```
import cv2
from mpl toolkits.basemap import Basemap
import os
import glob
img_dir = "../input/uni-campus-dataset/RGB-img" # Enter Directory of all images
Category = ['img']
for category in Category:
    folder = os.path.join(img_dir,category)
for files in os.listdir(folder):
    img path = os.path.join(folder,files)
                                                                                                       In [107]:
import exifread
from PIL import Image
from PIL.ExifTags import TAGS, GPSTAGS
import pandas as pd
def get exif data(image):
    """Returns a dictionary from the exif data of an PIL Image item. Also converts the GPS Tags"""
    exif data = {}
    info = image._getexif()
    if info:
        for tag, value in info.items():
            decoded = TAGS.get(tag, tag)
            if decoded == "GPSInfo":
                gps_data = {}
                for t in value:
                     sub decoded = GPSTAGS.get(t, t)
                     gps_data[sub_decoded] = value[t]
                exif_data[decoded] = gps_data
            else:
                exif data[decoded] = value
    return exif data
def get if exist(data, key):
    if key in data:
        return data[key]
    return None
def _convert_to_degress(value):
    """Helper function to convert the GPS coordinates stored in the EXIF to degress in float format"""
    d0 = value[0]
    d = float(d0)
    m1 = value[1]
    m = float(m1)
    s0 = value[2]
    s = float(s0)
    return d + (m / 60.0) + (s / 3600.0)
def get lat lon(exif data):
    """Returns the latitude and longitude, if available, from the provided exif data (obtained through g_{i}
    lat = None
    lon = None
    if "GPSInfo" in exif data:
        gps_info = exif_data["GPSInfo"]
        gps latitude = get if exist(gps info, "GPSLatitude")
        gps_latitude_ref = _get_if_exist(gps_info, 'GPSLatitudeRef')
        gps longitude = get if exist(gps info, 'GPSLongitude')
        gps_longitude_ref = _get_if_exist(gps_info, 'GPSLongitudeRef')
```

```
if gps_latitude and gps_latitude_ref and gps_longitude and gps_longitude_ref:
             lat = convert to degress(gps latitude)
             if gps_latitude_ref != "N":
                 lat = 0 - lat
             lon = convert to degress(gps longitude)
             if gps longitude ref != "E":
                 lon = 0 - lon
    return lon, lat
################
# Example #####
#################
if __name__ == "__main__":
    img_dir = "../input/uni-campus-dataset/RGB-img" # Enter Directory of all images
    Category = ['img']
    for category in Category:
        folder = os.path.join(img_dir,category)
    for files in os.listdir(folder):
        data = []
        img path = os.path.join(folder,files)
        image = Image.open(img_path)
        exif_data = get_exif_data(image)
(lon,lat) = get_lat_lon(exif_data)
        print(lat)
```

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                                                                                                                                                                                                                                          In [ ]:
 data
                                                                                                                                                                                                                                     In [111]:
 from mpl_toolkits.basemap import Basemap
 import matplotlib.pyplot as plt
 import numpy as np
 fig = plt.figure(figsize=(12,5))
 m = Basemap(projection='mill',
                             llcrnrlat=-90,
                             urcrnrlat=90,
                             llcrnrlon=-180,
                             urcrnrlon=180,
                            resolution='c')
 m.drawcoastlines()
 m.drawparallels(np.arange(-90,90,10),labels=[True,False,False,False])
 m.drawmeridians(np.arange(-180,180,30), labels=[0,0,0,1])
 lon = [100.61806575638889, 100.60708245472222, 100.61606427166666], \#100.60805817666666, 100.61008061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944443, 100.608061944444, 100.608061944444, 100.608061944444, 100.608061944444, 100.608061944444, 100.608061944444, 100.60806194444, 100.60806194444, 100.60806194444, 100.60806194444, 100.60806194444, 100.60806194444, 100.60806194444, 100.6080619444, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.608061944, 100.60
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```

lat = [14.073395685277777,14.067295146944444,14.066033934722222]#14.067816876111111,14.073615746666666

m.scatter(lon,lat,latlon=True,s=5000,marker='^')
plt.title('Basemap', fontsize=20)
plt.show()



