

Appendix - B

$$ds^2 = 2A(u, v) du dv + g(u, v) h_{ij}(x^j) dx^i dx^j \quad (B.1)$$

This metric is assumed to satisfy Einstein's vacuum eqns. We introduced a shock wave by keeping (B.1) for $u < 0$ but replacing v by $v + f(x_i)$ for $u > 0$

$$ds^2 = 2A(u, v + \theta f) du (dv + \theta f_i dx^i) + g(u, v + \theta f) h_{ij} dx^i dx^j \quad (B.2)$$

where $\theta = \theta(u)$ is the usual step function. Changing to coordinates $(\hat{u}, \hat{v}, \hat{x}^i)$ defined by

$$\left. \begin{aligned} \hat{u} &= u \\ \hat{v} &= v + \theta f \\ \hat{x}^i &= x^i \end{aligned} \right\} \quad (B.3)$$

we ~~for~~ obtain

$$ds^2 = 2A(\hat{u}, \hat{v}) d\hat{u} (d\hat{v} - \delta(\hat{u}) f d\hat{u}) + g(\hat{u}, \hat{v}) h_{ij} d\hat{x}^i d\hat{x}^j \quad (B.4)$$

We note that the metric ds^2 given by (B.2) and (B.4) is in fact continuous, i.e. \exists coordinates $(\bar{u}, \bar{v}, \bar{x}^i)$ s.t. the metric coeff. are cont. A possible choice is ~~simply~~ given implicitly by

$$\begin{aligned} \hat{u} &= \bar{u} \\ \hat{v} &= \bar{v} + \theta \bar{f} - \frac{1}{2} \bar{u} \theta^2 \frac{\hat{A}}{\hat{g}} h^{mn} \bar{f}_{,m} \bar{f}_{,n} \\ \hat{x}^i &= \bar{x}^i - u \theta \frac{\hat{A}}{\hat{g}} h^{im} \bar{f}_{,m} \end{aligned} \quad (B.5)$$

where $\bar{f} = f(\bar{x}^i) ; \hat{g} = g(\hat{u}, \hat{v})$ (B.6)

$\hat{A} = A(\hat{u}, \hat{v}) ; h^{ij} = h^{ij}(\bar{x}^i)$

$$R_{\hat{u}\hat{i}} = - \frac{\hat{A}_{,v}}{\hat{A}} f_{,i} \delta$$

$$R_{\hat{v}\hat{i}} = 0$$

$$R_{\hat{i}\hat{j}} = R_{ij}^{(2)} - h_{ij} \left[\frac{\hat{g}_{,\hat{u}\hat{v}}}{\hat{A}} + \frac{\hat{g}_{\hat{u}\hat{v}}}{\hat{A}} f \delta \right]$$

(B.7)

Ignoring δ^2 terms we transform to (u, v, x^i) coordinates and insert the vacuum equations (obtained ~~from~~ by setting $f=0$) to get

$$R_{\hat{v}\hat{v}} = R_{vv} = 0$$

$$R_{vi} = R_{\hat{v}\hat{i}} = 0$$

$$R_{ij} = R_{\hat{i}\hat{j}} = - h_{ij} \frac{\hat{g}_{,\hat{u}\hat{v}}}{\hat{A}} f \delta$$

$$R_{vi} = R_{\hat{u}\hat{i}} + R_{\hat{u}\hat{v}} \theta f_{,i}$$

$$= f_{,i} \delta \left[- \frac{\hat{A}_{,v}}{\hat{A}} + \theta f \left(\frac{\hat{A}_{,v}^2}{\hat{A}^2} - \frac{\hat{A}_{,\hat{u}\hat{v}}}{\hat{A}} - \frac{\hat{g}_{,\hat{v}} \hat{A}_{,\hat{v}}}{\hat{g} \hat{A}} \right) \right]$$

(B.8)

The stress-energy tensor for a massless particle located at the origin $p=0$ of the (x^i) 2-surface and at $u=0$ is

$$T^{ab} = 4p\delta(p)\delta(u)\delta_v^a\delta_v^b \quad (B.9)$$

where p is the momentum of the particle. Thus, the only non-zero component is

$$T_{uv} = 4pA^2\delta(p)\delta(u) \quad (B.10)$$

Inserting (B.8) and (B.10) into the Einstein field equations, partially integrating the δ' term, noting that e.g. $\hat{A}_{,\hat{v}}(\hat{u}=0)$
 $\Leftrightarrow A_{,u}(u=0)=0$ yield eq.(5).

$$R_{uv} - \frac{1}{2}g_{uv}R = 8\pi\Theta T_{uv}$$

$$\Rightarrow \frac{\hat{A}}{\hat{g}} \Delta f \delta(u) + \frac{1}{4} \cancel{R} = 32\pi p A^2 \Theta \delta(p)\delta(u) \quad \boxed{A_{,u}(u=0) = A_{,v}(u=0) = g_{,u}(u=0) = g_{,v}(u=0)}$$

$$\Rightarrow -\frac{2\hat{g}_{,uv}}{\hat{g}} f \delta(u) - \frac{\hat{g}_{,v}}{\hat{g}} f \delta'$$

$$\Rightarrow \frac{\hat{A}}{\hat{g}} \Delta f - \frac{2\hat{g}_{,uv}}{\hat{g}} f = 32\pi p A^2 \Theta \delta(p)$$