

Lecture 3

1. Install ROS2
2. Download serta Install webots



3. Install webots ROS2 package dengan syntax “sudo apt -get install rosfoxy-webots-ros2” tunggu hingga proses selesai

```
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
E: Unable to locate package ros-foxy-webots-ros2
```

4. Saya tidak tahu mengapa unable locate, tetapi sudah mencoba mencari Solusi di chatgpt tetap tidak bisa menyelesaikan masalah saya. Karena itu saya tidak dapat melanjutkan pengerjaan.

The screenshot shows a YouTube video player. The video title is 'ROS 1 Services vs ROS 2 Services'. The video content is a comparison table between ROS 1 and ROS 2 services. The table has two columns: 'ROS 1 Services' and 'ROS 2 Services'. The video is part of the 'Webots ROS2 Tutorial Series'.

The screenshot shows a YouTube video player. The video title is 'Applications of publisher in ROS 2'. The video content shows a list of applications for publishers in ROS 2, such as 'To control the system real time', 'To inform system about updated environment', 'Internal communication of the system', 'To control the actuators position and velocity for their motion', 'To perform action in sequence', and 'To handle emergency stopping situation'. The video is part of the 'Webots ROS2 Tutorial Series'.

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