1) Calculating 
$$\nabla_{\mathbf{w}} \log \pi_{\mathbf{w}} (A_{\mathbf{t}} | \mathbf{s}_{\mathbf{t}})$$

Gradient w.r.t weights  $\Rightarrow s = h$ 

$$= h \begin{cases} -\rho (a_{\mathbf{j}} | \mathbf{s}_{\mathbf{t}}) - \rho (a_{\mathbf{j}} | \mathbf{s}_{\mathbf{t}}$$

$$\Rightarrow \nabla \omega \left[ \log \left( e^{\omega_{\text{st,at}}/\gamma} \right) - \log \left( \underbrace{z}_{a'} e^{\omega_{\text{st,at}}} \right) \right]$$

While w is a 4x4 motrix, we only have gredients through the specific row Crepresenting state st of our choosing). Therefore:

for some 
$$i$$
:

i)  $\nabla_{w_{st,i}} \log \left( e^{w_{s_t,at}} / \gamma \right) = \nabla_{w_{st,i}} \frac{w_{s_t,a_t}}{\gamma} = \begin{cases} 1/\gamma & i=a_t \\ 0 & i\neq a_t \end{cases}$ 

$$| O |_{i \neq a_{\xi}}$$

2) 
$$\pi_{k}(a|s) = \frac{1}{\sigma \sqrt{2\pi}} \times e^{-\frac{(a-ks)^{2}}{2\sigma^{2}}}$$

$$\log \pi_{k}(a|s) = \log \left(\frac{1}{\sigma \sqrt{2\pi}} \times e^{-\frac{(a-ks)^{2}}{2\sigma^{2}}}\right)$$

$$= \log \left(\frac{1}{6\sqrt{2\pi}}\right) - \left(a - k_s\right)^2$$

$$= 26^2$$

$$\sqrt{k} \log \pi k (als) = \frac{1}{26^2} \sqrt{k} (a - k_s)^2$$

$$\frac{\alpha - ks}{6^2}$$

2.1 Linear Policy

 $N(s) = ks \Rightarrow s = \begin{bmatrix} x-pes \\ velocity \end{bmatrix}$   $k = 2 \begin{bmatrix} k, \\ k_2 \end{bmatrix}$ Mean is a linear combination of features k, x pos + kzvelocity