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Component in machine learning algorithms. In machine learning algorithms some kind of loss is defined and then this loss is function is optimized by adjusting the weights. This loss function is optimized using some optimization routine. The choice optimization

algorithm can make a difference between

getting a good accuracy in hours ordays.

Examples:

1. Logistic Regression:

Here the loss function is optimised.

Output = 0 or 1.

Hypothesis Z=WX+B

 $h_{\theta}(x) = \text{sigmoid}(z)$

Nows, we define the cost function.

cost $(h_0(x), Y) = -\log(h_0(x))$ if y=1= $-\log(l_0-h_0(x))$ if y=0

This may be written as C= cost (ho(a), y)= -y log (ho(a)) =-

(1-4) log (1-ho(2))

. The formulation is

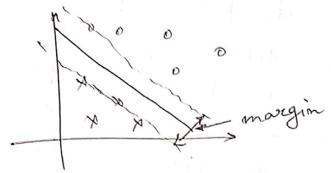
minimite (east (ho(a), y))

This may be done using gradient descent

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2. SVM.

In SVM we optimize the man function so as to maximize the margin between the data points and the hyperplane. This loss Junction is known as hinge loss.



for fi = +1, WX: +6>0. Ji=-1, WA: +620.

scaling we get Vi=1 Wxi+b>1 -0 Vi=-1 Wxi+b<-1 -0

man. margin width is $M = (x^{+} - x^{-}) \cdot n \cdot = (x^{+} - x^{-}) \cdot \frac{W}{|W||} = \frac{2}{|W||}$

x+-x- = 2 from @ and @

maximize 1/1/11 such that

WX: + 6>+1 Yi=+1 MXitb L-1 Yi=-L

minimize 1 11 W112 such that
yi (NX7b) 7.1

This can optimized using Quadratic Programming

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95 when we solve a non-linear problem (b) it is very imposstant to know if the problem is convex or not. The convexity characteristics decide which solution method is suitable to use and what solution quality we can expect when applying this method. If the problem is convex then each local optimum will also be a global oftimum. Since most methods are search methods that only guarantee to find a local optimum, the convexity properties decide if we with certainty or not can announce that the solution we have found is the global optimum.

if f(a) is twice differentiable. then,

- · f(x) is an convex function if hessian matrix H is positive semi-definite for all aex.
- · f(2) is concave if H is -ve semi-definity. Yacx.

Say, for example of (3) = -

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f(21, x2) = - x2 - 422 + 2122 001610501020 V = [-224 -8x2 - 8x2 + x1] Now find eigen value. | H- /I = 0 @ or, (-2-7)(-8-7)-1=0. $2^{2}+10\lambda+15=0$ 1. 1 = -5+ 110 Az=-5-110. · .: All eigen values avre 120 -: f(21,72) is not convex. f(xy) 72) = 212+ 72 \$ V 2 [2q 272] $H = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$ [H-]I = 0 $\begin{vmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{vmatrix} = 0.$ A = 2.

• +ve definite H

f(21,22) is convex.

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In duality we consider each Q5(c) constraint as a variable and the RHS as its coefficient. Basically solving a dual problem is equivalent to solving its primal problem.

In LP models, the parameters are usually not exact. InCEB, The parameters may change withing certain limits without changing the optimal solution. This is referred to as sensitivity analysis.

Relaxation is expanding the feasible region by making constraints "less restrictive"

+ Removing a constraint

· Increasing RHS of < constraint

, Decreasing RHS of > constraint. when we relax a binding constraint, the optimal objective function value will improve or stay the same. For non-ton

binding it remains same.

Restriction is contracting the feasible region by making worstraints more restrictive.

. Adding a new constraint. . Decreasing RHS < constraint

. Encreasing RHS > constraint. Objective functions workers or remains same Anwian Chakraborty

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