```
In [3]:
```

```
!pip install torchsummary
```

Requirement already satisfied: torchsummary in /opt/conda/lib/python3.7/site-packages (1.5.1)

#### In [4]:

```
import numpy as np
import scipy.io
import os
from numpy.linalg import norm, det, inv, svd
from scipy.linalg import rq
import math
import matplotlib.pyplot as plt
import numpy as np
import math
import random
import sys
from scipy import ndimage, spatial
from tqdm.notebook import trange,tqdm
import torch
import torch.nn as nn
import torch.optim as optim
from torch.optim import lr scheduler
from torch.autograd import Variable
import torchvision
from torchvision import datasets, models, transforms
from torch.utils.data import Dataset, DataLoader, ConcatDataset
from skimage import io, transform, data
from torchvision import transforms, utils
import os
import sklearn.svm
import cv2
from os.path import exists
import pandas as pd
import PIL
from sklearn.metrics.cluster import completeness score
from sklearn.cluster import KMeans
from tqdm import tqdm,tqdm notebook
from functools import partial
from torchsummary import summary
from torchvision.datasets import ImageFolder
from torch.utils.data.sampler import SubsetRandomSampler
```

## In [5]:

```
class Image:
    def init (self,img,position):
        self.img = img
        self.position = position
inliner matchset = []
def features_matching(a, keypointlength, threshold):
    bestmatch = np.empty((keypointlength), dtype=np.int16)
    imglindex = np.empty((keypointlength),dtype=np.init16)
    distance = np.empty((keypointlength))
    index = 0
    for j in range(0, keypointlength):
        x=a[j]
        listx = x.tolist()
       x.sort()
       minval1=x[0]
       minval2=x[1]
        itemindex1 = listx.index(minval1)
        itemindex2 = listx.index(minval2)
```

```
ratio = minval1/minval2
        if ratio < threshold:</pre>
            bestmatch[index] = itemindex1
            distance[index] = minval1
            imglindex[index] = j
            index = index + 1
    return [cv2.DMatch(imglindex[i], bestmatch[i].astype(int), distance[i]) for i in range
(0, index)]
def compute Hmography(im1 pts,im2 pts):
    num matches=len(im1 pts)
    num rows = 2*num matches
   num_cols = 9
    A matrix shape = (num rows, num cols)
   A = np.zeros(A matrix shape)
    a index = 0
    for i in range(0, num matches):
        (a_x, a_y) = iml_pts[i]
        (b_x, b_y) = im2_pts[i]
        row1 = [a_x, a_y, 1, 0, 0, -b_x*a_x, -b_x*a_y, -b_x]
        row2 = [0,0,0,a_x,a_y,1,-b_y*a_x,-b_y*a_y,-b_y]
        A[a index] = row1
        A[a index+1] = row2
        a index += 2
    U,s,Vt = np.linalg.svd(A)
    H = np.eye(3)
    H = Vt[-1].reshape(3,3)
    return H
def displayplot(img, title):
    plt.figure(figsize=(15,15))
    plt.title(title)
    plt.imshow(cv2.cvtColor(img,cv2.COLOR BGR2RGB))
   plt.show()
def RANSAC alg(f1, f2, matches, nRANSAC, RANSACthresh):
   minMatches = 4
   nBest = 0
   best inliners = []
    H = stimate = np.eye(3,3)
   global inliner matchset
    inliner matchset = []
    for iteration in range(nRANSAC):
        matchSimple = random.sample(matches, minMatches)
        im1 pts = np.empty((minMatches,2))
        im2 pts = np.empty((minMatches,2))
        for i in range(0,minMatches):
            m = matchSimple[i]
            im1 pts[i] = f1[m.queryIdx].pt
            im2 pts[i] = f2[m.trainIdx].pt
        H estimate = compute Hmography(im1 pts,im2 pts)
        inliners = get inliners(f1, f2, matches, H estimate, RANSACthresh)
        if len(inliners) > nBest:
            nBest = len(inliners)
            best inliners inliners
    print("Number of best inliners", len(best inliners))
    for i in range(len(best inliners)):
        inliner matchset.append(matches[best inliners[i]])
    im1 pts = np.empty((len(best inliners),2))
    im2 pts = np.empty((len(best_inliners),2))
    for i in range(0,len(best inliners)):
        m = inliner matchset[i]
        im1 pts[i] = f1[m.queryIdx].pt
        im2 pts[i] = f2[m.trainIdx].pt
    M = compute Hmography(im1 pts,im2 pts)
    return M, len(best inliners)
```

```
In [1]:
!pip install opency-python==3.4.2.17
!pip install opency-contrib-python==3.4.2.17
Requirement already satisfied: opencv-python==3.4.2.17 in /opt/conda/lib/python3.7/site-p
ackages (3.4.2.17)
Requirement already satisfied: numpy>=1.14.5 in /opt/conda/lib/python3.7/site-packages (f
rom opency-python==3.4.2.17) (1.19.5)
Requirement already satisfied: opency-contrib-python==3.4.2.17 in /opt/conda/lib/python3.
7/site-packages (3.4.2.17)
Requirement already satisfied: numpy>=1.14.5 in /opt/conda/lib/python3.7/site-packages (f
rom opencv-contrib-python==3.4.2.17) (1.19.5)
In [2]:
import cv2
cv= cv2.xfeatures2d.SIFT create()
In [6]:
files all = os.listdir('../input/uni-campus-dataset/RGB-img/img/')
files all.sort()
folder path = '../input/uni-campus-dataset/RGB-img/img/'
left files path rev = []
right files path = []
for file in files all[:51]:
    left files path rev.append(folder path + file)
left files path = left files path rev[::-1]
for file in files all[50:100]:
    right_files_path.append(folder_path + file)
In [7]:
gridsize = 8
clahe = cv2.createCLAHE(clipLimit=2.0, tileGridSize=(gridsize, gridsize))
images left bgr = []
images right bgr = []
images left = []
images right = []
for file in tqdm(left files path):
    left image sat= cv2.imread(file)
    lab = cv2.cvtColor(left image sat, cv2.COLOR BGR2LAB)
    lab[...,0] = clahe.apply(lab[...,0])
    left_image_sat = cv2.cvtColor(lab, cv2.COLOR LAB2BGR)
    left_img = cv2.resize(left_image sat, None, fx=0.35, fy=0.35, interpolation = cv2.INTE
R CUBIC)
    images left.append(cv2.cvtColor(left img, cv2.COLOR BGR2GRAY).astype('float32')/255.)
    images left bgr.append(left img)
for file in tqdm(right files path):
    right image sat= cv2.imread(file)
    lab = cv2.cvtColor(right image sat, cv2.COLOR BGR2LAB)
    lab[...,0] = clahe.apply(lab[...,0])
    right image sat = cv2.cvtColor(lab, cv2.COLOR LAB2BGR)
    right img = cv2.resize(right image sat, None, fx=0.35, fy=0.35, interpolation = cv2.INT
ER CUBIC)
    images_right.append(cv2.cvtColor(right_img, cv2.COLOR BGR2GRAY).astype('float32')/255
. )
```

images right bgr.append(right img)

| 51/51 [00:56<00:00, 1.10s/it]

| 50/50 [00:53<00:00, 1.08s/it]

100%|

100%|

```
In [8]:
```

```
Threshl=60;
Octaves=8;
#PatternScales=1.0f;
brisk = cv2.BRISK create(Threshl,Octaves)
keypoints all left brisk = []
descriptors all left brisk = []
points all left brisk=[]
keypoints_all_right_brisk = []
descriptors all right brisk = []
points all right brisk=[]
for imgs in tqdm(images left bgr):
    kpt = brisk.detect(imgs, None)
    kpt, descrip = brisk.compute(imgs, kpt)
    keypoints all left brisk.append(kpt)
    descriptors all left brisk.append(descrip)
    points_all_left_brisk.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr):
    kpt = brisk.detect(imgs, None)
    kpt, descrip = brisk.compute(imgs, kpt)
    keypoints all right brisk.append(kpt)
    descriptors all right brisk.append(descrip)
   points all right brisk.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

```
orb = cv2.0RB_create(5000)
keypoints_all_left_orb = []
descriptors_all_left_orb = []
points_all_left_orb=[]

keypoints_all_right_orb = []
descriptors_all_right_orb = []
points_all_right_orb=[]

for imgs in tqdm(images_left_bgr):
    kpt = orb.detect(imgs, None)
    kpt,descrip = orb.compute(imgs, kpt)
    keypoints_all_left_orb.append(kpt)
    descriptors_all_left_orb.append(descrip)
    points_all_left_orb.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))

for imgs in tqdm(images_right_bgr):
    kpt = orb.detect(imgs, None)
```

```
kpt,descrip = orb.compute(imgs, kpt)
keypoints_all_right_orb.append(kpt)
descriptors_all_right_orb.append(descrip)
points_all_right_orb.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

```
kaze = cv2.KAZE create()
keypoints all left kaze = []
descriptors all left kaze = []
points all left kaze=[]
keypoints all right kaze = []
descriptors all right kaze = []
points_all_right_kaze=[]
for imgs in tqdm(images left bgr):
    kpt = kaze.detect(imgs, None)
    kpt, descrip = kaze.compute(imgs, kpt)
    keypoints all left kaze.append(kpt)
    descriptors all left kaze.append(descrip)
   points_all_left_kaze.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr):
    kpt = kaze.detect(imgs, None)
    kpt, descrip = kaze.compute(imgs, kpt)
    keypoints all_right_kaze.append(kpt)
    descriptors all right kaze.append(descrip)
    points all right kaze.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

#### In [9]:

```
tqdm = partial(tqdm, position=0, leave=True)
```

## In [10]:

```
akaze = cv2.AKAZE create()
keypoints all left akaze = []
descriptors all left akaze = []
points all left akaze=[]
keypoints all right akaze = []
descriptors all right akaze = []
points all right akaze=[]
for imgs in tqdm(images left bgr):
    kpt = akaze.detect(imgs, None)
    kpt, descrip = akaze.compute(imgs, kpt)
    keypoints all left akaze.append(kpt)
    descriptors_all_left_akaze.append(descrip)
    points_all_left_akaze.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images_right_bgr):
    kpt = akaze.detect(imgs, None)
    kpt, descrip = akaze.compute(imgs, kpt)
    keypoints all right akaze.append(kpt)
    descriptors all right akaze.append(descrip)
    points all right akaze.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
               | 51/51 [01:15<00:00, 1.49s/it]
100%1
               | 50/50 [01:10<00:00, 1.41s/it]
```

```
star = cv2.xfeatures2d.StarDetector_create()
brief = cv2.xfeatures2d.BriefDescriptorExtractor_create()
keypoints_all_left_star = []
descriptors_all_left_brief = []
points_all_left_star=[]
keypoints_all_right_star = []
```

```
descriptors_all_right_brief = []
points_all_right_star=[]

for imgs in tqdm(images_left_bgr):
    kpt = star.detect(imgs,None)
    kpt,descrip = brief.compute(imgs, kpt)
    keypoints_all_left_star.append(kpt)
    descriptors_all_left_brief.append(descrip)
    points_all_left_star.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))

for imgs in tqdm(images_right_bgr):
    kpt = star.detect(imgs,None)
    kpt,descrip = brief.compute(imgs, kpt)
    keypoints_all_right_star.append(kpt)
    descriptors_all_right_brief.append(descrip)
    points_all_right_star.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

#### In [9]:

```
Threshl=60;
Octaves=8;
#PatternScales=1.0f;
brisk = cv2.BRISK_create(Threshl,Octaves)
freak = cv2.xfeatures2d.FREAK create()
keypoints_all left freak = []
descriptors all left freak = []
points all left freak=[]
keypoints_all_right_freak = []
descriptors_all_right_freak = []
points all right freak=[]
for imgs in tqdm(images left bgr):
    kpt = brisk.detect(imgs)
    kpt, descrip = freak.compute(imgs, kpt)
    keypoints all left freak.append(kpt)
    descriptors all left freak.append(descrip)
    points all left freak.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images_right bgr):
    kpt = brisk.detect(imgs,None)
    kpt, descrip = freak.compute(imgs, kpt)
    keypoints all right_freak.append(kpt)
    descriptors all right freak.append(descrip)
    points all right freak.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
               | 51/51 [00:46<00:00, 1.10it/s]
               50/50 [00:41<00:00,
                                     1.21it/sl
100%1
```

```
mser = cv2.MSER create()
sift = cv2.xfeatures2d.SIFT create()
keypoints all left mser = []
descriptors all left mser = []
points_all left mser=[]
keypoints_all_right_mser = []
descriptors all right mser = []
points all right mser=[]
for imgs in tqdm(images left bgr no enhance):
    kpt = mser.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints all left mser.append(kpt)
   descriptors all left mser.append(descrip)
    points all left mser.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr no enhance):
    kpt = mser.detect(imgs, None)
```

```
kpt, descrip = sift.compute(imgs, kpt)
keypoints_all_right_mser.append(kpt)
descriptors_all_right_mser.append(descrip)
points_all_right_mser.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

### In [10]:

```
agast = cv2.AgastFeatureDetector create()
sift = cv2.xfeatures2d.SIFT create()
keypoints all left agast = []
descriptors_all_left_agast = []
points all left agast=[]
keypoints all right agast = []
descriptors all right agast = []
points all right agast=[]
for imgs in tqdm(images left bgr no enhance):
    kpt = agast.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints_all_left_agast.append(kpt)
    descriptors_all_left_agast.append(descrip)
    points all left agast.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr no enhance):
    kpt = agast.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints_all_right_agast.append(kpt)
    descriptors_all_right_agast.append(descrip)
    points all right agast.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
               | 51/51 [07:00<00:00, 8.25s/it]
100%1
               | 50/50 [07:01<00:00,
100%|
                                     8.42s/it]
```

#### In [9]:

```
fast = cv2.FastFeatureDetector create()
sift = cv2.xfeatures2d.SIFT create()
keypoints_all_left_fast = []
descriptors all left fast = []
points all left fast=[]
keypoints all right fast = []
descriptors all right fast = []
points all right fast=[]
for imgs in tqdm(images left bgr no enhance):
    kpt = fast.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints all left fast.append(kpt)
    descriptors_all_left_fast.append(descrip)
    points all left fast.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr no enhance):
    kpt = fast.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints all right fast.append(kpt)
    descriptors_all_right_fast.append(descrip)
    points all right fast.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
100%|
               | 51/51 [06:10<00:00,
                                      7.26s/it]
100%|
               | 50/50 [06:16<00:00,
                                      7.53s/it]
```

```
gftt = cv2.GFTTDetector_create()
sift = cv2.xfeatures2d.SIFT_create()
keypoints_all_left_gftt = []
descriptors_all_left_gftt = []
points_all_left_gftt=[]
```

```
keypoints_all_right_gftt = []
descriptors_all_right_gftt = []
points_all_right_gftt=[]
for imgs in tqdm(images_left_bgr_no_enhance):
    kpt = gftt.detect(imgs,None)
    kpt,descrip = sift.compute(imgs, kpt)
    keypoints_all_left_gftt.append(kpt)
    descriptors_all_left_gftt.append(descrip)
    points_all_left_gftt.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))

for imgs in tqdm(images_right_bgr_no_enhance):
    kpt = gftt.detect(imgs,None)
    kpt,descrip = sift.compute(imgs, kpt)
    keypoints_all_right_gftt.append(kpt)
    descriptors_all_right_gftt.append(descrip)
    points_all_right_gftt.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

```
daisy = cv2.xfeatures2d.DAISY create()
sift = cv2.xfeatures2d.SIFT create()
keypoints_all_left_daisy = []
descriptors all left daisy = []
points all left daisy=[]
keypoints all right daisy = []
descriptors all right daisy = []
points all right daisy=[]
for imgs in tqdm(images left bgr no enhance):
    kpt = sift.detect(imgs, None)
    kpt, descrip = daisy.compute(imgs, kpt)
    keypoints all left daisy.append(kpt)
    descriptors all left daisy.append(descrip)
    points all left daisy.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr no enhance):
    kpt = sift.detect(imgs, None)
    kpt, descrip = daisy.compute(imgs, kpt)
    keypoints_all_right_daisy.append(kpt)
    descriptors all right daisy.append(descrip)
    points all right daisy.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

```
surf = cv2.xfeatures2d.SURF create()
sift = cv2.xfeatures2d.SIFT create()
keypoints all left surfsift = []
descriptors all left surfsift = []
points_all_left_surfsift=[]
keypoints all right surfsift = []
descriptors all right surfsift = []
points all right surfsift=[]
for imgs in tqdm(images left bgr no enhance):
    kpt = surf.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints all left surfsift.append(kpt)
   descriptors all left surfsift.append(descrip)
   points all left surfsift.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr no enhance):
    kpt = surf.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints all right surfsift.append(kpt)
    descriptors all right surfsift.append(descrip)
    points_all_right_surfsift.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

```
In [ ]:
sift = cv2.xfeatures2d.SIFT create()
keypoints all left sift = []
descriptors all left sift = []
points all left sift=[]
keypoints all right sift = []
descriptors all right sift = []
points_all_right_sift=[]
for imgs in tqdm(images_left_bgr_no enhance):
    kpt = sift.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints_all_left_sift.append(kpt)
    descriptors all left sift.append(descrip)
    points all left sift.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr no enhance):
    kpt = sift.detect(imgs, None)
    kpt, descrip = sift.compute(imgs, kpt)
    keypoints all right sift.append(kpt)
    descriptors all right sift.append(descrip)
    points all right sift.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
```

```
surf = cv2.xfeatures2d.SURF create()
keypoints all left surf = []
descriptors all left surf = []
points_all_left_surf=[]
keypoints all right surf = []
descriptors all right surf = []
points all right surf=[]
for imgs in tqdm(images left bgr):
    kpt = surf.detect(imgs,None)
    kpt, descrip = surf.compute(imgs, kpt)
    keypoints_all_left_surf.append(kpt)
    descriptors all left surf.append(descrip)
   points all left surf.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr):
    kpt = surf.detect(imgs, None)
    kpt, descrip = surf.compute(imgs, kpt)
    keypoints_all_right_surf.append(kpt)
    descriptors_all_right_surf.append(descrip)
   points_all_right_surf.append(np.asarray([[p.pt[0],p.pt[1]] for p in kpt]))
```

#### In [ ]:

```
# sift = cv2.xfeatures2d.SURF_Create()
# keypoints_all_left_surf = []
# descriptor_all_left_surf = []
# points_all_right_surf = []
# keypoints_all_right_surf = []
# descriptor_all_right_surf = []
# points_all_right_surf = []
# for images in tqdm(left_images_bgr):
# kpt = surf.detect(imgs, None)
# kpt, descrip = surf.compute(imgs, kpt)
# keypoints_all_left_surf.append(kpt)
# descriptor_all_left_surf.append(descrip)
# points_all_left_surf.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
# points_all_left_surf.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]]))
```

## In [10]:

```
class RootSIFT:
```

```
def init (self):
    # initialize the SIFT feature extractor
    #self.extractor = cv2.DescriptorExtractor create("SIFT")
   self.sift = cv2.xfeatures2d.SIFT create()
def compute(self, image, kps, eps=1e-7):
    # compute SIFT descriptors
    (kps, descs) = self.sift.compute(image, kps)
    # if there are no keypoints or descriptors, return an empty tuple
   if len(kps) == 0:
       return ([], None)
    # apply the Hellinger kernel by first L1-normalizing, taking the
    # square-root, and then L2-normalizing
   descs /= (np.linalg.norm(descs, axis=0, ord=2) + eps)
   descs /= (descs.sum(axis=0) + eps)
   descs = np.sqrt(descs)
    #descs /= (np.linalg.norm(descs, axis=0, ord=2) + eps)
    # return a tuple of the keypoints and descriptors
   return (kps, descs)
```

#### In [11]:

```
sift = cv2.xfeatures2d.SIFT create()
rootsift = RootSIFT()
keypoints all left rootsift = []
descriptors all left rootsift = []
points all left rootsift=[]
keypoints all right rootsift = []
descriptors all right rootsift = []
points all right rootsift=[]
for imgs in tqdm(images left bgr):
    kpt = sift.detect(imgs, None)
    kpt, descrip = rootsift.compute(imgs, kpt)
    keypoints all left rootsift.append(kpt)
   descriptors all left rootsift.append(descrip)
   points all left rootsift.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
for imgs in tqdm(images right bgr):
    kpt = sift.detect(imgs, None)
    kpt, descrip = rootsift.compute(imgs, kpt)
    keypoints_all_right_rootsift.append(kpt)
    descriptors all right rootsift.append(descrip)
    points all right rootsift.append(np.asarray([[p.pt[0], p.pt[1]] for p in kpt]))
100%|
               | 51/51 [02:30<00:00, 2.96s/it]
               50/50 [02:30<00:00, 3.01s/it]
100%|
```

#### In [10]:

```
git clone https://github.com/magicleap/SuperPointPretrainedNetwork.git
```

fatal: destination path 'SuperPointPretrainedNetwork' already exists and is not an empty directory.

### In [11]:

```
weights_path = 'SuperPointPretrainedNetwork/superpoint_v1.pth'
cuda = 'True'
```

## In [12]:

```
def to_kpts(pts,size=1):
    return [cv2.KeyPoint(pt[0],pt[1],size) for pt in pts]
```

#### In [13]:

```
torch.cuda.empty_cache()
class SuperPointNet(nn.Module):
    def __init__(self):
        super(SuperPointNet,self).__init__()
        self.relu = nn.ReLU(inplace=True)
```

```
self.pool = nn.MaxPool2d(kernel_size=2, stride=2)
        c1, c2, c3, c4, c5, d1 = 64, 64, 128, 128, 256, 256
        self.convla = nn.Conv2d(1,c1,kernel size=3,stride=1,padding=1)
        self.conv1b = nn.Conv2d(c1,c1,kernel_size=3,stride=1,padding=1)
        self.conv2a = nn.Conv2d(c1,c2,kernel size=3,stride=1,padding=1)
        self.conv2b = nn.Conv2d(c2,c2,kernel size=3,stride=1,padding=1)
        self.conv3a = nn.Conv2d(c2,c3,kernel size=3,stride=1,padding=1)
        self.conv3b = nn.Conv2d(c3,c3,kernel size=3,stride=1,padding=1)
        self.conv4a = nn.Conv2d(c3,c4,kernel size=3,stride=1,padding=1)
        self.conv4b = nn.Conv2d(c4,c4,kernel size=3,stride=1,padding=1)
        self.convPa = nn.Conv2d(c4,c5,kernel size=3,stride=1,padding=1)
        self.convPb = nn.Conv2d(c5,65,kernel size=1,stride=1,padding=0)
        self.convDa = nn.Conv2d(c4,c5,kernel size=3,stride=1,padding=1)
        self.convDb = nn.Conv2d(c5,d1,kernel size=1,stride=1,padding=0)
    def forward(self,x):
        x = self.relu(self.conv1a(x))
        x = self.relu(self.conv1b(x))
        x = self.pool(x)
        x = self.relu(self.conv2a(x))
        x = self.relu(self.conv2b(x))
        x = self.pool(x)
        x = self.relu(self.conv3a(x))
        x = self.relu(self.conv3b(x))
        x = self.pool(x)
        x = self.relu(self.conv4a(x))
        x = self.relu(self.conv4b(x))
        cPa = self.relu(self.convPa(x))
        semi = self.convPb(cPa)
        cDa = self.relu(self.convDa(x))
        desc = self.convDb(cDa)
        dn = torch.norm(desc, p=2, dim=1)
        desc = desc.div(torch.unsqueeze(dn,1))
        return semi, desc
class SuperPointFrontend(object):
    def init (self, weights path, nms dist, conf thresh, nn thresh, cuda=True):
        self.name = 'SuperPoint'
        self.cuda = cuda
        self.nms dist = nms dist
        self.conf thresh = conf thresh
        self.nn thresh = nn thresh
        self.cell = 8
        self.border remove = 4
        self.net = SuperPointNet()
            self.net.load state dict(torch.load(weights path))
            self.net = self.net.cuda()
        else:
            self.net.load state dict(torch.load(weights path, map location=lambda storage
, loc: storage))
        self.net.eval()
    def nms fast(self,in corners,H,W,dist thresh):
        grid = np.zeros((H,W)).astype(int)
        inds = np.zeros((H,W)).astype(int)
        inds1 = np.argsort(-in corners[2,:])
        corners = in corners[:,inds1]
        rcorners = corners[:2,:].round().astype(int)
        if rcorners.shape[1] == 0:
            return np.zeros((3,0)).astype(int), np.zeros(0).astype(int)
        if rcorners.shape[1] == 1:
            out = np.vstack((rcorners,in corners[2])).reshape(3,1)
            return out, np.zeros((1)).astype(int)
        for i, rc in enumerate(rcorners.T):
            grid[rcorners[1,i],rcorners[0,i]] =1
            inds[rcorners[1,i],rcorners[0,i]] =i
        pad = dist thresh
```

```
grid = np.pad(grid, ((pad, pad), (pad, pad)), mode='constant')
    count = 0
   for i,rc in enumerate(rcorners.T):
        pt = (rc[0]+pad, rc[1]+pad)
        if grid[pt[1], pt[0]] == 1:
            grid[pt[1]-pad:pt[1]+pad+1, pt[0]-pad:pt[0]+pad+1]=0
            grid[pt[1], pt[0]] = -1
            count += 1
    keepy, keepx = np.where(grid==-1)
    keepy, keepx = keepy-pad , keepx-pad
   inds keep = inds[keepy, keepx]
   out = corners[:,inds keep]
   values = out[-1,:]
   inds2 = np.argsort(-values)
   out = out[:,inds2]
   out inds = inds1[inds keep[inds2]]
   return out, out_inds
def run(self,img):
   assert img.ndim == 2
   assert img.dtype == np.float32
   H,W = img.shape[0], img.shape[1]
    inp = img.copy()
   inp = (inp.reshape(1, H, W))
   inp = torch.from numpy(inp)
   inp = torch.autograd.Variable(inp).view(1,1,H,W)
   if self.cuda:
       inp = inp.cuda()
   outs = self.net.forward(inp)
    semi, coarse desc = outs[0], outs[1]
    semi = semi.data.cpu().numpy().squeeze()
   dense = np.exp(semi)
   dense = dense / (np.sum(dense,axis=0)+.00001)
   nodust = dense[:-1,:,:]
   Hc = int(H / self.cell)
   Wc = int(W / self.cell)
   nodust = np.transpose(nodust,[1,2,0])
   heatmap = np.reshape(nodust,[Hc,Wc,self.cell,self.cell])
   heatmap = np.transpose(heatmap, [0, 2, 1, 3])
   heatmap = np.reshape(heatmap,[Hc*self.cell, Wc*self.cell])
   prob map = heatmap/np.sum(np.sum(heatmap))
   return heatmap, coarse desc
def key pt sampling(self,img,heat map,coarse desc,sampled):
   H,W = img.shape[0], img.shape[1]
   xs,ys = np.where(heat_map >= self.conf thresh)
   if len(xs) == 0:
        return np.zeros((3,0)), None, None
   print("Number of pts selected:",len(xs))
   pts = np.zeros((3, len(xs)))
   pts[0,:] = ys
   pts[1,:] = xs
   pts[2,:] = heat map[xs,ys]
   pts, = self.nms fast(pts,H,W,dist thresh=self.nms dist)
   inds = np.argsort(pts[2,:])
   pts = pts[:,inds[::-1]]
   bord = self.border remove
   toremoveW = np.logical or(pts[0,:] < bord, pts[0,:] >= (W-bord))
    toremoveH = np.logical or(pts[1,:] < bord, pts[0,:] >= (H-bord))
   toremove = np.logical_or(toremoveW, toremoveH)
   pts = pts[:,~toremove]
   pts = pts[:,0:sampled]
    D = coarse desc.shape[1]
   if pts.shape[1] == 0:
       desc = np.zeros((D, 0))
```

```
else:
    samp_pts = torch.from_numpy(pts[:2,:].copy())
    samp_pts[0,:] = (samp_pts[0,:] / (float(W)/2.))-1.
    samp_pts[1,:] = (samp_pts[1,:] / (float(W)/2.))-1.
    samp_pts = samp_pts.transpose(0,1).contiguous()
    samp_pts = samp_pts.view(1,1,-1,2)
    samp_pts = samp_pts.float()
    if self.cuda:
        samp_pts = samp_pts.cuda()
    desc = nn.functional.grid_sample(coarse_desc, samp_pts)
    desc = desc.data.cpu().numpy().reshape(D,-1)
    desc /= np.linalg.norm(desc,axis=0)[np.newaxis,:]
return_pts,desc
```

#### In [14]:

Load pre trained network Successfully loaded pretrained network

#### In [17]:

```
keypoint_all_left_superpoint = []
descriptor all_left_superpoint = []
point_all_left_superpoint = []
keypoints all right superpoint = []
descriptors all right superpoint = []
points all right superpoint = []
for ifpth in tqdm(images left):
    heatmap1, coarse desc1 = fe.run(ifpth)
   pts_1, desc_1 = fe.key_pt_sampling(ifpth,heatmap1,coarse_desc1,2000)
    keypoint all left superpoint.append(to kpts(pts 1.T))
   descriptor all left superpoint.append(desc_1.T)
   point all left superpoint.append(pts 1.T)
for rfpth in tqdm(images right):
   heatmap1, coarse_desc1 = fe.run(rfpth)
   pts 1, desc 1 = fe.key pt sampling(rfpth,heatmap1,coarse desc1,2000)
    keypoints all right superpoint.append(to kpts(pts 1.T))
    descriptors all right superpoint.append(desc 1.T)
    points all right superpoint.append(pts 1.T)
 0%|
               | 0/51 [00:00<?, ?it/s]
```

Number of pts selected: 54477

/opt/conda/lib/python3.7/site-packages/torch/nn/functional.py:3385: UserWarning: Default grid\_sample and affine\_grid behavior has changed to align\_corners=False since 1.3.0. Plea se specify align\_corners=True if the old behavior is desired. See the documentation of grid\_sample for details.

```
warnings.warn("Default grid_sample and affine_grid behavior has changed "
2%| | 1/51 [00:01<01:17, 1.55s/it]</pre>
```

Number of pts selected: 64559

```
4%| | 2/51 [00:02<00:48, 1.01it/s]
```

Number of pts selected: 62731

```
6%| | 3/51 [00:02<00:38, 1.26it/s]
```

```
Number of pts selected: 66915
       | 4/51 [00:03<00:33, 1.41it/s]
Number of pts selected: 65977
       | 5/51 [00:03<00:30, 1.51it/s]
10%|
Number of pts selected: 62256
12%| | 6/51 [00:04<00:28, 1.61it/s]
Number of pts selected: 58441
       | 7/51 [00:04<00:25, 1.70it/s]
14%|
Number of pts selected: 52856
      | 8/51 [00:05<00:24, 1.79it/s]
16%|
Number of pts selected: 53728
       | 9/51 [00:05<00:22, 1.85it/s]
18%|
Number of pts selected: 52870
        | 10/51 [00:06<00:21, 1.90it/s]
20%|
Number of pts selected: 48261
22%| | 11/51 [00:06<00:20, 1.97it/s]
Number of pts selected: 53550
24%| | 12/51 [00:07<00:19, 1.98it/s]
Number of pts selected: 53340
25%| | | 13/51 [00:07<00:19, 1.99it/s]
Number of pts selected: 55541
27%| | 14/51 [00:08<00:18, 1.98it/s]
Number of pts selected: 53723
29%| | 15/51 [00:08<00:18, 2.00it/s]
Number of pts selected: 63642
31%| | 16/51 [00:09<00:19, 1.76it/s]
Number of pts selected: 63850
33%| | | 17/51 [00:10<00:19, 1.77it/s]
Number of pts selected: 63381
35%| | 18/51 [00:10<00:18, 1.78it/s]
Number of pts selected: 57585
37%| | 19/51 [00:11<00:17, 1.82it/s]
Number of pts selected: 45309
39%| | 20/51 [00:11<00:16, 1.93it/s]
Number of pts selected: 43137
41%| 21/51 [00:12<00:14, 2.02it/s]
Number of pts selected: 32917
43%| 22/51 [00:12<00:13, 2.18it/s]
Number of pts selected: 36228
45%| | 23/51 [00:12<00:12, 2.27it/s]
```

```
Number of pts selected: 36082
47%| 24/51 [00:13<00:11, 2.35it/s]
Number of pts selected: 35452
          | 25/51 [00:13<00:10, 2.41it/s]
49%|
Number of pts selected: 41594
51%| | 26/51 [00:14<00:10, 2.39it/s]
Number of pts selected: 41845
53%| 27/51 [00:14<00:10, 2.37it/s]
Number of pts selected: 52565
55%| | 28/51 [00:15<00:10, 2.26it/s]
Number of pts selected: 51583
57%| 29/51 [00:15<00:10, 2.18it/s]
Number of pts selected: 53865
59%|
           | 30/51 [00:16<00:09, 2.11it/s]
Number of pts selected: 51580
61%| | 31/51 [00:16<00:09, 2.10it/s]
Number of pts selected: 52497
63%| | 32/51 [00:17<00:09, 2.08it/s]
Number of pts selected: 53351
65%| | 33/51 [00:17<00:08, 2.06it/s]
Number of pts selected: 58937
67%| 34/51 [00:18<00:08, 2.01it/s]
Number of pts selected: 63670
69%| | 35/51 [00:18<00:08, 1.95it/s]
Number of pts selected: 63164
71%| | 36/51 [00:19<00:07, 1.90it/s]
Number of pts selected: 61341
73%| | 37/51 [00:19<00:07, 1.89it/s]
Number of pts selected: 62577
75%| | 38/51 [00:20<00:07, 1.73it/s]
Number of pts selected: 60963
76%| | 39/51 [00:20<00:06, 1.76it/s]
Number of pts selected: 59765
78%| 40/51 [00:21<00:06, 1.79it/s]
Number of pts selected: 59418
80%| 41/51 [00:21<00:05, 1.82it/s]
Number of pts selected: 57060
82%|
     | 42/51 [00:22<00:05, 1.66it/s]
Number of pts selected: 60042
84%| 43/51 [00:23<00:04, 1.60it/s]
```

```
Number of pts selected: 60481
 86%| 44/51 [00:23<00:04, 1.67it/s]
Number of pts selected: 61320
 88%| | 45/51 [00:24<00:03, 1.73it/s]
Number of pts selected: 60846
 90%| | 46/51 [00:24<00:02, 1.77it/s]
Number of pts selected: 57839
 92%| | 47/51 [00:25<00:02, 1.81it/s]
Number of pts selected: 59702
 94%| 48/51 [00:26<00:01, 1.82it/s]
Number of pts selected: 58094
 96%| 49/51 [00:26<00:01, 1.85it/s]
Number of pts selected: 59875
 Number of pts selected: 57318
100%| 51/51 [00:27<00:00, 1.85it/s]
  0%| | 0/50 [00:00<?, ?it/s]
Number of pts selected: 54477
 2%|
            | 1/50 [00:00<00:24, 2.00it/s]
Number of pts selected: 56486
            | 2/50 [00:01<00:24, 1.99it/s]
 4 % |
Number of pts selected: 43862
             | 3/50 [00:01<00:22,
                                2.14it/s]
Number of pts selected: 50000
            | 4/50 [00:01<00:21, 2.15it/s]
 8%|
Number of pts selected: 43516
        | 5/50 [00:02<00:20, 2.21it/s]
10%|
Number of pts selected: 41297
         | 6/50 [00:02<00:19, 2.27it/s]
12%|
Number of pts selected: 42597
         | 7/50 [00:03<00:18, 2.31it/s]
14%|
Number of pts selected: 44806
       | 8/50 [00:03<00:20, 2.06it/s]
16%|
Number of pts selected: 43315
 18%|
            | 9/50 [00:04<00:19, 2.13it/s]
Number of pts selected: 39997
        | 10/50 [00:04<00:17, 2.23it/s]
 20%|
Number of pts selected: 37697
22%|
            | 11/50 [00:04<00:16, 2.32it/s]
Number of pts selected: 41027
```

```
24%| | | 12/50 [00:05<00:16, 2.36it/s]
Number of pts selected: 45908
26%| | 13/50 [00:05<00:15, 2.34it/s]
Number of pts selected: 49188
        | 14/50 [00:06<00:15, 2.30it/s]
28%|
Number of pts selected: 57475
30%| | 15/50 [00:06<00:15, 2.20it/s]
Number of pts selected: 55483
32%| | 16/50 [00:07<00:15, 2.15it/s]
Number of pts selected: 52557
34%| | 17/50 [00:07<00:15, 2.14it/s]
Number of pts selected: 55422
36%| | 18/50 [00:08<00:15, 2.11it/s]
Number of pts selected: 54316
38%| | 19/50 [00:08<00:15, 2.06it/s]
Number of pts selected: 51662
40%| 20/50 [00:09<00:14, 2.08it/s]
Number of pts selected: 50162
42%| 21/50 [00:09<00:13, 2.10it/s]
Number of pts selected: 48664
44%| 22/50 [00:10<00:13, 2.14it/s]
Number of pts selected: 46023
46%| 23/50 [00:10<00:12, 2.19it/s]
Number of pts selected: 48049
48%| 24/50 [00:11<00:11, 2.20it/s]
Number of pts selected: 57650
50%| | 25/50 [00:11<00:11, 2.13it/s]
Number of pts selected: 70799
52%| | 26/50 [00:12<00:12, 1.97it/s]
Number of pts selected: 72440
54%| 27/50 [00:12<00:12, 1.88it/s]
Number of pts selected: 75195
56%| | 28/50 [00:13<00:12, 1.80it/s]
Number of pts selected: 72197
58%| 29/50 [00:13<00:11, 1.77it/s]
Number of pts selected: 66162
60%| | 30/50 [00:14<00:11, 1.73it/s]
Number of pts selected: 59430
62%| | 31/50 [00:15<00:11, 1.70it/s]
Number of pts selected: 61074
```

```
64%| 32/50 [00:15<00:10, 1.75it/s]
Number of pts selected: 50121
             | 33/50 [00:16<00:09,
                                1.85it/sl
66%1
Number of pts selected: 33851
             | 34/50 [00:16<00:07, 2.05it/s]
Number of pts selected: 32768
           | 35/50 [00:16<00:06,
                                 2.21it/s]
Number of pts selected: 36270
2.28it/s1
Number of pts selected: 50163
74%|
           | 37/50 [00:17<00:05,
                                 2.24it/s1
Number of pts selected: 47558
76%|
     | 38/50 [00:18<00:05,
                                2.24it/s]
Number of pts selected: 54703
           | 39/50 [00:18<00:05, 2.16it/s]
Number of pts selected: 60403
80%| 40/50 [00:19<00:04,
                                 2.09it/s]
Number of pts selected: 73839
82%| | 41/50 [00:19<00:04, 1.95it/s]
Number of pts selected: 72110
84%| 42/50 [00:20<00:04,
                                1.86it/sl
Number of pts selected: 70241
86% | 43/50 [00:20<00:03,
                                 1.80it/s]
Number of pts selected: 65699
88% | 44/50 [00:21<00:03,
                                1.78it/s]
Number of pts selected: 63686
90%| 45/50 [00:22<00:02,
                                1.80it/s]
Number of pts selected: 57061
                                1.86it/s]
Number of pts selected: 44654
    | 47/50 [00:23<00:01, 1.97it/s]
94%|
Number of pts selected: 42427
     | 48/50 [00:23<00:00,
                                 2.08it/s]
Number of pts selected: 41848
98% | 49/50 [00:23<00:00,
                                 2.17it/s]
Number of pts selected: 43600
100%| 50/50 [00:24<00:00,
                                 2.06it/s]
In [19]:
num kps superpoint = []
for j in tqdm(keypoint all left superpoint + keypoints all right superpoint):
   num kps superpoint.append(len(j))
```

```
100%| 101/101 [00:00<00:00, 452590.50it/s]
In [ ]:
num kps brisk = []
for j in tqdm(keypoints_all_left_brisk + keypoints_all_right_brisk):
   num kps brisk.append(len(j))
In [ ]:
num kps orb = []
for j in tqdm(keypoints_all_left_orb + keypoints_all_right_orb):
   num kps orb.append(len(j))
In [15]:
num kps fast = []
for j in tqdm(keypoints all left fast + keypoints all right fast):
   num kps fast.append(len(j))
100%| 101/101 [00:00<00:00, 388290.29it/s]
In [ ]:
num kps kaze = []
for j in tqdm(keypoints all left kaze + keypoints all right kaze):
   num kps kaze.append(len(j))
In [16]:
num kps akaze = []
for j in tqdm(keypoints all left akaze + keypoints all right akaze):
    num kps akaze.append(len(j))
100%| | 101/101 [00:00<00:00, 231996.00it/s]
In [15]:
num kps freak = []
for j in tqdm(keypoints_all_left_freak + keypoints all right freak):
   num kps freak.append(len(j))
         | 101/101 [00:00<00:00, 402302.66it/s]
In [ ]:
num kps mser =[]
for j in tqdm(keypoints all left mser + keypoints all right mser):
   num_kps_mser.append(len(j))
In [ ]:
num kps gftt =[]
for j in tqdm(keypoints all left gftt + keypoints all right gftt):
   num kps gftt.append(len(j))
In [ ]:
num kps daisy = []
for j in tqdm(keypoints all left daisy + keypoints all right daisy):
   num_kps_daisy.append(j)
In [ ]:
num kps star = []
for j in tqdm(keypoints all left star + keypoints all right star):
```

```
num kps star.append(len(j))
In [ ]:
num kps sift = []
for j in tqdm(keypoints all left sift + keypoints all right sift):
    num kps sift.append(len(j))
In [ ]:
num kps surf = []
for j in tqdm(keypoints all left surf + keypoints all right surf):
   num kps surf.append(len(j))
In [ ]:
num kps surfsift = []
for j in tqdm(keypoints all left surfsift + keypoints all right surfsift):
   num kps surfsift.append(len(j))
In [16]:
num kps agast = []
for j in tqdm(keypoints_all_left_agast + keypoints_all_right agast):
    num kps agast.append(len(j))
          | 101/101 [00:00<00:00, 422779.15it/s]
In [16]:
def compute homography fast(matched pts1, matched pts2,thresh=4):
    #matched pts1 = cv2.KeyPoint convert(matched kp1)
    #matched pts2 = cv2.KeyPoint convert(matched kp2)
    # Estimate the homography between the matches using RANSAC
    H, inliers = cv2.findHomography(matched pts1, matched pts2, cv2.RANSAC, ransacReprojTh
reshold =thresh)
    inliers = inliers.flatten()
    return H, inliers
In [17]:
def get Hmatrix(imgs,keypts,pts,descripts,ratio=0.8,thresh=4,disp=False):
    FLANN INDEX KDTREE = 2
    index params = dict(algorithm=FLANN INDEX KDTREE, trees=5)
    search params = dict(checks=50)
    flann = cv2.FlannBasedMatcher(index params, search params)
    #flann = cv2.BFMatcher()
    lff1 = np.float32(descripts[0])
    lff = np.float32(descripts[1])
    matches lf1 lf = flann.knnMatch(lff1, lff, k=2)
    print("\nNumber of matches", len(matches_lf1_lf))
   matches 4 = []
    ratio = ratio
    # loop over the raw matches
    for m in matches lf1 lf:
        # ensure the distance is within a certain ratio of each
        # other (i.e. Lowe's ratio test)
        if len(m) == 2 and m[0].distance < m[1].distance * ratio:</pre>
            matches 4.append(m[0])
    print("Number of matches After Lowe's Ratio",len(matches 4))
    matches idx = np.array([m.queryIdx for m in matches 4])
    imm1 pts = np.array([keypts[0][idx].pt for idx in matches idx])
    matche idx = np.array([m.trainIdx for m in matches 4])
    imm2 pts = np.array([keypts[1][idx].pt for idx in matche idx])
    111
    # Estimate homography 1
    #Compute H1
    # Estimate homography 1
    #Compute H1
```

```
imm1_pts=np.empty((len(matches_4),2))
    imm2_pts=np.empty((len(matches_4),2))
    for i in range(0,len(matches 4)):
    m = matches 4[i]
    (a x, a y) = keypts[0][m.queryIdx].pt
    (b \ x, \ b \ y) = keypts[1][m.trainIdx].pt
    imm1 pts[i] = (a x, a y)
    imm2 pts[i] = (b x, b y)
    H=compute Homography(imm1 pts,imm2 pts)
    #Robustly estimate Homography 1 using RANSAC
    Hn, best inliers=RANSAC alg(keypts[0], keypts[1], matches 4, nRANSAC=1000, RANSACthre
sh=6)
    , ,
    Hn, inliers = compute homography fast(imm1 pts, imm2 pts)
    inlier matchset = np.array(matches 4)[inliers.astype(bool)].tolist()
    print("Number of Robust matches", len(inlier matchset))
    print("\n")
    111
    if len(inlier_matchset) < 50:</pre>
        matches_4 = []
        ratio = 0.67
        # loop over the raw matches
        for m in matches 1f1 1f:
           # ensure the distance is within a certain ratio of each
           # other (i.e. Lowe's ratio test)
           if len(m) == 2 and m[0].distance < m[1].distance * ratio:</pre>
           #matches 1.append((m[0].trainIdx, m[0].queryIdx))
           matches 4.append(m[0])
        print("Number of matches After Lowe's Ratio New", len(matches 4))
        matches idx = np.array([m.queryIdx for m in matches 4])
        imm1 pts = np.array([keypts[0][idx].pt for idx in matches idx])
        matches idx = np.array([m.trainIdx for m in matches 4])
        imm2 pts = np.array([keypts[1][idx].pt for idx in matches idx])
        Hn,inliers = compute_homography_fast_other(imm1_pts,imm2_pts)
        inlier matchset = np.array(matches 4)[inliers.astype(bool)].tolist()
        print("Number of Robust matches New",len(inlier matchset))
        print("\n")
    #H=compute Homography(imm1 pts,imm2 pts)
    #Robustly estimate Homography 1 using RANSAC
    \#Hn=RANSAC\_alg(keypts[0], keypts[1], matches\_4, nRANSAC=1500, RANSACthresh=6)
    #global inlier matchset
    if disp==True:
        dispimg1=cv2.drawMatches(imgs[0], keypts[0], imgs[1], keypts[1], inlier matcheet
, None, flags=2)
        displayplot(dispimg1, 'Robust Matching between Reference Image and Right Image ')
    return Hn/Hn[2,2], len(matches lf1 lf), len(inlier matchset)
In [18]:
```

```
from functools import partial
from tqdm import tqdm
tqdm = partial(tqdm, position=0, leave=True)
```

```
H_left_brisk = []
H_right_brisk = []
num_matches_brisk = []
num_good_matches_brisk = []

for j in tqdm(range(len(images_left))):
    if j==len(images_left)-1:
        break

    H_a,matches,gd_matches = get_Hmatrix(images_left_bgr[j:j+2][::-1],keypoints_all_left_brisk[j:j+2][::-1])
    H_left_brisk.append(H_a)
```

```
H = []
H right orb = []
num matches orb = []
num_good_matches_orb = []
for j in tqdm(range(len(images_left))):
              if j==len(images left)-1:
                           break
              H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
_orb[j:j+2][::-1],points_all_left_orb[j:j+2][::-1],descriptors_all_left_orb[j:j+2][::-1]
              H_left_orb.append(H_a)
              num matches orb.append(matches)
              num good matches orb.append(gd matches)
for j in tqdm(range(len(images right))):
              if j==len(images right)-1:
              H_a, matches, gd_matches = get_Hmatrix(images_right_bgr[j:j+2][::-1], keypoints all rig
\label{lem:ht_orb} $$ ht_orb[j:j+2][::-1]$, points_all_right_orb[j:j+2][::-1]$, descriptors_all_right_orb[j:j+2][::-1]$, points_all_right_orb[j:j+2][::-1]$, and the property of the propert
              H_right_orb.append(H_a)
              num matches orb.append(matches)
              num good matches orb.append(gd matches)
```

#### In [20]:

```
H left akaze = []
H_right_akaze = []
num_matches_akaze = []
num_good_matches_akaze = []
for j in tqdm(range(len(images left))):
    if j==len(images_left)-1:
    H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
akaze[j:j+2][::-1],points all left akaze[j:j+2][::-1],descriptors all left akaze[j:j+2]
[::-1])
    H left akaze.append(H a)
    num_matches_akaze.append(matches)
    num_good_matches_akaze.append(gd_matches)
for j in tqdm(range(len(images right))):
   if j==len(images right)-1:
       break
    H a, matches, gd matches = get Hmatrix(images right bgr[j:j+2][::-1], keypoints all rig
ht_akaze[j:j+2][::-1],points_all_right_akaze[j:j+2][::-1],descriptors_all_right_akaze[j:
j+2][::-1])
    H right akaze.append(H a)
```

```
num_matches_akaze.append(matches)
    num_good_matches_akaze.append(gd_matches)
  2%|
               | 1/51 [00:01<00:53, 1.06s/it]
Number of matches 20465
Number of matches After Lowe's Ratio 2247
Number of Robust matches 1631
  4%|
               | 2/51 [00:02<01:00, 1.24s/it]
Number of matches 19280
Number of matches After Lowe's Ratio 2600
Number of Robust matches 1667
  6%|
               | 3/51 [00:03<01:00, 1.27s/it]
Number of matches 21349
Number of matches After Lowe's Ratio 2768
Number of Robust matches 1957
  8%|
               | 4/51 [00:05<01:06, 1.42s/it]
Number of matches 21345
Number of matches After Lowe's Ratio 4124
Number of Robust matches 3132
 10%|
               | 5/51 [00:06<01:06, 1.45s/it]
Number of matches 20541
Number of matches After Lowe's Ratio 3174
Number of Robust matches 2271
 12%|
               | 6/51 [00:08<01:06, 1.47s/it]
Number of matches 19544
Number of matches After Lowe's Ratio 3406
Number of Robust matches 2447
 14%|
               | 7/51 [00:09<01:04, 1.46s/it]
Number of matches 19557
Number of matches After Lowe's Ratio 3165
Number of Robust matches 2512
 16%|
               | 8/51 [00:11<01:01, 1.42s/it]
Number of matches 19398
Number of matches After Lowe's Ratio 4086
Number of Robust matches 3101
 18%|
               | 9/51 [00:12<01:00, 1.43s/it]
Number of matches 19838
Number of matches After Lowe's Ratio 4548
Number of Robust matches 3222
```

20%1

| 10/51 [00:13<00:57, 1.41s/it]

Number of matches 19744 Number of matches After Lowe's Ratio 4021 Number of Robust matches 3321 22%| | 11/51 [00:15<00:55, 1.40s/it] Number of matches 20624 Number of matches After Lowe's Ratio 3423 Number of Robust matches 2348 24%| | 12/51 [00:16<00:54, 1.41s/it] Number of matches 19950 Number of matches After Lowe's Ratio 3061 Number of Robust matches 2221 | 13/51 [00:18<00:54, 1.44s/it] 25%| Number of matches 20566 Number of matches After Lowe's Ratio 2810 Number of Robust matches 1688 27%| | 14/51 [00:20<00:56, 1.53s/it] Number of matches 20559 Number of matches After Lowe's Ratio 2376 Number of Robust matches 1599 29%| | 15/51 [00:21<00:54, 1.50s/it] Number of matches 24258 Number of matches After Lowe's Ratio 2050 Number of Robust matches 1134 31%| | 16/51 [00:23<00:54, 1.57s/it] Number of matches 20958 Number of matches After Lowe's Ratio 1793 Number of Robust matches 754 | 17/51 [00:25<00:58, 1.71s/it] 33%| Number of matches 22246 Number of matches After Lowe's Ratio 2174 Number of Robust matches 1102

## 35%| | | 18/51 [00:26<00:55, 1.69s/it]

Number of matches 20947

Number of matches After Lowe's Ratio 2166

Number of Robust matches 943

## 37%| | | 19/51 [00:28<00:52, 1.64s/it]

Number of matches 24081

Number of matches After Lowe's Ratio 1522

Number of Robust matches 607

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39%| 20/51 [00:30<00:52, 1.68s/it]

Number of matches 22618

Number of matches After Lowe's Ratio 1557

Number of Robust matches 727

41%| | 21/51 [00:31<00:51, 1.72s/it]

Number of matches 23539

Number of matches After Lowe's Ratio 954

Number of Robust matches 328

Number of matches 19832

Number of matches After Lowe's Ratio 476

Number of Robust matches 73

Number of matches 19393

Number of matches After Lowe's Ratio 1889

Number of Robust matches 1071

47%| | 24/51 [00:36<00:41, 1.52s/it]

Number of matches 17976

Number of matches After Lowe's Ratio 2000

Number of Robust matches 1191

49%| | 25/51 [00:37<00:36, 1.42s/it]

Number of matches 19408

Number of matches After Lowe's Ratio 2052

Number of Robust matches 1304

51%| | 26/51 [00:39<00:35, 1.44s/it]

Number of matches 23039

Number of matches After Lowe's Ratio 2408

Number of Robust matches 1370

53%| | 27/51 [00:40<00:36, 1.52s/it]

Number of matches 26557

Number of matches After Lowe's Ratio 2007

Number of Robust matches 908

55%| | 28/51 [00:43<00:40, 1.74s/it]

Number of matches 28674

Number of matches After Lowe's Ratio 2370

Number of Robust matches 800

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```
Number of matches After Lowe's Ratio 2276
Number of Robust matches 1089
 59%|
              | 30/51 [00:47<00:39, 1.88s/it]
Number of matches 22062
Number of matches After Lowe's Ratio 2516
Number of Robust matches 1233
             | 31/51 [00:48<00:35, 1.79s/it]
Number of matches 20521
Number of matches After Lowe's Ratio 2763
Number of Robust matches 1726
 63%|
          | 32/51 [00:50<00:32, 1.69s/it]
Number of matches 19126
Number of matches After Lowe's Ratio 2912
Number of Robust matches 1836
            | 33/51 [00:51<00:28, 1.58s/it]
 65%|
Number of matches 20186
Number of matches After Lowe's Ratio 3556
Number of Robust matches 2680
 67%| | 34/51 [00:53<00:28, 1.69s/it]
Number of matches 21213
Number of matches After Lowe's Ratio 3206
Number of Robust matches 2033
          | 35/51 [00:54<00:26, 1.64s/it]
Number of matches 21932
Number of matches After Lowe's Ratio 3698
Number of Robust matches 2462
 71%|
             | 36/51 [00:57<00:27, 1.82s/it]
Number of matches 21264
Number of matches After Lowe's Ratio 3861
Number of Robust matches 2570
     | 37/51 [00:58<00:24, 1.72s/it]
 73%|
Number of matches 20833
Number of matches After Lowe's Ratio 3430
Number of Robust matches 2329
             | 38/51 [01:00<00:21, 1.63s/it]
 75%|
Number of matches 18699
Number of matches After Lowe's Ratio 2091
```

| ∠9/31 [UU:43<UU:40, 1.038/16]

Number of matches 25251

## 76%| 39/51 [01:01<00:18, 1.57s/it]

Number of matches 17733

Number of matches After Lowe's Ratio 3728

Number of Robust matches 2775

### 78%| 40/51 [01:02<00:16, 1.47s/it]

Number of matches 18293

Number of matches After Lowe's Ratio 3590

Number of Robust matches 3077

## 80%| 41/51 [01:04<00:14, 1.48s/it]

Number of matches 16473

Number of matches After Lowe's Ratio 2100

Number of Robust matches 1614

## 82%| 42/51 [01:05<00:12, 1.38s/it]

Number of matches 17759

Number of matches After Lowe's Ratio 2215

Number of Robust matches 1616

### 84%| 43/51 [01:06<00:10, 1.33s/it]

Number of matches 18253

Number of matches After Lowe's Ratio 3005

Number of Robust matches 2313

### 86%| 44/51 [01:08<00:09, 1.36s/it]

Number of matches 18717

Number of matches After Lowe's Ratio 1934

Number of Robust matches 1140

### 88%| 45/51 [01:09<00:08, 1.35s/it]

Number of matches 18943

Number of matches After Lowe's Ratio 2377

Number of Robust matches 1691

## 90%| 46/51 [01:10<00:06, 1.33s/it]

Number of matches 18446

Number of matches After Lowe's Ratio 2212

Number of Robust matches 1328

### 92%| 47/51 [01:11<00:05, 1.33s/it]

Number of matches 19154

Number of matches After Lowe's Ratio 2731

Number of Robust matches 1355

```
| 48/51 [01:13<00:03, 1.33s/it]
Number of matches 20674
Number of matches After Lowe's Ratio 1805
Number of Robust matches 779
          | 49/51 [01:15<00:02, 1.49s/it]
 96%|
Number of matches 20317
Number of matches After Lowe's Ratio 2136
Number of Robust matches 925
 98%|
              | 50/51 [01:16<00:01, 1.53s/it]
  0%|
               | 0/50 [00:00<?, ?it/s]
Number of matches 17535
Number of matches After Lowe's Ratio 738
Number of Robust matches 196
  2%|
               | 1/50 [00:01<00:53, 1.10s/it]
Number of matches 21469
Number of matches After Lowe's Ratio 1232
Number of Robust matches 704
               | 2/50 [00:02<01:01, 1.29s/it]
  4%|
Number of matches 15748
Number of matches After Lowe's Ratio 1871
Number of Robust matches 1189
  6%|
               | 3/50 [00:03<00:55, 1.18s/it]
Number of matches 20428
Number of matches After Lowe's Ratio 1277
Number of Robust matches 654
  8%|
               | 4/50 [00:05<01:00, 1.32s/it]
Number of matches 19049
Number of matches After Lowe's Ratio 2520
Number of Robust matches 1507
 10%|
               | 5/50 [00:06<00:58, 1.30s/it]
Number of matches 18754
Number of matches After Lowe's Ratio 2341
Number of Robust matches 1155
 12%|
               | 6/50 [00:07<00:56, 1.28s/it]
Number of matches 18110
Number of matches After Lowe's Ratio 2267
Number of Robust matches 1154
               | 7/50 [00:09<00:57, 1.34s/it]
 14%|
Number of matches 18547
```

Number of matches After Lowe's Ratio 2210 Number of Robust matches 1399 16%| | 8/50 [00:10<00:57, 1.37s/it] Number of matches 21720 Number of matches After Lowe's Ratio 493 Number of Robust matches 34 18%| | 9/50 [00:12<01:03, 1.56s/it] Number of matches 16167 Number of matches After Lowe's Ratio 826 Number of Robust matches 282 20%| | 10/50 [00:13<00:56, 1.41s/it] Number of matches 16819 Number of matches After Lowe's Ratio 948 Number of Robust matches 421 22%| | 11/50 [00:14<00:51, 1.33s/it] Number of matches 18233 Number of matches After Lowe's Ratio 1422 Number of Robust matches 824 24%| | 12/50 [00:15<00:49, 1.30s/it] Number of matches 20771 Number of matches After Lowe's Ratio 2613 Number of Robust matches 1736

### 26%| | 13/50 [00:17<00:50, 1.36s/it]

Number of matches 18297

Number of matches After Lowe's Ratio 2757

Number of Robust matches 2066

## 28%| | 14/50 [00:18<00:47, 1.32s/it]

Number of matches 15660

Number of matches After Lowe's Ratio 1374

Number of Robust matches 863

## 30%| | | 15/50 [00:19<00:44, 1.28s/it]

Number of matches 19968

Number of matches After Lowe's Ratio 623

Number of Robust matches 218

# 32%| | 16/50 [00:21<00:44, 1.31s/it]

Number of matches 15728

Number of matches After Lowe's Ratio 2079

Number of Robust matches 1414

| 17/50 [00:22<00:40, 1.24s/it] Number of matches 21692 Number of matches After Lowe's Ratio 1834 Number of Robust matches 1234 36%| | 18/50 [00:23<00:42, 1.33s/it] Number of matches 21865 Number of matches After Lowe's Ratio 3695 Number of Robust matches 2800 38%| | 19/50 [00:25<00:44, 1.43s/it] Number of matches 21455 Number of matches After Lowe's Ratio 5039 Number of Robust matches 3608 | 20/50 [00:27<00:43, 1.45s/it] 40%| Number of matches 19571 Number of matches After Lowe's Ratio 4118 Number of Robust matches 3154 42%| | 21/50 [00:28<00:41, 1.42s/it] Number of matches 20134 Number of matches After Lowe's Ratio 3983 Number of Robust matches 2691 44%| | 22/50 [00:29<00:40, 1.45s/it] Number of matches 21099 Number of matches After Lowe's Ratio 2882 Number of Robust matches 2074 | 23/50 [00:31<00:41, 1.55s/it] 46%| Number of matches 22136 Number of matches After Lowe's Ratio 3600 Number of Robust matches 2639 48%| | 24/50 [00:33<00:40, 1.56s/it] Number of matches 23198 Number of matches After Lowe's Ratio 2987 Number of Robust matches 2021 | 25/50 [00:34<00:40, 1.61s/it] 50%| Number of matches 24310 Number of matches After Lowe's Ratio 2984 Number of Robust matches 1573

52%|

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| 26/50 [00:36<00:41, 1.72s/it]

Number of matches After Lowe's Ratio 3148 Number of Robust matches 1698

54%| | 27/50 [00:38<00:39, 1.74s/it]

Number of matches 22984

Number of matches After Lowe's Ratio 3152

Number of Robust matches 1662

56%| 28/50 [00:40<00:37, 1.72s/it]

Number of matches 21716

Number of matches After Lowe's Ratio 2724

Number of Robust matches 1311

58%| | 29/50 [00:42<00:37, 1.77s/it]

Number of matches 22411

Number of matches After Lowe's Ratio 3286

Number of Robust matches 1623

60%| | 30/50 [00:44<00:38, 1.93s/it]

Number of matches 20504

Number of matches After Lowe's Ratio 2743

Number of Robust matches 1169

62%| 31/50 [00:46<00:33, 1.78s/it]

Number of matches 20204

Number of matches After Lowe's Ratio 2642

Number of Robust matches 1030

64%| | 32/50 [00:47<00:30, 1.68s/it]

Number of matches 20233

Number of matches After Lowe's Ratio 2172

Number of Robust matches 1156

66%| | 33/50 [00:49<00:27, 1.63s/it]

Number of matches 27287

Number of matches After Lowe's Ratio 797

Number of Robust matches 203

68%| | 34/50 [00:51<00:29, 1.81s/it]

Number of matches 25609

Number of matches After Lowe's Ratio 1247

Number of Robust matches 385

70%| | | 35/50 [00:53<00:29, 1.97s/it]

Number of matches 29338

Number of matches After Lowe's Ratio 481

Number of Robust matches 5

| 36/50 [00:55<00:29, 2.08s/it] 72%| Number of matches 24561 Number of matches After Lowe's Ratio 1198 Number of Robust matches 397 74%| 37/50 [00:57<00:26, 2.01s/it] Number of matches 22164 Number of matches After Lowe's Ratio 2260 Number of Robust matches 1073

| 38/50 [00:59<00:23, 1.93s/it]

Number of matches 20348 Number of matches After Lowe's Ratio 2259 Number of Robust matches 973

| 39/50 [01:00<00:19, 1.78s/it] 78%|

Number of matches 19519 Number of matches After Lowe's Ratio 1972 Number of Robust matches 849

| 40/50 [01:02<00:16, 1.66s/it] 80%|

Number of matches 20911 Number of matches After Lowe's Ratio 2024 Number of Robust matches 729

82%| 41/50 [01:03<00:15, 1.67s/it]

Number of matches 20565 Number of matches After Lowe's Ratio 1760 Number of Robust matches 698

84%| 42/50 [01:05<00:13, 1.66s/it]

Number of matches 20347 Number of matches After Lowe's Ratio 3746 Number of Robust matches 1570

| 43/50 [01:07<00:11, 1.61s/it]

Number of matches 22441 Number of matches After Lowe's Ratio 1810 Number of Robust matches 818

88%| 44/50 [01:08<00:09, 1.61s/it]

Number of matches 21870 Number of matches After Lowe's Ratio 3146 Number of Robust matches 1725

90%| 45/50 [01:10<00:07, 1.58s/it]

```
Number of matches 20671
Number of matches After Lowe's Ratio 2296
Number of Robust matches 1293
              | 46/50 [01:11<00:06,
                                     1.53s/it]
Number of matches 18732
Number of matches After Lowe's Ratio 2371
Number of Robust matches 1514
              | 47/50 [01:13<00:04,
 94%|
                                     1.50s/it]
Number of matches 18770
Number of matches After Lowe's Ratio 1822
Number of Robust matches 1323
          | 48/50 [01:14<00:02, 1.44s/it]
Number of matches 18471
Number of matches After Lowe's Ratio 1874
Number of Robust matches 1217
             | 49/50 [01:15<00:01,
                                     1.55s/it]
 98%|
Number of matches 17991
Number of matches After Lowe's Ratio 2162
Number of Robust matches 1552
In [ ]:
H left kaze = []
H right kaze = []
num matches kaze = []
num good matches kaze = []
for j in tqdm(range(len(images left))):
    if j==len(images left)-1:
        break
    H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
 _kaze[j:j+2][::-1],points_all_left_kaze[j:j+2][::-1],descriptors_all_left_kaze[j:j+2][::
-1])
    H left kaze.append(H a)
    num_matches_kaze.append(matches)
    num good matches kaze.append(gd matches)
for j in tqdm(range(len(images right))):
    if j==len(images_right)-1:
    H a, matches, gd matches = get Hmatrix(images right bgr[j:j+2][::-1], keypoints all rig
ht kaze[j:j+2][::-1], points all right kaze[j:j+2][::-1], descriptors all right kaze[j:j+2
][::-1])
    H right kaze.append(H a)
    num matches kaze.append(matches)
    num good matches kaze.append(gd matches)
```

In [19]:

H\_left\_freak = []
H right freak = []

```
num_matches_freak = []
num good matches freak = []
for j in tqdm(range(len(images left))):
    if j==len(images left)-1:
       break
    H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
 freak[j:j+2][::-1], points all left freak[j:j+2][::-1], descriptors all left freak[j:j+2]
    H left freak.append(H a)
    num matches freak.append(matches)
    num good matches freak.append(gd matches)
for j in tqdm(range(len(images right))):
    if j==len(images right)-1:
        break
    H_a, matches, gd_matches = get_Hmatrix(images_right_bgr[j:j+2][::-1], keypoints_all_rig
ht freak[j:j+2][::-1], points all right freak[j:j+2][::-1], descriptors all right freak[j:
j+2][::-1])
    H right freak.append(H a)
    num matches freak.append(matches)
    num good matches freak.append(gd matches)
  2%|
               | 1/51 [00:02<01:51, 2.23s/it]
Number of matches 30963
Number of matches After Lowe's Ratio 1989
Number of Robust matches 1063
  4%|
               | 2/51 [00:04<01:59,
                                     2.45s/it]
Number of matches 30334
Number of matches After Lowe's Ratio 1980
Number of Robust matches 1153
  6%|
               | 3/51 [00:08<02:14, 2.80s/it]
Number of matches 35225
Number of matches After Lowe's Ratio 2066
Number of Robust matches 956
  8%|
               | 4/51 [00:11<02:25,
                                     3.09s/it]
Number of matches 34588
Number of matches After Lowe's Ratio 2630
Number of Robust matches 1743
 10%|
               | 5/51 [00:14<02:20,
                                     3.04s/it]
Number of matches 32541
Number of matches After Lowe's Ratio 2201
Number of Robust matches 1205
 12%|
               | 6/51 [00:17<02:11, 2.92s/it]
Number of matches 28721
Number of matches After Lowe's Ratio 2114
Number of Robust matches 1159
```

14%1

1 7/51 [00·19<02·02 2 79s/i+1

| 1/01 [00.13.02.02| 2.130/10] Number of matches 30225 Number of matches After Lowe's Ratio 2198 Number of Robust matches 1272 16%| | 8/51 [00:22<02:00, 2.80s/it] Number of matches 30991 Number of matches After Lowe's Ratio 2537 Number of Robust matches 1528 18%| | 9/51 [00:25<01:54, 2.72s/it] Number of matches 29265 Number of matches After Lowe's Ratio 2787 Number of Robust matches 1671 20%| | 10/51 [00:27<01:49, 2.66s/it] Number of matches 29356 Number of matches After Lowe's Ratio 2183 Number of Robust matches 1273 | 11/51 [00:30<01:44, 2.60s/it] 22%| Number of matches 30010 Number of matches After Lowe's Ratio 1764 Number of Robust matches 821 24%| | 12/51 [00:32<01:44, 2.67s/it] Number of matches 29570 Number of matches After Lowe's Ratio 1823 Number of Robust matches 828 | 13/51 [00:35<01:41, 2.68s/it] 25%| Number of matches 30831 Number of matches After Lowe's Ratio 2044 Number of Robust matches 1017 27%| | 14/51 [00:38<01:43, 2.81s/it] Number of matches 33305 Number of matches After Lowe's Ratio 1758 Number of Robust matches 811 29%| | 15/51 [00:41<01:45, 2.93s/it] Number of matches 41880 Number of matches After Lowe's Ratio 1803 Number of Robust matches 608 | 16/51 [00:45<01:53, 3.24s/it] 31%| Number of matches 35904 Number of matches After Lowe's Ratio 1755 M.....bas of Dalasse matches E40

## 33%| | 17/51 [00:48<01:47, 3.18s/it]

Number of matches 30389

Number of matches After Lowe's Ratio 1716

Number of Robust matches 688

### 35%| | 18/51 [00:51<01:39, 3.02s/it]

Number of matches 28704

Number of matches After Lowe's Ratio 1403

Number of Robust matches 359

# 37%| | 19/51 [00:54<01:32, 2.90s/it]

Number of matches 31542

Number of matches After Lowe's Ratio 991

Number of Robust matches 252

## 39%| | 20/51 [00:56<01:27, 2.83s/it]

Number of matches 31853

Number of matches After Lowe's Ratio 1369

Number of Robust matches 433

#### 41%| | 21/51 [00:59<01:24, 2.83s/it]

Number of matches 32825

Number of matches After Lowe's Ratio 866

Number of Robust matches 126

## 43%| | 22/51 [01:02<01:20, 2.77s/it]

Number of matches 22605

Number of matches After Lowe's Ratio 512

Number of Robust matches 28

### 45%| | 23/51 [01:04<01:09, 2.47s/it]

Number of matches 23139

Number of matches After Lowe's Ratio 1334

Number of Robust matches 431

#### 47%| | 24/51 [01:06<01:02, 2.31s/it]

Number of matches 19638

Number of matches After Lowe's Ratio 1239

Number of Robust matches 502

#### 49%| 25/51 [01:07<00:54, 2.11s/it]

Number of matches 24280

Number of matches After Lowe's Ratio 1330

Number of Robust matches 473

Number of matches 29286 Number of matches After Lowe's Ratio 1620 Number of Robust matches 547 | 27/51 [01:12<00:56, 2.36s/it] 53%| Number of matches 41948 Number of matches After Lowe's Ratio 1624 Number of Robust matches 443 | 28/51 [01:17<01:08, 3.00s/it] 55%| Number of matches 45777 Number of matches After Lowe's Ratio 2082 Number of Robust matches 563 57%| | 29/51 [01:21<01:14, 3.38s/it] Number of matches 41498 Number of matches After Lowe's Ratio 1897 Number of Robust matches 539 59%| | 30/51 [01:25<01:13, 3.49s/it] Number of matches 32765 Number of matches After Lowe's Ratio 1963 Number of Robust matches 683 | 31/51 [01:28<01:07, 3.35s/it] 61%| Number of matches 30811 Number of matches After Lowe's Ratio 2127 Number of Robust matches 1067 | 32/51 [01:30<00:58, 3.10s/it] 63%| Number of matches 28921 Number of matches After Lowe's Ratio 2084 Number of Robust matches 967 | 33/51 [01:33<00:52, 2.92s/it] Number of matches 28541 Number of matches After Lowe's Ratio 2300 Number of Robust matches 1337 67%| | 34/51 [01:35<00:47, 2.78s/it] Number of matches 34315 Number of matches After Lowe's Ratio 2273 Number of Robust matches 1125 69%| | 35/51 [01:39<00:46, 2.93s/it]

| 26/51 [01:09<00:54, 2.16s/it]

Number of matches 37159

Number of matches After Lowe's Ratio 2701

# 71%| | 36/51 [01:43<00:48, 3.26s/it]

Number of matches 35439

Number of matches After Lowe's Ratio 2474

Number of Robust matches 1151

### 73%| 37/51 [01:46<00:44, 3.21s/it]

Number of matches 36939

Number of matches After Lowe's Ratio 2565

Number of Robust matches 1078

# 

Number of matches 30760

Number of matches After Lowe's Ratio 1669

Number of Robust matches 747

### 76%| 39/51 [01:52<00:37, 3.09s/it]

Number of matches 29514

Number of matches After Lowe's Ratio 2856

Number of Robust matches 1773

# 78%| 40/51 [01:54<00:31, 2.87s/it]

Number of matches 28402

Number of matches After Lowe's Ratio 2520

Number of Robust matches 1533

### 80%| 41/51 [01:56<00:26, 2.68s/it]

Number of matches 25855

Number of matches After Lowe's Ratio 1488

Number of Robust matches 705

# 82%| 42/51 [01:59<00:22, 2.53s/it]

Number of matches 25442

Number of matches After Lowe's Ratio 1541

Number of Robust matches 761

# 84%| | 43/51 [02:01<00:19, 2.44s/it]

Number of matches 25540

Number of matches After Lowe's Ratio 1967

Number of Robust matches 1047

### 86%| 44/51 [02:03<00:16, 2.34s/it]

Number of matches 31109

Number of matches After Lowe's Ratio 1914

```
| 45/51 [02:05<00:14, 2.39s/it]
Number of matches 25420
Number of matches After Lowe's Ratio 1734
Number of Robust matches 1047
 90%|
        | 46/51 [02:08<00:11, 2.34s/it]
Number of matches 27131
Number of matches After Lowe's Ratio 1672
Number of Robust matches 570
         | 47/51 [02:10<00:09, 2.36s/it]
 92%|
Number of matches 30777
Number of matches After Lowe's Ratio 2582
Number of Robust matches 950
 94%|
         | 48/51 [02:13<00:07, 2.47s/it]
Number of matches 31215
Number of matches After Lowe's Ratio 1673
Number of Robust matches 530
           | 49/51 [02:16<00:05,
                                    2.73s/it]
Number of matches 34016
Number of matches After Lowe's Ratio 2530
Number of Robust matches 749
 98%|
              | 50/51 [02:19<00:02, 2.79s/it]
  0%|
              | 0/50 [00:00<?, ?it/s]
Number of matches 23270
Number of matches After Lowe's Ratio 866
Number of Robust matches 138
 2%|
              | 1/50 [00:02<01:38, 2.00s/it]
Number of matches 28885
Number of matches After Lowe's Ratio 1186
Number of Robust matches 521
  4% |
              | 2/50 [00:04<01:54, 2.38s/it]
Number of matches 20799
Number of matches After Lowe's Ratio 1332
Number of Robust matches 692
  6%|
               | 3/50 [00:06<01:37, 2.07s/it]
Number of matches 29762
Number of matches After Lowe's Ratio 1188
Number of Robust matches 376
  8%|
              | 4/50 [00:08<01:41, 2.20s/it]
Number of matches 24534
```

NUMBER OF MUCCINOS 21001 Number of matches After Lowe's Ratio 1507 Number of Robust matches 709 10%| | 5/50 [00:10<01:34, 2.11s/it] Number of matches 26179 Number of matches After Lowe's Ratio 1624 Number of Robust matches 524 12%| | 6/50 [00:12<01:33, 2.13s/it] Number of matches 21791 Number of matches After Lowe's Ratio 1331 Number of Robust matches 501 14%| | 7/50 [00:14<01:29, 2.07s/it] Number of matches 23985 Number of matches After Lowe's Ratio 1338 Number of Robust matches 579 16%| | 8/50 [00:16<01:25, 2.03s/it] Number of matches 29091 Number of matches After Lowe's Ratio 681 Number of Robust matches 8 18%| | 9/50 [00:19<01:26, 2.11s/it] Number of matches 23038 Number of matches After Lowe's Ratio 816 Number of Robust matches 185 20%| | 10/50 [00:20<01:21, 2.05s/it] Number of matches 21727 Number of matches After Lowe's Ratio 669 Number of Robust matches 167 22%| | 11/50 [00:22<01:15, 1.94s/it] Number of matches 23257 Number of matches After Lowe's Ratio 889 Number of Robust matches 253 24%| | 12/50 [00:24<01:16, 2.02s/it] Number of matches 33002 Number of matches After Lowe's Ratio 1687 Number of Robust matches 830 26%| | 13/50 [00:28<01:30, 2.45s/it] Number of matches 26873 Number of matches After Lowe's Ratio 1814

28%| | 14/50 [00:30<01:24, 2.33s/it] Number of matches 24439 Number of matches After Lowe's Ratio 1101 Number of Robust matches 527 30%| | 15/50 [00:32<01:16, 2.20s/it] Number of matches 22762 Number of matches After Lowe's Ratio 632 Number of Robust matches 156 32%| | 16/50 [00:33<01:09, 2.04s/it] Number of matches 19743 Number of matches After Lowe's Ratio 1460 Number of Robust matches 909 34%| | 17/50 [00:35<01:06, 2.03s/it] Number of matches 29263 Number of matches After Lowe's Ratio 1152 Number of Robust matches 445 | 18/50 [00:38<01:08, 2.15s/it] 36%| Number of matches 29662 Number of matches After Lowe's Ratio 2355 Number of Robust matches 1398 38%| | 19/50 [00:40<01:09, 2.26s/it] Number of matches 31340 Number of matches After Lowe's Ratio 2436 Number of Robust matches 1743 40%| | 20/50 [00:43<01:10, 2.35s/it] Number of matches 28069 Number of matches After Lowe's Ratio 1984 Number of Robust matches 1200 | 21/50 [00:45<01:09, 2.40s/it] 42%| Number of matches 30957 Number of matches After Lowe's Ratio 2200 Number of Robust matches 1536 44%| | 22/50 [00:48<01:11, 2.56s/it] Number of matches 30565 Number of matches After Lowe's Ratio 1679 Number of Robust matches 882

| 23/50 [00:51<01:09, 2.58s/it]

Number of matches 32974 Number of matches After Lowe's Ratio 2125 Number of Robust matches 1229

48%| 24/50 [00:54<01:11, 2.73s/it]

Number of matches 36549

Number of matches After Lowe's Ratio 2051

Number of Robust matches 1008

50%| | 25/50 [00:58<01:14, 2.99s/it]

Number of matches 35159

Number of matches After Lowe's Ratio 2170

Number of Robust matches 870

52%| | 26/50 [01:02<01:17, 3.24s/it]

Number of matches 38169

Number of matches After Lowe's Ratio 2397

Number of Robust matches 1054

54%| | 27/50 [01:05<01:15, 3.30s/it]

Number of matches 33493

Number of matches After Lowe's Ratio 2151

Number of Robust matches 872

56%| | 28/50 [01:08<01:10, 3.21s/it]

Number of matches 27254

Number of matches After Lowe's Ratio 1779

Number of Robust matches 673

58%| 29/50 [01:10<01:02, 2.97s/it]

Number of matches 29921

Number of matches After Lowe's Ratio 2036

Number of Robust matches 679

60%| | 30/50 [01:13<00:56, 2.82s/it]

Number of matches 27914

Number of matches After Lowe's Ratio 1944

Number of Robust matches 628

62%| | 31/50 [01:15<00:50, 2.63s/it]

Number of matches 22382

Number of matches After Lowe's Ratio 1393

Number of Robust matches 454

64%| 32/50 [01:17<00:42, 2.37s/it]

Number of matches 26806

Number of matches After Lowe's Ratio 1380

| 33/50 [01:20<00:42, 2.51s/it] 66%| Number of matches 43407

Number of matches After Lowe's Ratio 886

Number of Robust matches 53

68%| | 34/50 [01:24<00:47, 3.00s/it]

Number of matches 39639

Number of matches After Lowe's Ratio 1032

Number of Robust matches 258

70%| | 35/50 [01:28<00:49, 3.31s/it]

Number of matches 44415

Number of matches After Lowe's Ratio 733

Number of Robust matches 7

| 36/50 [01:33<00:53, 3.79s/it]

Number of matches 34575

Number of matches After Lowe's Ratio 978

Number of Robust matches 183

| 37/50 [01:36<00:46, 3.60s/it] 74%|

Number of matches 32318

Number of matches After Lowe's Ratio 1672

Number of Robust matches 485

76%| | 38/50 [01:39<00:40, 3.35s/it]

Number of matches 30468

Number of matches After Lowe's Ratio 1794

Number of Robust matches 461

| 39/50 [01:41<00:34, 3.16s/it] 78%|

Number of matches 26838

Number of matches After Lowe's Ratio 1530

Number of Robust matches 423

80%| 40/50 [01:44<00:28, 2.85s/it]

Number of matches 24184

Number of matches After Lowe's Ratio 1216

Number of Robust matches 294

| 41/50 [01:46<00:23, 2.62s/it] 82%|

Number of matches 25941

Number of matches After Lowe's Ratio 1191

Number of Robust matches 316

84%| 42/50 [01:48<00:19, 2.46s/it]

```
Number of matches 27985
Number of matches After Lowe's Ratio 2088
Number of Robust matches 622
 86%| 43/50 [01:50<00:17, 2.44s/it]
Number of matches 29906
Number of matches After Lowe's Ratio 1419
Number of Robust matches 361
 888|
       | 44/50 [01:53<00:15, 2.53s/it]
Number of matches 26647
Number of matches After Lowe's Ratio 1659
Number of Robust matches 616
 90%|
       | 45/50 [01:55<00:12, 2.49s/it]
Number of matches 30823
Number of matches After Lowe's Ratio 1837
Number of Robust matches 608
         | 46/50 [01:58<00:09, 2.48s/it]
Number of matches 23861
Number of matches After Lowe's Ratio 1340
Number of Robust matches 529
          | 47/50 [02:00<00:06,
                                   2.30s/it]
Number of matches 26390
Number of matches After Lowe's Ratio 1064
Number of Robust matches 500
     | 48/50 [02:02<00:04, 2.30s/it]
Number of matches 26937
Number of matches After Lowe's Ratio 1336
Number of Robust matches 733
     | 49/50 [02:05<00:02, 2.56s/it]
Number of matches 26134
Number of matches After Lowe's Ratio 1284
Number of Robust matches 585
In [ ]:
H left mser = []
H right mser = []
num matches mser = []
num good matches mser = []
for j in tqdm(range(len(images_left))):
    if j==len(images_left)-1:
       break
```

```
H_a,matches,gd_matches = get_Hmatrix(images_left_bgr[j:j+2][::-1],keypoints_all_left_mser[j:j+2][::-1], descriptors_all_left_mser[j:j+2][::-1])

H_left_mser.append(H_a)
    num_matches_mser.append(matches)
    num_good_matches_mser.append(gd_matches)

for j in tqdm(range(len(images_right))):
    if j==len(images_right)-1:
        break

H_a,matches,gd_matches = get_Hmatrix(images_right_bgr[j:j+2][::-1],keypoints_all_right_mser[j:j+2][::-1])

H_right_mser.append(H_a)
    num_matches_mser.append(matches)
    num_good_matches_mser.append(gd_matches)
```

### In [23]:

```
H left superpoint = []
H_right_superpoint = []
num matches superpoint = []
num good matches superpoint = []
for j in tqdm(range(len(images left))):
   if j==len(images left)-1:
       break
   H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoint all left
superpoint[j:j+2][::-1],point all left superpoint[j:j+2][::-1],descriptor all left super
point[j:j+2][::-1])
    H left superpoint.append(H a)
    num matches superpoint.append(matches)
    num good matches superpoint.append(gd matches)
for j in tqdm(range(len(images right))):
   if j==len(images right)-1:
       break
    H a, matches, gd matches = get Hmatrix(images right bgr[j:j+2][::-1], keypoints all rig
ht superpoint[j:j+2][::-1], points all right superpoint[j:j+2][::-1], descriptors all righ
t superpoint[j:j+2][::-1])
    H right superpoint.append(H a)
    num matches superpoint.append(matches)
    num good matches superpoint.append(gd matches)
 2%|
               | 1/51 [00:00<00:22, 2.25it/s]
```

```
Number of matches 2000
Number of matches After Lowe's Ratio 279
Number of Robust matches 62
```

```
4%| | 2/51 [00:00<00:21, 2.26it/s]
```

Number of matches 2000 Number of matches After Lowe's Ratio 118 Number of Robust matches 38

```
6%| | 3/51 [00:01<00:21, 2.23it/s]
```

```
Number of matches 2000
Number of matches After Lowe's Ratio 126
Number of Robust matches 33
```

```
| 4/51 [00:01<00:20, 2.25it/s]
  88|
Number of matches 2000
Number of matches After Lowe's Ratio 223
Number of Robust matches 58
 10%|
               | 5/51 [00:02<00:20, 2.24it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 212
Number of Robust matches 54
 12%|
               | 6/51 [00:02<00:20, 2.22it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 130
Number of Robust matches 34
 14%|
               | 7/51 [00:03<00:19, 2.22it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 230
Number of Robust matches 46
 16%|
              | 8/51 [00:03<00:20, 2.11it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 255
Number of Robust matches 51
 18%|
              | 9/51 [00:04<00:27, 1.55it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 325
Number of Robust matches 69
 20%|
               | 10/51 [00:05<00:25, 1.59it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 219
Number of Robust matches 51
 22%|
               | 11/51 [00:05<00:22, 1.74it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 200
Number of Robust matches 51
               | 12/51 [00:06<00:20, 1.86it/s]
 24%|
Number of matches 2000
Number of matches After Lowe's Ratio 236
Number of Robust matches 42
 25%|
               | 13/51 [00:06<00:19, 1.95it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 115
```

# 27%| | 14/51 [00:07<00:18, 2.02it/s] Number of matches 2000 Number of matches After Lowe's Ratio 168 Number of Robust matches 26 29%| | 15/51 [00:07<00:17, 2.09it/s] Number of matches 2000 Number of matches After Lowe's Ratio 63 Number of Robust matches 18 | 16/51 [00:07<00:16, 2.11it/s] 31%| Number of matches 2000 Number of matches After Lowe's Ratio 69 Number of Robust matches 22 33%| | 17/51 [00:08<00:15, 2.13it/s] Number of matches 2000 Number of matches After Lowe's Ratio 209 Number of Robust matches 50 35%| | 18/51 [00:08<00:15, 2.12it/s] Number of matches 2000 Number of matches After Lowe's Ratio 84 Number of Robust matches 19 37%| | 19/51 [00:09<00:15, 2.13it/s] Number of matches 2000 Number of matches After Lowe's Ratio 47 Number of Robust matches 7 39%| | 20/51 [00:09<00:14, 2.16it/s] Number of matches 2000 Number of matches After Lowe's Ratio 161 Number of Robust matches 24 41%| | 21/51 [00:10<00:13, 2.15it/s] Number of matches 2000 Number of matches After Lowe's Ratio 91 Number of Robust matches 22

```
43%| | 22/51 [00:10<00:13, 2.21it/s]
```

Number of matches 2000
Number of matches After L

Number of matches After Lowe's Ratio 12

```
| 23/51 [00:11<00:12, 2.21it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 235
Number of Robust matches 40
 47%|
               | 24/51 [00:11<00:12, 2.20it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 245
Number of Robust matches 36
 49%|
               | 25/51 [00:12<00:11, 2.18it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 186
Number of Robust matches 30
 51%|
              | 26/51 [00:12<00:11, 2.15it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 252
Number of Robust matches 49
 53%|
               | 27/51 [00:13<00:11, 2.14it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 197
Number of Robust matches 23
 55%|
               | 28/51 [00:13<00:10, 2.12it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 233
Number of Robust matches 28
 57%|
             | 29/51 [00:14<00:10, 2.14it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 153
Number of Robust matches 30
             | 30/51 [00:14<00:09, 2.18it/s]
 59%|
Number of matches 2000
Number of matches After Lowe's Ratio 210
Number of Robust matches 41
             | 31/51 [00:14<00:09, 2.20it/s]
 61%|
Number of matches 2000
Number of matches After Lowe's Ratio 231
Number of Robust matches 50
 63%|
             | 32/51 [00:15<00:10, 1.90it/s]
```

Number of matches 2000

Number of matches After Lowe's Ratio 229

MARKOL OF MACCINED THESE HOME D MACE 227

Number of Robust matches 57

Number of matches 2000

Number of matches After Lowe's Ratio 289

Number of Robust matches 69

67%| | 34/51 [00:16<00:08, 2.05it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 166

Number of Robust matches 29

69%| | 35/51 [00:16<00:07, 2.07it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 195

Number of Robust matches 33

71%| | 36/51 [00:17<00:07, 2.11it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 208

Number of Robust matches 45

73%| | 37/51 [00:17<00:06, 2.16it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 191

Number of Robust matches 43

75%| | 38/51 [00:18<00:06, 2.10it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 127

Number of Robust matches 24

76%| 39/51 [00:18<00:05, 2.12it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 367

Number of Robust matches 77

78%| 40/51 [00:19<00:05, 2.14it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 310

Number of Robust matches 55

80%| 41/51 [00:19<00:04, 2.17it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 194

```
Number of matches 2000
Number of matches After Lowe's Ratio 180
Number of Robust matches 39
 84%| 43/51 [00:20<00:03, 2.19it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 225
Number of Robust matches 43
 86%| 44/51 [00:21<00:03, 2.21it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 95
Number of Robust matches 27
 88%| 45/51 [00:21<00:02, 2.20it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 152
Number of Robust matches 33
 90%| 46/51 [00:21<00:02, 2.20it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 149
Number of Robust matches 32
 92%| 47/51 [00:22<00:01, 2.21it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 246
Number of Robust matches 60
            | 48/51 [00:22<00:01, 2.22it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 85
Number of Robust matches 12
       | 49/51 [00:23<00:00, 2.15it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 200
Number of Robust matches 30
 98%|
            | 50/51 [00:23<00:00, 2.10it/s]
              | 0/50 [00:00<?, ?it/s]
 0%|
Number of matches 2000
Number of matches After Lowe's Ratio 30
Number of Robust matches 7
```

82%| 42/51 [00:20<00:04, 2.16it/s]

2%|

| 1/50 [00:00<00:22, 2.16it/s]

```
Number of matches After Lowe's Ratio 73
Number of Robust matches 20
  4%|
               | 2/50 [00:00<00:22, 2.09it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 81
Number of Robust matches 17
  6%|
               | 3/50 [00:01<00:22, 2.06it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 92
Number of Robust matches 21
  8%|
               | 4/50 [00:01<00:22, 2.08it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 140
Number of Robust matches 33
 10%|
               | 5/50 [00:02<00:25, 1.79it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 236
Number of Robust matches 46
 12%|
               | 6/50 [00:03<00:23, 1.84it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 141
Number of Robust matches 33
 14%|
               | 7/50 [00:03<00:22, 1.93it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 205
Number of Robust matches 45
 16%|
               | 8/50 [00:04<00:21, 1.99it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 14
Number of Robust matches 4
 18%|
               | 9/50 [00:04<00:20, 1.99it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 58
Number of Robust matches 10
 20%|
               | 10/50 [00:05<00:19, 2.05it/s]
Number of matches 2000
Number of matches After Lowe's Ratio 49
Number of Robust matches 13
```

Number of matches 2000

| 11/50 [00:05<00:19, 2.02it/s] 22%| Number of matches 2000 Number of matches After Lowe's Ratio 212 Number of Robust matches 33 24%| | 12/50 [00:06<00:18, 2.04it/s] Number of matches 2000 Number of matches After Lowe's Ratio 281 Number of Robust matches 73 26%| | 13/50 [00:06<00:18, 2.05it/s] Number of matches 2000 Number of matches After Lowe's Ratio 329 Number of Robust matches 78 28%| | 14/50 [00:06<00:17, 2.05it/s] Number of matches 2000 Number of matches After Lowe's Ratio 115 Number of Robust matches 24 | 15/50 [00:07<00:16, 2.09it/s] 30%| Number of matches 2000 Number of matches After Lowe's Ratio 30 Number of Robust matches 8 | 16/50 [00:07<00:16, 2.10it/s] 32%| Number of matches 2000 Number of matches After Lowe's Ratio 216 Number of Robust matches 54 34%| | 17/50 [00:08<00:15, 2.13it/s] Number of matches 2000 Number of matches After Lowe's Ratio 117 Number of Robust matches 26 36%| | 18/50 [00:08<00:14, 2.16it/s] Number of matches 2000 Number of matches After Lowe's Ratio 387 Number of Robust matches 85 38%| | 19/50 [00:09<00:14, 2.19it/s] Number of matches 2000 Number of matches After Lowe's Ratio 256 Number of Robust matches 65

| 20/50 [00:09<00:13, 2.16it/s]

40%|

Number of matches 2000 Number of matches After Lowe's Ratio 233 Number of Robust matches 59

42%| 21/50 [00:10<00:13, 2.17it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 294

Number of Robust matches 71

44%| | 22/50 [00:10<00:12, 2.17it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 112

Number of Robust matches 29

46%| 23/50 [00:11<00:12, 2.16it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 200

Number of Robust matches 45

48%| | 24/50 [00:11<00:12, 2.15it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 205

Number of Robust matches 38

50%| 25/50 [00:12<00:11, 2.12it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 195

Number of Robust matches 36

52%| | 26/50 [00:12<00:11, 2.03it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 227

Number of Robust matches 32

54%| 27/50 [00:13<00:15, 1.52it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 236

Number of Robust matches 33

56%| | 28/50 [00:14<00:14, 1.51it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 200

Number of Robust matches 30

58%| 29/50 [00:14<00:12, 1.67it/s]

Number of matches 2000

Number of matches After Lowe's Ratio 370

| 30/50 [00:15<00:11, 1.77it/s] Number of matches 2000 Number of matches After Lowe's Ratio 283 Number of Robust matches 33 62%| | 31/50 [00:15<00:10, 1.86it/s] Number of matches 2000 Number of matches After Lowe's Ratio 188 Number of Robust matches 49 64%| 32/50 [00:16<00:09, 1.97it/s] Number of matches 2000 Number of matches After Lowe's Ratio 183 Number of Robust matches 48 66%| 33/50 [00:16<00:08, 2.02it/s] Number of matches 2000 Number of matches After Lowe's Ratio 25 Number of Robust matches 6 68%| 34/50 [00:17<00:07, 2.04it/s] Number of matches 2000 Number of matches After Lowe's Ratio 63 Number of Robust matches 14 | 35/50 [00:17<00:07, 2.08it/s] Number of matches 2000 Number of matches After Lowe's Ratio 12 Number of Robust matches 4 | 36/50 [00:18<00:06, 2.07it/s] 72%| Number of matches 2000 Number of matches After Lowe's Ratio 105 Number of Robust matches 21 74%| 37/50 [00:18<00:06, 2.09it/s] Number of matches 2000 Number of matches After Lowe's Ratio 321 Number of Robust matches 48 | 38/50 [00:19<00:05, 2.08it/s] Number of matches 2000 Number of matches After Lowe's Ratio 252

78%| | 39/50 [00:19<00:05, 2.10it/s]

Number of matches 2000
Number of matches After Lowe's Ratio 178
Number of Robust matches 24

80%| | 40/50 [00:19<00:04, 2.08it/s]

Number of matches 2000
Number of matches After Lowe's Ratio 201
Number of Robust matches 39

82%| 41/50 [00:20<00:04, 2.05it/s]

Number of matches 2000 Number of matches After Lowe's Ratio 131 Number of Robust matches 18

84%| 42/50 [00:20<00:03, 2.05it/s]

Number of matches 2000 Number of matches After Lowe's Ratio 334 Number of Robust matches 54

86%| | 43/50 [00:21<00:03, 2.05it/s]

Number of matches 2000 Number of matches After Lowe's Ratio 132 Number of Robust matches 24

88%| 44/50 [00:21<00:02, 2.10it/s]

Number of matches 2000 Number of matches After Lowe's Ratio 148 Number of Robust matches 44

90%| 45/50 [00:22<00:02, 2.07it/s]

Number of matches 2000 Number of matches After Lowe's Ratio 262 Number of Robust matches 53

92%| 46/50 [00:22<00:01, 2.09it/s]

Number of matches 2000 Number of matches After Lowe's Ratio 135 Number of Robust matches 32

94%| 47/50 [00:23<00:01, 2.16it/s]

Number of matches 2000 Number of matches After Lowe's Ratio 66 Number of Robust matches 21

96%| 48/50 [00:23<00:00, 2.15it/s]

Number of matches 2000 Number of matches After Lowe's Ratio 295 Number of Robust matches 67

```
98%| 49/50 [00:24<00:00, 2.01it/s]
```

```
Number of matches 2000
Number of matches After Lowe's Ratio 182
Number of Robust matches 43
```

### In [ ]:

```
H left gftt = []
H right gftt = []
num matches gftt = []
num good matches gftt = []
for j in tqdm(range(len(images left))):
    if j==len(images left)-1:
    H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
_gftt[j:j+2][::-1],points_all_left_gftt[j:j+2][::-1],descriptors_all_left_gftt[j:j+2][::
-1])
    H_left_gftt.append(H a)
    num matches gftt.append(matches)
    num good matches gftt.append(gd matches)
for j in tqdm(range(len(images right))):
    if j==len(images right)-1:
        break
    H a, matches, gd matches = get Hmatrix(images right bgr[j:j+2][::-1], keypoints all rig
 \texttt{ht gftt}[\texttt{j:j+2}]\texttt{[::-1]}, \texttt{points all right\_gftt}[\texttt{j:j+2}]\texttt{[::-1]}, \texttt{descriptors\_all\_right\_gftt}[\texttt{j:j+2}]
][::-1])
    H right gftt.append(H a)
    num matches gftt.append(matches)
    num good matches gftt.append(gd matches)
```

### In [ ]:

```
H left_daisy = []
H_right_daisy = []
num matches daisy = []
num_good_matches_daisy = []
for j in tqdm(range(len(images left))):
   if j==len(images left)-1:
       break
    H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
daisy[j:j+2][::-1], points all left daisy[j:j+2][::-1], descriptors all left daisy[j:j+2]
[::-1])
    H left daisy.append(H a)
    num matches daisy.append(matches)
    num_good_matches_daisy.append(gd_matches)
for j in tqdm(range(len(images right))):
    if j==len(images right)-1:
        break
    H a, matches, gd matches = get Hmatrix(images right bgr[j:j+2][::-1], keypoints all rig
ht_daisy[j:j+2][::-1],points_all_right_daisy[j:j+2][::-1],descriptors_all_right_daisy[j:
j+2][::-1])
    H right daisy.append(H a)
    num matches daisy.append(matches)
    num good matches daisy.append(gd matches)
```

```
H left fast = []
H_right_fast = []
num matches fast = []
num good matches fast = []
for j in tqdm(range(len(images left))):
    if j==len(images left)-1:
        break
    H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
 fast[j:j+2][::-1],points all left fast[j:j+2][::-1],descriptors all left fast[j:j+2][::
<u>-</u>1])
    H left fast.append(H a)
    num matches fast.append(matches)
    num_good_matches_fast.append(gd_matches)
for j in tqdm(range(len(images_right))):
    if j==len(images right)-1:
        break
    H a, matches, gd matches = get Hmatrix(images right bgr[j:j+2][::-1], keypoints all rig
ht_fast[j:j+2][::-1],points_all_right_fast[j:j+2][::-1],descriptors_all_right_fast[j:j+2
][::-1])
    H right fast.append(H a)
    num matches fast.append(matches)
    num good matches fast.append(gd matches)
  2%|
               | 1/51 [00:13<11:36, 13.94s/it]
Number of matches 87536
Number of matches After Lowe's Ratio 10285
Number of Robust matches 7414
  4%|
               | 2/51 [00:31<12:55, 15.83s/it]
Number of matches 75857
Number of matches After Lowe's Ratio 644
Number of Robust matches 360
  6%|
               | 3/51 [00:47<12:45, 15.95s/it]
Number of matches 97150
Number of matches After Lowe's Ratio 3315
Number of Robust matches 2144
Number of matches 98403
Number of matches After Lowe's Ratio 7816
  8%|
               | 4/51 [01:06<13:31, 17.26s/it]
Number of Robust matches 5167
 10%|
               | 5/51 [01:25<13:43, 17.91s/it]
Number of matches 94577
Number of matches After Lowe's Ratio 10068
Number of Robust matches 6903
Number of matches 94935
Number of matches After Lowe's Ratio 7153
```

In [19]:

| 6/51 [01:44<13:41, 18.26s/it] 12%| Number of Robust matches 5243 14%| | 7/51 [02:03<13:39, 18.63s/it] Number of matches 101108 Number of matches After Lowe's Ratio 12097 Number of Robust matches 8939 Number of matches 103611 Number of matches After Lowe's Ratio 25654 | 8/51 [02:25<13:55, 19.44s/it] Number of Robust matches 21024 18%| | 9/51 [02:46<14:06, 20.15s/it] Number of matches 106411 Number of matches After Lowe's Ratio 22967 Number of Robust matches 17258 20%| | 10/51 [03:08<14:04, 20.60s/it] Number of matches 115231 Number of matches After Lowe's Ratio 14042 Number of Robust matches 9206 22%| | 11/51 [03:32<14:22, 21.57s/it] Number of matches 117947 Number of matches After Lowe's Ratio 4381 Number of Robust matches 2563 Number of matches 111829 Number of matches After Lowe's Ratio 24831 24%| | 12/51 [03:55<14:27, 22.23s/it] Number of Robust matches 17367 25%| | 13/51 [04:18<14:13, 22.47s/it] Number of matches 112111 Number of matches After Lowe's Ratio 4896 Number of Robust matches 2316 27%| | 14/51 [04:41<13:53, 22.53s/it] Number of matches 116212 Number of matches After Lowe's Ratio 18905 Number of Robust matches 11974 29%| | 15/51 [05:05<13:50, 23.08s/it] Number of matches 123205 Number of matches After Lowe's Ratio 101

# 31%| | 16/51 [05:30<13:41, 23.47s/it]

Number of matches 109372

Number of matches After Lowe's Ratio 392

Number of Robust matches 119

#### 

Number of matches 112914

Number of matches After Lowe's Ratio 12118

Number of Robust matches 5780

### 35%| | | 18/51 [06:14<12:33, 22.83s/it]

Number of matches 109913

Number of matches After Lowe's Ratio 465

Number of Robust matches 118

### 37%| | 19/51 [06:37<12:13, 22.93s/it]

Number of matches 120423

Number of matches After Lowe's Ratio 251

Number of Robust matches 73

### 39%| | 20/51 [07:01<11:59, 23.22s/it]

Number of matches 121925

Number of matches After Lowe's Ratio 6830

Number of Robust matches 2945

### 41%| | 21/51 [07:25<11:40, 23.35s/it]

Number of matches 116705

Number of matches After Lowe's Ratio 4466

Number of Robust matches 2003

#### 

Number of matches 109716

Number of matches After Lowe's Ratio 47

Number of Robust matches 8

#### 

Number of matches 110779

Number of matches After Lowe's Ratio 20404

Number of Robust matches 12165

### 47%| | 24/51 [08:32<10:07, 22.52s/it]

Number of matches 109349

Number of matches After Lowe's Ratio 19120

```
Number of matches 115938
Number of matches After Lowe's Ratio 17206
Number of Robust matches 9056
               | 26/51 [09:18<09:30, 22.82s/it]
 51%|
Number of matches 122855
Number of matches After Lowe's Ratio 14504
Number of Robust matches 7178
 53%|
               | 27/51 [09:42<09:19, 23.31s/it]
Number of matches 133153
Number of matches After Lowe's Ratio 18941
Number of Robust matches 9616
Number of matches 139272
Number of matches After Lowe's Ratio 21770
Number of Robust matches 8807
 57%|
               | 29/51 [10:36<09:13, 25.18s/it]
Number of matches 132310
Number of matches After Lowe's Ratio 20357
Number of Robust matches 11194
 59%|
               | 30/51 [11:01<08:48, 25.17s/it]
Number of matches 117037
Number of matches After Lowe's Ratio 21976
Number of Robust matches 11928
Number of matches 112444
Number of matches After Lowe's Ratio 25813
               | 31/51 [11:25<08:14, 24.71s/it]
Number of Robust matches 14385
Number of matches 105817
Number of matches After Lowe's Ratio 25373
               | 32/51 [11:47<07:33, 23.85s/it]
Number of Robust matches 18998
 65%|
             | 33/51 [12:08<06:55, 23.08s/it]
Number of matches 103385
Number of matches After Lowe's Ratio 22741
Number of Robust matches 16336
```

| 25/51 [08:55<09:48, 22.62s/it]

Number of matches 109002

| 34/51 [12:29<06:22, 22.49s/it]

Number of matches After Lowe's Ratio 21629 Number of Robust matches 14253

Number of matches 112071

Number of matches After Lowe's Ratio 23284

Number of Robust matches 16528

Number of matches 106802

Number of matches After Lowe's Ratio 25177

Number of Robust matches 15680

73%| | 37/51 [13:36<05:13, 22.39s/it]

Number of matches 101920

Number of matches After Lowe's Ratio 18163

Number of Robust matches 11825

Number of matches 85971

Number of matches After Lowe's Ratio 10146

Number of Robust matches 7521

Number of matches 81836

Number of matches After Lowe's Ratio 23569

Number of Robust matches 18118

78%| 40/51 [14:30<03:31, 19.23s/it]

Number of matches 87852

Number of matches After Lowe's Ratio 18363

Number of Robust matches 14441

80%| 41/51 [14:48<03:08, 18.83s/it]

Number of matches 90007

Number of matches After Lowe's Ratio 18022

Number of Robust matches 11814

82%| | 42/51 [15:05<02:45, 18.36s/it]

Number of matches 89119

Number of matches After Lowe's Ratio 17660

Number of Robust matches 13178

Number of matches 93962

Number of matches After Lowe's Ratio 25922

```
| 44/51 [15:42<02:08, 18.29s/it]
Number of matches 90558
Number of matches After Lowe's Ratio 7651
Number of Robust matches 5005
 88%| | 45/51 [16:00<01:49, 18.28s/it]
Number of matches 89788
Number of matches After Lowe's Ratio 5179
Number of Robust matches 2932
Number of matches 94690
Number of matches After Lowe's Ratio 11661
 90%| | 46/51 [16:19<01:31, 18.33s/it]
Number of Robust matches 5986
Number of matches 98372
Number of matches After Lowe's Ratio 10484
       | 47/51 [16:38<01:14, 18.65s/it]
Number of Robust matches 5047
Number of matches 97482
Number of matches After Lowe's Ratio 5874
 94%| 48/51 [16:58<00:57, 19.01s/it]
Number of Robust matches 2490
          | 49/51 [17:18<00:38, 19.24s/it]
Number of matches 100849
Number of matches After Lowe's Ratio 12345
Number of Robust matches 5167
            | 50/51 [17:37<00:21, 21.16s/it]
 98%|
 0%|
              | 0/50 [00:00<?, ?it/s]
Number of matches 92828
Number of matches After Lowe's Ratio 1114
Number of Robust matches 339
Number of matches 104129
Number of matches After Lowe's Ratio 6041
              | 1/50 [00:14<12:09, 14.89s/it]
 2%|
Number of Robust matches 3455
  4%|
              | 2/50 [00:34<14:17, 17.87s/it]
Number of matches 85258
Number of matches After Lowe's Ratio 5598
```

```
6%|
               | 3/50 [00:53<14:26, 18.44s/it]
Number of matches 113643
Number of matches After Lowe's Ratio 11815
Number of Robust matches 7010
  8%|
               | 4/50 [01:16<15:21, 20.03s/it]
Number of matches 105684
Number of matches After Lowe's Ratio 2658
Number of Robust matches 1457
 10%|
               | 5/50 [01:38<15:31, 20.69s/it]
Number of matches 109972
Number of matches After Lowe's Ratio 5694
Number of Robust matches 2745
 12%|
               | 6/50 [02:00<15:30, 21.14s/it]
Number of matches 107417
Number of matches After Lowe's Ratio 1195
Number of Robust matches 451
 14%|
               | 7/50 [02:21<15:11, 21.20s/it]
Number of matches 106987
Number of matches After Lowe's Ratio 15391
Number of Robust matches 7978
 16%|
               | 8/50 [02:43<15:03, 21.52s/it]
Number of matches 121549
Number of matches After Lowe's Ratio 106
Number of Robust matches 15
 18%|
               | 9/50 [03:07<15:05, 22.09s/it]
Number of matches 109090
Number of matches After Lowe's Ratio 1673
Number of Robust matches 669
 20%|
               | 10/50 [03:28<14:32, 21.81s/it]
Number of matches 105349
Number of matches After Lowe's Ratio 4230
Number of Robust matches 1866
 22%|
               | 11/50 [03:49<14:02, 21.59s/it]
Number of matches 108435
Number of matches After Lowe's Ratio 6737
Number of Robust matches 4144
```

24%|

| 12/50 [04:12<13:53, 21.93s/it]

Number of matches 123694 Number of matches After Lowe's Ratio 19791 Number of Robust matches 12013 26%| | 13/50 [04:35<13:43, 22.25s/it] Number of matches 96343 Number of matches After Lowe's Ratio 16656 Number of Robust matches 12393 28%| | 14/50 [04:52<12:32, 20.90s/it] Number of matches 54457 Number of matches After Lowe's Ratio 5962 Number of Robust matches 3988 30%| | 15/50 [05:04<10:33, 18.11s/it] Number of matches 74343 Number of matches After Lowe's Ratio 3528 Number of Robust matches 2306 32%| | 16/50 [05:18<09:36, 16.95s/it] Number of matches 57064 Number of matches After Lowe's Ratio 10178 Number of Robust matches 8030 34%| | 17/50 [05:32<08:47, 15.97s/it] Number of matches 104262 Number of matches After Lowe's Ratio 8765 Number of Robust matches 4524 36%| | 18/50 [05:53<09:22, 17.57s/it] Number of matches 105631 Number of matches After Lowe's Ratio 19903 Number of Robust matches 13545 38%| | 19/50 [06:14<09:36, 18.61s/it] Number of matches 108249 Number of matches After Lowe's Ratio 19738 Number of Robust matches 14067 40%| | 20/50 [06:36<09:47, 19.59s/it] Number of matches 106606 Number of matches After Lowe's Ratio 23842 Number of Robust matches 17248 Number of matches 120200 Number of matches After Lowe's Ratio 33402 | 21/50 [06:59<09:59, 20.66s/it] 42%|

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### 44%| 22/50 [07:24<10:12, 21.88s/it]

Number of matches 125528

Number of matches After Lowe's Ratio 9561

Number of Robust matches 5903

### 46%| 23/50 [07:49<10:15, 22.79s/it]

Number of matches 129552

Number of matches After Lowe's Ratio 16308

Number of Robust matches 10996

### 48%| 24/50 [08:15<10:19, 23.81s/it]

Number of matches 131203

Number of matches After Lowe's Ratio 18799

Number of Robust matches 12482

### 50%| 25/50 [08:41<10:11, 24.47s/it]

Number of matches 128349

Number of matches After Lowe's Ratio 14196

Number of Robust matches 8418

Number of matches 125112

Number of matches After Lowe's Ratio 9449

### 52%| | 26/50 [09:07<09:56, 24.84s/it]

Number of Robust matches 4233

### 54%| 27/50 [09:31<09:25, 24.57s/it]

Number of matches 115397

Number of matches After Lowe's Ratio 18333

Number of Robust matches 8579

### 56%| | 28/50 [09:54<08:49, 24.07s/it]

Number of matches 107757

Number of matches After Lowe's Ratio 14595

Number of Robust matches 7553

### 58%| | 29/50 [10:16<08:12, 23.45s/it]

Number of matches 108520

Number of matches After Lowe's Ratio 21524

Number of Robust matches 10171

# 60%| 30/50 [10:37<07:36, 22.84s/it]

Number of matches 105170

Number of matches After Lowe's Ratio 21763

| 31/50 [10:58<07:03, 22.27s/it]

Number of matches 101842

Number of matches After Lowe's Ratio 6660

Number of Robust matches 3337

| 32/50 [11:19<06:33, 21.88s/it]

Number of matches 114806

Number of matches After Lowe's Ratio 7725

Number of Robust matches 3925

| 33/50 [11:43<06:22, 22.52s/it]

Number of matches 144158 Number of matches After Lowe's Ratio 2994

Number of Robust matches 1244

68%| 34/50 [12:11<06:24, 24.06s/it]

Number of matches 129327 Number of matches After Lowe's Ratio 13126

Number of Robust matches 4588

70%| 35/50 [12:38<06:12, 24.87s/it]

Number of matches 150305 Number of matches After Lowe's Ratio 52

Number of Robust matches 11

72%| | 36/50 [13:06<06:02, 25.91s/it]

Number of matches 125780

Number of matches After Lowe's Ratio 10461

Number of Robust matches 3901

74%| | 37/50 [13:31<05:33, 25.64s/it]

Number of matches 122865

Number of matches After Lowe's Ratio 7103

Number of Robust matches 2399

76%| 38/50 [13:54<04:59, 24.94s/it]

Number of matches 105783

Number of matches After Lowe's Ratio 17566

Number of Robust matches 8140

78%| | 39/50 [14:15<04:21, 23.81s/it]

Number of matches 102138

Number of matches After Lowe's Ratio 5707

Number of Robust matches 2790

Number of matches 89671

Number of matches After Lowe's Ratio 10545

| 40/50 [14:36<03:47, 22.72s/it] Number of Robust matches 4038 Number of matches 96125 Number of matches After Lowe's Ratio 16071 82%| 41/50 [14:54<03:11, 21.30s/it] Number of Robust matches 6874 Number of matches 100177 Number of matches After Lowe's Ratio 26715 84%| 42/50 [15:14<02:47, 20.94s/it] Number of Robust matches 11299 | 43/50 [15:34<02:25, 20.84s/it] Number of matches 107031 Number of matches After Lowe's Ratio 13205 Number of Robust matches 6459 | 44/50 [15:56<02:05, 21.00s/it] Number of matches 103108 Number of matches After Lowe's Ratio 505 Number of Robust matches 153 | 45/50 [16:16<01:44, 20.95s/it] Number of matches 107375 Number of matches After Lowe's Ratio 10404 Number of Robust matches 5760

92%| 46/50 [16:38<01:24, 21.04s/it]

Number of matches 108739 Number of matches After Lowe's Ratio 7698 Number of Robust matches 3892

94%| 47/50 [17:00<01:04, 21.46s/it]

Number of matches 116973 Number of matches After Lowe's Ratio 5070 Number of Robust matches 2995

96%| 48/50 [17:24<00:44, 22.10s/it]

Number of matches 116549 Number of matches After Lowe's Ratio 10498 Number of Robust matches 7584

Number of matches 107771 Number of matches After Lowe's Ratio 8033

98%| 49/50 [17·46<00·21 21 77e/i+1

Number of Robust matches 4890

```
In [ ]:
```

```
H left star = []
H right star = []
num matches star = []
num good matches star = []
for j in tqdm(range(len(images left))):
    if j==len(images left)-1:
       break
   H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
_star[j:j+2][::-1],points_all_left_star[j:j+2][::-1],descriptors_all_left_brief[j:j+2][:
:-1])
    H left_star.append(H_a)
    num_matches_star.append(matches)
    num good matches star.append(gd matches)
for j in tqdm(range(len(images right))):
    if j==len(images right)-1:
   H_a, matches, gd_matches = get_Hmatrix(images_right_bgr[j:j+2][::-1], keypoints_all_rig
ht star[j:j+2][::-1], points all right star[j:j+2][::-1], descriptors all right brief[j:j+
2][::-1])
   H right star.append(H a)
    num matches star.append(matches)
    num good matches star.append(gd matches)
```

### In [ ]:

```
H left sift = []
H right sift = []
num matches sift = []
num good matches sift = []
for j in tqdm(range(len(images left))):
    if j==len(images left)-1:
       break
    H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
sift[j:j+2][::-1], points all left sift[j:j+2][::-1], descriptors all left sift[j:j+2][::
-1])
    H left sift.append(H a)
    num matches sift.append(matches)
    num_good_matches_sift.append(gd_matches)
for j in tqdm(range(len(images right))):
    if j==len(images_right)-1:
       break
   H a, matches, gd matches = get Hmatrix(images right bgr[j:j+2][::-1], keypoints all rig
ht sift[j:j+2][::-1],points all right sift[j:j+2][::-1],descriptors all right sift[j:j+2
][::-1])
   H right sift.append(H a)
    num matches sift.append(matches)
    num good matches sift.append(gd matches)
```

### In [ ]:

```
H_left_surf = []
H_right_surf = []
```

```
num_matches_surf = []
num_good_matches_surf = []
for j in tqdm(range(len(images left))):
   if j==len(images left)-1:
       break
    H a, matches, gd matches = get Hmatrix(images left bgr[j:j+2][::-1], keypoints all left
surf[j:j+2][::-1],points all left surf[j:j++2][::-1],descriptors all left surf[j:j+2][:
:-1])
    H left surf.append(H a)
    num matches surf.append(matches)
    num good matches surf.append(gd matches)
for j in tqdm(range(len(images right))):
    if j==len(images right)-1:
    H_a, matches, gd_matches = get_Hmatrix(images_right_bgr[j:j+2][::-1], keypoints_all_rig
ht_surf[j:j+2][::-1],points_all_right_surf[j:j+2][::-1],descriptors_all_right_surf[j:j+2
][::-1])
   H right surf.append(H a)
    num_matches_surf.append(matches)
    num good matches surf.append(gd matches)
```

### In [ ]:

```
H left surfsift = []
H right surfsift = []
num matches surfsift = []
num good matches surfsift = []
for j in tqdm(range(len(images left))):
   if j==len(images left)-1:
    H_a, matches, gd_matches = get_Hmatrix(images_left_bgr[j:j+2][::-1], keypoints_all_left
surfsift[j:j+2][::-1],points_all_left_surfsift[j:j++2][::-1],descriptors_all_left_surfs
ift[j:j+2][::-1])
    H_left_surfsift.append(H_a)
    num matches surfsift.append(matches)
    num good matches surfsift.append(gd matches)
for j in tqdm(range(len(images right))):
    if j==len(images right)-1:
        break
    H_a, matches, gd_matches = get_Hmatrix(images_right_bgr[j:j+2][::-1], keypoints_all_rig
ht surfsift[j:j+2][::-1], points all right surfsift[j:j+2][::-1], descriptors all right su
rfsift[j:j+2][::-1])
    H right surfsift.append(H a)
    num matches surfsift.append(matches)
    num good matches surfsift.append(gd matches)
```

### In [20]:

```
num_matches_agast.append(matches)
    num_good_matches_agast.append(gd_matches)
for j in tqdm(range(len(images right))):
    if j==len(images right)-1:
        break
    H a, matches, gd matches = get Hmatrix(images right bgr[j:j+2][::-1], keypoints all rig
ht agast[j:j+2][::-1], points all right agast[j:j+2][::-1], descriptors all right agast[j:
j+2][::-1])
    H right agast.append(H a)
    num matches agast.append(matches)
    num good matches agast.append(gd matches)
               | 0/51 [00:00<?, ?it/s]
Number of matches 98954
Number of matches After Lowe's Ratio 9380
  2%|
               | 1/51 [00:15<13:06, 15.74s/it]
Number of Robust matches 6059
  4%|
               | 2/51 [00:34<14:16, 17.48s/it]
Number of matches 79366
Number of matches After Lowe's Ratio 593
Number of Robust matches 304
  6%|
               | 3/51 [00:51<13:56, 17.43s/it]
Number of matches 110204
Number of matches After Lowe's Ratio 3245
Number of Robust matches 2087
  8%|
               | 4/51 [01:13<15:01, 19.19s/it]
Number of matches 105901
Number of matches After Lowe's Ratio 7215
Number of Robust matches 4947
 10%|
               | 5/51 [01:34<15:09, 19.78s/it]
Number of matches 107504
Number of matches After Lowe's Ratio 9704
Number of Robust matches 7356
 12%|
               | 6/51 [01:55<15:01, 20.02s/it]
Number of matches 103271
Number of matches After Lowe's Ratio 6633
Number of Robust matches 5082
 14%|
               | 7/51 [02:16<15:07, 20.61s/it]
Number of matches 116933
Number of matches After Lowe's Ratio 11628
Number of Robust matches 9142
Number of matches 119028
Number of matches After Lowe's Ratio 25392
```

```
Number of Robust matches 21361
Number of matches 124258
Number of matches After Lowe's Ratio 22155
               | 9/51 [03:05<15:43, 22.47s/it]
Number of Robust matches 13957
 20%|
               | 10/51 [03:30<15:57, 23.35s/it]
Number of matches 131124
Number of matches After Lowe's Ratio 13375
Number of Robust matches 8887
 22%|
              | 11/51 [03:56<16:09, 24.24s/it]
Number of matches 134054
Number of matches After Lowe's Ratio 4552
Number of Robust matches 2757
Number of matches 127609
Number of matches After Lowe's Ratio 24165
 24%|
          | 12/51 [04:23<16:21, 25.17s/it]
Number of Robust matches 17371
 25%|
               | 13/51 [04:49<16:01, 25.30s/it]
Number of matches 124545
Number of matches After Lowe's Ratio 4827
Number of Robust matches 2325
Number of matches 130795
Number of matches After Lowe's Ratio 17823
               | 14/51 [05:14<15:32, 25.19s/it]
Number of Robust matches 12487
               | 15/51 [05:41<15:24, 25.67s/it]
 29%|
Number of matches 141804
Number of matches After Lowe's Ratio 98
Number of Robust matches 17
 31%|
              | 16/51 [06:09<15:25, 26.43s/it]
Number of matches 128214
Number of matches After Lowe's Ratio 483
Number of Robust matches 138
```

| 17/51 [06:35<14:53, 26.28s/it]

16%|

33%|

| 8/51 [02:40<15:34, 21.74s/it]

Number of matches 130355 Number of matches After Lowe's Ratio 11437 Number of Robust matches 5760

35%| | 18/51 [07:00<14:19, 26.04s/it]

Number of matches 120660

Number of matches After Lowe's Ratio 463

Number of Robust matches 128

Number of matches 137824

Number of matches After Lowe's Ratio 263

Number of Robust matches 79

39%| | 20/51 [07:52<13:30, 26.15s/it]

Number of matches 141614

Number of matches After Lowe's Ratio 6793

Number of Robust matches 2746

41%| | 21/51 [08:20<13:15, 26.51s/it]

Number of matches 131535

Number of matches After Lowe's Ratio 4291

Number of Robust matches 1657

Number of matches 127536

Number of matches After Lowe's Ratio 58

Number of Robust matches 11

45%| | 23/51 [09:11<12:11, 26.13s/it]

Number of matches 129839

Number of matches After Lowe's Ratio 20514

Number of Robust matches 12835

47%| | 24/51 [09:37<11:42, 26.02s/it]

Number of matches 126651

Number of matches After Lowe's Ratio 18600

Number of Robust matches 11649

Number of matches 135662

Number of matches After Lowe's Ratio 16962

Number of Robust matches 10211

51%| | 26/51 [10:29<10:53, 26.15s/it]

Number of matches 139772

Number of matches After Lowe's Ratio 13798

Number of matches 152790
Number of matches After Lowe's Ratio 18978
Number of Robust matches 9749

Number of matches 158880
Number of matches After Lowe's Ratio 21063
Number of Robust matches 9734

55%| | 28/51 [11:30<10:53, 28.39s/it]

Number of matches 152717

Number of matches After Lowe's Ratio 20181

57%| 29/51 [12:01<10:41, 29.17s/it]

Number of Robust matches 9721

59%| | 30/51 [12:31<10:14, 29.28s/it]

Number of matches 132257

Number of matches After Lowe's Ratio 21394

Number of Robust matches 11899

Number of matches 126012 Number of matches After Lowe's Ratio 25535

61%| | 31/51 [12:58<09:33, 28.67s/it]

Number of Robust matches 15492

Number of matches 118729

Number of matches After Lowe's Ratio 25260

Number of Robust matches 17911

65%| | 33/51 [13:46<07:50, 26.16s/it]

Number of matches 112501

Number of matches After Lowe's Ratio 21357

Number of Robust matches 12944

67%| | 34/51 [14:09<07:09, 25.29s/it]

Number of matches 120367

Number of matches After Lowe's Ratio 21552

Number of Robust matches 14063

Number of matches 128900

Number of matches After Lowe's Ratio 22874

69%| | 35/51 [14:35<06:49, 25.62s/it]

Number of Robust matches 15481

Number of matches 118239 Number of matches After Lowe's Ratio 24094 Number of Robust matches 14131

73%| | 37/51 [15:25<05:52, 25.15s/it]

Number of matches 117746

Number of matches After Lowe's Ratio 17921

Number of Robust matches 11227

Number of matches 94610

Number of matches After Lowe's Ratio 9216

Number of Robust matches 6658

Number of matches 93123

Number of matches After Lowe's Ratio 22665

76%| | 39/51 [16:07<04:35, 22.98s/it]

Number of Robust matches 14114

78%| | 40/51 [16:26<03:58, 21.66s/it]

Number of matches 94525

Number of matches After Lowe's Ratio 16661

Number of Robust matches 9543

80%| | 41/51 [16:45<03:28, 20.83s/it]

Number of matches 97507

Number of matches After Lowe's Ratio 17477

Number of Robust matches 11025

Number of matches 93618

Number of matches After Lowe's Ratio 16473

82%| 42/51 [17:04<03:02, 20.30s/it]

Number of Robust matches 11280

Number of matches 100100

Number of matches After Lowe's Ratio 24989

84%| 43/51 [17:23<02:40, 20.01s/it]

Number of Robust matches 16093

86%| 44/51 [17:43<02:19, 20.00s/it]

Number of matches 102617

Number of matches After Lowe's Ratio 7552

Number of Robust matches 4608

Number of matches 103996

Number of matches After Lowe's Ratio 5151

88%| 45/51 [18:03<02:00, 20.04s/it] Number of Robust matches 2985 | 46/51 [18:25<01:42, 20.48s/it] Number of matches 112006 Number of matches After Lowe's Ratio 11259 Number of Robust matches 5926 92%| 47/51 [18:47<01:23, 21.00s/it] Number of matches 111932 Number of matches After Lowe's Ratio 9440 Number of Robust matches 4507 94%| | 48/51 [19:10<01:04, 21.64s/it] Number of matches 115210 Number of matches After Lowe's Ratio 5950 Number of Robust matches 2380 | 49/51 [19:34<00:44, 22.19s/it] 96%| Number of matches 116566 Number of matches After Lowe's Ratio 11728 Number of Robust matches 6179 98%| | 50/51 [19:57<00:23, 23.95s/it] 0%| | 0/50 [00:00<?, ?it/s] Number of matches 108059 Number of matches After Lowe's Ratio 1188 Number of Robust matches 423 2%| | 1/50 [00:16<13:13, 16.19s/it]

Number of matches 113929

Number of matches After Lowe's Ratio 5928

Number of Robust matches 3305

4%| | 2/50 [00:38<15:54, 19.89s/it]

Number of matches 100181

Number of matches After Lowe's Ratio 5535

Number of Robust matches 3058

6%| | 3/50 [01:00<16:10, 20.65s/it]

Number of matches 127159

Number of matches After Lowe's Ratio 11330

Number of Robust matches 6738

8%| | 4/50 [01:26<17:28, 22.79s/it]

Number of matches 120719

Number of matches After Lowe's Ratio 2706

# 10%| | 5/50 [01:51<17:40, 23.57s/it] Number of matches 127483 Number of matches After Lowe's Ratio 5828 Number of Robust matches 2950 12%| | 6/50 [02:16<17:45, 24.21s/it] Number of matches 119944 Number of matches After Lowe's Ratio 1346 Number of Robust matches 550 14%| | 7/50 [02:41<17:26, 24.34s/it] Number of matches 119233 Number of matches After Lowe's Ratio 15219 Number of Robust matches 9118 16%| | 8/50 [03:06<17:08, 24.49s/it] Number of matches 135893 Number of matches After Lowe's Ratio 109 Number of Robust matches 16 18%| | 9/50 [03:32<17:09, 25.10s/it] Number of matches 123626 Number of matches After Lowe's Ratio 1806 Number of Robust matches 687 20%| | 10/50 [03:57<16:37, 24.94s/it] Number of matches 117876 Number of matches After Lowe's Ratio 3970 Number of Robust matches 1919 22%| | 11/50 [04:21<16:02, 24.68s/it] Number of matches 120007 Number of matches After Lowe's Ratio 6810 Number of Robust matches 3838 Number of matches 136160 Number of matches After Lowe's Ratio 19054 | 12/50 [04:45<15:37, 24.67s/it] Number of Robust matches 12081 Number of matches 106595 Number of matches After Lowe's Ratio 15909

| 13/50 [05:12<15:29, 25.12s/it]

26%|

Number of Robust matches 12150

28%| | 14/50 [05:31<13:57, 23.28s/it] Number of matches 58345 Number of matches After Lowe's Ratio 5456 Number of Robust matches 3889 30%| | 15/50 [05:43<11:42, 20.08s/it] Number of matches 81499 Number of matches After Lowe's Ratio 3471 Number of Robust matches 1966 32%| | 16/50 [05:59<10:36, 18.73s/it] Number of matches 63079 Number of matches After Lowe's Ratio 9610 Number of Robust matches 6701 34%| | 17/50 [06:14<09:45, 17.74s/it] Number of matches 114291 Number of matches After Lowe's Ratio 8634 Number of Robust matches 4714 36%| | 18/50 [06:38<10:23, 19.48s/it] Number of matches 116170 Number of matches After Lowe's Ratio 18935 Number of Robust matches 11406 38%| | 19/50 [07:01<10:35, 20.50s/it] Number of matches 119668 Number of matches After Lowe's Ratio 18911 Number of Robust matches 12735 40%| | 20/50 [07:25<10:52, 21.75s/it] Number of matches 117998 Number of matches After Lowe's Ratio 22979 Number of Robust matches 16462 Number of matches 132866 Number of matches After Lowe's Ratio 33225 | 21/50 [07:51<11:06, 22.98s/it] 42%| Number of Robust matches 22450 44%| | 22/50 [08:19<11:22, 24.36s/it] Number of matches 140126

Number of matches After Lowe's Ratio 9334

l 23/50 [08·47<11·27 25 48s/i+1

Number of Robust matches 6913

46%1

| 20/00 [00.1/11.21.2/ 20.100/10] Number of matches 141469 Number of matches After Lowe's Ratio 15281 Number of Robust matches 10019 48%| | 24/50 [09:15<11:24, 26.32s/it] Number of matches 145304 Number of matches After Lowe's Ratio 18170 Number of Robust matches 9201 50%| | 25/50 [09:43<11:12, 26.88s/it] Number of matches 140550 Number of matches After Lowe's Ratio 12908 Number of Robust matches 6371 52%| | 26/50 [10:11<10:53, 27.23s/it] Number of matches 145499 Number of matches After Lowe's Ratio 9533 Number of Robust matches 3913 | 27/50 [10:41<10:39, 27.81s/it] 54%| Number of matches 131418 Number of matches After Lowe's Ratio 16844 Number of Robust matches 7725 56%| 28/50 [11:06<09:57, 27.14s/it] Number of matches 118887 Number of matches After Lowe's Ratio 13539 Number of Robust matches 6862 58%| | 29/50 [11:30<09:10, 26.20s/it] Number of matches 120713 Number of matches After Lowe's Ratio 20902 Number of Robust matches 9338 60%| | 30/50 [11:54<08:29, 25.48s/it] Number of matches 119094 Number of matches After Lowe's Ratio 21504 Number of Robust matches 9107 Number of matches 110691 Number of matches After Lowe's Ratio 6409

Number of matches 128357

Number of Robust matches 3214

64%|

| 31/50 [12:17<07:52, 24.86s/it]

| 32/50 [12:40<07:16, 24.24s/it]

Number of Robust matches 4140  $\,$ 

66%| 33/50 [13:07<07:04, 24.96s/it]

Number of matches 157198

Number of matches After Lowe's Ratio 3021

Number of Robust matches 1039

68%| | 34/50 [13:37<07:06, 26.66s/it]

Number of matches 141400

Number of matches After Lowe's Ratio 13136

Number of Robust matches 5338

70%| | 35/50 [14:05<06:46, 27.09s/it]

Number of matches 162834

Number of matches After Lowe's Ratio 36

Number of Robust matches 8

72%| | 36/50 [14:37<06:36, 28.31s/it]

Number of matches 136771

Number of matches After Lowe's Ratio 10597

Number of Robust matches 4613

74%| 37/50 [15:04<06:02, 27.90s/it]

Number of matches 139861

Number of matches After Lowe's Ratio 7004

Number of Robust matches 2436

76%| | 38/50 [15:31<05:32, 27.72s/it]

Number of matches 121764

Number of matches After Lowe's Ratio 16901

Number of Robust matches 7137

78%| | 39/50 [15:55<04:51, 26.54s/it]

Number of matches 110405

Number of matches After Lowe's Ratio 5286

Number of Robust matches 2552

80%| 40/50 [16:15<04:07, 24.75s/it]

Number of matches 96942

Number of matches After Lowe's Ratio 10306

Number of Robust matches 3413

82%| 41/50 [16:35<03:30, 23.34s/it]

Number of matches 106417

Number of matches After Lowe's Ratio 15769

Number of Robust matches 6164

| 46/50 [18:33<01:35, 23.90s/it] 92%| Number of matches 121827 Number of matches After Lowe's Ratio 7500 Number of Robust matches 4169 | 47/50 [18:57<01:11, 23.99s/it] 94%| Number of matches 133957 Number of matches After Lowe's Ratio 5160 Number of Robust matches 3112 96%| 48/50 [19:24<00:49, 24.98s/it] Number of matches 132546 Number of matches After Lowe's Ratio 9959 Number of Robust matches 6884 98%| | 49/50 [19:50<00:24, 24.30s/it] Number of matches 122243 Number of matches After Lowe's Ratio 7812 Number of Robust matches 4973 In [20]: def warpnImages(images\_left, images\_right, H\_left, H\_right): #img1-centre,img2-left,img3-right h, w = images left[0].shape[:2] pts left = []

Number of matches 110856

Number of matches 119085

Number of matches 119392

Number of matches 128047

Number of Robust matches 5162

Number of Robust matches 179

Number of Robust matches 6113

Number of Robust matches 11975

Number of matches After Lowe's Ratio 26934

Number of matches After Lowe's Ratio 13437

Number of matches After Lowe's Ratio 580

Number of matches After Lowe's Ratio 10055

86%| 43/50 [17:20<02:39, 22.78s/it]

| 42/50 [16:57<03:03, 22.95s/it]

| 44/50 [17:43<02:18, 23.03s/it]

| 45/50 [18:08<01:57, 23.45s/it]

```
pts_right = []
   pts centre = np.float32([[0, 0], [0, h], [w, h], [w, 0]]).reshape(-1, 1, 2)
   for j in range(len(H left)):
     pts = np.float32([[0, 0], [0, h], [w, h], [w, 0]]).reshape(-1, 1, 2)
     pts left.append(pts)
   for j in range(len(H right)):
     pts = np.float32([[0, 0], [0, h], [w, h], [w, 0]]).reshape(-1, 1, 2)
     pts right.append(pts)
   pts left transformed=[]
   pts right transformed=[]
   for j,pts in enumerate(pts left):
     if j==0:
       H trans = H left[j]
     else:
       H_trans = H_trans@H_left[j]
     pts_ = cv2.perspectiveTransform(pts, H trans)
     pts left transformed.append(pts )
   for j,pts in enumerate(pts right):
     if j==0:
       H trans = H right[j]
     else:
       H trans = H trans@H right[j]
     pts = cv2.perspectiveTransform(pts, H trans)
     pts right transformed.append(pts )
   print('Step1:Done')
   #pts = np.concatenate((pts1, pts2), axis=0)
   pts concat = np.concatenate((pts centre, np.concatenate(np.array(pts left transformed
),axis=0),np.concatenate(np.array(pts_right_transformed),axis=0)), axis=0)
    [xmin, ymin] = np.int32(pts concat.min(axis=0).ravel() - 0.5)
   [xmax, ymax] = np.int32(pts concat.max(axis=0).ravel() + 0.5)
   t = [-xmin, -ymin]
   Ht = np.array([[1, 0, t[0]], [0, 1, t[1]], [0, 0, 1]]) # translate
   print('Step2:Done')
   return xmax, xmin, ymax, ymin, t, h, w, Ht
```

## In [21]:

```
def final steps left union(images left, H left, xmax, xmin, ymax, ymin, t, h, w, Ht):
    for j,H in enumerate(H left):
        if j== 0:
            H trans = Ht@H
        else:
            H_trans = H_trans@H
        result = cv2.warpPerspective(images left[j+1], H trans, (xmax-xmin, ymax-ymin))
        warp img init curr = result
        if j == 0:
            result[t[1]:h+t[1],t[0]:w+t[0]] = images left[0]
            warp img init prev = result
            continue
        black_pixels = np.where((warp_img_init_prev[:,:,0]==0)&(warp_img_init_prev[:,:,1
]==0) & (warp img init prev[:,:,2]==0))
        warp img init prev[black pixels] = warp img init curr[black pixels]
    print('step31:Done')
```

```
return warp_img_init_prev
def final step right union (warp img prev, images right, H right, xmax, xmin, ymax, ymin, t, h, w,
Ht):
             for j,H in enumerate(H right):
                         if j== 0:
                                      H trans = Ht@H
                         else:
                                      H trans = H trans@H
                         result = cv2.warpPerspective(images right[j+1], H trans, (xmax-xmin, ymax-ymin))
                         warp img init curr = result
                         black pixels = np.where((warp img prev[:,:,0]==0) & (warp img prev[:,:,1]==0) & (warp img prev[:,:]=0) & (
p img prev[:,:,2]==0))
                         warp img prev[black pixels] = warp img init curr[black pixels]
             print('step32:Done')
            return warp_img_prev
In [27]:
xmax, xmin, ymax, ymin, t, h, w, Ht = warpnImages (images left bgr no enhance, images right bgr
no enhance, H left superpoint, H right superpoint)
Step1:Done
Step2:Done
In [ ]:
warp imgs left = final steps left union(images left bgr no enhance, H left superpoint, xmax
, xmin, ymax, ymin, t, h, w, Ht)
In [ ]:
warp imgs all star = final step right union(warp imgs left,images right bgr no enhance, H
```

right star,xmax,xmin,ymax,ymin,t,h,w,Ht)

## In [ ]:

xmax, xmin, ymax, ymin, t, h, w, Ht = warpnImages (images left bgr no enhance, images right bgr no\_enhance,H\_left\_star,H\_right\_star)

## In [ ]:

warp imgs left = final steps left union(images left bgr no enhance, H left star, xmax, xmin, ymax,ymin,t,h,w,Ht)

## In [ ]:

warp imgs all star = final step right union(warp imgs left,images right bgr no enhance, H right star, xmax, xmin, ymax, ymin, t, h, w, Ht)

## In [ ]:

```
plt.figure(figsize=(20,20))
plt.imshow(warp_imgs_all_star)
plt.title(' Mosaic using STAR Image')
```

# In [ ]:

omax,omin,umax,umin,T,H,W,HT = warpnImages(images left bgr no enhance, images right bgr no enhance, H left sift, H right sift)

## In [ ]:

warp img = final steps left union(images left bgr no enhance, H left sift, omax, omin, umax, u min, T, H, W, HT)

```
In [ ]:
warp imgs all sift = final step right union(warp img,images right bgr no enhance,H right
sift,omax,omin,umax,umin,T,H,W,HT)
In [ ]:
plt.figure(figsize=(20,20))
plt.imshow(warp imgs all sift)
plt.title(' Mosaic using SIFT Image')
In [ ]:
mmax, mmin, nmax, nmin, d, e, f, g = warpnImages (images left bgr no enhance, images right bgr n
o enhance,H_left_fast,H_right_fast)
In [ ]:
warp imgs fast = final steps left union(images left bgr no enhance, H left fast, mmax, mmin,
nmax, nmin, d, e, f, g)
In [ ]:
warp imgs all fast = final step right union(warp imgs fast, images right bgr no enhance, H
right fast, mmax, mmin, nmax, nmin, d, e, f, g)
In [ ]:
plt.figure(figsize=(20,20))
plt.imshow(warp_imgs_all_fast)
plt.title(' Mosaic using FAST Image')
In [24]:
omax, omin, umax, umin, T, H, W, HT = warpnImages (images left bgr no enhance, images right bgr
no enhance, H left akaze, H right akaze)
Step1:Done
Step2:Done
In [ ]:
warp_img_kaze = final_steps_left_union(images_left_bgr_no_enhance,H_left_akaze,omax,omin,
umax, umin, T, H, W, HT)
In [ ]:
warp imgs all akaze = final step right union(warp img kaze,images right bgr no enhance, H
right akaze,omax,omin,umax,umin,T,H,W,HT)
In [ ]:
plt.figure(figsize=(20,20))
plt.imshow(warp imgs all akaze)
plt.title('Mosaic using Akaze Image')
In [22]:
amax, amin, zmax, zmin, d, i, q, ht = warpnImages (images left bgr no enhance, images right bgr
no enhance, H left freak, H right freak)
Step1:Done
Step2:Done
In [23]:
warp image left = final steps left union(images left bgr no enhance, H left freak, amax, ami
n, zmax, zmin, d, i, q, ht)
```

step31:Done

# In [24]:

warp\_imgs\_all\_gftt = final\_step\_right\_union(warp\_image\_left,images\_right\_bgr\_no\_enhance,H
\_right\_freak,amax,amin,zmax,zmin,d,i,q,ht)

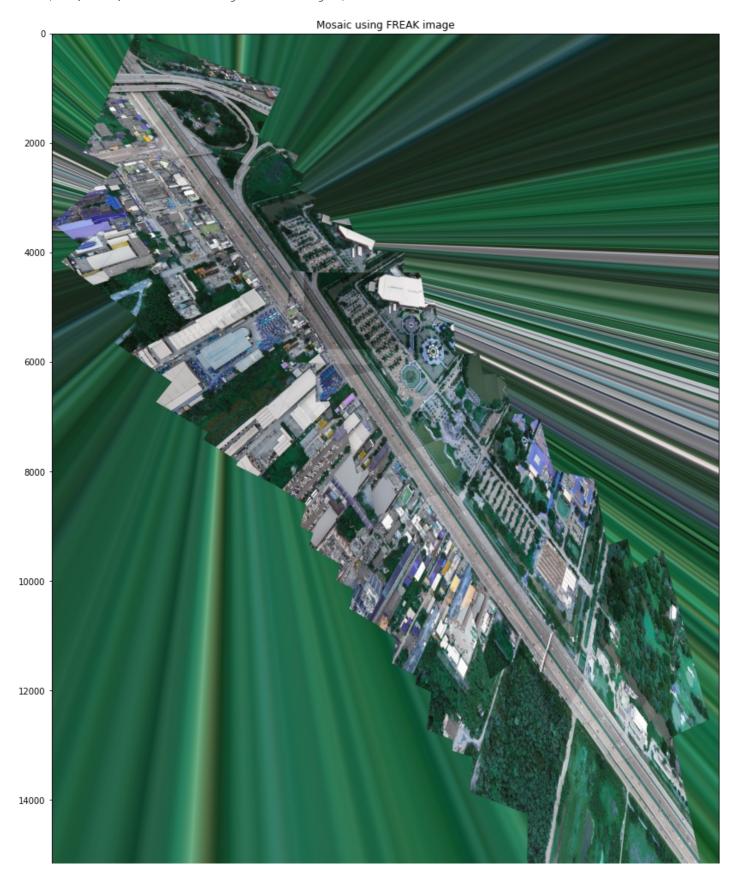
step32:Done

# In [26]:

```
plt.figure(figsize=(20,20))
plt.imshow(warp_imgs_all_gftt)
plt.title('Mosaic using FREAK image')
```

## Out[26]:

Text(0.5, 1.0, 'Mosaic using FREAK image')



#### In [22]:

amax,amin,zmax,zmin,d,i,q,ht = warpnImages(images\_left\_bgr\_no\_enhance, images\_right\_bgr\_
no enhance,H left fast,H right fast)

Step1:Done
Step2:Done

#### In [ ]:

warp\_image\_left = final\_steps\_left\_union(images\_left\_bgr\_no\_enhance,H\_left\_fast,amax,amin
,zmax,zmin,d,i,q,ht)

## In [ ]:

warp\_imgs\_all\_agast = final\_step\_right\_union(warp\_image\_left,images\_right\_bgr\_no\_enhance,
H\_right\_fast,amax,amin,zmax,zmin,d,i,q,ht)

## In [ ]:

```
plt.figure(figsize=(20,20))
plt.imshow(warp_imgs_all_fast)
plt.title('Mosaic using FAST image')
```

## In [23]:

amax,amin,zmax,zmin,d,i,q,ht = warpnImages(images\_left\_bgr\_no\_enhance, images\_right\_bgr\_ no\_enhance,H\_left\_agast,H\_right\_agast)

Step1:Done
Step2:Done

#### In [ ]:

warp\_image\_left = final\_steps\_left\_union(images\_left\_bgr\_no\_enhance,H\_left\_agast,amax,ami
n,zmax,zmin,d,i,q,ht)

#### In [ ]:

warp\_imgs\_all\_agast = final\_step\_right\_union(warp\_image\_left,images\_right\_bgr\_no\_enhance,
H\_right\_agast,amax,amin,zmax,zmin,d,i,q,ht)

## In [ ]:

```
plt.figure(figsize=(20,20))
plt.imshow(warp_imgs_all_agast)
plt.title('Mosaic using AGAST image')
```

#### In [ ]: