EE3900 : Gate Assignment-1

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Download all python codes from

https://github.com/Rahul27n/EE3900/blob/main/ Gate Assignment 1/Gate Assignment 1.py

and latex-tikz codes from

and

$$\mathbf{X} = \begin{pmatrix} 12\\2j\\0\\-2j \end{pmatrix} \tag{2.0.5}$$

Now we need to find X_1 satisfying the relation :

$$\mathbf{X_1} = \mathbf{W_{12}X_1} \tag{2.0.6}$$

where

1 QUESTION: Q.33 EC-GATE-2016

The Discrete Fourier Transform (DFT) of the 4 point sequence $x[n] = \{3, 2, 3, 4\}$ is given by X[k] = $\{12, 2j, 0, -2j\}$. If $X_1[k]$ is the DFT of the 12 point sequence $x_1[n] = \{3, 0, 0, 2, 0, 0, 3, 0, 0, 4, 0, 0\}$, the value of $\left|\frac{X_1[8]}{X_1[11]}\right|$ is:

2 SOLUTION

The 4-point DFT matrix is given by:

$$\mathbf{W_4} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & \omega^1 & \omega^2 & \omega^3 \\ 1 & \omega^2 & \omega^4 & \omega^6 \\ 1 & \omega^3 & \omega^6 & \omega^9 \end{pmatrix}$$
(2.0.1)

$$= \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{pmatrix}$$
 (2.0.2)

$$\mathbf{X} = \mathbf{W_4}\mathbf{x} \tag{2.0.3}$$

$$\mathbf{x} = \begin{pmatrix} 3 \\ 2 \\ 3 \\ 4 \end{pmatrix} \tag{2.0.4}$$

$$\mathbf{x_1} = \begin{pmatrix} 3 \\ 0 \\ 0 \\ 2 \\ 0 \\ 0 \\ 3 \\ 0 \\ 0 \\ 4 \\ 0 \\ 0 \end{pmatrix} \tag{2.0.7}$$

where

$$\Omega = e^{\frac{-2\pi j}{12}}$$

$$= \frac{\sqrt{3} - j}{2}$$
(2.0.8)

We can express x_1 in terms of x as follows:

$$\mathbf{x_1} = \mathbf{A}\mathbf{x} \tag{2.0.10}$$

where

$$\implies \mathbf{A} = \begin{pmatrix} \mathbf{e_1} \ \mathbf{e_4} \ \mathbf{e_7} \ \mathbf{e_{10}} \end{pmatrix} \tag{2.0.12}$$

where e_1, e_4, e_7, e_{10} represent the unit basis vectors in a subspace of \mathbb{R}^{12} . Now from (2.0.6) have :

$$\mathbf{X}_1 = (\mathbf{W}_{12}\mathbf{A})\mathbf{x} \tag{2.0.13}$$

Only the red coloured columns in W_{12} give non-zero output when multiplied with A. We can express the matrix W_{12} as a block matrix in the following way:

$$\mathbf{W}_{12} = \begin{pmatrix} \mathbf{c}_1 & \mathbf{c}_2 & \mathbf{c}_3 & \mathbf{c}_4 & \mathbf{c}_5 & \mathbf{c}_6 & \mathbf{c}_7 & \mathbf{c}_8 & \mathbf{c}_9 & \mathbf{c}_{10} & \mathbf{c}_{11} & \mathbf{c}_{12} \end{pmatrix}$$
(2.0.14)

where $\mathbf{c_i}$ is the i^{th} column matrix of $\mathbf{W_{12}}$. Now we have:

$$X_{1} = \begin{pmatrix} c_{1} & c_{2} & c_{3} & c_{4} & c_{5} & c_{6} & c_{7} & c_{8} & c_{9} & c_{10} & c_{11} & c_{12} \end{pmatrix} Ax$$

$$\implies X_{1} = \begin{pmatrix} c_{1} & c_{4} & c_{7} & c_{10} \end{pmatrix} x \qquad (2.0.15)$$

We can also express W_4 as block matrix as follows:

$$\mathbf{W_4} = \left(\mathbf{w_1} \ \mathbf{w_2} \ \mathbf{w_3} \ \mathbf{w_4}\right) \tag{2.0.16}$$

where $\mathbf{w_i}$ is the i^{th} column matrix of $\mathbf{W_4}$.

We can importantly note that:

$$\mathbf{c_1} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \otimes \mathbf{w_1} \tag{2.0.17}$$

$$\mathbf{c_4} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \otimes \mathbf{w_2} \tag{2.0.18}$$

$$\mathbf{c_7} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \otimes \mathbf{w_3} \tag{2.0.19}$$

$$\mathbf{c_{10}} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \otimes \mathbf{w_4} \tag{2.0.20}$$

where \otimes represents the **Kronecker Product**.

Therefore from (2.0.15) we have:

$$\mathbf{X}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \otimes \left(\mathbf{w}_1 \ \mathbf{w}_2 \ \mathbf{w}_3 \ \mathbf{w}_4 \right) \mathbf{x} \tag{2.0.21}$$

$$= \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \otimes \mathbf{X} \tag{2.0.22}$$

$$=\begin{pmatrix} 12\\2j\\0\\-2j\\12\\2j\\0\\-2j\\12\\2j\\0\\-2i \end{pmatrix}$$
(2.0.23)

Therefore we have:

$$\left| \frac{\mathbf{X}_1[8]}{\mathbf{X}_1[11]} \right| = \left| \frac{12}{-2j} \right| = \left| 6j \right| = 6$$
 (2.0.24)

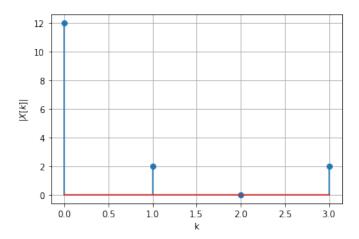


Fig. 0: Magnitude of X[k] vs k

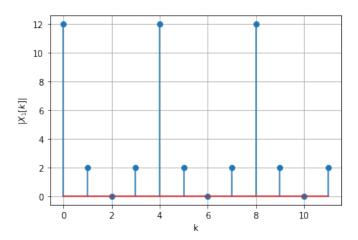


Fig. 0: Magnitude of $X_1[k]$ vs k