Part II

Mechanistic Models of cortical circuits

From spiking neurons to firing rate equations (2 lectures, Laureline Logiaco)

Inhibition stabilized networks and supralinear stabilized networks (Mario Dipoppa)

Neural variability in rate models; The choice of spiking vs. rate modeling (Mario Dipoppa)

Hopfield's memory network model and its equilibrium theory (Alessandro Ingrosso)

Chaotic rate networks studied with dynamic mean field theory (Alessandro Ingrosso)

Empirical vs. mechanistic modeling

Empirical models

Mechanistic models

Use a very flexible model that is empirically adjusted to observed data.

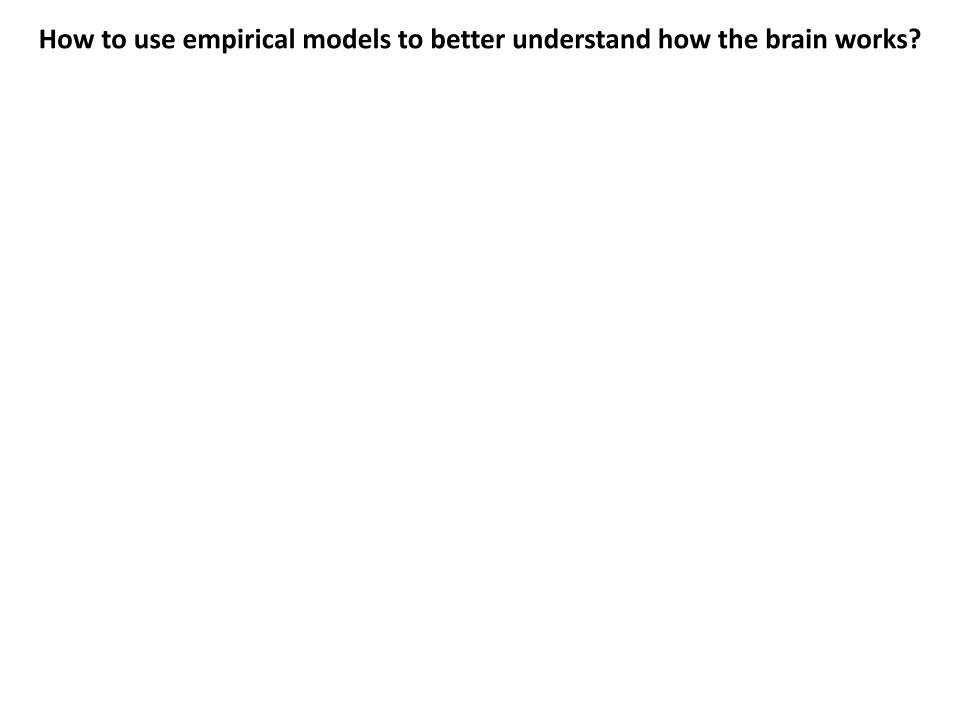
Use (bio)physically defined components.

Constrain the interactions between components (using data or making assumptions).

The behavior of the system mainly emerges due to the specific model constraints.

Part I of the class: empirical modeling

How to use empirical models to better understand how the brain works?



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- tear appart the processing of one area from the one of upstream areas

vs.

variable
$$\longrightarrow$$
 brain \longrightarrow \longrightarrow fitted activity

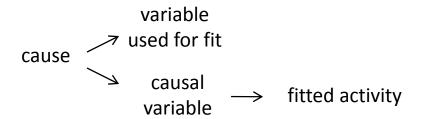
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• correlation vs. causation

VS.



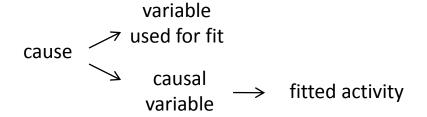
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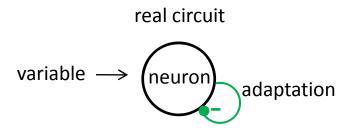
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correlation vs. causation

VS.



• effective modeling rather than explicit link to specific neuronal embodied objects; predictions?



variable → neuron + neuron

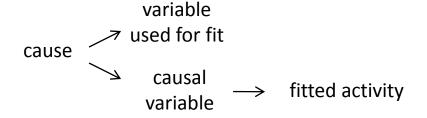
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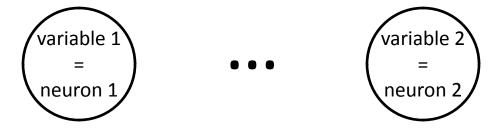
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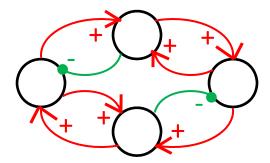
complex fitted model can be hard to understand

Alternative to empirical modeling: mechanistic modeling

1) Define model variables as biophysically defined components, e.g. neurons:



2) Define the interactions between components (using insights from data if possible)



3) Analyze, or predict, or observe through simulations, the connected system's behavior; compare to reality

Why mechanistic models?

• Pros:

Mapping between the world and model components made explicit at some level of description (often, individual neurons or populations of neurons)

Attempts to explain the function of the whole system through interactions between model components

When successful, brings both an understanding of the function and predictions

Cons:

Model often built with missing information (e.g. need to make assumptions about the connectivity)

No automatic « recipe » to make the model resemble the data at the system level

No automatic « recipe » to build intuition about emerging function in a complex system

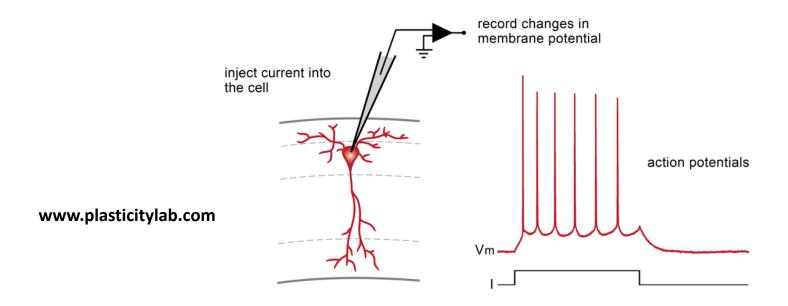
Difficulty choosing the right level of description (brain area, neuronal population, single neuron, ion channel)

Difficulty choosing what to model and what to leave out

How to choose a good single neuron model?

Map the input-output (spike times)

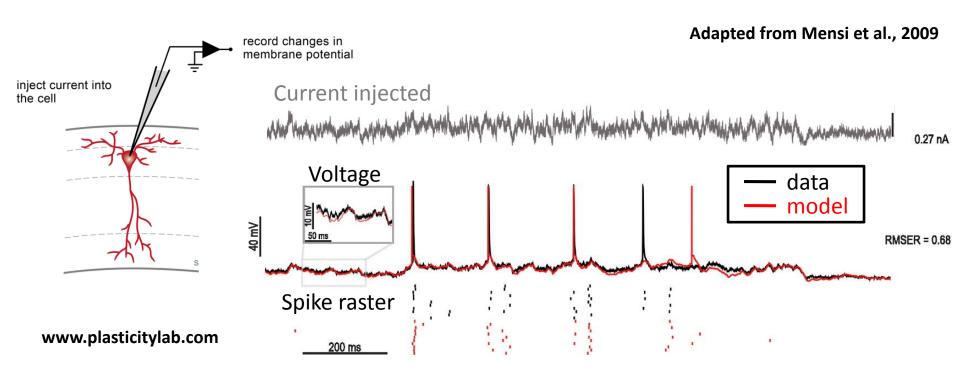
In a (silent) slice:



How to choose a good single neuron model?

Map the input-output (spike times)

Single neurons show reliable spiking patterns in response to in-vivo like fluctuating currents



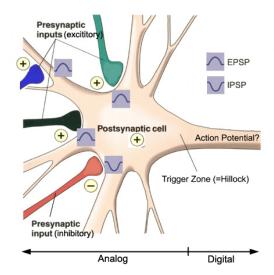
~80% of spikes predicted with 4 ms precision

Modeling the input-output function of neuron i:

$$\underbrace{p(spike)}_{dt} \lambda_i(t) = \lambda_o \exp(X_{syn,i}(t) + \eta * S_i(t))$$

Where: 1. $X_{syn,i}(t)$ is the synaptic input filtered by the neuron's membrane

$$X_{syn,i}(t) = \sum_{exc.inputs} EPSP + \sum_{inh.inputs} IPSP$$

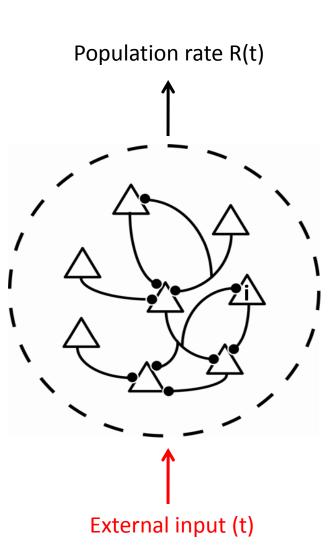


2. η is a spike-history filter with long timescales $S_i = \sum_t \delta \Big(t - t_{spike,\,i} \Big) \quad \text{is the spike train}$

$$\begin{array}{c|c} (t) & t_1 & t_2 \\ \hline & t_1 & t_2 \\ \hline \end{array}$$

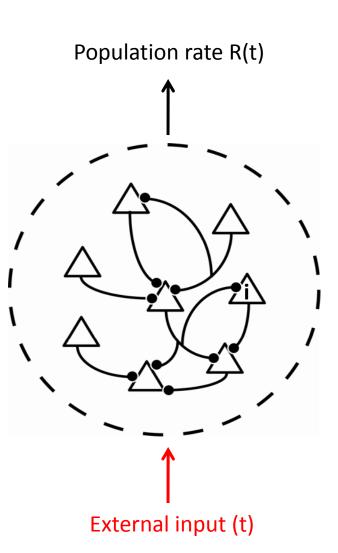
Model for single neuron i:

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Description of interactions between neurons = Description of correlations between different $X_{syn,i}(t)$

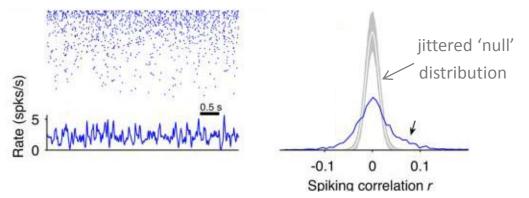
Population rate R(t) External input (t)

Model for single neuron i:

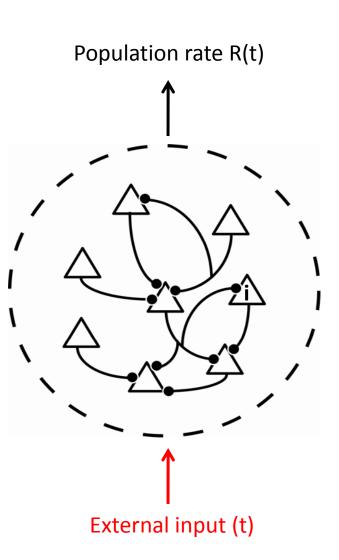
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Description of interactions between neurons = Description of correlations between different $X_{syn,i}(t)$

Raster of different neurons in rat's cortex in vivo



=> approximatively independent spike trains within a network.
Plausible causes: sparse connections and/or strong E-I balance
Renart et al, 2010

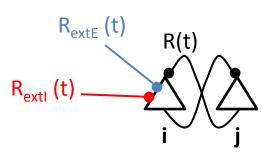


Model for single neuron i:

$$\lambda_i(t) = \lambda_o \exp(X_{syn,i}(t) + \eta * S_i(t))$$

We want to compute: $E_{neurons}[\lambda_i(t)] = R(t)$

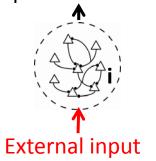
assuming uncorrelatedness between synaptic inputs.



$$X_{syn,i}(t) = \sum_{g} \sum_{j \to i \in g} \sum_{spikes \ neuron \ j: s_j} \kappa_g * \delta(t - t_j)$$

WHITE BOARD TIME!

Population rate R(t)



Model for single neuron i:

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assuming uncorrelatedness between synaptic inputs.

Steps:

-computing the input's mean and variance across the population

-separating the contribution of the input variability and of the intrinsic variability given a fixed input

-approximating the history dependence of the intrinsic variability through past escape rates (~Poisson)

-expressing the adaptation effect as a linear and a non-linear contribution in response to different inputs

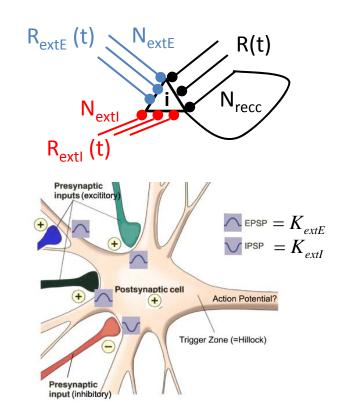
-neglecting the variance of the nonlinear adaptation effect when averaging the rate over different inputs

GLM:
$$\rho_i(t) = \lambda_o \exp(X_{syn,i}(t) + \eta * S_i(t))$$

Assume different neurons receive i.i.d. $X_{syn,i}(t)$

$$R(t) = E_{neurons i} \left[\rho_i(t) \right] \approx \lambda_0 \exp \left(\mu_Z(t) + \left(\frac{\sigma_Z^2(t)}{2} \right) \right)$$

Z: « effective drive», Gaussian variable related to X but approximately accounting for adaptation

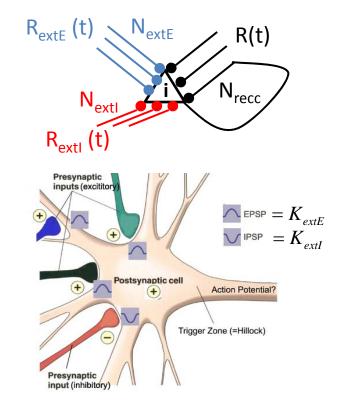


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MEAN DRIVE:
$$\mu_{Z} \approx E_{neurons\ i} \left[X_{syn,i}(t) + \eta * S_{i}(t) \right]$$

$$= N_{extE} K_{extE} * R_{extE} + N_{extI} K_{extI} * R_{extI} + N_{recc} K_{recc} * R + \tilde{\eta} * R$$
VARIANCE DRIVE:
$$\sigma_{Z}^{2} = N_{recc} \Lambda_{recc}^{2} * R + N_{extE} \Lambda_{extE}^{2} * R_{extE} + N_{extI} \Lambda_{extI}^{2} * R_{extI}$$
with $\forall s, \Lambda^{2}(s) = \left(K(s) + \tilde{\eta} * \Gamma_{R} * K(s)\right)^{2}$

How successful is this approach, compared to 'naive' approximations?

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Sources of errors beyond single-neuron stochasticity:

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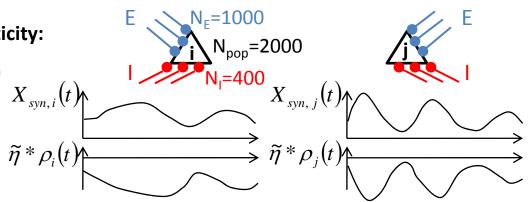


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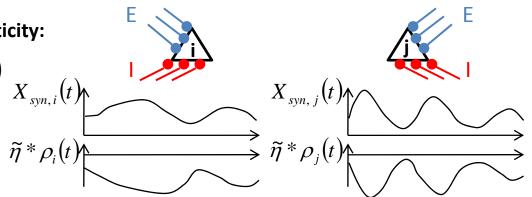


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Steady state: fluctuations due to finite, i.i.d. input

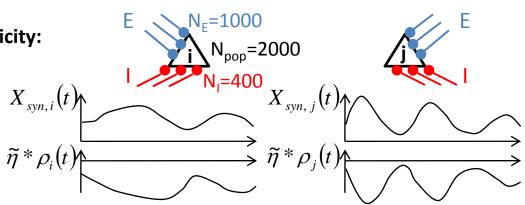
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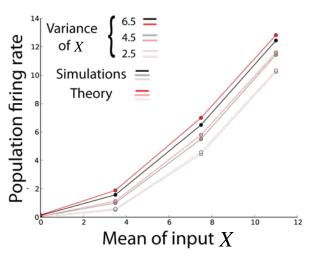
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Steady state: fluctuations due to finite, i.i.d. input

FULL THEORY

Lin. Approx. for var. of $\tilde{\eta} * \rho_i(t)$



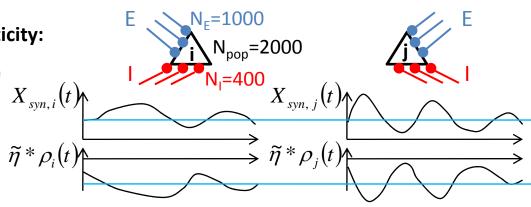
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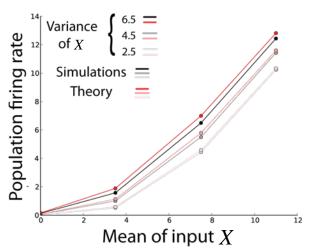
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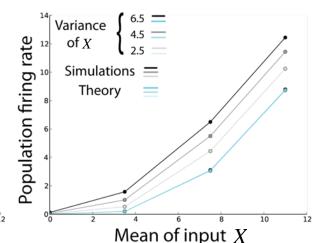
FULL THEORY

MEAN DRIVEN: neglect all variability

 $R(t) = \lambda_o \exp(E|X_{svn}(t)| + \widetilde{\eta} * R(t))$

Lin. Approx. for var. of $\tilde{\eta} * \rho_i(t)$





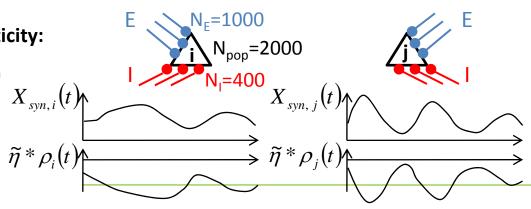
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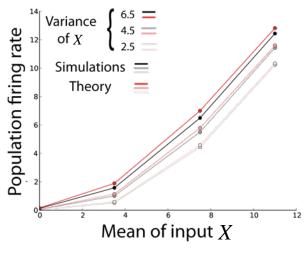
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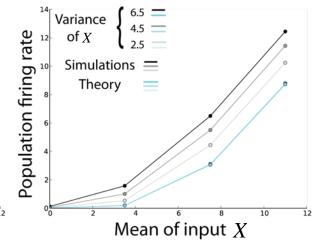
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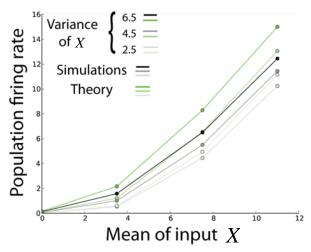
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$$R(t) = \lambda_o \exp(E[X_{syn}(t)] + \widetilde{\eta} * R(t))$$



Neglect adaptation variability

$$R(t) = \lambda_o \exp \left(E \left[X_{syn}(t) \right] + \frac{\operatorname{var} \left[X_{syn}(t) \right]}{2} + \widetilde{\eta} * R(t) \right)$$



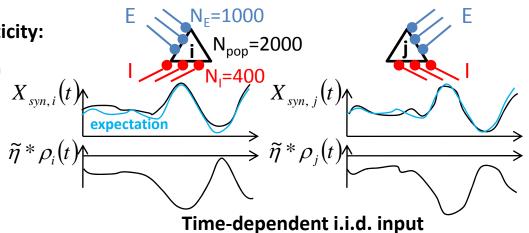


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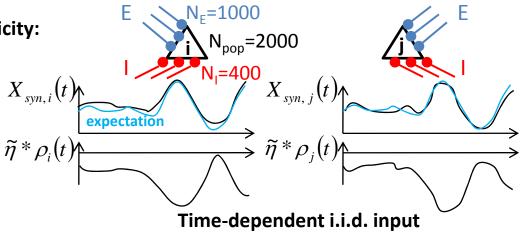


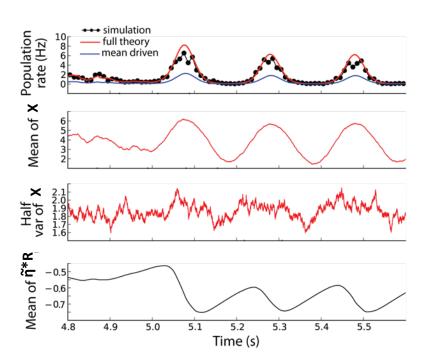
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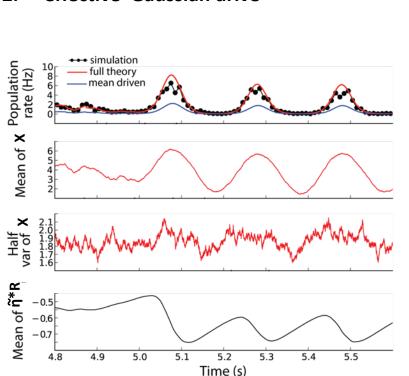
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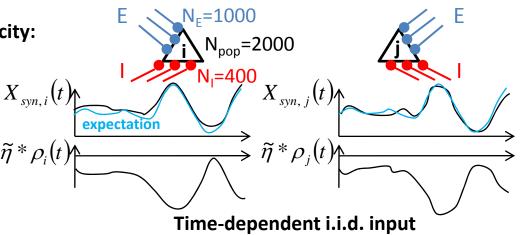
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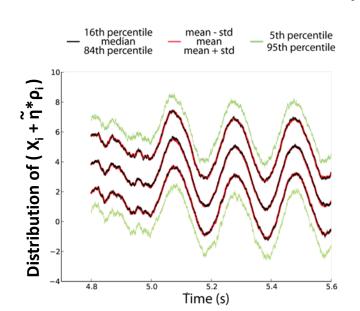
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Z: « effective Gaussian drive»





Gaussian distribution of instant drive in pop.





How successful is this approach, compared to 'naive' approximations?

Error from approx. of single-neuron stochasticity (S_i varies for fixed input):

Difference between:

$$\rho_i(t) = \lambda_o \exp \left(X_{syn}(t) + \eta * S_i(t) \right)$$

and the first order approximation:

$$\rho_i(t) \approx \lambda_o \exp \left(X_{syn}(t) + \widetilde{\eta} * \rho_i(t) \right)$$



How successful is this approach, compared to 'naive' approximations?

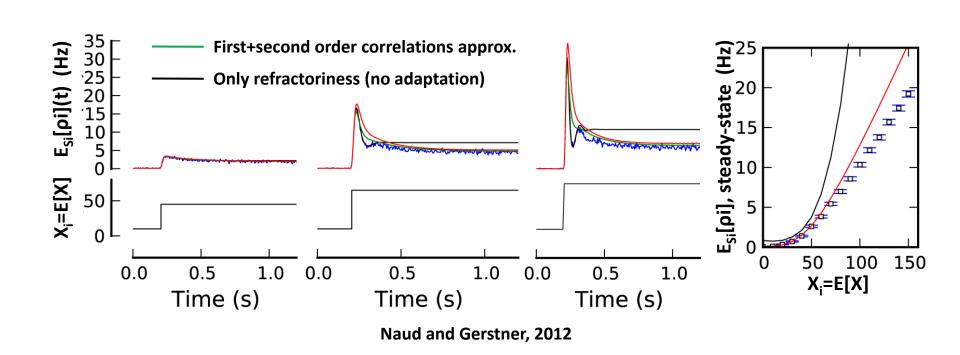
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How successful is this approach? Effect of all approximations:

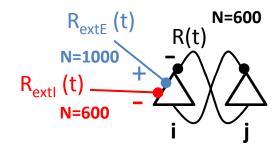
-Intrinsic stochasticity effects approximated through rate history
-variance of adaptation variable approximated through linear dependence on input variance
-Uncorrelated Poisson approximation for the recurrent input

Simulating a recurrent spiking inhibitory neurons network:

$$\rho_i(t) = \lambda_o \exp \left(X_{syn,i}(t) + \eta * S_i(t) \right)$$

$$R(t) = E[\rho_i(t)] \approx \lambda_o \exp\left(\mu_Z(t) + \left(\frac{\sigma_Z^2(t)}{2}\right)\right)$$

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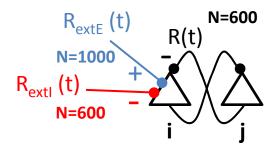
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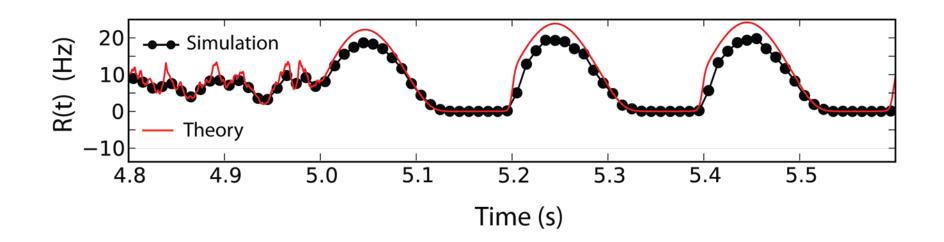
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Reduction to non-linear differential equations:

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$$\mu_{Z}(t) + \left(\frac{\sigma_{Z}^{2}(t)}{2}\right) \approx \sum_{g} \sum_{j=1}^{n_{g}} \left(\Lambda_{g,j} * R_{g}\right) \left(t\right) = \sum_{g} \sum_{j=1}^{n_{g}} V_{g,j}(t) \text{ where } \Lambda_{g,j}(s) = A_{g,j} \exp\left(-\frac{s}{\tau_{g,j}}\right) \Theta(s)$$

Exact when: $\tilde{\eta}(s) = A_0 \exp\left(-\frac{s}{\tau_{\eta}}\right) \Theta(s)$, becomes more accurate with larger n_g



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$$\frac{dV_{g,j}}{dt} = -\frac{V_{g,j}}{\tau_{g,j}} + A_{g,j} R_g \Rightarrow \frac{dV_{recc,j}}{dt} = -\frac{V_{recc,j}}{\tau_{recc,j}} + A_{recc,j} \lambda_0 \exp\left(V_{recc,j} + \sum_{g \neq recc} \sum_{j=1}^{n_g} V_{g,j}\right)$$

For several recurrently coupled populations, set of coupled non-linear differential equations.

Extensions?

More heterogeneities (distribution of input rates/weights,...) or correlations as long as the effective drive stays ~ Gaussianly distributed among neurons

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More heterogeneities (distribution of input rates/weights,...) or correlations as long as the effective drive stays ~ Gaussianly distributed among neurons

$$R(t) = E_{neurons i} \left[\rho_i(t) \right] \approx \lambda_0 \exp \left(\mu_Z(t) + \left(\frac{\sigma_Z^2(t)}{2} \right) \right)$$

Just need to compute:

$$\sigma_Z^2(t) = \operatorname{var}\left(\sum_{g} \sum_{j \in g} \left(K_{g,j} + \tilde{\eta} * \Gamma_{R_b} * K_{g,j}\right) * S_j\right)$$

1) Include spatiotemporal correlations

2) Use the law of total variance to account for the different sources of heterogeneities

Potential difficulties if/when needing self-consistency

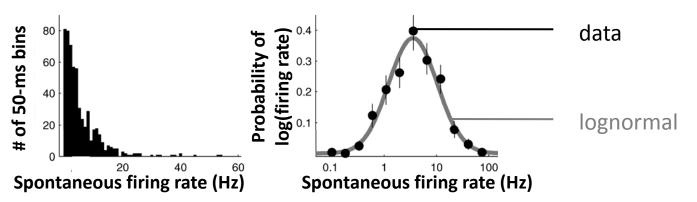
Population-level predictions/validations:

$$R = E[r_i], \quad r_i \propto \exp(Z)$$
 Z: Gaussian $R(t) \propto \exp\left(\mu_Z(t) + \left(\frac{\sigma_Z^2(t)}{2}\right)\right)$

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1) Log-normal distribution of instantaneous rates



Hromádka et al, 2008

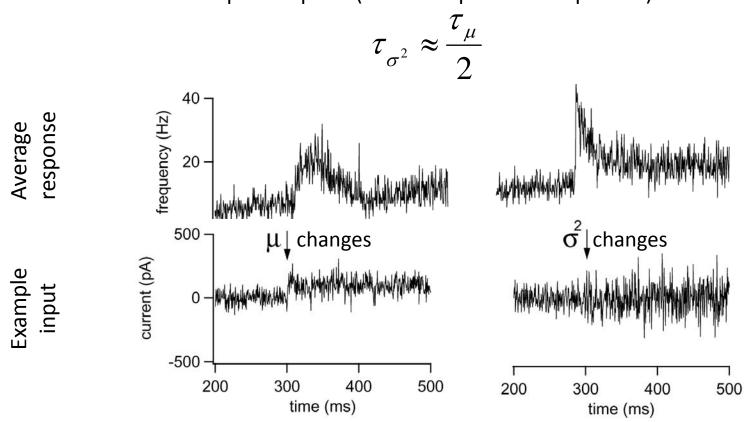
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2) Response to change in variance vs. mean of population input

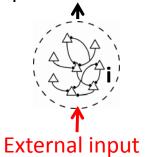
Silderberg et al, 2004

Response speed (both to input and adaptation):



Population equations from different single neuron models: e.g. integrate-and-fire

Population rate R(t)



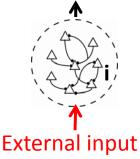
Membrane potential u_i pulled towards resting by $f(u_i)$. Input depolarizes neuron towards threshold Θ_{reset} .

$$\tau_{m} \frac{d}{dt} u_{i} = f(u_{i}) + R I_{i}(t) \quad \text{for} \quad u_{i} < \theta_{\text{reset}}$$

$$\lim_{N \to \infty} \left\{ \frac{\text{neurons with } u_{0} < u_{i}(t) \le u_{0} + \Delta u}{N} \right\} = \int_{u_{0}}^{u_{0} + \Delta u} p(u, t) du$$

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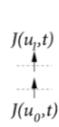
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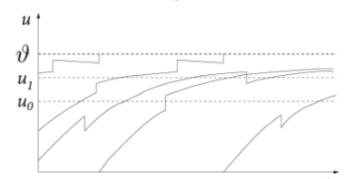
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$$\frac{\partial}{\partial t} \int_{u_0}^{u_1} p(u',t) \ \mathrm{d}u' = J(u_0,t) - J(u_1,t)$$

$$\frac{\partial}{\partial t} p(u,t) = -\frac{\partial}{\partial u} J(u,t) \quad \text{for } u \neq u_r \text{ and } u \neq \theta_{\text{reset}}$$

$$R_{\cdot}(t) = J(\theta_{\text{reset}}, t)$$

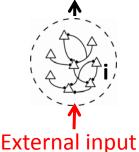




Neuronal dynamics, Gerstner 2014 L. F. Abbott and C. van Vreeswijk, 1993 N. Brunel and V. Hakim, 1999

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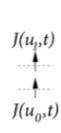
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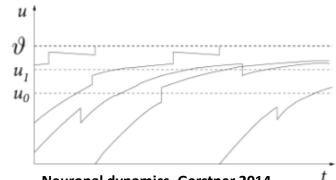
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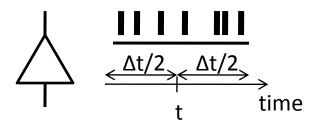
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Rate as a time-average for each single neuron: if very slow dynamics or ergodic system



$$R(t) = N_{spikes} / \Delta t$$

Ostojic, 2014