These filters are known as sobel filters and is used in edge detection.

Q4(a) Gaussian Noise also known as normal noise model is used frequently in practice.

The PDF of a Gaussian random variable z is given by

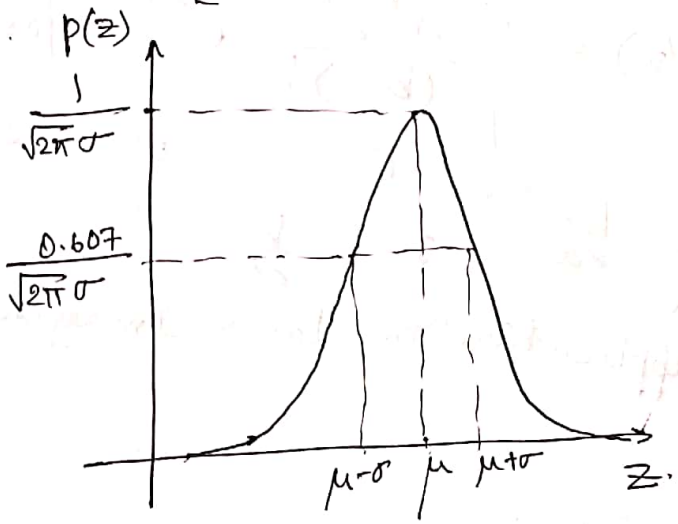
$$p(z) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(z-\mu)^2}{2\sigma^2}}$$

z = gray level.

μ = mean of average value of z.

σ = standard deviation of z.

In this distribution about 70% of its values will be in the range $[(\mu-\sigma), [\mu+\sigma]]$, and 95% in the range $[(\mu-2\sigma), (\mu+2\sigma)]$.



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• Rayleigh Noise

The PDF of the Rayleigh noise is given by

$$p(z) = \begin{cases} \frac{2}{b}(z-a)e^{-(z-a)^2/b} & \text{for } z \geq a \\ 0 & \text{for } z < a. \end{cases}$$

$$\mu = a + \sqrt{\pi b/4}$$

$$\sigma^2 = \frac{b(4-\pi)}{4}.$$

The shape is skewed to the right

• Gamma Noise

This noise also known as Erlang noise has the PDF

$$p(z) = \begin{cases} \frac{a^b z^{b-1}}{(b-1)!} e^{-az} & \text{for } z \geq a. \\ 0 & \text{for } z < a. \end{cases}$$

$$\mu = b/a \qquad \sigma^2 = \frac{b}{a^2}$$

$a > 0$, b = +ve integer

It has application in Laser Imaging.

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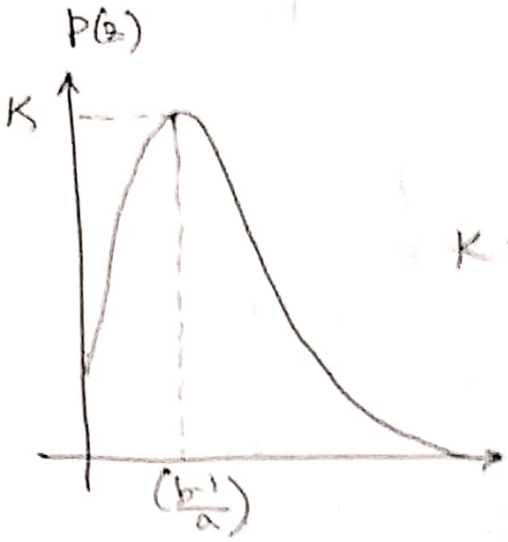

$$K = \frac{a(b-1)^{b-1}}{(b-1)!} e^{-(b-1)}.$$

Q4(b). Harmonic Mean filter.

It is used for removing ~~salt & pepper~~ noise

It is given by the equation

$$\hat{f}(x,y) = \frac{mn}{\sum_{(s,t)\in S_{xy}} \frac{1}{g(s,t)}}$$

where S_{xy} represents the set of coordinates in a rectangular subimage window of size $m \times n$ centered at the point (x,y).

$g(x,y)$ = pixel value of corrupted image at coordinates (x,y)

$\hat{f}(x,y)$ = value of restored image at coordinates (x,y).

The harmonic mean filter works well for salt noise but fails for pepper noise. It does well also with other types of noise like Gaussian noise.

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Contraharmonic Mean filter

The contraharmonic mean filtering operation yields a restored image based on

$$\hat{f}(x,y) = \frac{\sum_{(s,t)\in S_{xy}} g(s,t)^{Q+1}}{\sum_{(s,t)\in S_{xy}} g(s,t)^{Q}}$$

where Q is called the order of the filter All other symbols have the same meaning as in the previous equation.

This filter is well suited for reducing or virtually eliminating the effects of salt-and-pepper noise. For positive values of Q is eliminates ~~salt noise~~ pepper noise. For negative values Q it eliminates salt noise. It cannot do both simultaneously.

if $Q=0$ it reduces to arithmetic mean filter

if $Q=-1$ it reduces to the harmonic mean filter.

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Q5. Algorithm for construction of a Huffman Tree.

1. Begin
2. Create a table to store the frequency of each ~~character~~ symbol.
3. Create a leaf node for each symbol and add it to the priority queue. Lower the probability higher the priority. (higher frequency means lower priority).
4. While there is more than one node in the queue:
   - 4.1 Remove the two nodes of highest priority from the queue
   - 4.2 Create a new internal node with these two nodes ~~and~~ as children and with probability equal to the sum of two nodes' probabilities.
   - 4.3 Add the new node to the queue
5. The remaining node is the root node and the tree is complete.
6. End.

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Roll: 00161050102O

my name is anuran chakraborty.

Frequency table

ch	Frequency
a	5
space	4
n	3
r	3
m	2
y	2
e	1
i	1
s	1
u	1
c	1
h	1
k	1
b	1
o	1
t	1

If the frequencies are same the characters are selected in ~~the~~ any order

a(5) sp(4) n(3) r(3) m(2) y(2) e(1) i(1) s(1)

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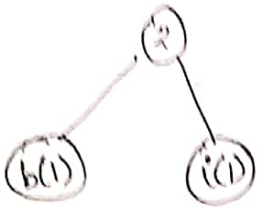
Roll: 001610501020.

1. Select highest priority characters.

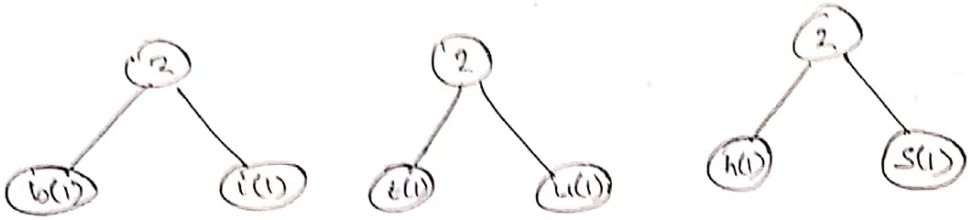
choose b, i



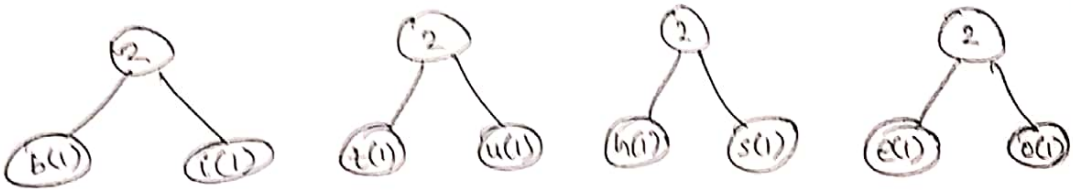
Remaining

choose t, u.

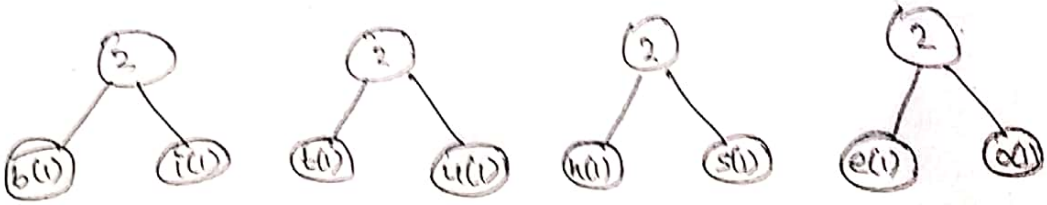
choose h, s.

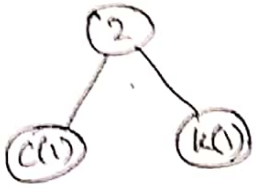


choose e, o.



choose c, k





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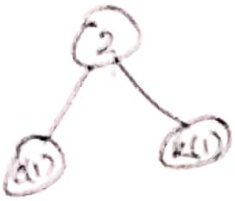
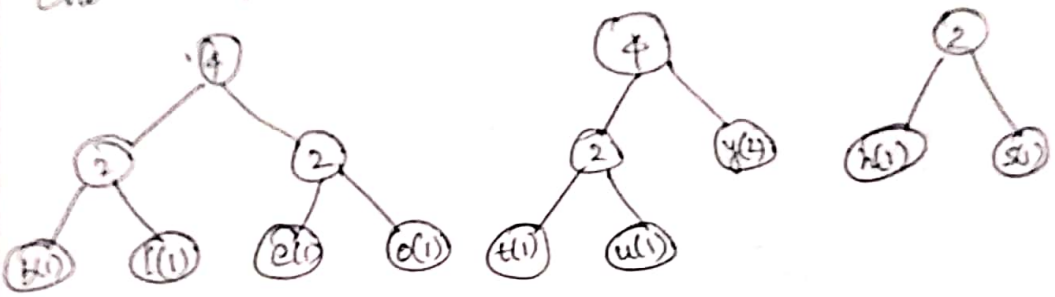
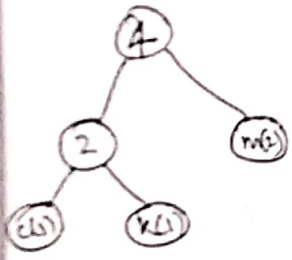
choose t, u and y as both have freq 2

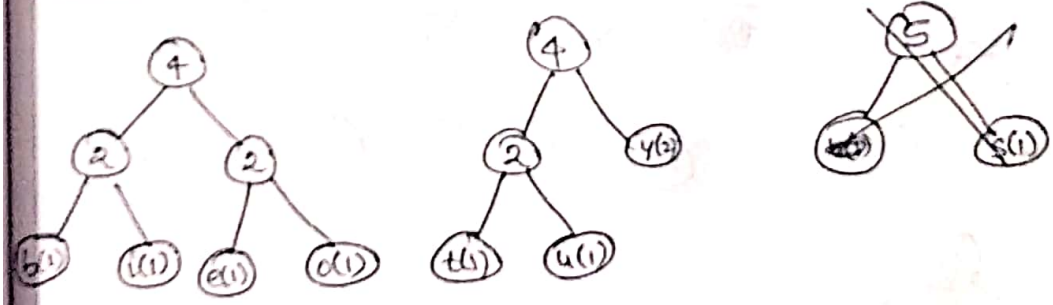


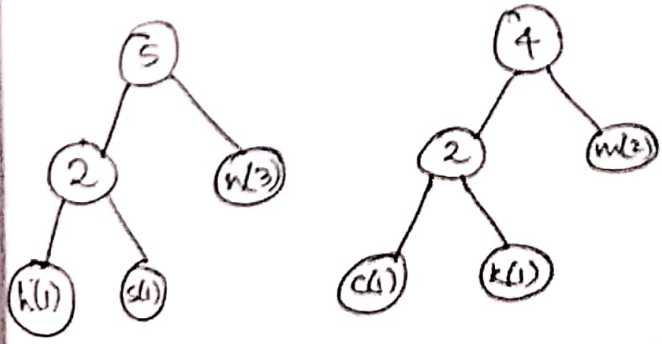
choose b, i and e, o | and c, k and m





Choose h, s and n.





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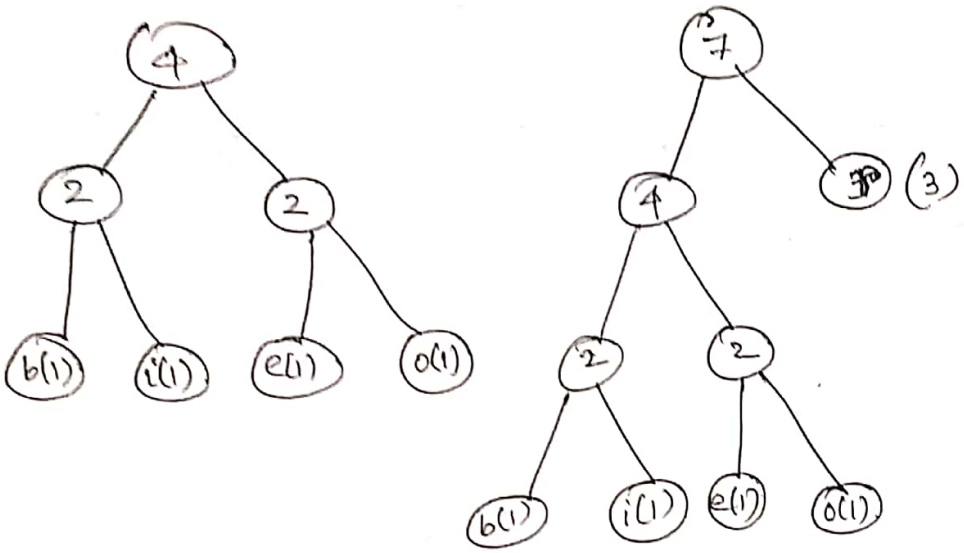
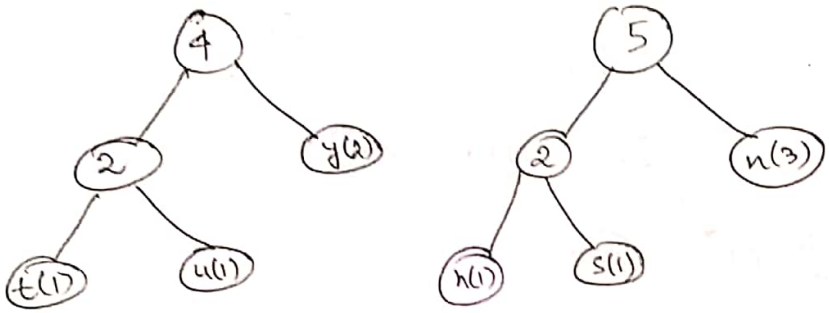
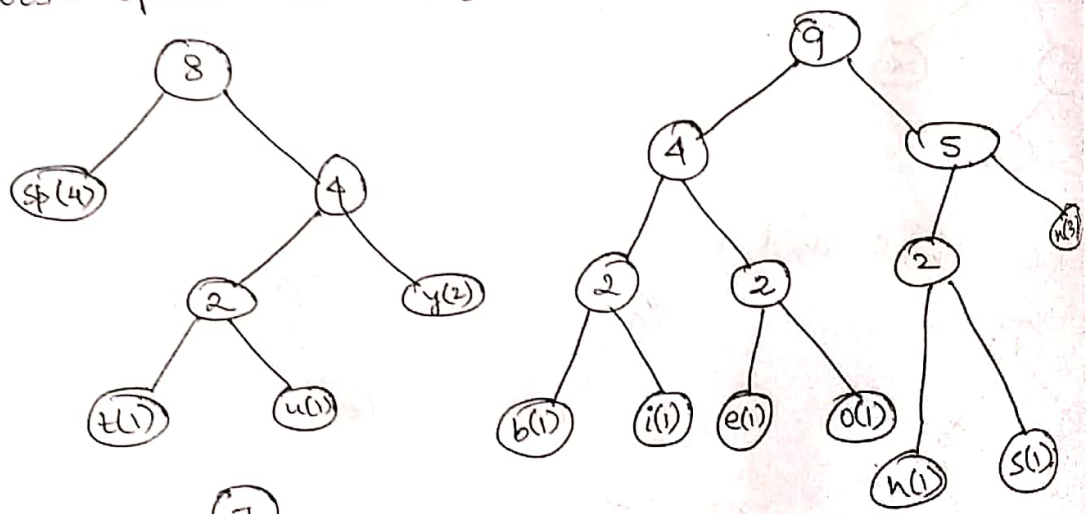
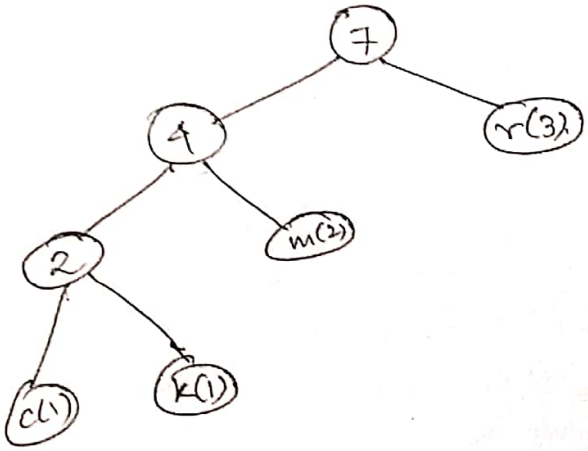
Next choose c, k, m and r.





Choose space and t, y, u | Merge b, i, e, o and h, s, n





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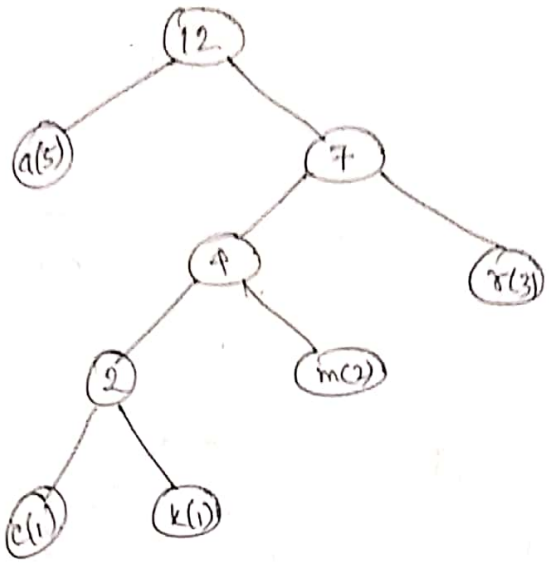
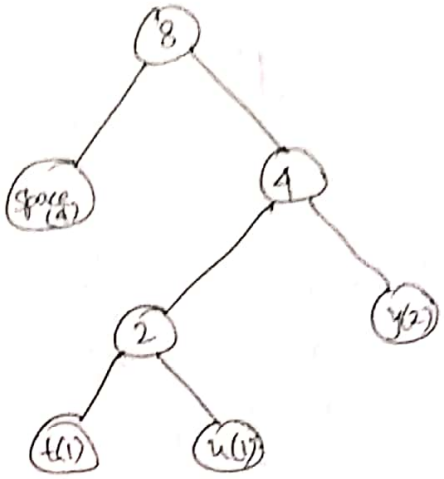
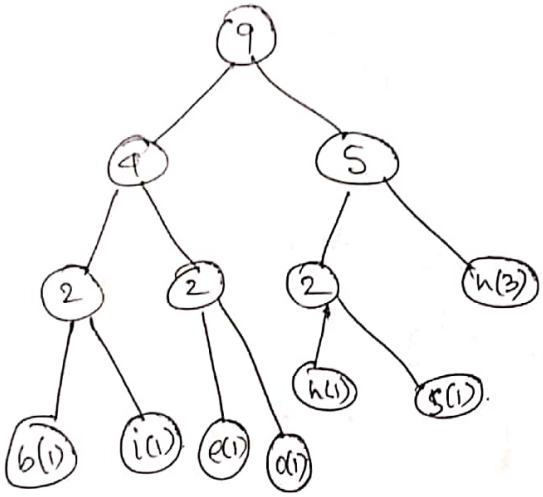
Roll : 001610501020

Choose ~~Merge~~ a(5) with c, k, m, r.







~~Merge twice~~,- Merge remaining and we get final tree.

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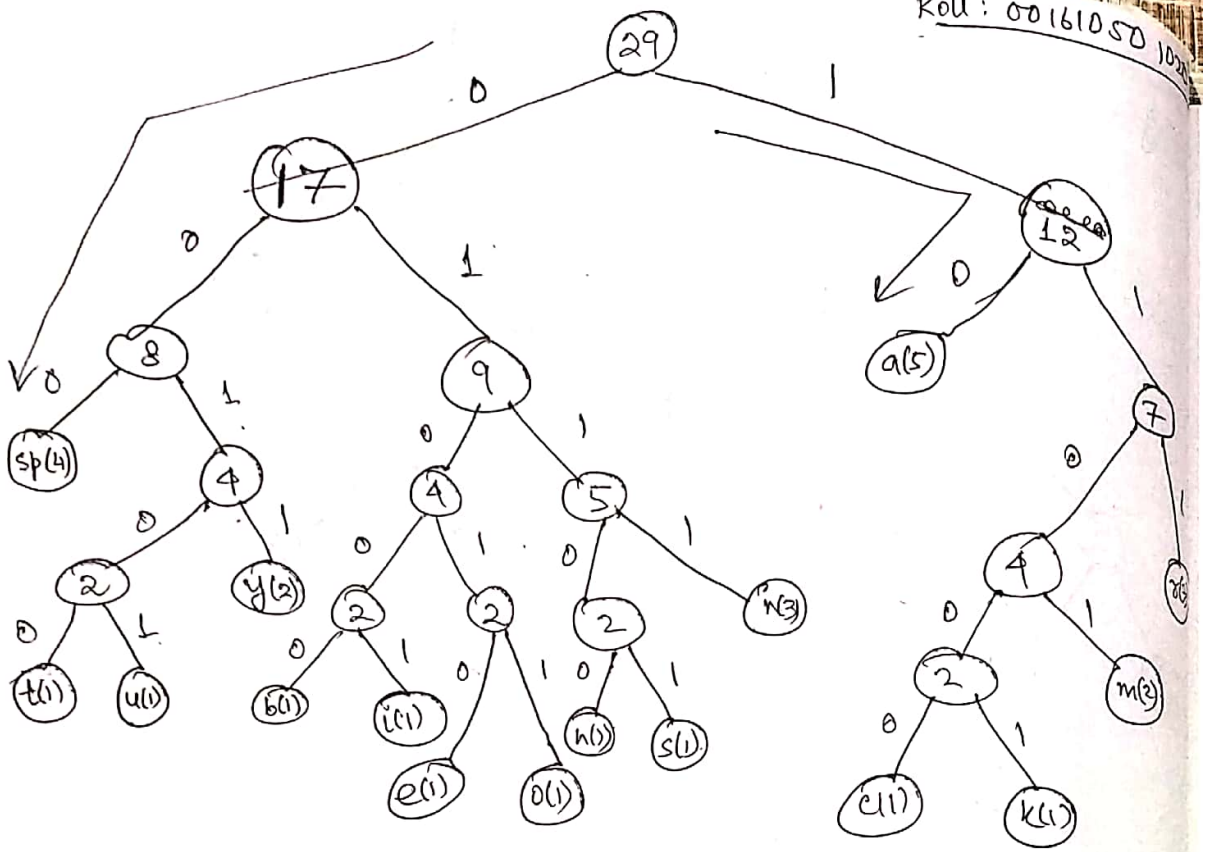

Huffman Codes

To find the codes traverse the tree to the character. Left node edge is 0 else 1.

a - 10
space - 000
n - 0111
r - 111
m - 1101
y - 0011
e - 01010
i - 01001
s - 01101
u - 00101
c - 11000
h - 01100
k - 11001
b - 01000
o - 01011
t - 00100

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Now concatenate the codes to get the encoded message

my name is anuran chakraborty

1101 0011 000 0111 10 1101 01010 000 01001 01101 000
m y sp n a m e sp i s sp

10 0111 00101 111 10 0111 000 11000 01100 10 11001 111 10
a n u r a n sp c h a k r a

01000 01011 11100100 0011
b o r t y .

In Huffman coding two codes of different length never have common prefix. So in decoding the above code.

1101 0011 0000 0111 . . . .

we see that the minimum length string having prefix 1101 is 4. and also no other string has the same code.

1101 → m
0011 → y.
000 → space.

and so on.

whenever we get a substring we check whether it is a valid code. If it is a valid code then we replace by that character as it will never be a prefix of a larger length code.

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