33 人赞同了该回答

Axiomatically, a parameterized smooth curve is delineated by an arc coordinate, "s" of "t" as follows:

Definition $\mathbf{I}: s(t) =: \int_{t_0}^t \left| \vec{r}'(t) \right| dt$, in which $\vec{r}(t)$ acts as a ritually defined position vector of any specific point on the curve, naturally $m{t}_0$ is a constant for gauging the arc coordinate.

Then
$$s'(t) = \left| ec{r}'(t) \right|$$

The pertinent propositions about curvature of interest can be viscerally obtained via vector calculus, which I think is the best way to give a curvature at any given point non-singular and of course, not reposing on the boundaris.

 ${f Definition}$ ${f II}$: The curvature $\,\kappa(t)=:\left|rac{dec{ au}(t)}{ds}
ight|\,$, in which $\,ec{ au}(t)\,$ represents the <code>unit vector</code> tangent to the curve at the point t.

It happens to come in line with the "ubiquitous" definitions in general textbooks as $\left|\frac{d\theta}{ds}\right|$.

Now just sit and watch some slick gimmicks manipulating Def 1 and 2.

Obviously,
$$\kappa(t) = \frac{|d\vec{ au}(t)|}{ds} = \frac{\frac{|d\vec{ au}(t)|}{dt}}{\frac{ds}{dt}}$$
, in which $\frac{ds}{dt} = s'(t) = \left|\vec{r}'(t)\right|$, and $\vec{r}'(t) = \left|\vec{r}'(t)\right|\vec{ au}(t)$ holds for nothing seductive.

Now we can easily derive something useful.

Lemma I: We have $\vec{\tau}(t) \cdot \vec{\tau}'(t) = 0$.

 $\mathbf{Proof}: ext{We have } \vec{ au}(t) \cdot \vec{ au}(t) = |\vec{ au}(t)|^2 = 1$, as $\vec{ au}(t)$ is a unit vector.

Then we take the derivative from both sides, there exists $2 \vec{ au}(t) \cdot \vec{ au}'(t) = 0$.

Lemma 1 predicates $ec{ au}(t)$ is perpendicular to $ec{ au}'(t)$.

Lemma II &Proof: We can obtain
$$\vec{r}''(t) = \frac{d}{dt} \left[|\vec{r}'(t)| \vec{\tau}(t) \right] = \frac{d|\vec{r}'(t)|}{dt} \vec{\tau}(t) + |\vec{r}'(t)| \vec{\tau}'(t)$$
, now take the cross product using the vector $\vec{r}'(t)$ from both sides^Q, we have

 $ec{r}'(t) imesec{r}''(t)=\leftertec{r}'(t)
ightert^2ec{ au}(t) imesec{ au}'(t)$,

now take the magnitude from both sides and note that the unit vector
$$ec{ au}(t)$$
 is perpendicular to $ec{ au}'(t)$, obtaining a compact gadget, $\left|ec{r}'(t) imesec{r}''(t)
ight|=\left|ec{r}'(t)
ight|^2\left|rac{dec{ au}(t)}{dt}
ight|$. 单位向量长度为1

Now let's flit back to the original problem. We shall instantaneously give

$$\mathbf{Proposition\ \&Proof}\ :\ \kappa(t) = rac{|dec{ au}(t)|}{ds} = rac{rac{|d au(t)|}{dt}}{rac{ds}{dt}} = rac{\left|ec{oldsymbol{r}'}(t) imesec{oldsymbol{r}''}(t)
ight|}{\left|ec{oldsymbol{r}'}(t)
ight|^3}$$
 ,

which is **exactly** what we are seeking for.

From *Prop* we can derive all forms of curvature from a hodgepodge of cumbersome derivation methods.

Tentatively, for simplicity I will show how some "domestic" conclusions stand using some results descended from *Prop*, and show you the impeccability and potency of the method.

We single out x for parameterizing the curve y = f(x)

Here exists
$$ec{r}(x)=inom{x}{y}$$
 , $ec{r}'(x)=inom{1}{y'}$, $ec{r}''(x)=inom{0}{y''}$

plug them all in *Prop*, we have

$$\left| \left(egin{array}{c} 1 \ y' \end{array}
ight) imes \left(egin{array}{c} 0 \ y'' \end{array}
ight)
ight| = \left| y''
ight| \; , \; \left| ec{r}'(x)
ight|^3 = \left(\sqrt{1 + y'^2}
ight)^3$$

yielding
$$\kappa(x)=rac{|y'|}{(1+y'^2)^{rac{3}{2}}}$$

$$ec{r} = ec{r}(heta) = egin{pmatrix} r\cos heta \ r\sin heta \end{pmatrix}$$
 , $ec{r}'(heta) = egin{pmatrix} r'\cos heta - r\sin heta \ r'\sin heta + r\cos heta \end{pmatrix}$, $ec{r}''(heta) = egin{pmatrix} r''\cos heta - 2r'\sin heta - r\cos heta \end{pmatrix}$,

$$ec{r}''(heta) = egin{pmatrix} r''\cos heta - 2r'\sin heta - r\cos heta \ r''\sin heta + 2r'\cos heta - r\sin heta \end{pmatrix} \; .$$

$$|r^2+2r'^2-rr''|$$

$$\left|ec{r}'(heta)
ight|^3 = \left(\sqrt{(r'\cos heta-r\sin heta)^2+(r'\sin heta+r\cos heta)^2}
ight)^3 = \left(r^2+r'^2
ight)^{rac{3}{2}}$$
 ,

yielding
$$\kappa(heta) = rac{ig|r^2 + 2r'^2 - rr''ig|}{ig(r^2 + r'^2ig)^{rac{3}{2}}}$$
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