

Softmax Policy Gradient

(1.1)

$$\pi_w(a|s) = \frac{e^{w_{s,a}/\tau}}{\sum_a e^{w_{s,a}/\tau}}$$

$$\nabla \log(\pi(a|s)) = \nabla \left[\frac{w_{s,a}}{\tau} - \log \left(\sum_a e^{w_{s,a}/\tau} \right) \right]$$

$$\text{cf: } \nabla_{w_{s,b}} \left[\frac{w_{s,a}}{\tau} - \log \left(\sum_a e^{w_{s,a}/\tau} \right) \right] \quad b \neq a$$

$$= \frac{1}{\tau} - \nabla_{w_{s,b}} \log \left(\sum_a e^{w_{s,a}/\tau} \right)$$

$$= \frac{1}{\tau} - \frac{1}{\sum_a e^{w_{s,a}/\tau}} \nabla_{w_{s,b}} \left(\sum_a e^{w_{s,a}/\tau} \right)$$

$$= \frac{1}{\tau} - \frac{\nabla_{w_{s,b}} (e^{w_{s,b}/\tau})}{\sum_a e^{w_{s,a}/\tau}}$$

$$= \frac{1}{\tau} - \frac{e^{w_{s,b}/\tau} \left(\frac{1}{\tau} \right)}{\sum_a e^{w_{s,a}/\tau}}$$

For $\tau \ll 1$,

$$\approx \left[\frac{1 - e^{w_{s,b}/\tau}}{\sum_a e^{w_{s,a}/\tau}} \right]$$

$$\text{L2: } \nabla_{w_{s,b}} \left[\frac{w_{s,a}}{\tau} - \log \left(\sum_a e^{w_{s,a}/\tau} \right) \right], \quad b \neq a$$

$$= 0 - \nabla_{w_{s,b}} \log \left(\sum_a e^{w_{s,a}/\tau} \right)$$

$$= - \frac{1}{\sum_a e^{w_{s,a}/\tau}} \nabla_{w_{s,b}} \left(\sum_a e^{w_{s,a}/\tau} \right)$$

$$= \left[\frac{- \frac{e^{w_{s,b}/\tau}}{\tau}}{\sum_a e^{w_{s,a}/\tau}} \right]$$

$$\text{L3: } \nabla_{w_{s,b}} \left[\frac{w_{s,a}}{\tau} - \log \left(\sum_a e^{w_{s,a}/\tau} \right) \right], \quad \text{if } s, b \neq a$$

Linear Policy Gradient

$$(2.1) \quad \pi_{\theta}(a|s) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(a-\theta^T s)^2}{2\sigma^2}}$$

$$\log \pi_{\theta}(a|s) = \log \left(\frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(a-\theta^T s)^2}{2\sigma^2}} \right)$$

$$= \log \left(\frac{1}{\sigma\sqrt{2\pi}} \right) + \log \left(e^{-\frac{(a-\theta^T s)^2}{2\sigma^2}} \right)$$

$$\nabla_{\theta} \log \pi_{\theta}(a|s) = \nabla_{\theta} \left[\log \left(\frac{1}{\sigma\sqrt{2\pi}} \right) + \log \left(e^{-\frac{(a-\theta^T s)^2}{2\sigma^2}} \right) \right]$$

$$= \nabla_{\theta} \log \left(\frac{1}{\sigma\sqrt{2\pi}} \right) + \nabla_{\theta} \left(-\frac{(a-\theta^T s)^2}{2\sigma^2} \right)$$

$$= -\frac{1}{2\sigma^2} \nabla_{\theta} (a-\theta^T s)^2$$

$$= -\frac{1}{\sigma^2} (s) (a-\theta^T s) \quad \cdot$$

$$= \frac{(a-\theta^T s)}{\sigma^2} s, \text{ where } \theta, s \text{ are vectors.}$$

Neural Network Gradient Derivation

(2-3)

x - input

α - learning rate

$z = w \cdot x + b$

* Derivation does not include

$h = \text{ReLU}(z)$

Sampling from the normal distribution

$\theta = w \cdot h + b$

- Here $J(\theta)$ would denote the mean MSE

$\hat{y} = \text{softmax}(\theta)$

$J(\theta) = (-\sum y_i \log(\hat{y}_i)) / n$

Here θ denotes the cross entropy loss function

if we minimize the likelihood the estimate is close to the actual output of \hat{y}

$-\sum y_i \log(\hat{y}_i)$

We assume that b is the bias in our network = 0

$\theta = w \cdot h$ and $z = w \cdot x$

We compute the following gradients:

$$\frac{\partial J}{\partial \theta} = \frac{\partial J}{\partial z} \cdot \frac{\partial z}{\partial w} = \frac{\partial J}{\partial x}$$

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$$\frac{\partial J}{\partial \theta} = (y - \hat{y}) / (w \cdot h) = \frac{\partial J}{\partial z} \cdot \frac{\partial z}{\partial w}$$

$$\frac{\partial \theta}{\partial w} = h$$

$$\text{ReLU}(x) = \max(x, 0)$$

$$\frac{\partial \text{ReLU}(x)}{\partial x} = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases}$$

$$= \frac{\partial \text{ReLU}(x)}{\partial x} = \text{sgn}(\text{ReLU}(x))$$

$$\frac{\partial J}{\partial w} = (y - \hat{y}) \cdot h$$

$$\frac{\partial J}{\partial z} = \frac{\partial \text{ReLU}(z)}{\partial z} \cdot \text{sgn}(\text{ReLU}(z))$$

if it is correct.

$$\frac{\partial J}{\partial w} = \left(\frac{\partial J}{\partial \theta} \right) \left(\frac{\partial \theta}{\partial w} \right) = \frac{\partial J}{\partial x}$$

$$= (y - \hat{y}) / (w \cdot h) \cdot \text{sgn}(\text{ReLU}(w))$$

$$\frac{\partial J}{\partial w} = \frac{\partial J}{\partial \theta} \cdot \frac{\partial \theta}{\partial w} = \frac{\partial J}{\partial x} = (y - \hat{y}) / (w \cdot h) \cdot \text{sgn}(\text{ReLU}(w))$$