

# Competitive Programmer's CodeBook

MIST\_EaglesExpr

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# 1 Useful Tips

**Big Integer C++** `_int128_t`

**C++ FastIO**

```
ios::sync_with_stdio(false); cin.tie(nullptr);
```

**Python FastIO**

```
import sys;
input = sys.stdin.readline
```

**Input From File**

```
freopen("input.txt", "r", stdin);
```

**Python Array Input**

```
list(map(int, input().split()))
```

**Vim Setup**

```
"install xclip, vim-gtk3
set nocp ai bs=2 hls ic is lbr ls
  =2 mouse=a nu ru sc scs smd so
  =3 sw=4 ts=4
filetype plugin indent on
syn on
map gA m'ggVG"+y'

inoremap {<CR> {<CR><Esc>ko
inoremap [<CR> [<CR><Esc>ko
inoremap (<CR> (<CR><Esc>ko
autocmd FileType cpp map <F9> :w<
  CR> :!clear; g++ % -DONPC -o
  %:r && ./%:r<CR>
nnoremap = gg=G
```

# 2 Formula

## 2.1 Area Formula

**Rectangle**  $Area = length * width$

**Square**  $Area = Side * Side$

**Triangle**  $Area = \frac{1}{2} * length * width$

**Circle**  $Area = \pi * radius^2$

**Parallelogram**  $Area = base * height$

**Pyramid Base**  $Area = \frac{1}{2} * base * slantHeight$

**Polygon**

- a  $Area = \frac{1}{2} | \sum_{n=1}^{n-1} (x_i y_{i+1}) |$
- b  $Area = a + \frac{b}{2} - 1$  (for int coordinates).  
Here  $a$  = int points inside polygon and  
 $b$  = int points outside polygon.

## 2.2 Perimeter Formulas

**Rectangle**  $Perimeter = 2 * (length + width)$

**Square**  $Perimeter = 4 * side$

**Triangle**  $Perimeter = 4 * side$

**Circle**  $Perimeter = 2 * \pi * radius$

## 2.3 Volume Formula

**Cube**  $Volume = side^3$

**Rect Prism**  $Volume = length * width * height$

**Cylinder**  $Volume = \pi * radius^2 * height$

**Sphere**  $Volume = \frac{4}{3} * \pi * radius^3$

**Pyramid**  $Volume = \frac{1}{3} * baseArea * height$

## 2.4 Surface Area Formula

**Cube**  $SurfaceArea = 6 * side^2$

**Rectangle Prism**  $SurfaceArea = 2 * (length * width + length * height + width * height)$

**Cylinder**  $SurfaceArea = 2 * \pi * radius * (radius + height)$

**Sphere**  $SurfaceArea = 4 * \pi * radius^2$

**Pyramid**  $SurfaceArea = basearea + \frac{1}{2} * perimeterOfBase * slantHeight$

## 2.5 Triangles

**Side Lengths**  $a, b, c$

**Semi Perimeter**  $p = \frac{a+b+c}{2}$

**Area**  $A = \sqrt{p(p-a)(p-b)(p-c)}$

**Circumstance**  $R = \frac{abc}{4A}$

**In Radius**  $r = \frac{A}{p}$

## 2.6 Summation Of Series

- $c^k + c^{k+1} + \dots + c^n = c^{n+1} - c^k$
- $1 + 2 + 3 + \dots + n = \frac{n(n+1)}{2}$
- $1^2 + 2^2 + 3^2 + \dots + n^2 = \frac{n(n+1)(2n+1)}{6}$
- $1^3 + 2^3 + 3^3 + \dots + n^3 = \left(\frac{n(n+1)}{2}\right)^2$

## 2.7 Miscellaneous

- $2^{100} = 2^{50} * 2^{50}$
- $\begin{bmatrix} F_n \\ F_{n-1} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^{n-1} \begin{bmatrix} F_1 \\ F_0 \end{bmatrix}$
- $\log n! = \log 1 + \log 2 + \dots + \log n$

# 3 Graph Theory

All about graph.

### 3.1 BFS

```
void bfs(int start, int target = -1) {
    queue<int> q;
    q.push(start);
    vis[start] = true;
    while (!q.empty()) {
        int u = q.front();
        q.pop();
        for (int i : adj[u]) {
            if (!vis[i]) {
                vis[i] = true;
                q.push(i);
            }
        }
    }
}
```

### 3.2 DFS

```
map<int, vector<int>>> adj;
map<int, int> visited, parent, level, color;

void dfs(int start)
{
    visited[start]=1;
    for (auto child : adj[start])
    {
        if (!visited[child])
        {
            dfs(child);
        }
    }
    visited[start]=2;
}
```

### 3.3 Dijkstra Algorithm

```
void Dijkstra(int start) {
    // vector<pair<int, int>> adj[N];
    priority_queue<pair<int, int>,
        vector<pair<int, int>>, greater<
        pair<int, int>>> pq;
    pq.push({0, start});
    while (!pq.empty()) {
        auto it = pq.top();
        pq.pop();
        int wt = it.first;
        int u = it.second;
        if (vis[u])
            continue;
        vis[u] = 1;
        for (pair<int, int> i : adj[u]) {
            int adjWt = i.second;
            int adjNode = i.first;
            if (dist[adjNode] > wt + adjWt)
            {
                dist[adjNode] = wt + adjWt;
                pq.push({dist[adjNode],
                    adjNode});
            }
        }
    }
}
```

```
    }
    }
}
```

### 3.4 Bellman Ford

```
vector<int> dist;
vector<int> parent;
vector<vector<pair<int, int>>> adj;
// resize the vectors from main
function
void bellmanFord(int num_of_nd, int
    src) {
    dist[src] = 0;
    for (int step = 0; step < num_of_nd;
        step++) {
        for (int i = 1; i <= num_of_nd; i
            ++){
            for (auto it : adj[i]) {
                int u = i;
                int v = it.first;
                int wt = it.second;
                if (dist[u] != inf &&
                    ((dist[u] + wt) < dist[v])
                ) {
                    if (step == num_of_nd - 1) {
                        cout << "Negative cycle
                            found\n ";
                        return;
                    }
                    dist[v] = dist[u] + wt;
                    parent[v] = u;
                }
            }
        }
    }
    for (int i = 1; i <= num_of_nd; i++)
        cout << dist[i] << " ";
    cout << endl;
}
```

### 3.5 Floyd Warshall Algorithm

```
typedef double T;
typedef vector<T> VT;
typedef vector<VT> VVT;
typedef vector<int> VI;
typedef vector<VI> VVI;
bool FloydWarshall(VVT &w, VVI &prev)
{
    int n = w.size();
    prev = VVI(n, VI(n, -1));
    for (int k = 0; k < n; k++) {
        for (int i = 0; i < n; i++) {
            for (int j = 0; j < n; j++) {
                if (w[i][j] > w[i][k] + w[k][j])
                {
                    w[i][j] = w[i][k] + w[k][j];
                    prev[i][j] = k;
                }
            }
        }
    }
}
```

```

    }
}
}
for (int i = 0; i < n; i++)
    if (w[i][i] < 0)
        return false;
return true;
}

```

### 3.6 Kruskal Algorithm (MST)

```

vector<pair<int, pair<int, int>>>
Kruskal(vector<pair<int, pair<int,
    int>>> &edges, int n) {
    sort(edges.begin(), edges.end());
    vector<pair<int, pair<int, int>>>
        ans;
    DisjointSet D(n);
    for (auto it : edges) {
        if (D.findUPar(it.second.first) !=
            D.findUPar(it.second.second))
        {
            ans.push_back({it.first, {it.
                second.first, it.second.
                second}});
            D.unionBySize(it.second.first,
                it.second.second);
        }
    }
    return ans;
}

```

### 3.7 Prims Algorithm (MST)

```

void Prims(int start) {
    // map<int, vector<pair<int, int>>>
    adj, ans;
    priority_queue<pair<int, pair<int,
        int>>, vector<pair<int, pair<int,
        int>>>, greater<pair<int, pair<
        int, int>>>> pq;
    pq.push({0, {start, -1}});
    while (!pq.empty()) {
        auto it = pq.top();
        pq.pop();
        int wt = it.first;
        int u = it.second.first;
        int v = it.second.second;
        if (vis[u]) continue;
        vis[u] = 1;
        if (v != -1) ans[u].push_back({v,
            wt});
        for (pair<int, int> i : adj[u]) {
            int adjWt = i.second;
            int adjNode = i.first;
            if (!vis[adjNode]) pq.push({
                adjWt, {adjNode, u}});
        }
    }
}

```

### 3.8 Strongly Connected Components

```

vector<bool> visited; // keeps track
    of which vertices are already
    visited

// runs depth first search starting at
    vertex v.
// each visited vertex is appended to
    the output vector when dfs leaves
    it.
void dfs(int v, vector<vector<int>>
    const &adj, vector<int> &output) {
    visited[v] = true;
    for (auto u : adj[v])
        if (!visited[u])
            dfs(u, adj, output);
    output.push_back(v);
}

// input: adj -- adjacency list of G
// output: components -- the strongly
    connected components in G
// output: adj_cond -- adjacency list
    of G^SCC (by root vertices)
void scc(vector<vector<int>> const &
    adj, vector<vector<int>> &
    components, vector<vector<int>> &
    adj_cond) {
    int n = adj.size();
    components.clear(), adj_cond.clear()
        ;

    vector<int> order; // will be a
        sorted list of G's vertices by
        exit time

    visited.assign(n, false);

    // first series of depth first
        searches
    for (int i = 0; i < n; i++)
        if (!visited[i])
            dfs(i, adj, order);

    // create adjacency list of G^T
    vector<vector<int>> adj_rev(n);
    for (int v = 0; v < n; v++)
        for (int u : adj[v])
            adj_rev[u].push_back(v);

    visited.assign(n, false);
    reverse(order.begin(), order.end());

    vector<int> roots(n, 0); // gives
        the root vertex of a vertex's
        SCC

    // second series of depth first
        searches
    for (auto v : order)
        if (!visited[v]) {

```

```

        std::vector<int> component;
        dfs(v, adj_rev, component);
        components.push_back(component);
        int root = *min_element(begin(
            component), end(component));
        for (auto u : component)
            roots[u] = root;
    }

    // add edges to condensation graph
    adj_cond.assign(n, {});
    for (int v = 0; v < n; v++)
        for (auto u : adj[v])
            if (roots[v] != roots[u])
                adj_cond[roots[v]].push_back(
                    roots[u]);
}

```

### 3.9 LCA

```

struct LCA {
    vector<int> height, euler, first,
        segtree, parent;
    vector<bool> visited;
    vector<vector<int>> jump;

    int n;

    LCA(vector<vector<int>> &adj, int
        root = 0) {
        n = adj.size();
        height.resize(n);
        first.resize(n);
        parent.resize(n);
        euler.reserve(n * 2);
        visited.assign(n, false);
        dfs(adj, root);
        int m = euler.size();
        segtree.resize(m * 4);
        build(1, 0, m - 1);

        jump.resize(n, vector<int>(32, -1));

        for(int i=0; i<n; i++) {
            jump[i][0] = parent[i];
        }

        for(int j=1; j<20; j++) {
            for(int i=0; i<n; i++) {
                int mid = jump[i][j-1];
                if (mid != -1) jump[i][j] =
                    jump[mid][j-1];
            }
        }
    }

    void dfs(vector<vector<int>> &adj,
        int node, int h = 0) {
        visited[node] = true;
        height[node] = h;
        first[node] = euler.size();

```

```

        euler.push_back(node);
        for (auto to : adj[node]) {
            if (!visited[to]) {
                parent[to] = node;
                dfs(adj, to, h + 1);
                euler.push_back(node);
            }
        }
    }

    void build(int node, int b, int e) {
        if (b == e) {
            segtree[node] = euler[b];
        } else {
            int mid = (b + e) / 2;
            build(node << 1, b, mid);
            build(node << 1 | 1, mid + 1, e);
            ;
            int l = segtree[node << 1], r =
                segtree[node << 1 | 1];
            segtree[node] = (height[l] <
                height[r]) ? l : r;
        }
    }

    int query(int node, int b, int e,
        int L, int R) {
        if (b > R || e < L)
            return -1;
        if (b >= L && e <= R)
            return segtree[node];
        int mid = (b + e) >> 1;

        int left = query(node << 1, b, mid,
            L, R);
        int right = query(node << 1 | 1,
            mid + 1, e, L, R);
        if (left == -1)
            return right;
        if (right == -1)
            return left;
        return height[left] < height[right]
            ? left : right;
    }

    int lca(int u, int v) {
        int left = first[u], right = first[v];
        if (left > right)
            swap(left, right);
        return query(1, 0, euler.size() -
            1, left, right);
    }

    int kthParent(int u, int k) {
        for(int i=0; i<19; i++) {
            if (k & (1LL<<i)) u = jump[u][i];
        }
        return u;
    }
};

```

### 3.10 Max Flow

```
const int N = 505;
int capacity[N][N];
int vis[N], p[N];
int n, m;

int bfs(int s, int t) {
    memset(vis, 0, sizeof vis);
    queue<int> qu;
    qu.push(s);
    vis[s] = 1;
    while (!qu.empty()) {
        int u = qu.front();
        qu.pop();
        for (int i = 0; i <= n + m + 2; i++) {
            if (capacity[u][i] > 0 && !vis[i]) {
                p[i] = u;
                vis[i] = 1;
                qu.push(i);
            }
        }
    }
    return vis[t] == 1;
}

int maxflow(int s, int t) {
    int cnt = 0;
    while (bfs(s, t)) {
        int cur = t;
        while (cur != s) {
            int prev = p[cur];
            capacity[prev][cur] -= 1;
            capacity[cur][prev] += 1;
            cur = prev;
        }
        cnt++;
    }
    return cnt;
}
```

## 4 Data Structures

Different Data Structures.

### 4.1 Segment Tree

```
constexpr int N = 100005;
int arr[N], seg[N];

void build(int ind, int low, int high) {
    if (low == high) {
        seg[ind] = arr[low];
        return;
    }
    int mid = (low + high) / 2;
    build(2 * ind + 1, low, mid);
    build(2 * ind + 2, mid + 1, high);
```

```
    seg[ind] = seg[2 * ind + 1] + seg[2 * ind + 2];
}

int query(int ind, int low, int high, int l, int r) {
    if (low >= l && high <= r) return seg[ind];
    if (low > r || high < l) return 0;
    int mid = (low + high) / 2;
    int left = query(2 * ind + 1, low, mid, l, r);
    int right = query(2 * ind + 2, mid + 1, high, l, r);
    return left + right;
}

void update(int ind, int low, int high, int node, int val) {
    if (low == high) {
        seg[ind] = val;
        return;
    }
    int mid = (low + high) / 2;
    if (low <= node && node <= mid)
        update(2 * ind + 1, low, mid, node, val);
    else
        update(2 * ind + 2, mid + 1, high, node, val);
    seg[ind] = seg[2 * ind + 1] + seg[2 * ind + 2];
}
```

### 4.2 Segment Tree Lazy

```
const int N = 1e5 + 5;
int arr[N], seg[N << 2], lz[N << 2];

void pull(int node, int l, int r) {
    seg[node] = seg[node << 1] + seg[node << 1 | 1];
}

void push(int node, int l, int r) {
    int mid = (l + r) >> 1;
    lz[node << 1] += lz[node];
    seg[node << 1] += lz[node] * (mid - l + 1);
    lz[node << 1 | 1] += lz[node];
    seg[node << 1 | 1] += lz[node] * (r - mid);
    lz[node] = 0;
}

void build(int node, int l, int r) {
    if (l == r) {
        seg[node] = arr[l];
        lz[node] = 0;
        return;
    }
    int mid = (l + r) >> 1;
    build(node << 1, l, mid);
    build(node << 1 | 1, mid + 1, r);
    pull(node, l, r);
}
```

```

}

void update(int node, int l, int r,
            int ql, int qr, int val) {
    if(qr < l || r < ql) return;
    if(ql <= l && r <= qr) {
        seg[node] += val;
        lz[node] += val;
        return;
    }

    push(node, l, r);

    int mid = (l + r) >> 1;
    update(node << 1, l, mid, ql, qr,
           val);
    update(node << 1 | 1, mid + 1, r, ql,
           qr, val);

    pull(node, l, r);
}

int query(int node, int l, int r, int
          ql, int qr) {
    if(qr < l || r < ql) return 0;
    if(ql <= l && r <= qr) return seg[
        node];

    push(node, l, r);

    int mid = (l + r) >> 1;
    return query(node << 1, l, mid, ql,
                 qr) + query(node << 1 | 1, mid +
                             1, r, ql, qr);
}

```

### 4.3 Fenwick Tree

```

int fenwick[N];

void update(int ind, int val) {
    while (ind < N) {
        fenwick[ind] += val;
        ind += ind & -ind;
    }
}

int query(int ind) {
    int sum = 0;
    while (ind > 0) {
        sum += fenwick[ind];
        ind -= ind & -ind;
    }
    return sum;
}

```

### 4.4 DisjointSet

```

class DisjointSet {
    vector<int> parent, sz;

public:

```

```

    DisjointSet(int n) {
        sz.resize(n + 1);
        parent.resize(n + 2);
        for (int i = 1; i <= n; i++)
            parent[i] = i, sz[i] = 1;
    }

    int findUPar(int u) { return parent[
        u] == u ? u : parent[u] =
        findUPar(parent[u]); }

    void unionBySize(int u, int v) {
        int a = findUPar(u);
        int b = findUPar(v);
        if (sz[a] < sz[b]) swap(a, b);
        if (a != b) {
            parent[b] = a;
            sz[a] += sz[b];
        }
    }
};

```

### 4.5 TRIE

```

const int N = 26;
class Node {
public:
    int EoW;
    Node* child[N];
    Node() {
        EoW = 0;
        for (int i = 0; i < N; i++) child[
            i] = NULL;
    }
};

void insert(Node* node, string s) {
    for (size_t i = 0; i < s.size(); i
        ++){
        int r = s[i] - 'A';
        if (node->child[r] == NULL) node->
            child[r] = new Node();
        node = node->child[r];
    }
    node->EoW += 1;
}

int search(Node* node, string s) {
    for (size_t i = 0; i < s.size(); i
        ++){
        int r = s[i] - 'A';
        if (node->child[r] == NULL) return
            0;
    }
    return node->EoW;
}

void print(Node* node, string s = "")
{
    if (node->EoW) cout << s << "\n";
    for (int i = 0; i < N; i++) {
        if (node->child[i] != NULL) {
            char c = i + 'A';
            print(node->child[i], s + c);
        }
    }
}

```



```

    }
}

bool isChild(Node* node) {
    for (int i = 0; i < N; i++)
        if (node->child[i] != NULL) return true;
    return false;
}

bool isJunc(Node* node) {
    int cnt = 0;
    for (int i = 0; i < N; i++) {
        if (node->child[i] != NULL) cnt++;
    }
    if (cnt > 1) return true;
    return false;
}

int trie_delete(Node* node, string s,
    int k = 0) {
    if (node == NULL) return 0;
    if (k == (int)s.size()) {
        if (node->EoW == 0) return 0;
        if (isChild(node)) {
            node->EoW = 0;
            return 0;
        }
        return 1;
    }
    int r = s[k] - 'A';
    int d = trie_delete(node->child[r],
        s, k + 1);
    int j = isJunc(node);
    if (d) delete node->child[r];
    if (j) return 0;
    return d;
}

void delete_trie(Node* node) {
    for (int i = 0; i < 15; i++) {
        if (node->child[i] != NULL)
            delete_trie(node->child[i]);
    }
    delete node;
}

```

## 5 Algorithms

All about algorithms.

### 5.1 KMP

```

vector<int> prefix_function(string s)
{
    int n = (int)s.length();
    vector<int> pi(n);
    for (int i = 1; i < n; i++) {
        int j = pi[i - 1];
        while (j > 0 && s[i] != s[j])
            j = pi[j - 1];
    }
}

```

```

        if (s[i] == s[j]) j++;
        pi[i] = j;
    }
    return pi;
}

vector<int> find_matches(string text,
    string pat) {
    int n = pat.length(), m = text.
        length();
    string s = pat + "$" + text;
    vector<int> pi = prefix_function(s), ans;
    for (int i = n; i <= n + m; i++) {
        if (pi[i] == n) {
            ans.push_back(i - 2 * n);
        }
    }
    return ans;
}

```

### 5.2 Monotonic Stack (Immediate Small)

```

for (int i = n - 1; i >= 0; i--) {
    while (!stk.empty() && v[i] >= v[stk.
        .top()]) stk.pop();
    ind[i] = stk.empty() ? -1 : stk.top
        ();
    stk.push(i);
}
// 3 1 5 4 10
// 2 2 4 4 -1

```

### 5.3 Kadane's Algorithm

```

int maxSubArraySum(vector<int> &a) {
    int size = a.size();
    int maxTill = INT_MIN, maxEnd = 0;
    for (int i = 0; i < size; i++) {
        maxEnd = maxEnd + a[i];
        if (maxTill < maxEnd) maxTill =
            maxEnd;
        if (maxEnd < 0) maxEnd = 0;
    }
    return maxTill;
}

```

### 5.4 2D Prefix Sum

```

pref[i][j] = a[i][j] + pref[i - 1][j]
    + pref[i][j - 1] - pref[i - 1][j -
        1];

```

## 6 Number Theory/Math

All about math.

## 6.1 nCr

```
int inverseMod(int a, int m) { return
    power(a, m - 2); }

int nCr(int n, int r, int m = mod){
    if(r==0) return 1;
    if(r>n) return 0;
    return (fact[n] * inverseMod((fact[
        r] * fact[n-r]) % m , m)) % m;
}
```

## 6.2 Power

```
int power(int base, int n, int m = mod
) {
    if (n == 0) return 1;
    if (n & 1) {
        int x = power(base, n / 2);
        return ((x * x) % m * base) % m;
    }
    else {
        int x = power(base, n / 2);
        return (x * x) % m;
    }
}
```

## 6.3 Miller Rabin

```
using u64 = uint64_t;
using u128 = __uint128_t;

u64 binpower(u64 base, u64 e, u64 mod)
{
    u64 result = 1;
    base %= mod;
    while (e) {
        if (e & 1) result = (u128)result *
            base % mod;
        base = (u128)base * base % mod;
        e >>= 1;
    }
    return result;
}

bool check_composite(u64 n, u64 a, u64
    d, int s) {
    u64 x = binpower(a, d, n);
    if (x == 1 || x == n - 1) return
        false;
    for (int r = 1; r < s; r++) {
        x = (u128)x * x % n;
        if (x == n - 1) return false;
    }
    return true;
};

bool MillerRabin(u64 n, int iter = 5)
{ // returns true if n is
  probably prime, else returns false
  .
```

```
if (n < 4) return n == 2 || n == 3;
int s = 0;
u64 d = n - 1;
while ((d & 1) == 0) {
    d >>= 1;
    s++;
}

for (int i = 0; i < iter; i++) {
    int a = 2 + rand() % (n - 3);
    if (check_composite(n, a, d, s))
        return false;
}
return true;
}
```

## 6.4 Sieve

```
const int N = 1e7 + 3;
vector<int> primes;
int notprime[N];

void sieve() {
    primes.push_back(2);
    for (int i = 2; i < N; i += 2) {
        notprime[i] = true;
    }
    for (int i = 3; i < N; i += 2) {
        if (!notprime[i]) {
            primes.push_back(i);
            for (int j = i * i; j < N; j +=
                2 * i) {
                notprime[j] = true;
            }
        }
    }
}
```

## 6.5 Inverse Mod

```
int modInverse(int a, int m) {
    int m0 = m, t, q;
    int x0 = 0, x1 = 1;
    if (m == 1) return 0;
    while (a > 1) {
        q = a / m;
        t = m;
        m = a % m, a = t;
        t = x0;
        x0 = x1 - q * x0;
        x1 = t;
    }
    if (x1 < 0) x1 += m0;
    return x1;
}
```

## 6.6 Bitset Sieve

```
const int sieve_size = 10000006;
bitset<sieve_size> sieve;
```

```

void Sieve() {
    sieve.flip();
    int finalBit = sqrt(sieve.size()) +
        1;
    for (int i = 2; i < finalBit; ++i) {
        if (sieve.test(i))
            for (int j = 2 * i; j <
                sieve_size; j += i) sieve.
                reset(j);
    }
}

```

## 6.7 Divisors

```

constexpr int N = 1000005;

int Prime[N + 4], kk;
bool notPrime[N + 5];
void SieveOf() {
    notPrime[1] = true;
    Prime[kk++] = 2;
    for (int i = 4; i <= N; i += 2)
        notPrime[i] = true;
    for (int i = 3; i <= N; i += 2) {
        if (!notPrime[i]) {
            Prime[kk++] = i;
            for (int j = i * i; j <= N; j +=
                2 * i) notPrime[j] = true;
        }
    }
}

void Divisors(int n) {
    int sum = 1, total = 1;
    int mnP = INT_MAX, mxP = INT_MIN,
        cntP = 0, totalP = 0;
    for (int i = 0; i <= N && Prime[i] *
        Prime[i] <= n; i++) {
        if (n % Prime[i] == 0) {
            mnP = min(mnP, Prime[i]);
            mxP = max(mxP, Prime[i]);
            int k = 0;
            cntP++;
            while (n % Prime[i] == 0) {
                k++;
                n /= Prime[i];
            }

            sum *= (k + 1); // NOD
            totalP += k;
            int s = 0, p = 1;
            while (k-- >= 0) {
                s += p;
                p *= Prime[i];
            };
            total *= s; // SOD
        }
    }
    if (n > 1) {
        cntP++, totalP++;
        sum *= 2;
    }
}

```

```

        total *= (1 + n);
        mnP = min(mnP, n);
        mxP = max(mxP, n);
    }
    cout << mnP << " " << mxP << " " <<
        cntP << " " << totalP << " " <<
        sum << " " << total << "\n";
}

```

## 6.8 Euler's Totient Phi Function

```

const int N = 5000005;
int phi[N];
unsigned long long phiSum[N];
void phiCalc() {
    for (int i = 2; i < N; i++) phi[i] =
        i;
    for (int i = 2; i < N; i++) {
        if (phi[i] == i) {
            for (int j = i; j < N; j += i) {
                phi[j] -= phi[j] / i;
            }
        }
    }
    for (int i = 2; i < N; i++) {
        phiSum[i] = (unsigned long long)
            phi[i] * (unsigned long long)
            phi[i] + phiSum[i - 1];
    }
}

```

## 6.9 Log a base b

```

int logab (int a, int b){
    return log2(a) / log2(b);
}

```

# 7 Dynamic Programming

## 7.1 LCS

```

string s, t;
vector<vector<int>> dp(3003, vector<
    int>(3003, -1));
vector<vector<int>> mark(3003, vector<
    int>(3003));

int f(int i, int j) {
    if (i < 0 || j < 0) return 0;
    if (dp[i][j] != -1) return dp[i][j];
    int res = 0;
    if (s[i] == t[j]) {
        mark[i][j] = 1;
        res = 1 + f(i - 1, j - 1);
    }
    else {
        int iC = f(i - 1, j);
        int jC = f(i, j - 1);
        if (iC > jC) mark[i][j] = 2;
    }
}

```

```

        else mark[i][j] = 3;
        res = max(iC, jC);
    }
    return dp[i][j] = res;
}

void printWay(int i, int j) {
    if (i < 0 || j < 0) return;
    if (mark[i][j] == 1) printWay(i - 1,
        j - 1), cout << s[i];
    else if (mark[i][j] == 2) printWay(i
        - 1, j);
    else if (mark[i][j] == 3) printWay(i
        , j - 1);
}

```

## 7.2 LIS

```

void lis(vector<int> &v) {
    int n = v.size();
    vector<int> dp(n + 1, 1), hash(n);
    int mx = 1, lastInd = 0;
    for (int i = 0; i < n; i++) {
        hash[i] = i;
        for (int prev = 0; prev < i; prev
            ++){

```

```

            if (v[i] > v[prev] && 1 + dp[
                prev] > dp[i]) {
                dp[i] = 1 + dp[prev];
                hash[i] = prev;
            }
        }
        if (mx < dp[i]) {
            mx = dp[i];
            lastInd = i;
        }
    }
    vector<int> printSeq;
    printSeq.push_back(v[lastInd]);
    while (hash[lastInd] != lastInd) {
        lastInd = hash[lastInd];
        printSeq.push_back(v[lastInd]);
    }
    reverse(printSeq.begin(), printSeq.
        end());
    cout << mx << "\n";
    for (int i : printSeq) cout << i <<
        " ";
    cout << "\n";
}

```