

Practicing PL & Resolution & Gametree questions from previous years' question papers

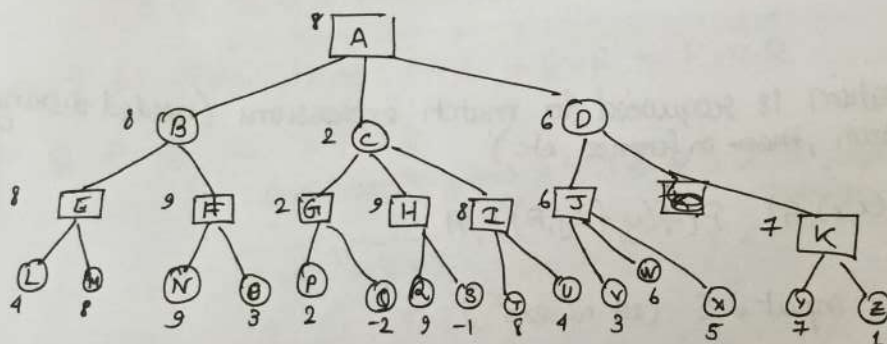
2015

Q4

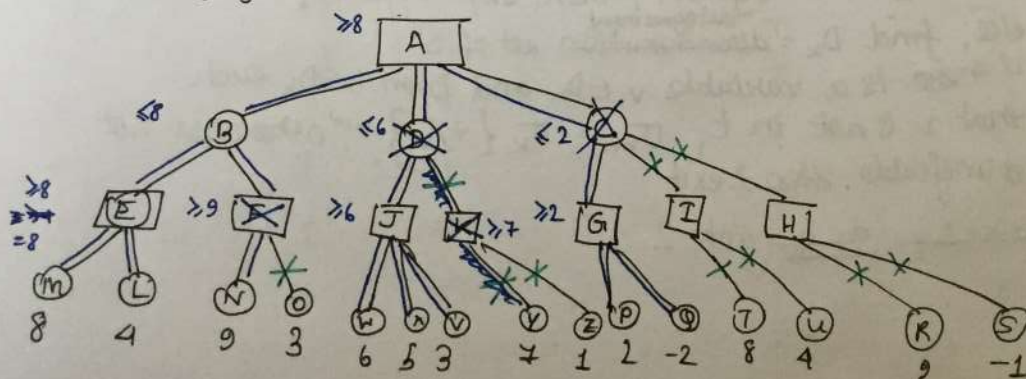
- (i) The nodes corresponding the MIN's next move are designated as 'AND' nodes because from MAX's point of view, a win must be obtainable from all possible moves of min
- (ii) The ordering of leaf nodes that results in best pruning requires that
- for every MAX node, largest successors with backed up value be examined first (descending order)
 - for every MIN node, successors with smallest backed up value be examined first (ascending order)

Reforming a min

Backed up values of all nodes



Now, rearranging so that



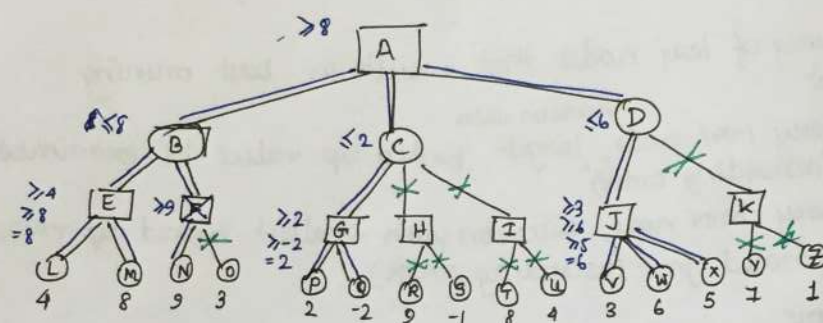
(ii) α -cutoff

→ search can be terminated below MIN node with $\beta \leq \alpha$ of any ancestor

β -cutoff

→ search may be terminated below any MAX node with $\alpha \geq \beta$ of any ancestor

180



Q6)

(a) Unification is required to match expressions (needed during resolution, ~~then~~ inference, etc)

(b) $P(f(x, z), A), P(f(y, f(y, A)), A)$

Unification: input = S (set of exp^r)

- 1 $k=0, \sigma_k = \{\}$
- 2 if $S\sigma_k$ is a singleton, then stop. mgu = σ_k
 else, find $D_k =$ ^{disagreement} ~~determination~~ set of S
 if there is a variable $v \in D_k$ and term $t \in D_k$ such that v is not in t , $\sigma_{k+1} = \sigma_k \{t/v\}$, ^{k+1} otherwise not unifiable. stop & exit
- 3 $k=k+1, S=S\sigma_k$ goto 2

k	σ_k
0	$\{\}$
1	$\{x/y\}$

Not unifiable

(c)

Resolution is a

$P \vdash Q$

A ~~rule~~, rule, is

if $P \vdash Q$

or, if P derives

Resolution rule

$P \vdash Q$

$P \vee$

\therefore we need to

(Also of $P \vdash$

P	Q	R
F	F	F
F	F	T
F	T	F
F	T	T
T	F	F
T	F	T
T	T	F
T	T	T

Hence prove

α
of any
ancestor

k	σ_k	$\delta \sigma_k$ $\delta \sigma_k$ $\delta \sigma_k$	D_k	σ_{k+1}
0	{}	$P(f(x,z), A), P(f(y, f(y, A)), A)$	$\{x, y\}$	$\{x/y\}$
1	{} $\{x/y\}$	$P(f(x, x), A), P(f(x, f(x, A)), A)$	$\{x, f(x, A)\}$	not valid <u>failure</u>

Not unifiable

(c)

Resolution is a sound rule of inference

A ~~rule~~ $P \vdash Q$ is a sound rule of inference when

if $P \vdash Q$ then $P \models Q$

or, if P derives Q then Q logically follows P

Resolution rule is as follows

$$PAQ, Q$$

$$P \vee Q, \sim Q \vee R \vdash P \vee R$$

\therefore we need to show that $P \vee Q, \sim Q \vee R \models P \vee R$

(Also $P \models Q$ iff $\models P \rightarrow Q$
(read as \vdash). (that is, $P \rightarrow Q$ is a valid proposition
tautology)

P	Q	R	$\overbrace{P \vee Q}^x$	$\overbrace{\sim Q \vee R}^y$	$\overbrace{P \vee R}^z$	$x \wedge y$	$x \wedge y \rightarrow z$
F	F	F	F	T	F	F	T
F	F	T	F	T	T	F	T
F	T	F	T	F	F	F	T
F	T	T	T	T	T	T	T
T	F	F	T	T	T	T	T
T	F	T	T	T	T	T	T
T	T	F	T	F	T	F	T
T	T	T	T	T	T	T	T

tautology

Hence proved

(d) $(\forall x) (CHILD(x) \rightarrow LOVES(x, SANTA))$
 $(\forall x) (LOVES(x, SANTA) \rightarrow \text{REINDEER}(x) \rightarrow LOVES(x, y))$
 $REINDEER(RUDOLPH) \wedge \text{REDNOSE}(RUDOLPH)$
 $(\forall x) (REDNOSE(x) \rightarrow WEIRD(x) \vee CLOWN(x))$
 $(\forall x) (REINDEER(x) \rightarrow \sim CLOWN(x))$
 $\sim CHILD(JOHN)$
 $(\forall x) (WEIRD(x) \rightarrow \sim LOVES(JOHN, x))$

Goal: $\sim CHILD(JOHN)$

Clausal form: $\sim CHILD(x_1) \vee LOVES(x_1, SANTA)$
 $\sim LOVES(x_2, SANTA) \vee \text{REINDEER}(y_1) \vee LOVES(x_2, y_1)$
 ~~$\sim LOVES(x_3, SANTA) \vee LOVES(x_3, y_2)$~~
 $REINDEER(RUDOLPH)$
 $REDNOSE(RUDOLPH)$
 $\sim REDNOSE(x_3) \vee WEIRD(x_3) \vee CLOWN(x_3)$
 $\sim REINDEER(x_4) \vee \sim CLOWN(x_4)$
 $\sim WEIRD(x_5) \vee \sim LOVES(JOHN, x_5)$

Rewrite as:
 $\sim C(x_1) \vee L(x_1, SANTA)$
 $\sim L(x_2, SANTA) \vee \sim R(y) \vee L(x_2, y)$
 $R(RUDOLPH)$
 $RN(RUDOLPH)$
 $\sim RN(x_3) \vee W(x_3) \vee Q(x_3)$
 $\sim R(x_4) \vee \sim Q(x_4)$
 $\sim W(x_5) \vee \sim L(x_5, JOHN, x_5)$
 Inverted goal: $\sim C(JOHN)$

$\sim C(x1) \vee L(x1, SANTA)$

$C(JOHN)$

$L(JOHN, SANTA)$

$\sim L(x2, SANTA) \vee \sim R(y) \vee \Rightarrow L(x2, y)$

$\sim R(y) \vee L(JOHN, y)$

$R(RUDOLPH)$

$\sim W(x5) \vee \sim L(JOHN, x5)$

$L(JOHN, RUDOLPH)$

$\sim RN(x3) \vee W(x3) \vee C2(x3)$

$\sim W(RUDOLPH)$

$\sim RN(RUDOLPH) \vee \sim W C2(RUDOLPH)$

$RN(RUDOLPH)$

$\sim R(x4) \vee \sim C2(x4)$

$C2(RUDOLPH)$

$\sim R(RUDOLPH)$

$R(RUDOLPH)$

NIL

Usage of AND-OR tree

- used to represent decomposable production systems
- Nodes labelled by compound databases have a set of successor nodes are AND nodes — in order to process to completion, all component databases must be processed to termination
- Nodes labelled by component databases are OR nodes — to process to completion, the database resulting from just one of the rule applications must process to termination
- Examples: Chemical structure generation
Symbolic integration
- Modeled as hypergraphs
 - ↳ Hyperarcs or k -connectors connecting parent to k successors

The terms AND nodes & OR nodes are restricted to AND-OR trees

2013

(86)

k	
0	
1	{
2	{n A

e) (i) (V)

(ii) (E)

2013

86)

k	σ_k	$S\sigma_k$	D_k	σ_{k+1}
0	$\{\}$	$P(x, g(y, A, h(y, B)))$ $P(h(A, B), g(A, y, x))$	$\{x, h(A, B)\}$	$\{h(A, B)/x\}$
1	$\{h(A, B)/x\}$	$P(h(A, B), g(y, A, h(y, B)))$ $P(h(A, B), g(A, y, h(A, B)))$	$\{y, A\}$	$\{A/y\}$
2	$\{h(A, B)/x, A/y\}$	$P(h(A, B), g(A, A, h(A, B)))$	—	—

↓ singleton exit

→ = mgu

$$\therefore mgu = \{h(A, B)/x, A/y\}$$

e) (i) ~~$(\forall x)(\forall y)$~~

$$(\forall x)(COUNTRY(x) \rightarrow (\forall y)(COUNTRY(y) \rightarrow$$

$$NEIGHBOR(x, y) \rightarrow \sim COLOUR$$

$$NEQUALS(COLOUR(x), COLOUR(y)))$$

(ii) $(\exists x)(STUDENT(x) \wedge FAILED(MATHS))$

$$\wedge (\forall y)(STUDENT(y) \rightarrow \sim EQUALS(x, y)$$

$$\vee \sim FAILED(MATHS)))$$

(d) Zebras

$$(\forall x) (Z(x) \rightarrow M(x) \wedge S(x) \wedge \text{MedSize}(x))$$

$$(\forall x) (M(x) \rightarrow A(x) \wedge Wb(x))$$

$$(\forall x) (S(x) \rightarrow \text{NonSolid}(x) \wedge \text{NonSpotted}(x))$$

$$(\forall x) (M(x) \rightarrow \text{MedSize}(x) \rightarrow \sim \text{Large}(x) \wedge \sim \text{Small}(x))$$

~~Zeke~~
 $Z(\text{Zeke})$

Goal: ~~Zeke~~ $\wedge \sim \text{Large}(\text{Zeke})$

Clausal form

$$\sim Z(x_1) \vee M(x_1)$$

$$\sim Z(x_2) \vee S(x_2)$$

$$\sim Z(x_3) \vee \text{MedSize}(x_3)$$

$$\sim M(x_4) \vee A(x_4)$$

$$\sim M(x_5) \vee Wb(x_5)$$

$$\sim S(x_6) \vee \text{NonSolid}(x_6)$$

$$\sim S(x_7) \vee \text{NonSpotted}(x_7)$$

$$\sim \text{MedSize}(x_8) \vee \sim \text{Large}(x_8)$$

$$\sim \text{Small}(x_9)$$

$$\sim \text{MedSize}(x_9) \vee \sim \text{Small}(x_9)$$

$$Z(\text{zeke})$$

$$\text{Large}(\text{Zeke})$$