Lecture11_Approximation

1.introduction

Getting around NP-Completeness

- ☐ If N is small, even O(2N) is acceptable
- □ Solve some important **special cases** in polynomial time (加一些限制)
- ☐ Find **near-optimal** solutions in polynomial time
- ——approximation algorithm (和最优算法进行比较)

Approximation Ratio

definition:

[Definition] An algorithm has an *approximation ratio* of $\rho(n)$ if, for any input of size n, the cost C of the solution produced by the algorithm is within a factor of $\rho(n)$ of the cost C^* of an optimal solution:

 $\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n)$

If an algorithm achieves an approximation ratio of ρ (n), we call it a ρ (n)-approximation algorithm.

C*: min cost

approximation scheme

definition

[Definition] An *approximation scheme* for an optimization problem is an approximation algorithm that takes as input not only an instance of the problem, but also a value $\varepsilon > 0$ such that for any fixed ε , the scheme is a $(1+\varepsilon)$ -approximation algorithm.

We say that an approximation scheme is a *polynomial-time* approximation scheme (*PTAS*) if for any fixed $\varepsilon > 0$, the scheme runs in time polynomial in the size n of its input instance.

$$O(n^{2/\varepsilon})$$
 $O((1/\varepsilon)^2 n^3)$

 $O((1/\varepsilon)^2 n^3)$: fully polynomial-time approximation scheme

(FPTAS) 因为 1/e 和 n 都是线性的

2.bin packing

Given N items of sizes $S_1, S_2, ..., S_N$, such that $0 < S_i \le 1$ for all $1 \le i \le N$. Pack these items in the fewest number of bins, each of which has unit capacity.

NP Hard !!!

can we pack them? NPC

next fit

```
void NextFit ( )
{    read item1;
    while ( read item2 ) {
        if ( item2 can be packed in the same bin as item1 )
    place item2 in the bin;
        else
    create a new bin for item2;
        item1 = item2;
    } /* end-while */
}
```

Let M be the optimal number of bins required to pack a list I of items. Then next fit never uses more than 2M-1 bins. (There exist sequences such that next fit uses 2M-1 bins.) 严格的上界

说明, p(n) = 2;

证明:

A simple proof for Next Fit:

第一步,假设

If Next Fit generates 2M (or 2M+1) bins, then the optimal solution must generate at least M+1 bins.

Let $S(B_i)$ be the size of the *i*th bin. Then we must have:

$$S(B_1) + S(B_2) > 1$$
 第二步,根据假设推论 最优解相邻两个bin 不可以加在一起 $\sum_{i=1}^{2M} S(B_i) > M$ 第三步,可以推出,size之和 > M 也就是 > = M + 1 也就是说至少需要 M + 1 个bin. 矛盾 $\bigcup_{i=1}^{2M} S(B_i) > M$

The optimal solution needs at least [total size of all the items / 1] bins

first fit

```
void FirstFit ( )
{    while ( read item ) {
        scan for the first bin that is large enough for item;
        if ( found )
    place item in that bin;
        else
    create a new bin for item;
    } /* end-while */
}
```

O(N log N)

Then first fit never uses more than 17M / 10 bins. ratio =1.7

best fit

Place a new item in the **tightest**(放入东西后 剩余空间最小) spot among all bins.

O(N log N)bin no. <= 1.7M ratio =1.7

eg1:最优解显然是3

eg2:竖着看, 最优解是6, 但是next fit, first fit, best fit 结果都是10

[Example]
$$S_i = \frac{1}{7} + \varepsilon$$
, $\frac{1}{7} + \varepsilon$, $\frac{1}{3} + \varepsilon$, $\frac{1}{2} + \varepsilon$, $\frac{1$

online algorithm

Place an item before processing the next one, and can **NOT change decision**.

You never know when the input might end. No on-line algorithm can always give an optimal solution.

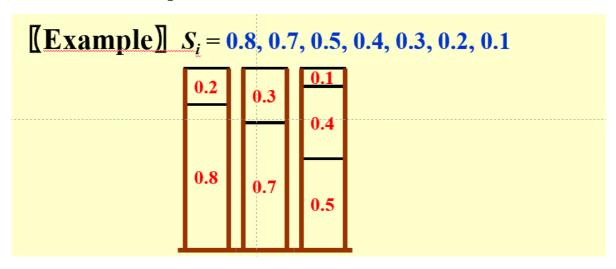
Theorem There are inputs that force any on-line bin-packing algorithm to use at least **5/3** the optimal number of bins.

off - line algorithms

View the entire item list before producing an answer.

Trouble-maker: The large items

Solution: Sort the items into non-increasing sequence of sizes. Then apply first (or best) fit – first (or best) fit decreasing.



[Theorem] Let M be the optimal number of bins required to pack a list I of items. Then first fit decreasing never uses more than 11M / 9 + 6/9 bins. There exist sequences such that first fit decreasing uses 11M / 9 + 6/9 bins.

3. The Knapsack Problem — fractional version

背包问题

A knapsack with a capacity M is to be packed. Given N items. Each item i has a weight w_i and a profit p_i . If x_i is the percentage of the item i being packed, then the packed profit will be $p_i x_i$.

An optimal packing is a feasible one with maximum profit. That is, we are supposed to find the values of x_i such that $\sum_{i=1}^{n} p_i x_i$ obtains its maximum under the constrains

$$\sum_{i=1}^{n} w_i x_i \le M \quad \text{and} \quad x_i \in [0,1] \quad \text{for} \quad 1 \le i \le n$$

Q: what must we do in each stage?

A: Pack one item into the knapsack.

Q: On which criterion shall we be greedy?

A: maximum profit density pi / wi

过程: 计算所有item 的 density 尽可能选择最大的

The Knapsack Problem — 0-1 version

take it or not take

$$ightharpoonup P_{\text{opt}} / P_{\text{greedy}} \le 1 + p_{max} / P_{\text{greedy}} \le 2$$

A Dynamic Programming Solution

考虑三个部分: subset profit weight

$W_{i,p}$ = the minimum weight of a collection from $\{1, ..., i\}$ with total profit being exactly p

① take
$$i: W_{i,p} = w_i + W_{i-1,p-p_i}$$

② skip
$$i: W_{i,p} = W_{i-1,p}$$

③ impossible to get
$$p: W_{i,p} = \infty$$

$$W_{i,p} = \begin{cases} \infty & i = 0 \\ W_{i-1,p} & p_{i} > p \\ \min\{W_{i-1,p}, w_{i} + W_{i-1,p-p_{i}}\} & otherwise \end{cases}$$

$$i = 1, ..., n; p = 1, ..., n p_{max} \longrightarrow O(n^{2}p_{max})$$

worst case 每一个p = p max

不是polynomial time,因为 p max不是定值 而是指数级的O(2^sizeof(pmax))

what if p max is LARGE?

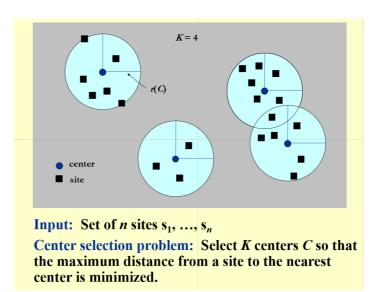
Item	Profit	Weight	Item	Profit	Weight	
1	134,221	1	1	2	1	
2	656,342	2	2	7	2	
3	1,810,013	5	3	19	5	
4	22,217,800	6	4	223	6	
5	28,343,199	7	5	284	7	
	M = 11			M = 11		

统一缩小,减小数据范围

Round all profit values up to lie in smaller range!

(1+
$$\varepsilon$$
) $P_{al\sigma} \le P$ for any feasible solution P

4.K-center problem



补充定义:

```
✓ \operatorname{dist}(x, x) = 0 (identity)

✓ \operatorname{dist}(x, y) = \operatorname{dist}(y, x) (symmetry)

✓ \operatorname{dist}(x, y) \le \operatorname{dist}(x, z) + \operatorname{dist}(z, y) (triangle inequality)

\operatorname{dist}(s_i, C) = \min_{c \in C} \operatorname{dist}(s_i, c)

= \operatorname{distance} \operatorname{from} s_i \operatorname{to} \operatorname{the} \operatorname{closest} \operatorname{center}

r(C) = \max_i \operatorname{dist}(s_i, C) = \operatorname{smallest} \operatorname{covering} \operatorname{radius}
```

number of candidate centers are infinite

A Greedy Solution

Put the first center at the **best possible location** for a single center, and then keep adding centers so as to **reduce the covering radius** each time by as much as possible.



第二个点怎么放?应该左右各一个center合适,这个算法有问题



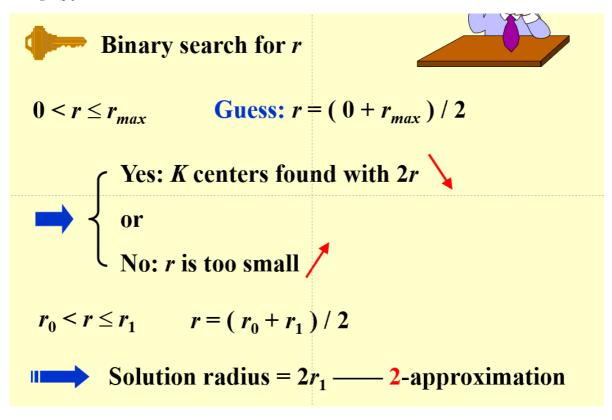
A Greedy method try again

如果已知 r(C*)

```
Centers Greedy-2r ( Sites S[ ], int n, int K, double r )
{    Sites S'[ ] = S[ ]; /* S' is the set of the remaining sites */
    Centers C[ ] = D;
    while ( S'[ ] != D ) {
        Select any s from S' and add it to C;
        Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from S' that are at dist(s', s) Delete all s' from
```

[Theorem] Suppose the algorithm selects more than K centers. Then for any set C* of size at most K, the covering radius is $r(C^*) > r$.

怎么找r?



```
Centers Greedy-Kcenter ( Sites S[], int n, int K )
{    Centers C[] = □;
    Select any s from S and add it to C;
    while ( |C| < K ) {
        Select s from S with maximum dist(s, C);
        Add s it to C;
    } /* end-while */
    return C;
}</pre>
```

[Theorem] The algorithm returns a set C of K centers such that $r(C) \le 2r(C *)$ where C* is an optimal set of K centers.

Theorem 1 Unless P = NP, there is **no** ρ -approximation for center-selection problem for any $\rho < 2$.

总结:

Three aspects to be considered:

A: Optimality -- quality of a solution

B: Efficiency -- cost of computations

C: All instances

Researchers are working on

A+C: Exact algorithms for all instances

A+B: Exact and fast algorithms for special cases

B+C: Approximation algorithms

Even if P=NP, still we cannot guarantee A+B+C.