

Why LPC is so popular (widely used)

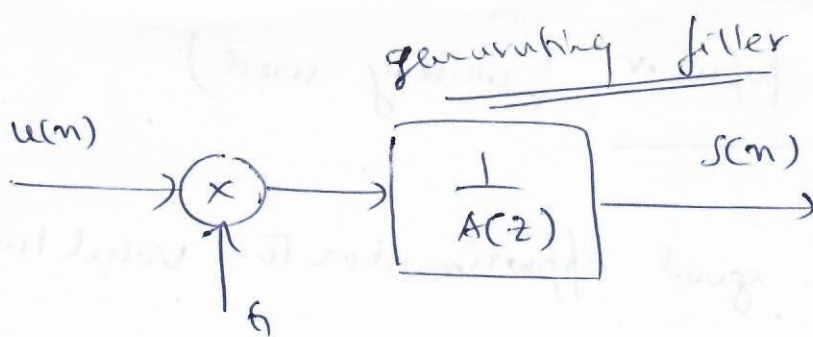
- LPC provides good approximation to vocal tract spectral shape for voiced sounds.
Can be effective for unvoiced & transient regions.
- LPC modeling can be used to separate source & filter separation.
- LPC can be analytically tractable model, mathematically precise. Computationally less complex compared to filter bank analysis.
- LPC model works well for speech recognition.

LPC Model

$$s(n) \approx a_1 s(n-1) + a_2 s(n-2) + \dots + a_p s(n-p) + u(n)$$
$$= \sum_{k=1}^p a_k s(n-k) + u(n)$$

$$S(z) = \sum_{k=1}^p a_k z^{-k} S(z) + U(z)$$

$$H(z) = \frac{S(z)}{U(z)} = \frac{1}{1 - \sum_{k=1}^p a_k z^{-k}} = \frac{1}{A(z)}$$



Synthesis Model

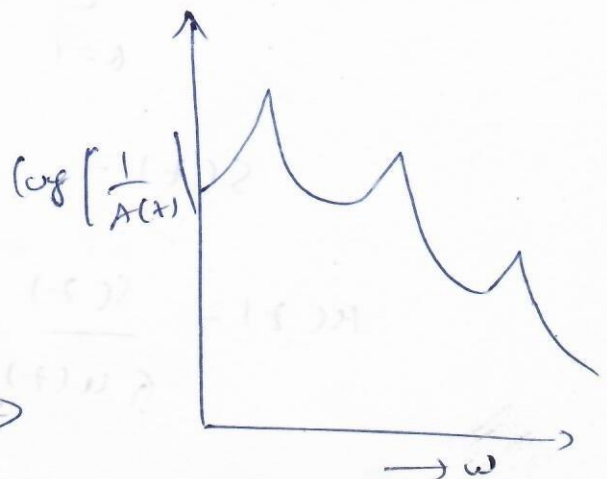
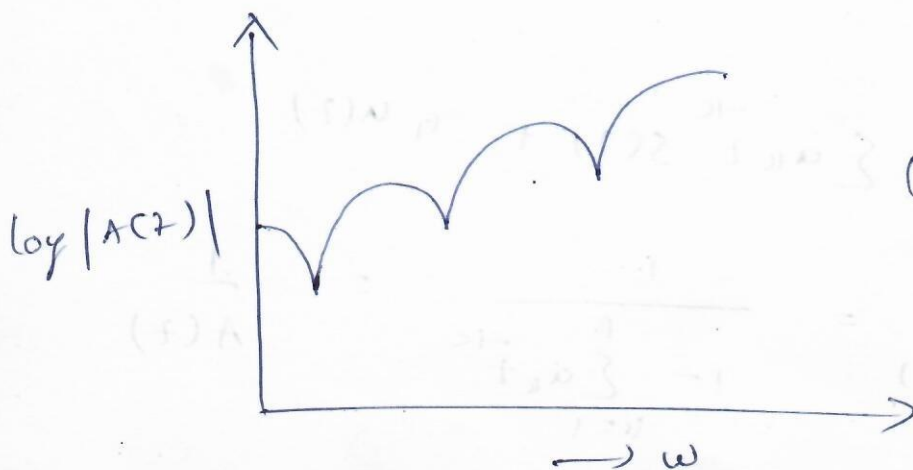
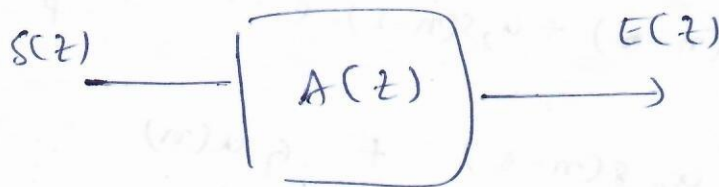
$$e(n) = s(n) - \hat{s}(n)$$

$$= s(n) - \sum_{k=1}^p a_k s(n-k)$$

$$E(z) = S(z) \left[1 - \sum_{k=1}^p a_k z^{-k} \right]$$

Analysis Model (inverse filter formulation)

$$\frac{E(z)}{S(z)} = 1 - \sum_{k=1}^p a_k z^{-k} = A(z)$$



LP analysis of speech

$$\hat{s}(n) = \sum_{k=1}^P a_k s(n-k)$$

$$e(n) = s(n) - \hat{s}(n) = s(n) - \sum_{k=1}^P a_k s(n-k)$$

$$E = \sum_n e^2(n) = \sum_n \left[s(n) - \sum_{k=1}^P a_k s(n-k) \right]^2$$

optimum values of a_k

$$\frac{\partial E}{\partial a_k} = 0 \quad k = 1, 2, \dots, P$$

Autocorrelation Method $\sum_k a_k \sum_n s_{n-k} s_{n-i} = - \sum_n s_n s_{n-i} \quad 1 \leq i \leq P$

$$\sum_k a_k R(i-k) = R(i) \quad i = 1, 2, \dots, P$$

$$\begin{bmatrix} R(0) & R(1) & R(2) & \dots & R(P-1) \\ R(1) & R(0) & R(1) & \dots & R(P-2) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ R(P-1) & R(P-2) & R(P-3) & \dots & R(0) \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_P \end{bmatrix} = \begin{bmatrix} R(1) \\ R(2) \\ \vdots \\ R(P) \end{bmatrix}$$

Co-variance Method

$$\phi(i, 0) = \sum_{k=1}^p a_k \phi(i, k)$$

$$\begin{bmatrix} \phi(1,1) & \phi(1,2) & \phi(1,3) & \dots & \phi(1,p) \\ \phi(2,1) & \phi(2,2) & \phi(2,3) & \dots & \phi(2,p) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \phi(p,1) & \phi(p,2) & \phi(p,3) & \dots & \phi(p,p) \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_p \end{bmatrix} = \begin{bmatrix} \phi(1,0) \\ \phi(2,0) \\ \vdots \\ \phi(p,0) \end{bmatrix}$$

$$\phi(i, k) = \sum_n s(n-i) s(n-k)$$

Total error (ϵ_{\min})

$$\epsilon = \sum_n \tilde{e}^2(n) = \sum_n \left[s(n) - \sum_{k=1}^p a_k s(n-k) \right]^2$$

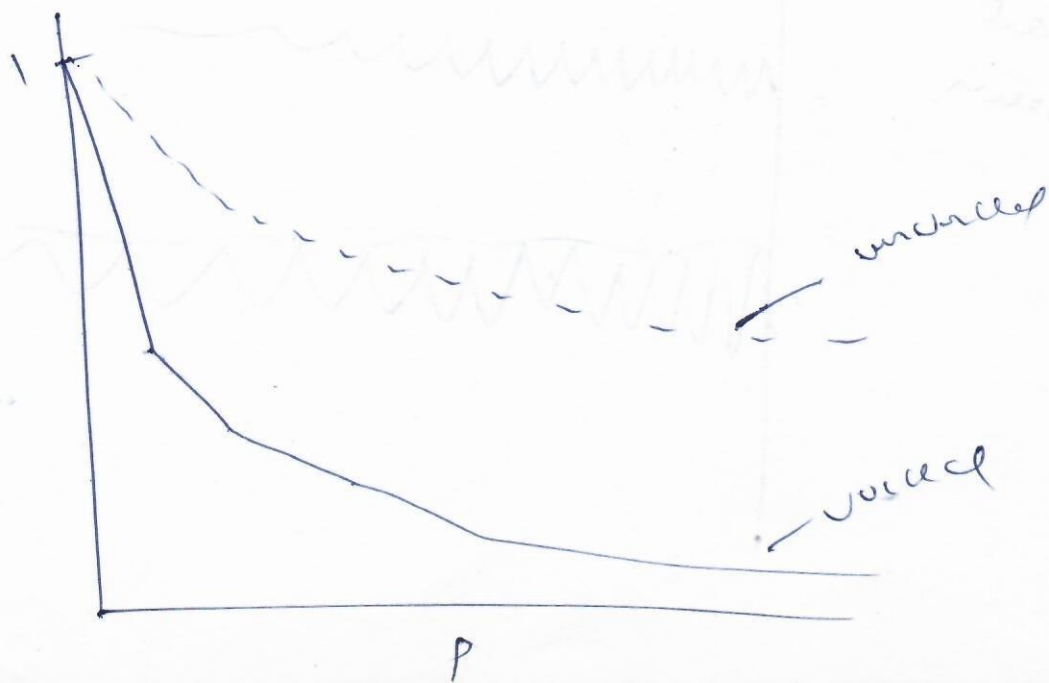
$$= \sum_n \tilde{s}^2(n) - \sum_{k=1}^p a_k \sum_n s(n) s(n-k)$$

$$= R(0) - \sum_{k=1}^p a_k R(k)$$

LP Spectrum with order p

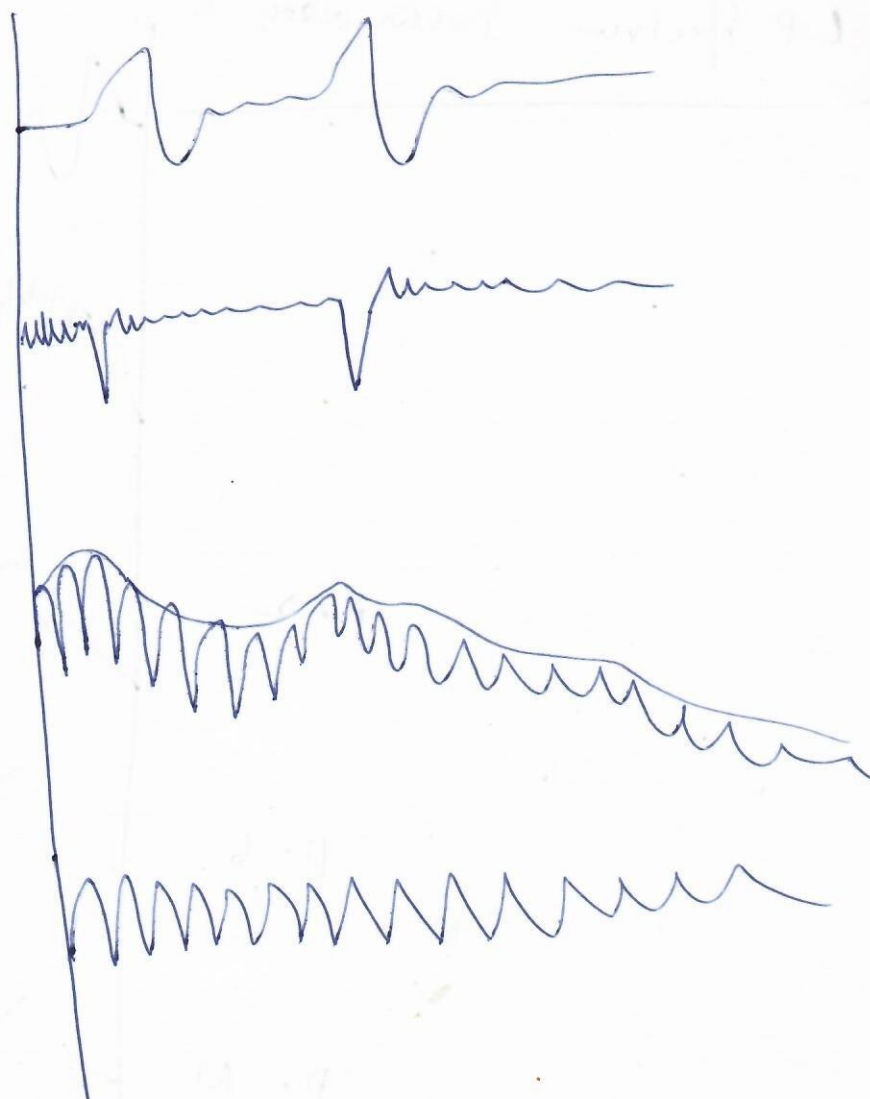


Normalized error with

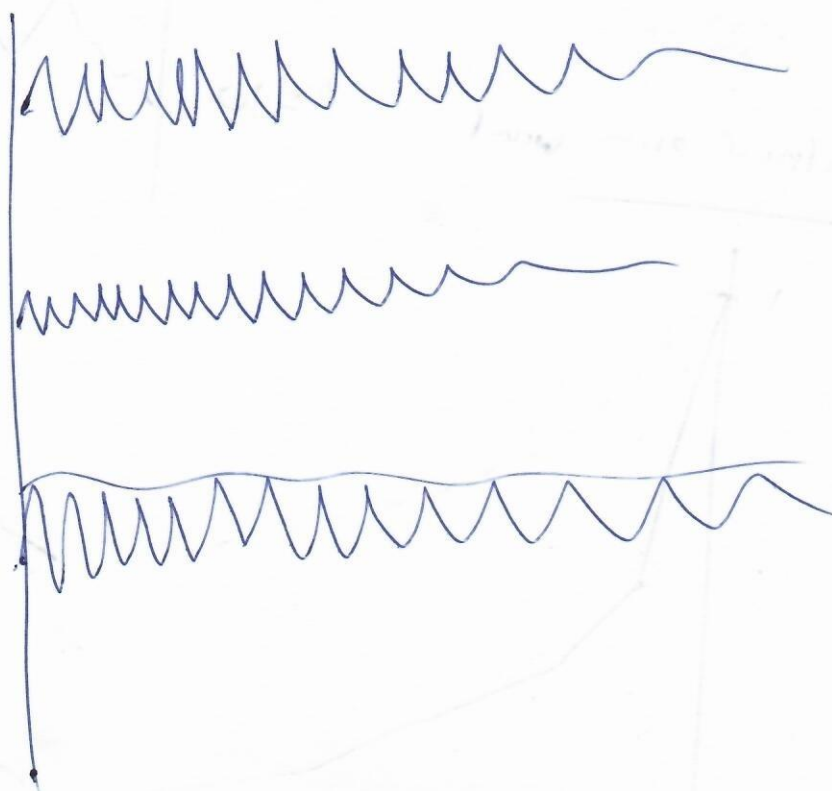


Illustrations

voiced
speech



unvoiced
speech



Frequency domain formulation

$$E(z) = \left[1 + \sum_{k=1}^p a_k z^{-k} \right] S(z) = A(z) S(z)$$

Parserval's theorem

$$E = \sum_{n=-\infty}^{\infty} e^2(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} |E(e^{j\omega})|^2 d\omega$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} |A(e^{j\omega})|^2 |S(e^{j\omega})|^2 d\omega$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} A(e^{j\omega}) A^*(e^{j\omega}) \cdot P(\omega) d\omega$$

minimize E w.r.t $a_k \Rightarrow \frac{\partial E}{\partial a_k} = 0$

$$R(i) = \sum_{k=1}^p a_k R(i-k) \quad i = 1, 2, \dots, p$$

$$R(i) = \frac{1}{2\pi} \int_{-\pi}^{\pi} P(\omega) e^{j\omega i} d\omega$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} P(\omega) \cos(\omega i) d\omega$$

LP Spectral Making

Signal spectrum = $P(\omega)$

All-pole model spectrum = $\hat{P}(\omega)$

$$\hat{P}(\omega) = |R(e^{j\omega})|^2 = \frac{\sigma^2}{|A(e^{j\omega})|^2 |1 + \sum a_n e^{-jn\omega}|^2}$$

$$P(\omega) = \frac{|E(e^{j\omega})|^2}{|A(e^{j\omega})|^2}$$

$$P(\omega) = \hat{P}(\omega) \Rightarrow |E(e^{j\omega})|^2 = \sigma^2$$

Picker $A(z) \rightarrow$ whitening filter

$$E = \frac{1}{2\pi} \int_{-\pi}^{\pi} |E(e^{j\omega})|^2 d\omega = \frac{1}{2\pi} \int_{-\pi}^{\pi} |A(e^{j\omega})|^2 |s(e^{j\omega})|^2 d\omega$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{P(\omega)}{\hat{P}(\omega)} \sigma^2 d\omega = \frac{\sigma^2}{2\pi} \int_{-\pi}^{\pi} \frac{P(\omega)}{\hat{P}(\omega)} d\omega$$

σ^2 can be obtained by $\hat{R}(0) = R(0)$

Cepstrum analysis



$$S(f) = E(f) * V(f)$$

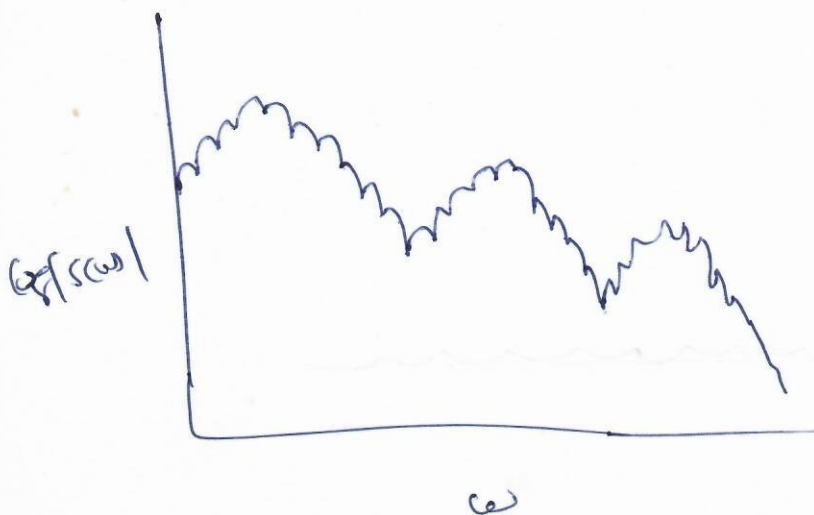
$$S(\omega) = E(\omega) \cdot V(\omega)$$

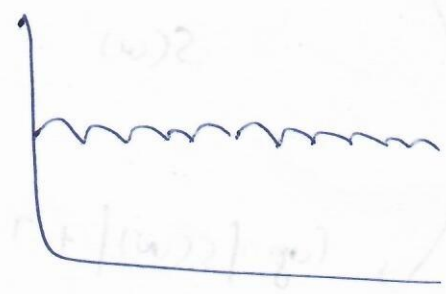
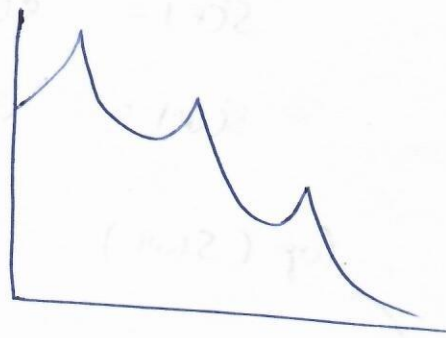
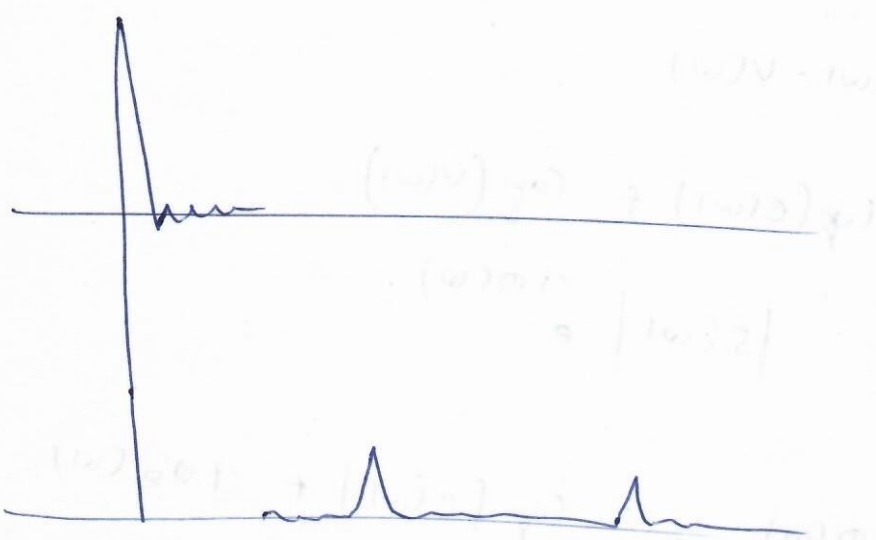
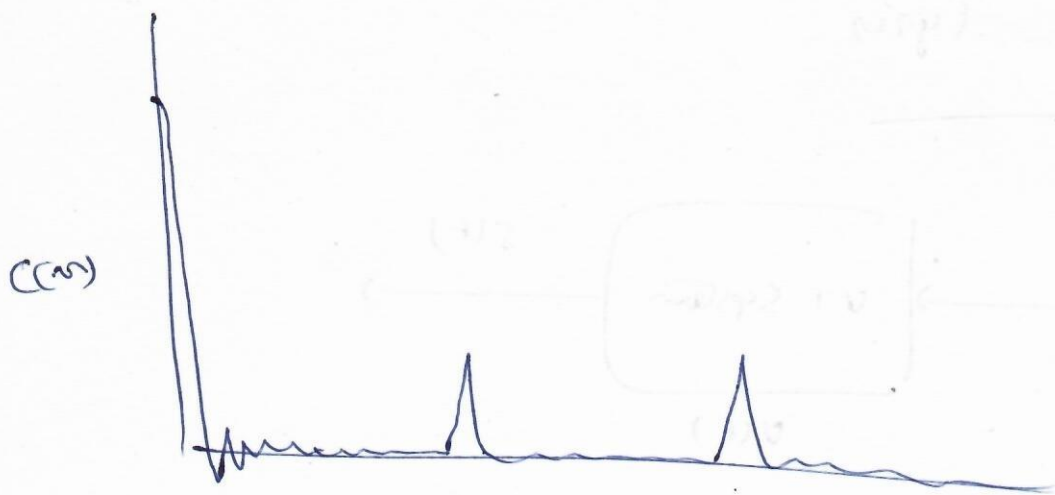
$$\log(S(\omega)) = \log(E(\omega)) + \log(V(\omega))$$

$$S(\omega) = |S(\omega)| e^{j\phi(\omega)}$$

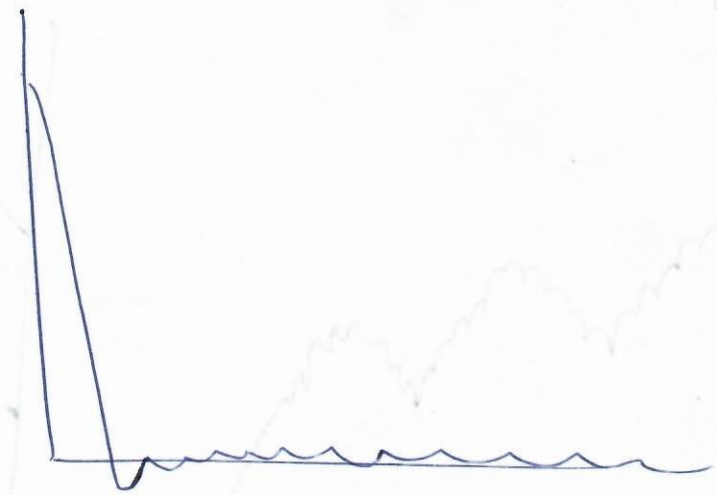
$$\log |S(\omega)| + j\phi(\omega) = \log |E(\omega)| + j\phi_e(\omega) + \log |V(\omega)| + j\phi_v(\omega)$$

$$\log |S(\omega)| = \log |V(\omega)| + \log |E(\omega)|$$





unvoiced cepstrum



Steps in Deriving the LPCs from speech

Preamphases

Frame blocking

Windowing

Autocorrelation analysis

LPC analysis

Cepstral analysis

Cepstral weighting

Cepstral covariance

Steps in Computation of ALPs

FFT (Power spectrum)

Critical band integration & resampling

- Trapezoidal filter (approximate to critical band masking curve)

Equal loudness curve - weighting

Power law of hearing (cube root or spectral exponent)

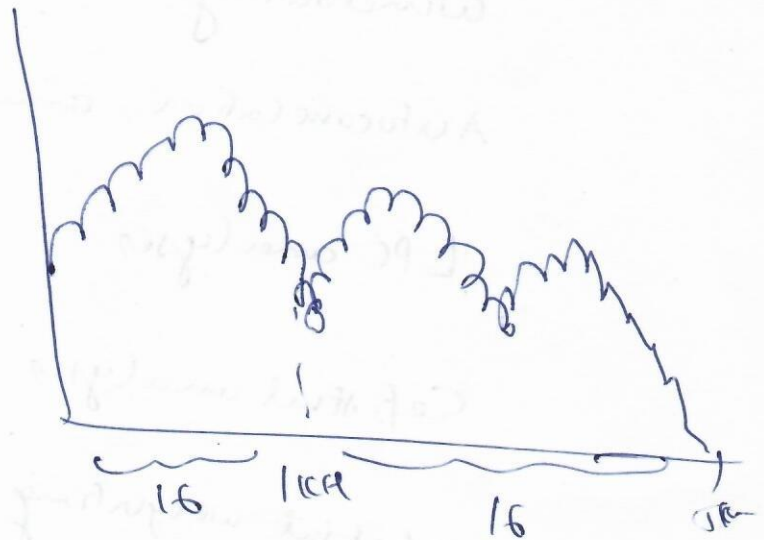
IDFT (and time auto correlation coefficients)

Spectral Smoothing

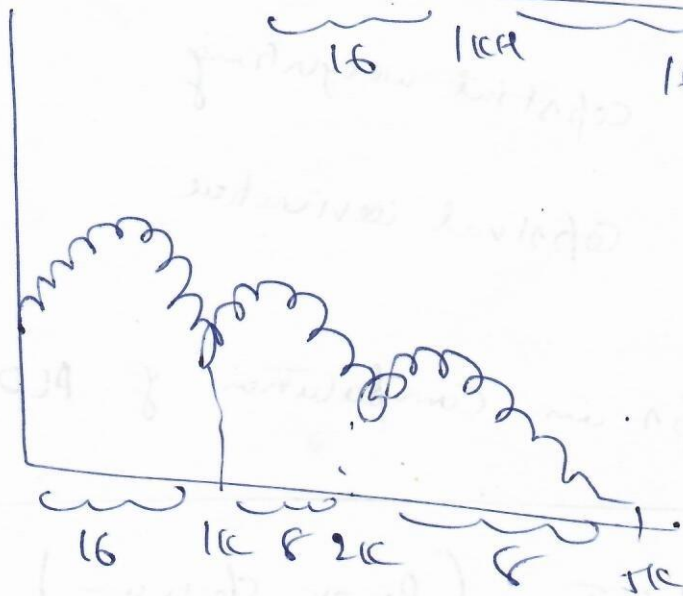
Solving the set of linear equations

cepstral coefficients

Spectral coefficients



mel-spectral



mel-cepstral

IFT [mel-spectral coefficients]

Different formulations of LP analysis

Mean square error

inverse filter

Autocorrelation matching

Autocovariance

Spectrum matching

Maximum entropy

Maximum likelihood

Lattice filter

$$E_{n+1} = (1 - k_n^2) E_n \quad n = 1, 2, \dots, p$$

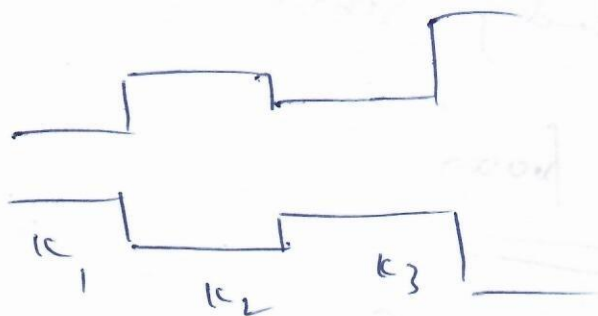
$$E_p = \prod_{n=1}^p (1 - k_n^2)$$

k_n — reflection coefficients

PARTIAL, Autocorrelation

$L(k_n)$

log error coefficients



$$g_m = \log \left(\frac{1 - k_n}{1 + k_n} \right)$$

Dynamic features

$$\Delta C_{\hat{n}}(n) = \frac{\sum_{k=-N}^N k C_{\hat{n}}(n+k)}{\sum_{k=-N}^N k^2}$$

RASTA - PLP

CMS: Cepstral Mean Subtraction

Robustness to convolutional errors.

Spectral Analysis

Range of compressing static nonlinearities — log

Range of linear BPF

Range of expanding static nonlinearities — exponent
also

PLP process

Spectral Subtraction (Robustness to additive noise)