

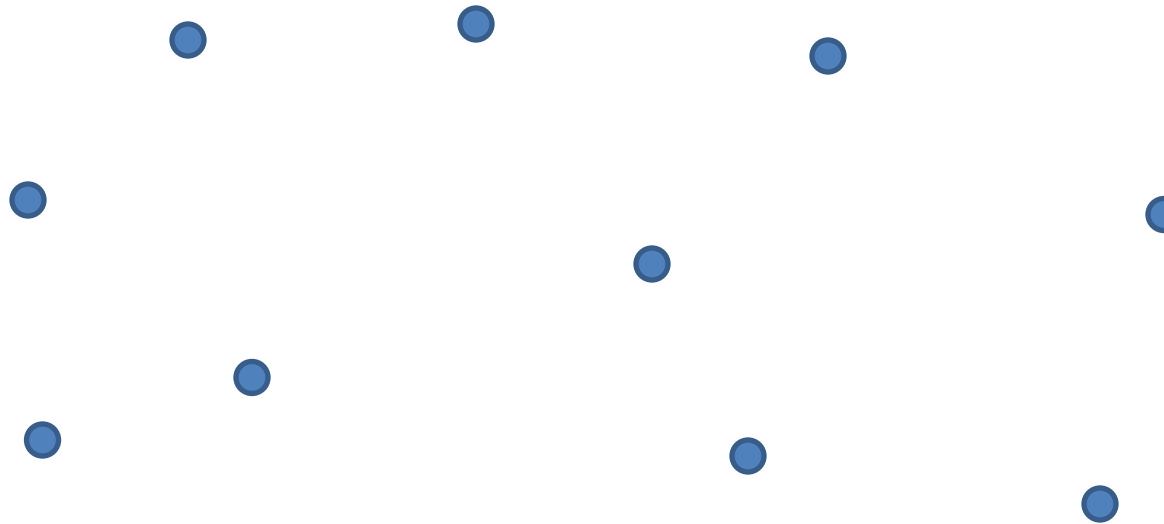
# **Module – 5 Geometric Algorithms**

## **Voronoi Diagram and Delaunay Triangulation**

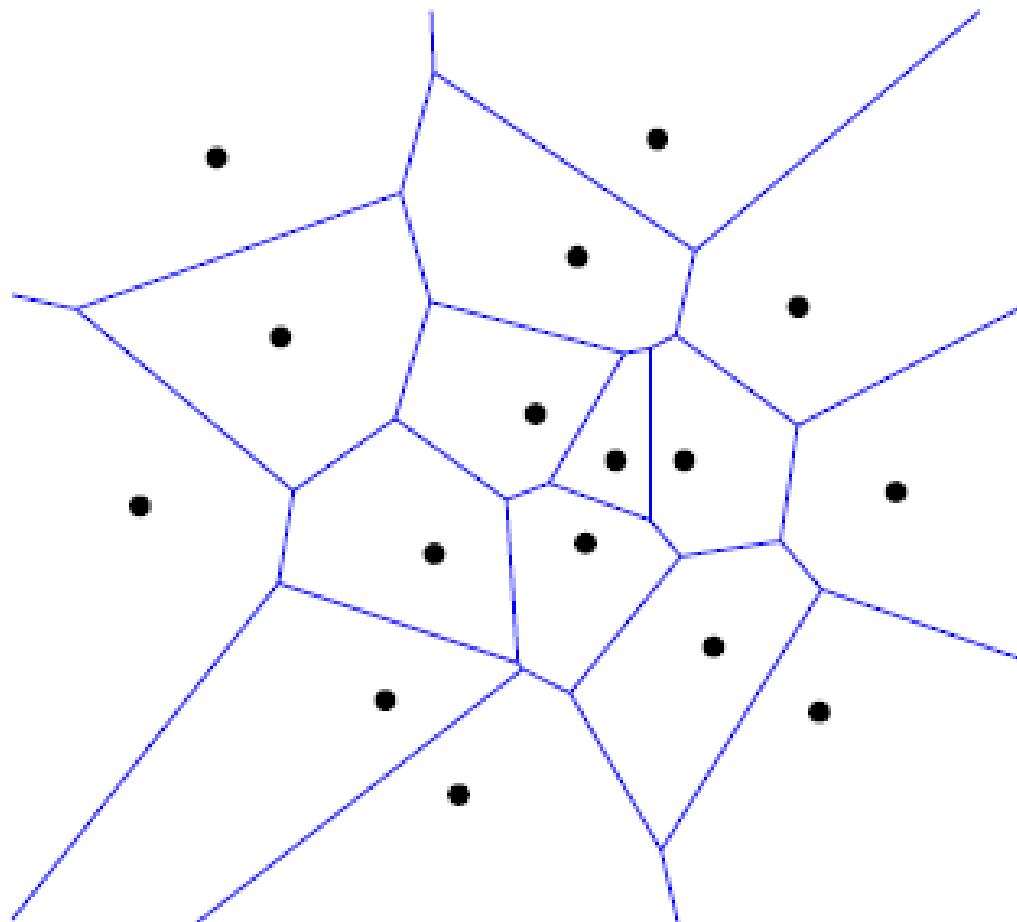
# Definition

- Voronoi Diagrams encode ***proximity information*** that help answer questions like:
  - **"Which object is closest to point p?"**
  - **"where is the nearest hospital from q?"**
- For a given set of objects,
  - called sites, each Voronoi cell defines the set of points in the plane
  - (or in any higher dimension) that are closer to each site than to any other site.
  - The outline of all ***voronoi cells*** form the ***Voronoi Diagram***.

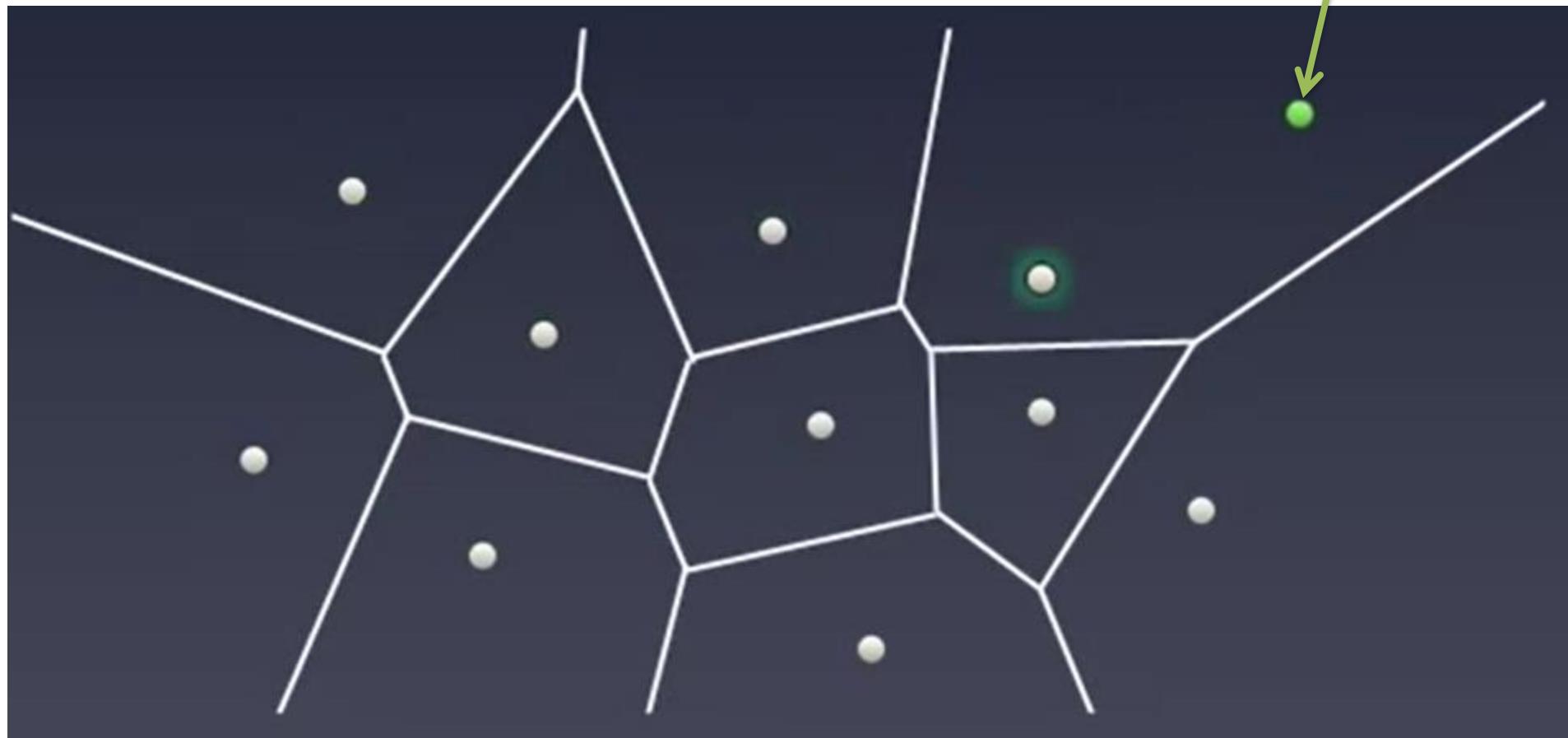
# Example: Set of sites



# Voronoi Diagram of Point set

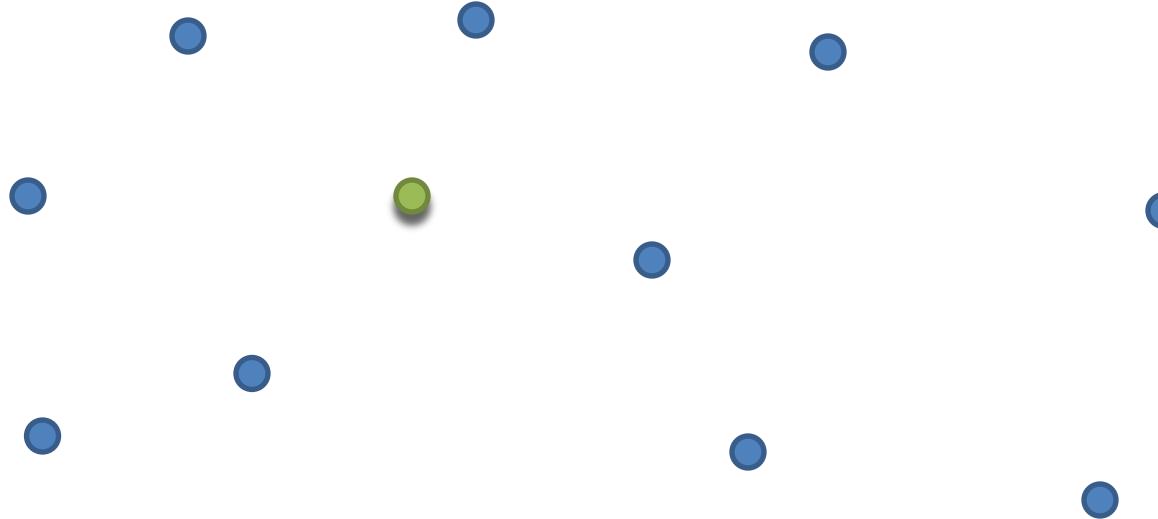


# How to find the query point q?



# Without Voronoi Diagram

- The increase in difficulty without a voronoi diagram.
- **O(n)** distance queries will be computed every frame



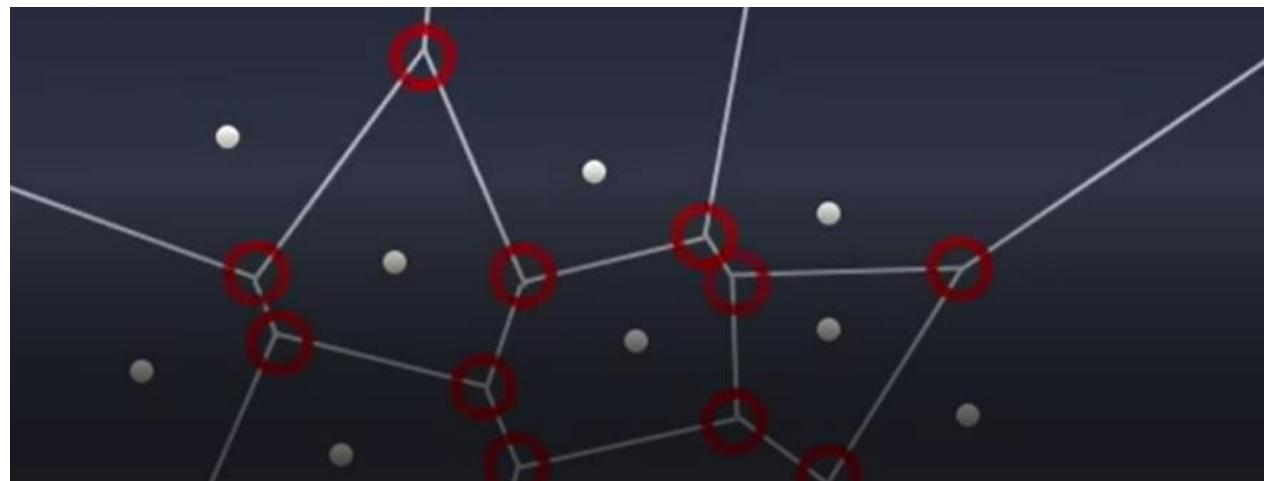
# With Voronoi Diagram

Given a voronoi diagram,

a point location query on the cell containing q can now be done in only  **$O(\log n)$  times.**

# Property #1

- Voronoi diagram is a *planar graph where every vertex is of degree 3* (assuming general position, where no sites are cocircular)

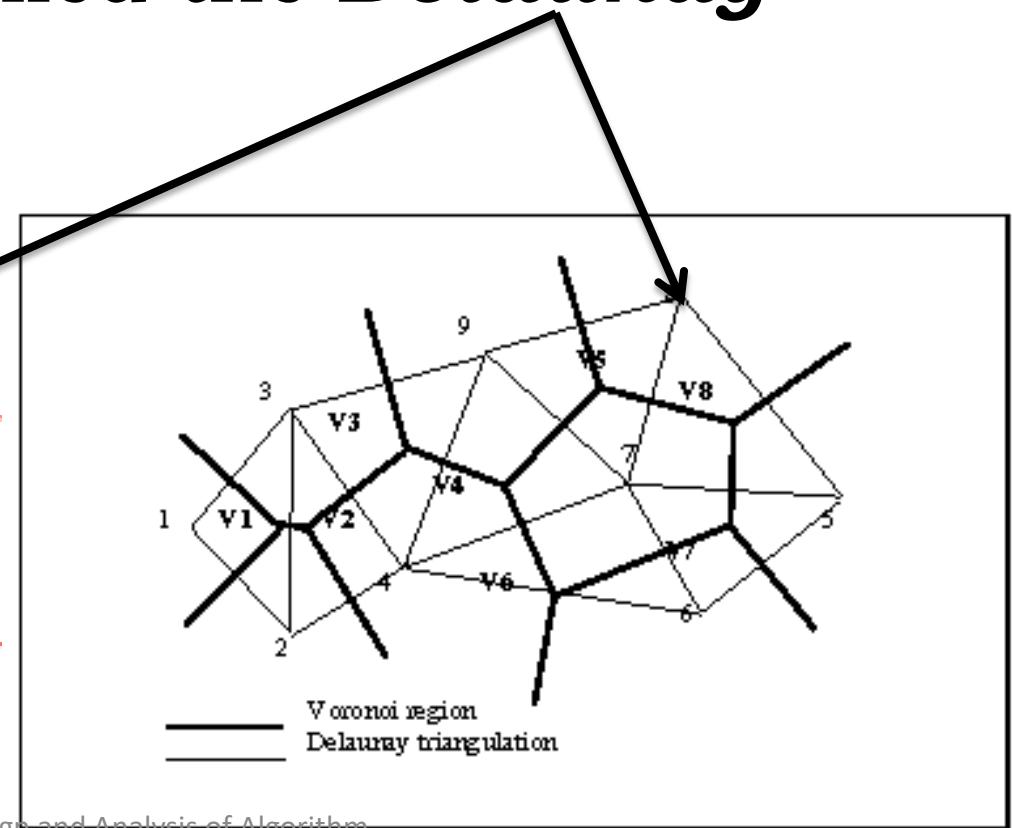
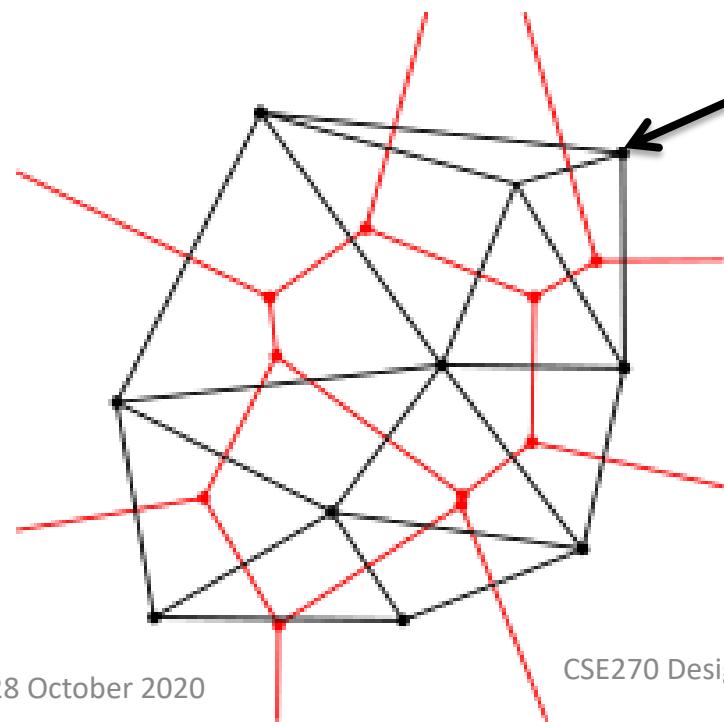


# Property #2

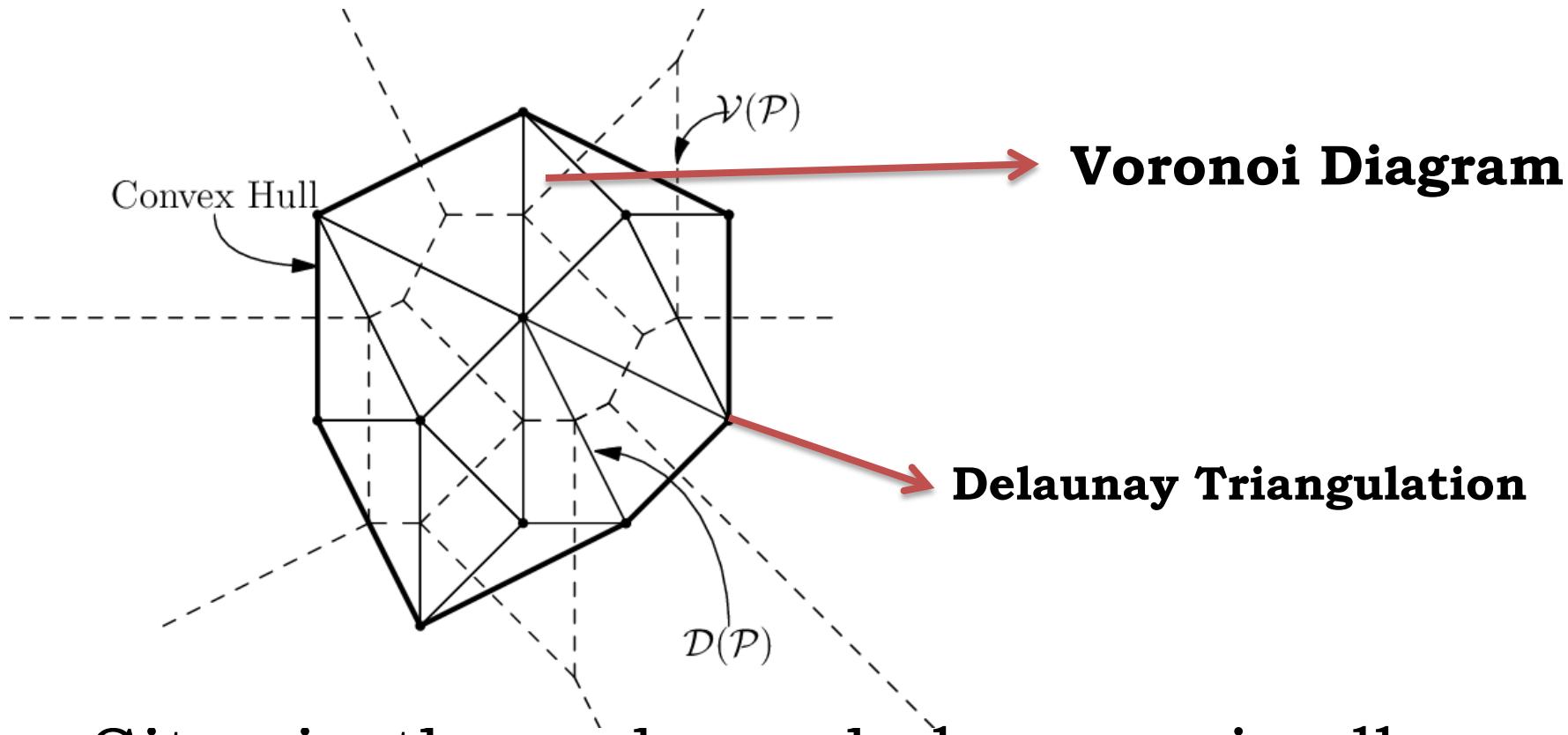
- The complexity of Voronoi diagram is ***linear***.
  - For  $n$  sites, there are ***n faces***, at most ***2n-5 vertices*** and at most ***3n-6 edges***.

# Property #3

- The dual graph forms a special kind of triangulation called the **Delaunay Triangulation**.



# Property #4



- Sites in the unbounded voronoi cells correspond to the vertices of the ***convex hull***

# General Properties

- If the points  $P$  are collinear, the voronoi diagram consists of  $n-1$  parallel lines forming  $n$  cells.
- If the points  $P$  are not collinear, the edges of the voronoi diagram are segments, or half lines( which may terminate at useful border).
- The number of vertices in a voronoi diagram of a set of  $n$  points is at most  $2n-5$  and the number of edges are at most  $3n-6$ .
- Voronoi cells or voronoi partitions are convex.
- The voronoi cell of  $P_i$  is unbounded if  $P_i$  lies on the convex hull of  $P$ .
- "Largest Empty Circle of  $q$  wrt  $P$ " is the largest circle whose center is  $q$  and which contains no point of  $P$  in its interior.
- A point  $q$  is a vertex of a voronoi diagram if its largest empty circle has three or more points of  $P$  on its circumference.
- This circle is the circumcircle of the corresponding Delaunay Triangle.
- The bisector between  $P_i$  and  $P_j$  defines an edge of the voronoi diagram of  $P$  iff there is a point  $q$  in the plane such that its largest empty circle contains both  $P_i$  and  $P_j$  on its circumference and no other member of  $P$ .

# PROPERTIES (without proofs)

- If the points  $P$  are collinear, the **voronoi diagram** consists of  **$n-1$  parallel lines forming  $n$  cells**.
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- The number of vertices in a voronoi diagram of a set of  $n$  points is at most  **$2n-5$**  and the number of edges are **at most  $3n-6$** .
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# Applications

- **Nearest neighbor search:** For a query point ,
  - finding its nearest neighbor from a fixed set of points is simply a matter of determining which cell in the Voronoi diagram of contains .
- **Facility location:** Suppose McDonald's wanted to open another restaurant.
  - To minimize interference with existing McDonald's, it should be located as far away from the closest restaurant as possible.
  - This location is always at a vertex of the Voronoi diagram, and it can be found in a linear-time search through all the Voronoi vertices.
- **Largest empty circle:** Suppose you needed to obtain a large,
  - contiguous, undeveloped piece of land on which to build a factory.
  - The same condition used for picking McDonald's locations is appropriate for other undesirable facilities, namely that it be as far as possible from any relevant sites of interest.
  - A Voronoi vertex defines the center of the largest empty circle among the points.
- **Path planning:** If the sites of are the centers of obstacles we seek to avoid,
  - the edges of the Voronoi diagram define the possible channels that maximize the distance to the obstacles.
  - Thus in planning paths among the sites, it will be safest to stick to the edges of the Voronoi diagram.