

ESC 407

Computational Methods in Engineering Science

Homework 6 Supplement

Pseudocode for Runge-Kutta Fehlberg

Maybe some text here?

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1: function RKF45( $\vec{f}$ , tspan:  $a$  and  $b$ ,  $y_0$ , tol,  $h_{\max}$ ,  $h_{\min}$ )
2:    $t_1 \leftarrow a$ 
3:    $y_1 \leftarrow y_0$                                 ▶ first row of the solution array is  $y_0$ 
4:    $h_1 \leftarrow h_{\max}$ 
5:   flag  $\leftarrow 1$                                 ▶ stop flag
6:    $i = 1$                                            ▶ initialize the array index
7:   while flag = 1 do
8:      $k_1 \leftarrow h_i f(t_i, y_i)$                 ▶ calculate all the  $k$ 's
9:      $k_2 \leftarrow h_i f(t_i + \frac{1}{4}h_i, y_i + \frac{1}{4}k_1)$ 
10:     $k_3 \leftarrow h_i f(t_i + \frac{3}{8}h_i, y_i + \frac{3}{32}k_1 + \frac{9}{32}k_2)$ 
11:     $k_4 \leftarrow h_i f(t_i + \frac{12}{13}h_i, y_i + \frac{1932}{2197}k_1 - \frac{7200}{2197}k_2 + \frac{7296}{2197}k_3)$ 
12:     $k_5 \leftarrow h_i f(t_i + h_i, y_i + \frac{439}{216}k_1 - 8k_2 + \frac{3680}{513}k_3 - \frac{845}{4104}k_4)$ 
13:     $k_6 \leftarrow h_i f(t_i + \frac{1}{2}h_i, y_i - \frac{8}{27}k_1 + 2k_2 - \frac{3544}{2565}k_3 + \frac{1859}{4104}k_4 - \frac{11}{40}k_5)$ 
14:     $e \leftarrow \min(|\frac{1}{h}[\frac{1}{360}k_1 - \frac{128}{4275}k_3 - \frac{2197}{75240}k_4 + \frac{1}{50}k_5 + \frac{2}{55}k_6]|)$  ▶ error between RK4 and RK5
15:    if  $e \leq \text{tol}$  then                            ▶ the error is acceptable
16:       $i \leftarrow i + 1$                                 ▶ increment the array index
17:       $h_i \leftarrow h_{i-1}$                             ▶ the step-size is unchanged
18:       $t_i \leftarrow t_{i-1} + h_i$                         ▶ the next time step
19:       $y_i \leftarrow y_{i-1} + \frac{25}{216}k_1 + \frac{1408}{2565}k_3 + \frac{2197}{4104}k_4 - \frac{1}{5}k_5$  ▶ the RK4 step
20:    end if
21:     $d \leftarrow 0.84 (\text{tol}/e)^{1/4}$                     ▶ compute the factor for scaling the step-size
22:    if  $d \leq 0.1$  then                                ▶ step-size change is too small
23:       $h_i \leftarrow 0.1h_i$ 
24:    else if  $d \geq 4$  then                            ▶ step-size change is too large
25:       $h_i \leftarrow 4h_i$ 
26:    else                                              ▶ step-size change is just right! 🐻
27:       $h_i = dh_i$ 
28:    end if
29:    if  $h_i > h_{\max}$  then                            ▶ if the new  $h$  is too large, set it to  $h_{\max}$ 
30:       $h_i \leftarrow h_{\max}$ 
31:    end if
32:    if  $t_i \geq b$  then
33:      flag = 0                                ▶ we've reached  $b$ , so we are done
34:    else if  $t_i + h_i > b$  then

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35:          $h_i = b - t_i$                                 ▶ if the next step goes past  $b$ , take next step exactly to  $b$ 
36:     else if  $h < h_{\min}$  then
37:         flag = 0                                          ▶ required step-size is too small so quit
38:         display minimum  $h$  exceeded
39:     end if
40: end while
41: end function
Output: solution array  $[y]$ , vector of solution times  $\vec{t}$ , vector of time steps  $\vec{h}$ 

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