Implement vaccum cleaner agent with 2 room setup.

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_	Implement vaccum cleanes agent for 2 sooms. Ente
	Algorithm: Ent
	Study To a series and Southed relate with dust and a
	Step 2: Implement 2x2 initial state with dust and vaccum cleanes and 2 Step 3: Vaccum cleanes is in some A and the in
	to the some of the some
	o was sucks dust
	Steps: Vc moves left and sucks dust in soom A.
	Step 6: Both scoms are clean a goal state is achieved Step 7: End
	THE PARTY OF THE P
	Implement vaccum
	Implement vaccum creanex agent for 4 rooms.
_	Step 1 Start
_	The second secon
30	step 2: 4 800ms A.B.C.D all are disty and vaccum cleaner is
9	tep 3: If room A is dirty, such dust
S	tep4: Ask wer for hard 10 10
C	tep4: Ask uses for input if they want to go to soom B or roome
	teps: If soom B is disty:
	suck dust and come down to soom D and go to step ?
Sh	To com C is disty:
	suck dust and go to room D and go to step 7
Sto	ep7: If 800m 0 is disty: 2 and a sun of billion +2: 1 the
	Court but the state of the stat
	suck dust and go to step 6
Ste	p8 Goal state is achieved, all go rooms are clean
0	go occaris ase clean
216	P9: End, putilists entire placem 4 essents unpag on taxable strains
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Code:

```
def vacuum_cleaner():
  # Input the state of rooms A and B
  state_A = int(input("Enter state of A (0 for clean, 1 for dirty): "))
  state_B = int(input("Enter state of B (0 for clean, 1 for dirty): "))
  location = input("Enter location (A or B): ").upper()
  cost = 0
  rooms = {'A': state_A, 'B': state_B}
  # Function to clean a room if dirty
  def clean_room(room):
     nonlocal cost
    if rooms[room] == 1:
       print(f"Cleaned {room}.")
       rooms[room] = 0
       cost += 1
    else:
       print(f"{room} is clean.")
  # Start cleaning based on location
  if location == 'A':
    clean_room('A')
     print("Moving vacuum right")
    clean_room('B')
  elif location == 'B':
    clean_room('B')
     print("Moving vacuum left")
    clean_room('A')
  else:
```

```
print("Invalid starting location!")

print(f"Cost: {cost}")

print(rooms)

if __name__ == "__main__":
    vacuum_cleaner()
```

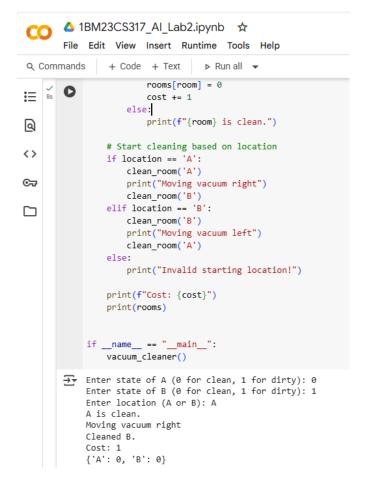
Outputs:

```
△ 1BM23CS317_Al_Lab2.ipynb ☆ △
       File Edit View Insert Runtime Tools Help
Q Commands
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                        rooms[room] = 0
:≡ 12s
       0
                        cost += 1
                    else:
                        print(f"{room} is clean.")
Q
                # Start cleaning based on location
<>
                if location == 'A':
                    clean_room('A')
☞
                    print("Moving vacuum right")
                    clean_room('B')
                elif location == 'B':
clean room('B')
                    print("Moving vacuum left")
                    clean_room('A')
                else:
                    print("Invalid starting location!")
                print(f"Cost: {cost}")
                print(rooms)
            if __name__ == "__main__":
                vacuum_cleaner()

→ Enter state of A (0 for clean, 1 for dirty): 1

            Enter state of B (0 for clean, 1 for dirty): 1
            Enter location (A or B): A
            Cleaned A.
            Moving vacuum right
            Cleaned B.
            Cost: 2
            {'A': 0, 'B': 0}
```

```
△ 1BM23CS317_Al_Lab2.ipynb ☆ ⑤ Saving...
        File Edit View Insert Runtime Tools Help
Q Commands + Code + Text ▶ Run all ▼
                          rooms[room] = 0
≔ 11s ○
                          cost += 1
        Run cell (Ctrl+Enter)
cell executed since last change f"{room} is clean.")
Q
        executed by Shreya Raj
2:35 PM (0 minutes ago)
executed in 11.438s 'A':
                                 ng based on location
<>
☞
                      print("Moving vacuum right")
                      clean_room('B')
                  elif location == 'B':
clean_room('B')
                      print("Moving vacuum left")
                      clean_room('A')
                      print("Invalid starting location!")
                  print(f"Cost: {cost}")
                  print(rooms)
             if __name__ == "__main__":
                  vacuum_cleaner()
        \rightarrow Enter state of A (0 for clean, 1 for dirty): 1
             Enter state of B (0 for clean, 1 for dirty): 0
             Enter location (A or B): B
             B is clean.
             Moving vacuum left
             Cleaned A.
             Cost: 1
             {'A': 0, 'B': 0}
```



△ 1BM23CS317_Al_Lab2.ipynb ☆ File Edit View Insert Runtime Tools Help Q Commands + Code + Text ▶ Run all ▼ rooms[room] = 0 0 ∷ cost += 1 else: print(f"{room} is clean.") Q # Start cleaning based on location <> if location == 'A': clean room('A') ☞ print("Moving vacuum right") clean room('B') elif location == 'B': \Box clean_room('B') print("Moving vacuum left") clean room('A') else: print("Invalid starting location!") print(f"Cost: {cost}") print(rooms) if __name__ == "__main__": vacuum_cleaner() → Enter state of A (0 for clean, 1 for dirty): 0 Enter state of B (0 for clean, 1 for dirty): 0 Enter location (A or B): B

B is clean.

A is clean. Cost: 0

Moving vacuum left

{'A': 0, 'B': 0}

Implement vaccum cleaner agent with 4 room setup.

```
Code:
# The state of each room (True = dirty, False = clean)
rooms = {
  'A': True,
  'B': True,
  'C': True,
  'D': True
}
# The agent's current location
current_room = 'A'
def vacuum_cleaner_agent():
  Simulates a vacuum cleaner agent cleaning four rooms without getting into an infinite
loop.
  ,,,,,,
  global current_room
  print("---Starting Vacuum Cleaner Agent---")
  print("Initial state:", rooms)
  print("Agent starts in room A.")
  # A set to track visited rooms to avoid loops
  visited = set()
  # While there's any dirty room left
  while any(rooms.values()):
```

```
# Clean the current room if dirty
     if rooms[current_room]:
       print(f"\nSucking dust in room {current_room}...")
       rooms[current_room] = False
       print(f"Room {current_room} is now clean.")
     visited.add(current_room)
     # Decide where to go next based on current location and available dirty rooms
     next_room = None
     if current_room == 'A':
       # Ask user only if both B and C are dirty and unvisited
       options = [room for room in ['B', 'C'] if rooms[room] and room not in visited]
       if options:
          while True:
            user_choice = input(f"Do you want to go to room {options[0]} or room
{options[-1]}? (Type '{options[0]}' or '{options[-1]}'): ").upper()
            if user_choice in options:
              next_room = user_choice
              break
            else:
              print("Invalid input. Please choose a valid dirty room.")
       else:
          # Default to B or C if no input needed
          for room in ['B', 'C']:
            if rooms[room] and room not in visited:
              next_room = room
              break
     elif current_room == 'B':
       if rooms['D'] and 'D' not in visited:
```

```
print("Moving to room D.")
     next\_room = 'D'
  elif rooms['A'] and 'A' not in visited:
     next_room = 'A'
elif current_room == 'C':
  if rooms['D'] and 'D' not in visited:
     print("Moving to room D.")
     next\_room = 'D'
  elif rooms['A'] and 'A' not in visited:
     next\_room = 'A'
elif current_room == 'D':
  if rooms['C'] and 'C' not in visited:
     print("Moving to room C.")
     next room = 'C'
  elif rooms['B'] and 'B' not in visited:
     next room = 'B'
# Fallback: find any remaining dirty room not visited yet
if not next_room:
  for room in ['A', 'B', 'C', 'D']:
     if rooms[room] and room not in visited:
       next_room = room
       break
if next_room:
  print(f"Moving to room {next_room}.")
  current_room = next_room
else:
```

No dirty unvisited rooms left break

```
print("\n---Goal State Achieved---")
print("All rooms are clean:", rooms)
print("---Agent is done---")
# Run the simulation
vacuum_cleaner_agent()
```

Outputs:

```
△ 1BM23CS317_Al_Lab2b.ipynb ☆ △
       File Edit View Insert Runtime Tools Help
Q Commands
                + Code + Text
                                   ▶ Run all ▼
       0
                    if next room:
:≡ | ∠s |
                        print(f"Moving to room {next_room}.")
                        current_room = next_room
Q
                        # No dirty unvisited rooms left
<>
                        break
                print("\n---Goal State Achieved---")
©⊋
                print("All rooms are clean:", rooms)
                print("---Agent is done---")
# Run the simulation
            vacuum_cleaner_agent()
       → ---Starting Vacuum Cleaner Agent---
            Initial state: {'A': True, 'B': True, 'C': True, 'D': True}
            Agent starts in room A.
            Sucking dust in room A...
            Room A is now clean.
            Do you want to go to room B or room C? (Type 'B' or 'C'): C
            Moving to room C.
            Sucking dust in room C...
            Room C is now clean.
            Moving to room D.
            Moving to room D.
            Sucking dust in room D...
            Room D is now clean.
            Moving to room B.
            Sucking dust in room B...
            Room B is now clean.
            ---Goal State Achieved---
            All rooms are clean: {'A': False, 'B': False, 'C': False, 'D': False}
            ---Agent is done---
```