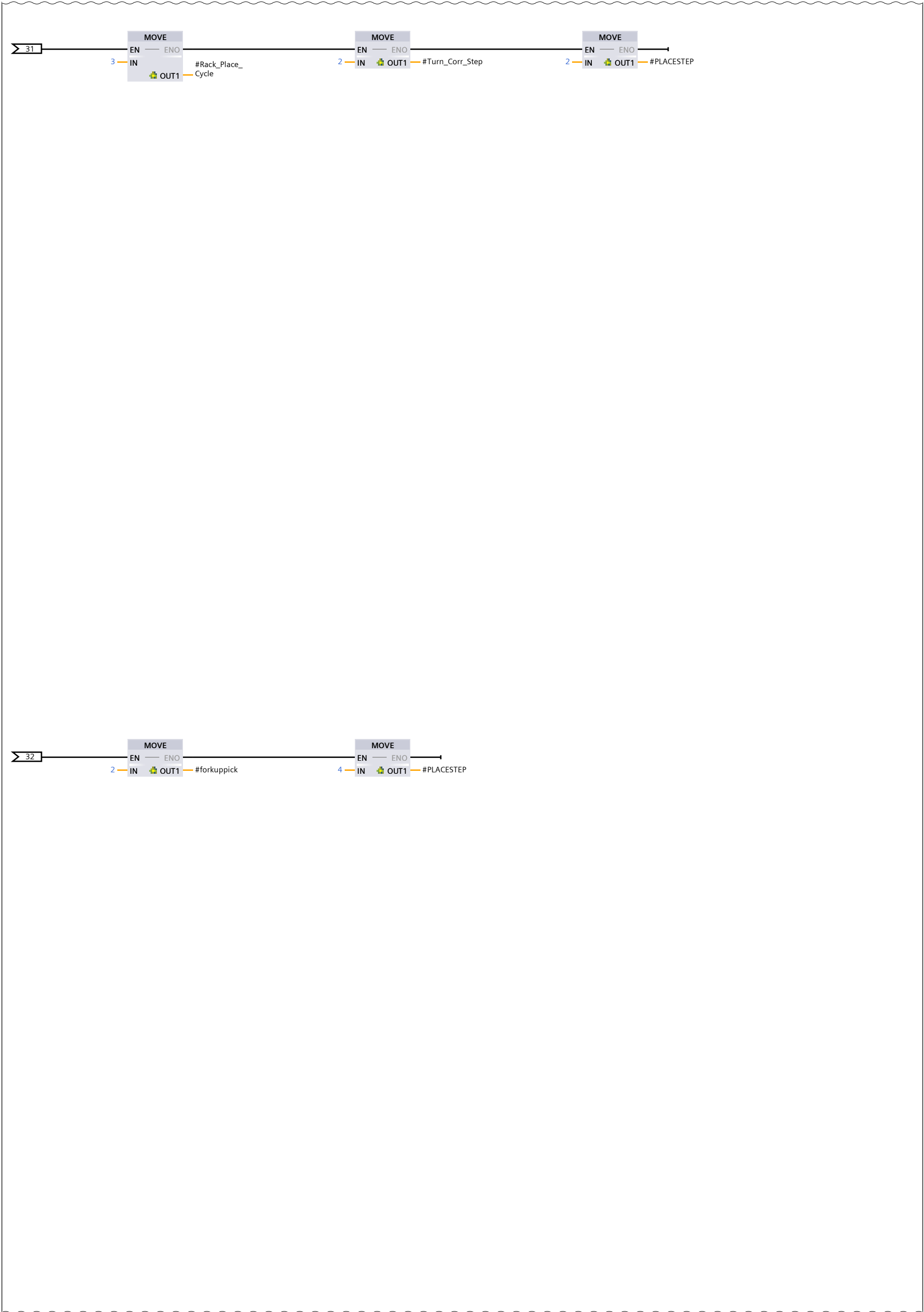


7.1 (Page1 - 27)



Network 6: place cycle (8.1 / 9.1)

7.1 (Page1 - 27)



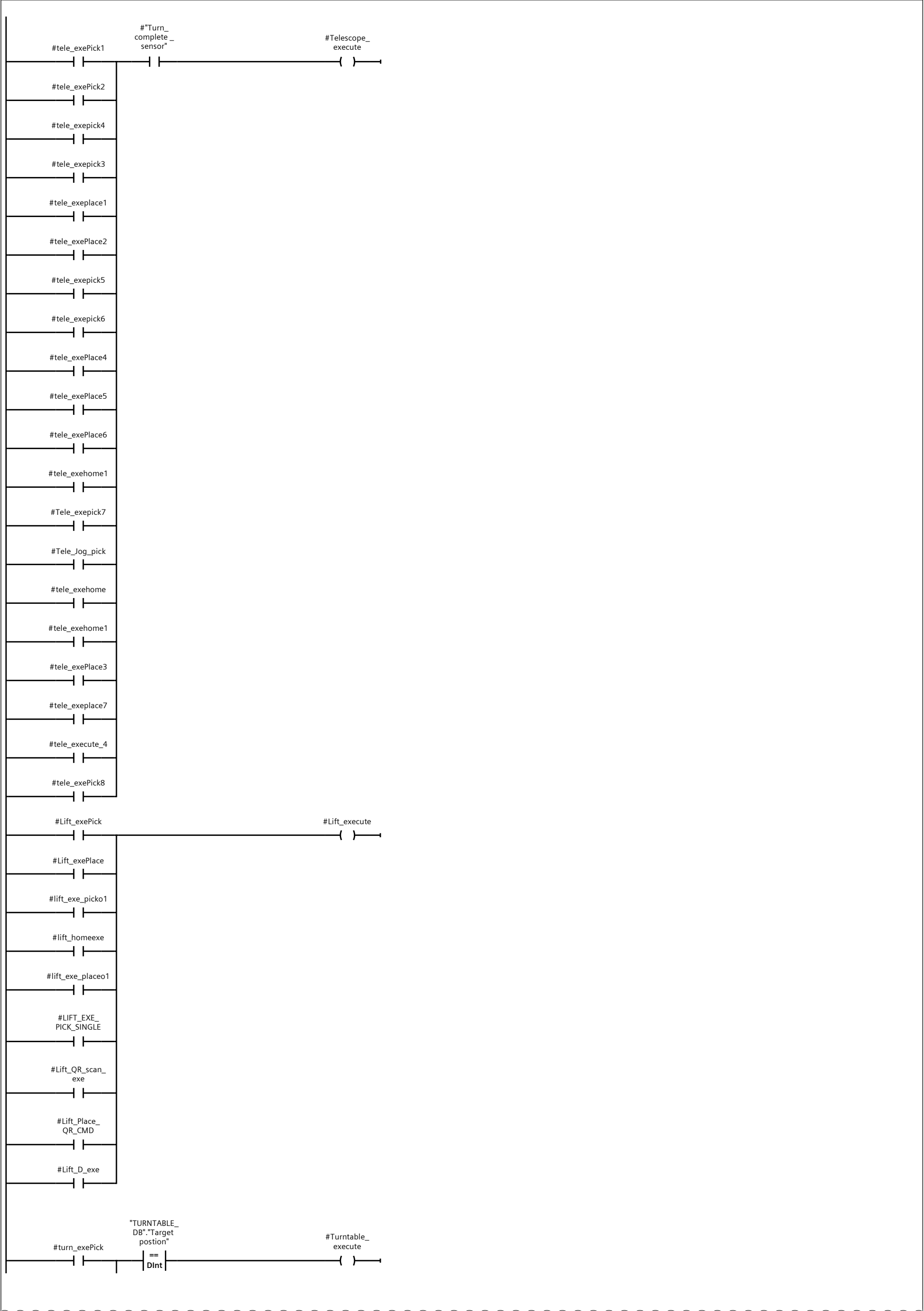
9.1 (Page1 - 29)

Network 6: place cycle (9.1 / 9.1)

8.1 (Page1 - 28)

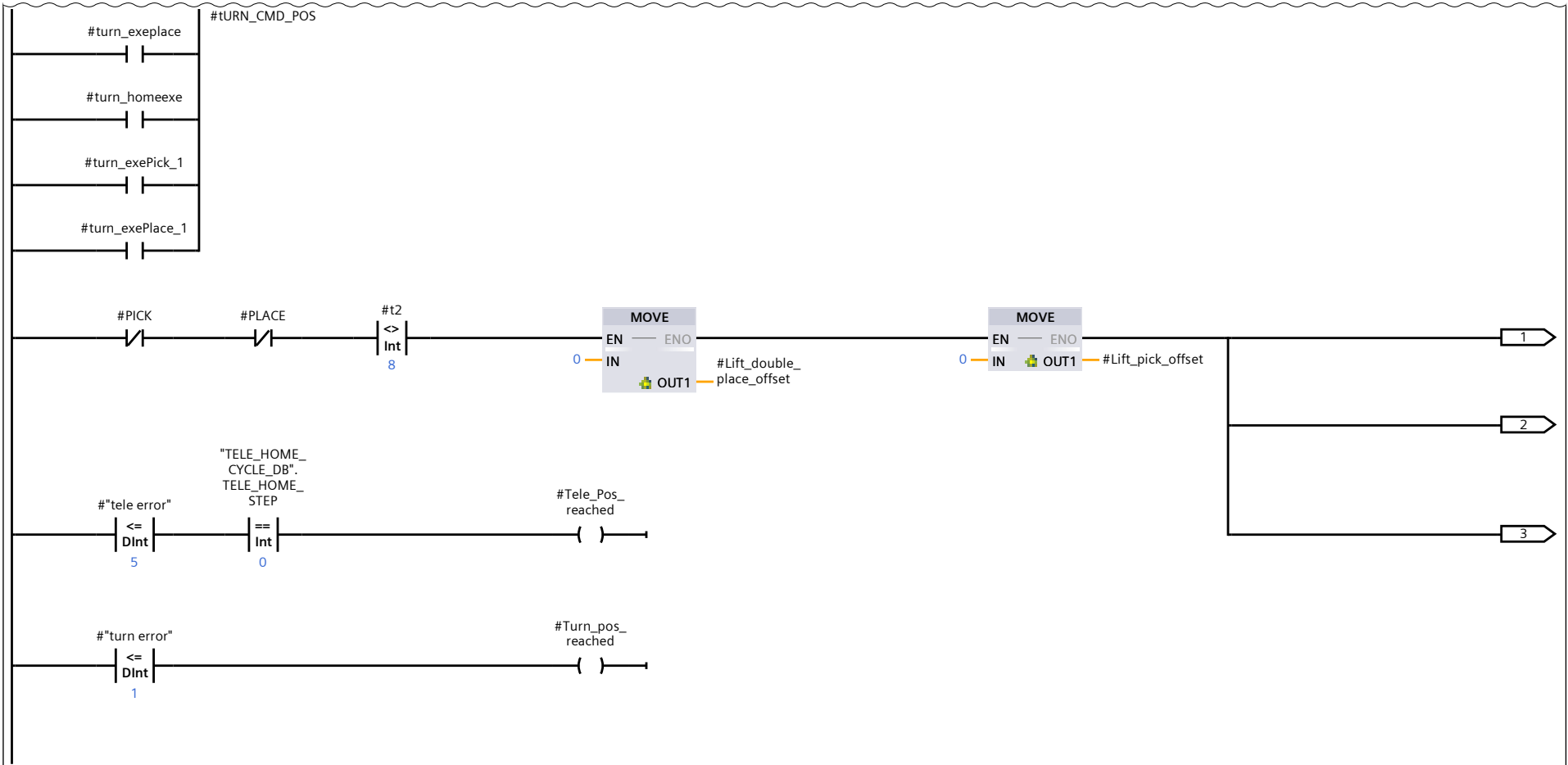


Network 7: (1.1 / 3.1)



Network 7: (2.1 / 3.1)

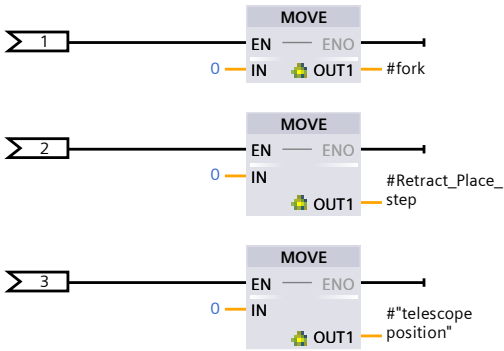
1.1 (Page1 - 31)



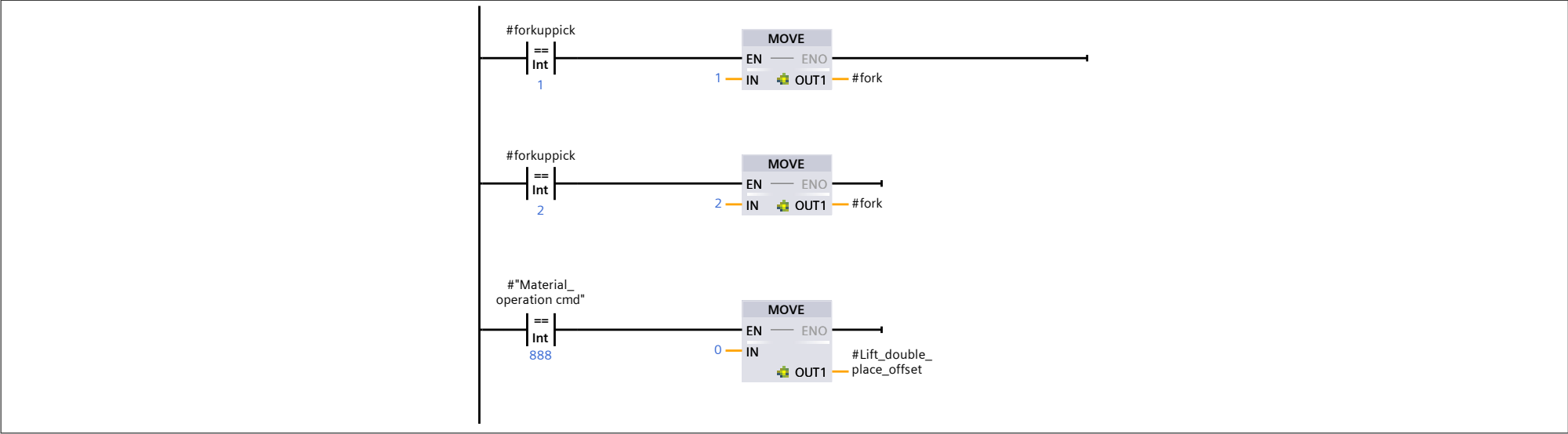
3.1 (Page1 - 33)

Network 7: (3.1 / 3.1)

2.1 (Page1 - 32)



Network 8:

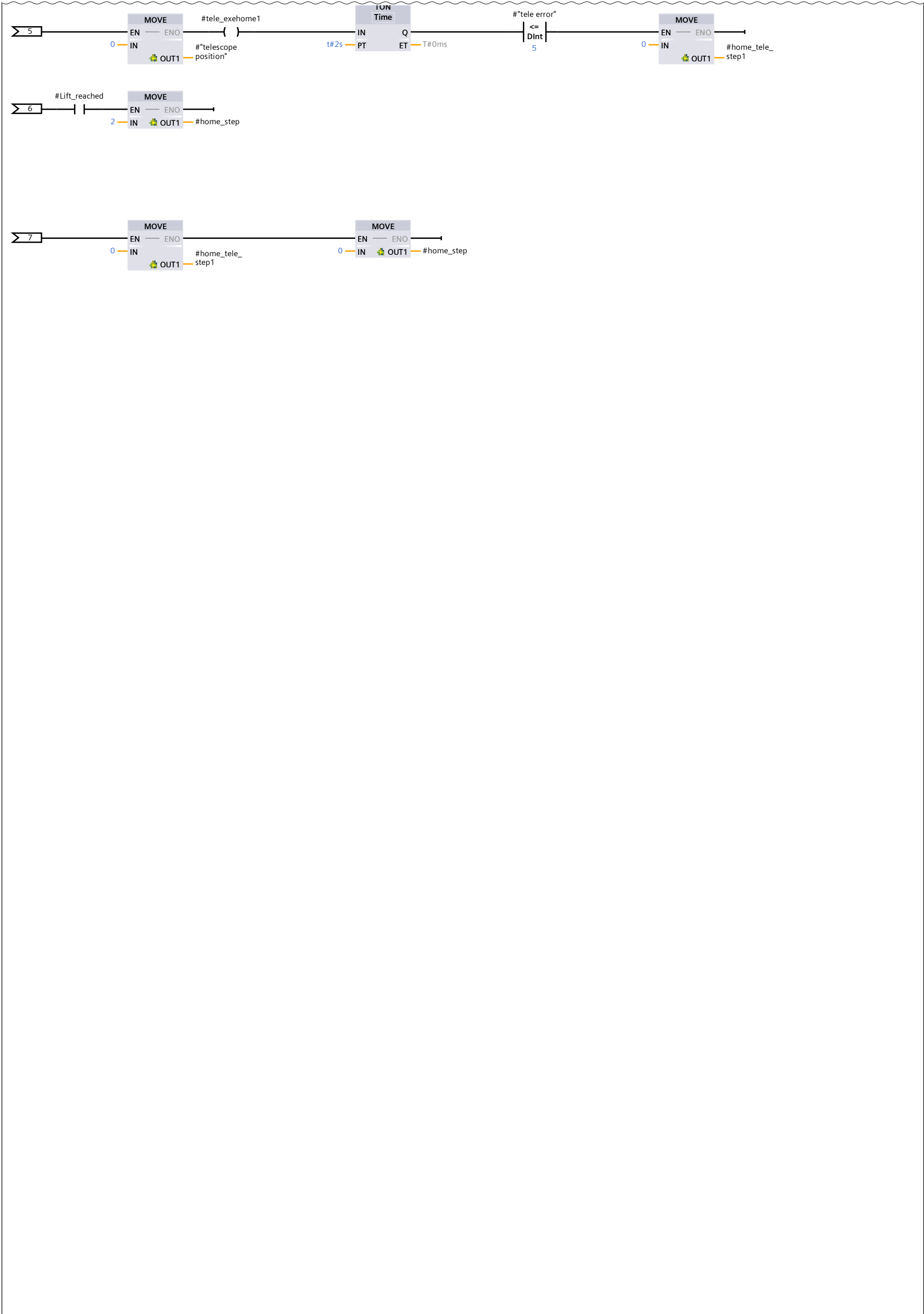


Network 9: Homing

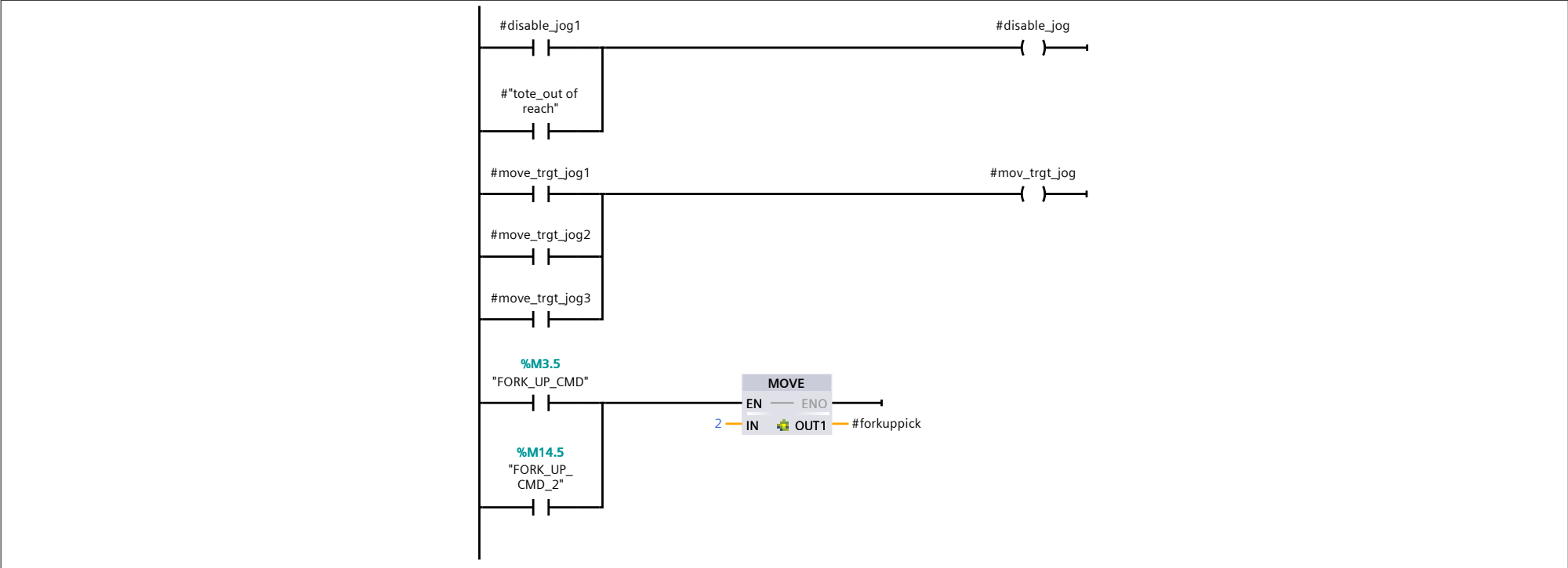


Network 9: Homing (2.1 / 2.1)

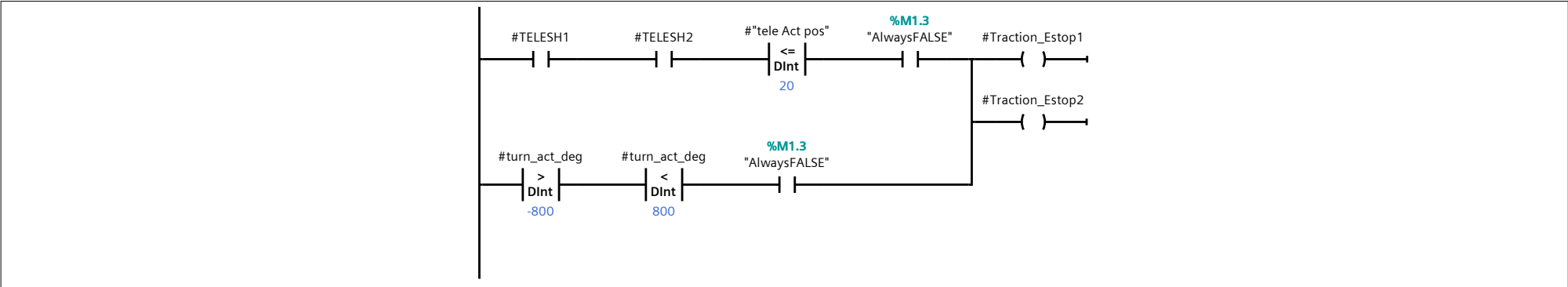
1.1 (Page1 - 35)



Network 10:

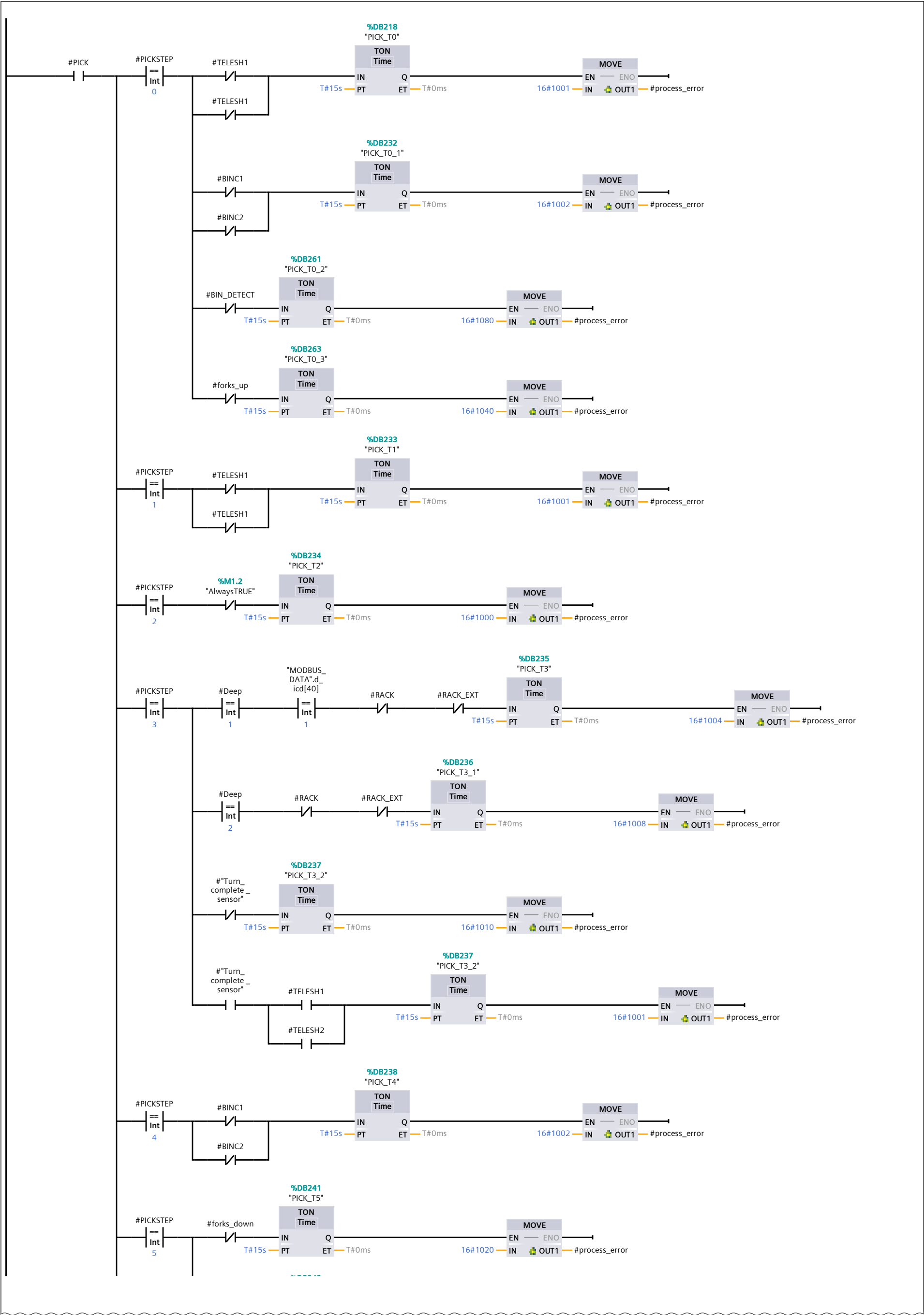


Network 11: Traction_Safety_Stop



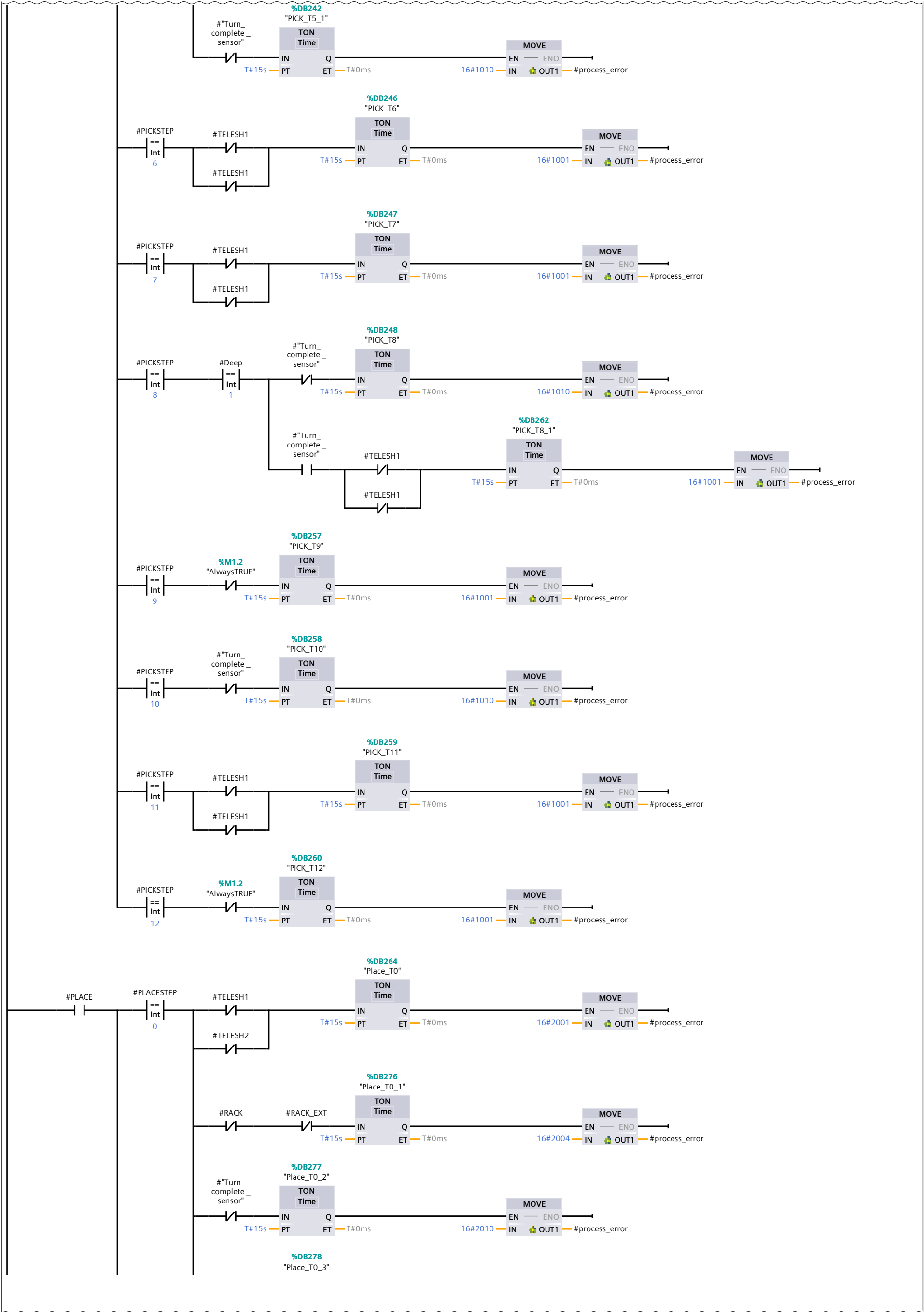
Network 12: Process Error Feedback

Network 12: Process Error Feedback (1.1 / 3.1)



Network 12: Process Error Feedback (2.1 / 3.1)

1.1 (Page1 - 38)



3.1 (Page1 - 40)

Network 12: Process Error Feedback (3.1 / 3.1)

2.1 (Page1 - 39)

