

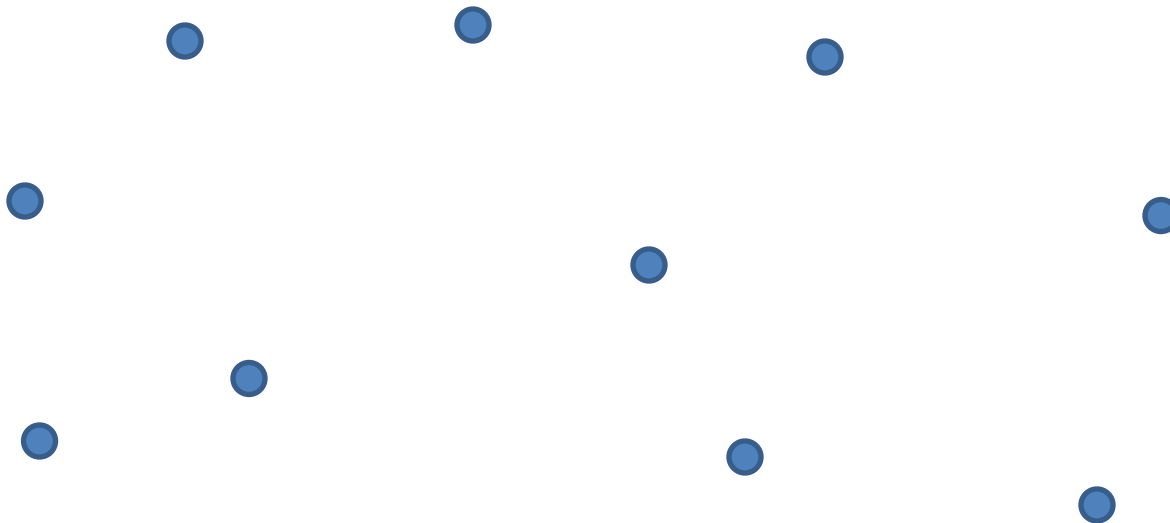
Module – 5 Geometric Algorithms

Voronoi Diagram and Delaunay Triangulation

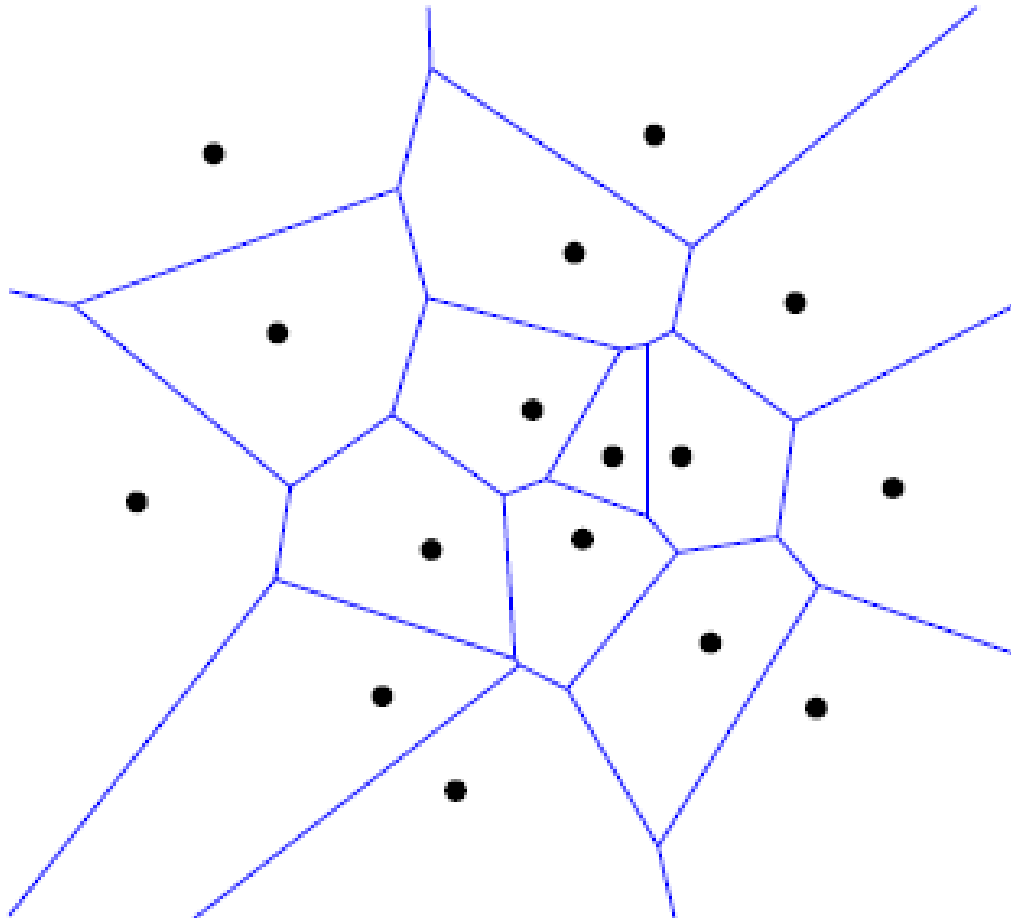
Definition

- Voronoi Diagrams encode ***proximity information*** that help answer questions like:
 - ***"Which object is closest to point p ?"***
 - ***"where is the nearest hospital from q ?"***
- For a given set of objects,
 - called sites, each Voronoi cell defines the set of points in the plane
 - (or in any higher dimension) that are closer to each site than to any other site.
 - The outline of all ***voronoi cells*** form the ***Voronoi Diagram***.

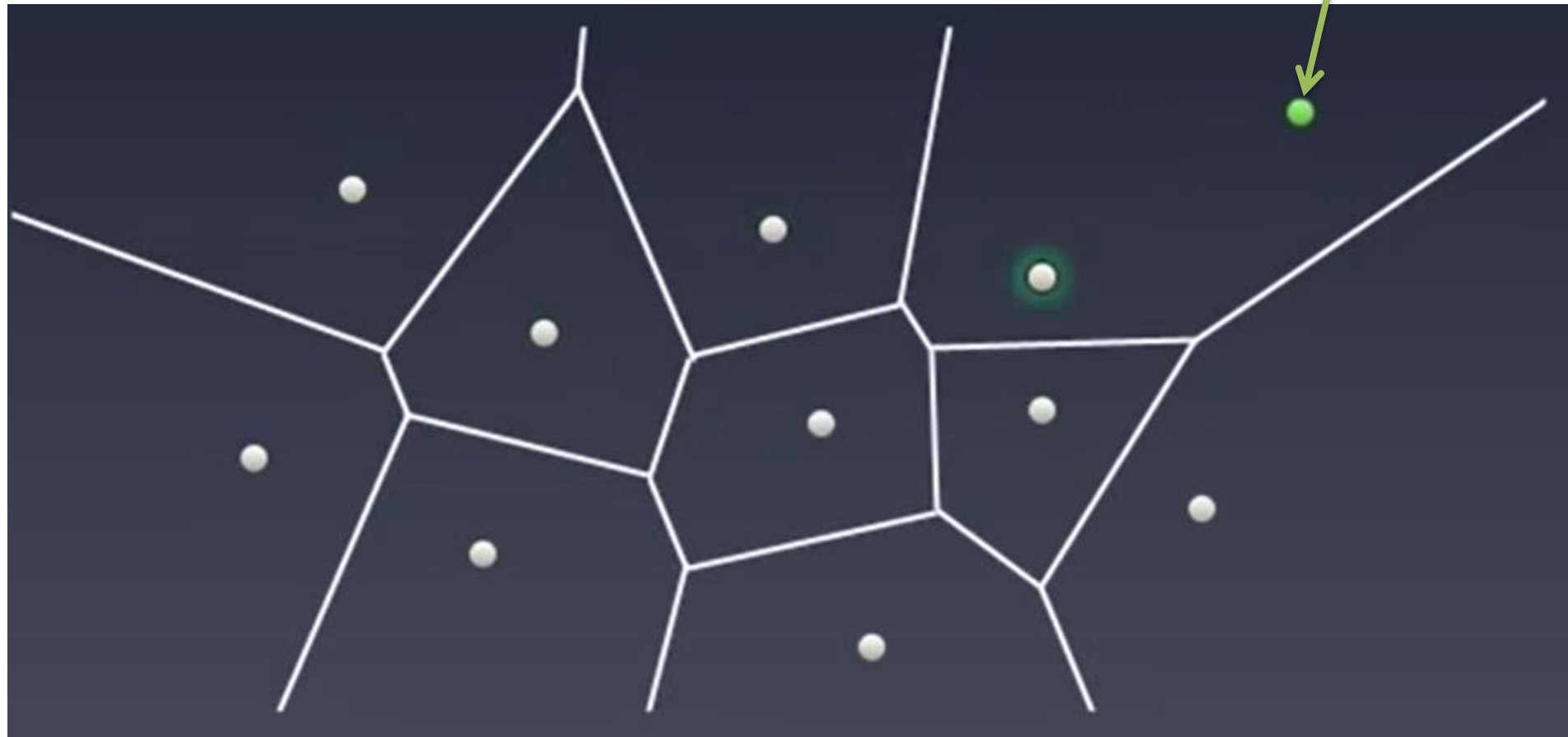
Example: Set of sites



Voronoi Diagram of Point set

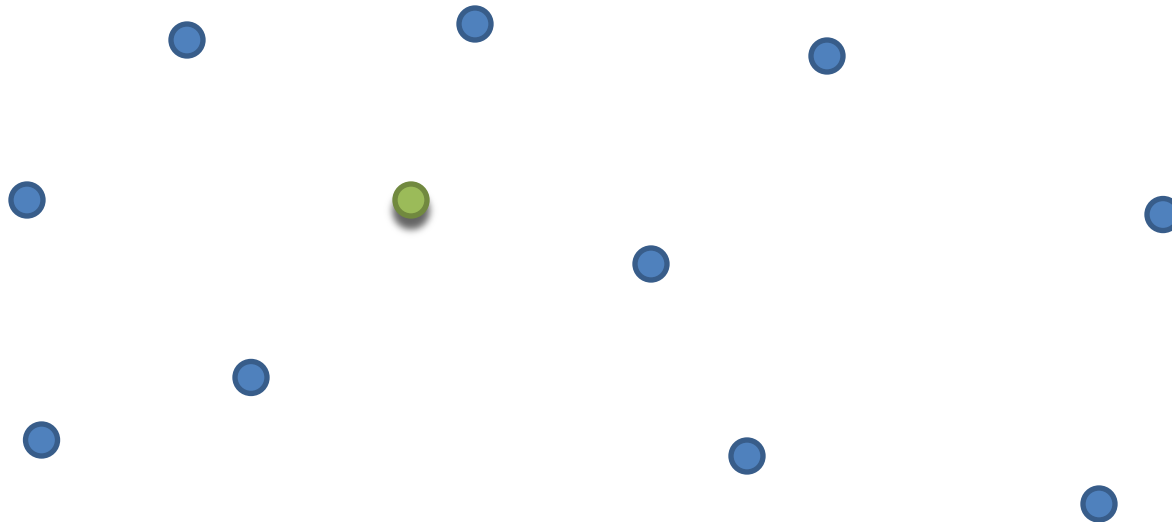


How to find the query point q ?



Without Voronoi Diagram

- The increase in difficulty without a voronoi diagram.
- **$O(n)$** distance queries will be computed every frame



With Voronoi Diagram

Given a voronoi diagram,

a point location query on the cell containing q can now be done in only **$O(\log n)$ times.**

Property #1

- Voronoi diagram is a ***planar graph where every vertex is of degree 3*** (assuming general position, where no sites are cocircular)

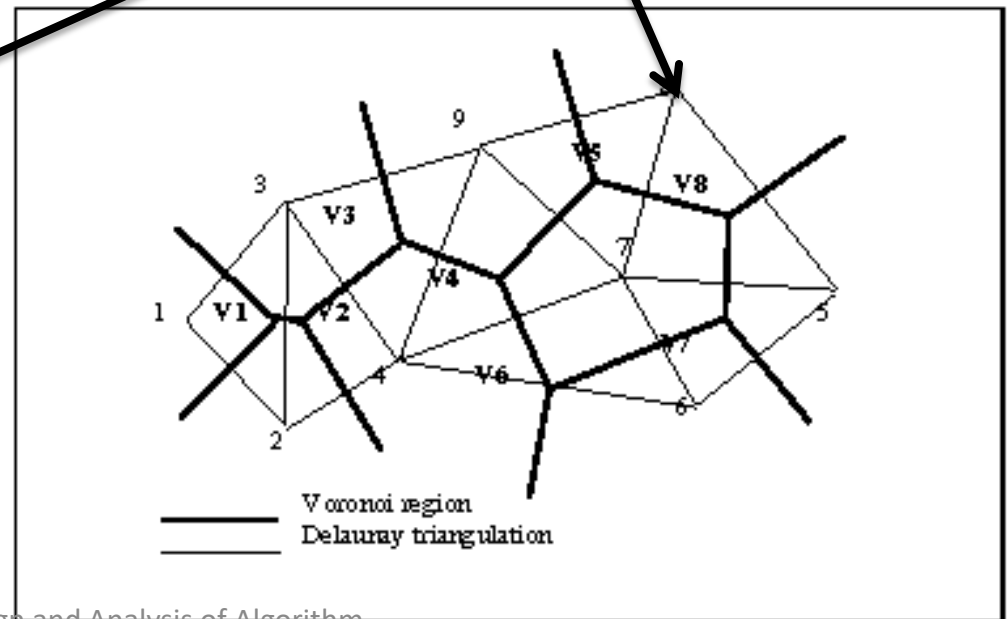
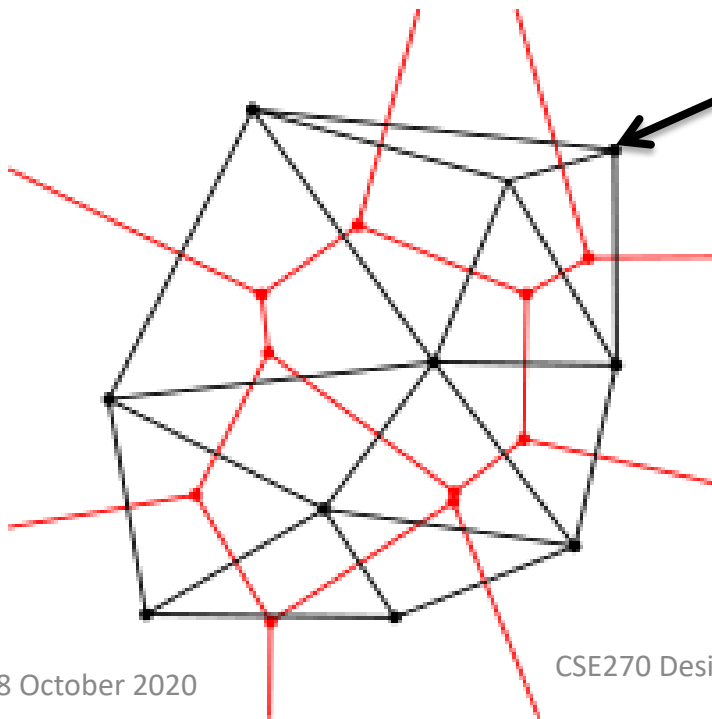


Property #2

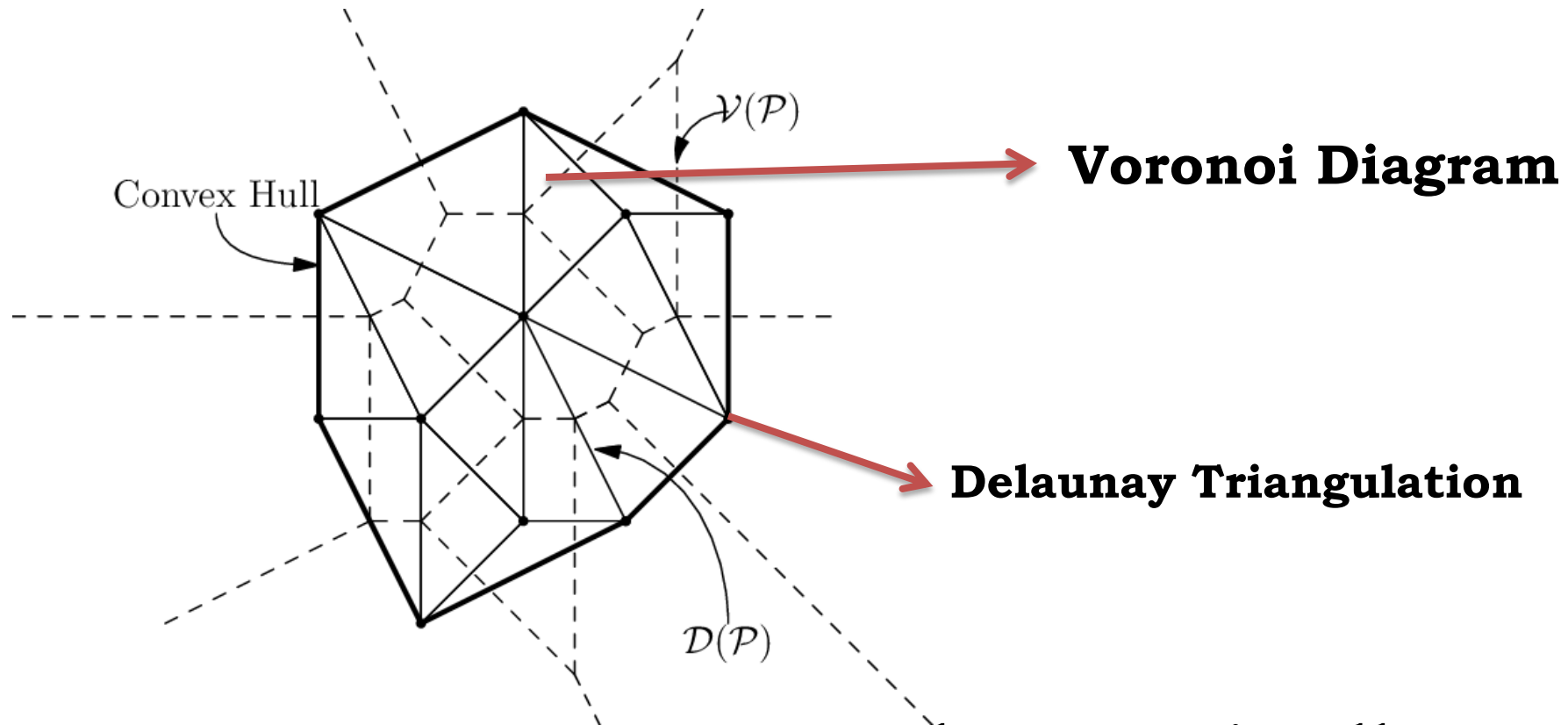
- The complexity of Voronoi diagram is ***linear***.
 - For n sites, there are ***n faces***, at most ***$2n-5$ vertices*** and at most ***$3n-6$ edges***.

Property #3

- The dual graph forms a special kind of triangulation called the ***Delaunay Triangulation***.



Property #4



- Sites in the unbounded voronoi cells correspond to the vertices of the ***convex hull***

General Properties

- If the points P are collinear, the voronoi diagram consists of $n-1$ parallel lines forming n cells.
- If the points P are not collinear, the edges of the voronoi diagram are segments, or half lines(which may terminate at useful border).
- The number of vertices in a voronoi diagram of a set of n points is at most $2n-5$ and the number of edges are at most $3n-6$.
- Voronoi cells or voronoi partitions are convex.
- The voronoi cell of P_i is unbounded if P_i lies on the convex hull of P .
- "Largest Empty Circle of q wrt P " is the largest circle whose center is q and which contains no point of P in its interior.
- A point q is a vertex of a voronoi diagram if its largest empty circle has three or more points of P on its circumference.
- This circle is the circumcircle of the corresponding Delaunay Triangle.
- The bisector between P_i and P_j defines an edge of the voronoi diagram of P iff there is a point q in the plane such that its largest empty circle contains both P_i and P_j on its circumference and no other member of P .

PROPERTIES (without proofs)

- If the points P are collinear, the **voronoi diagram** consists of **$n-1$ parallel lines forming n cells**.
- If the points P are not collinear, the edges of the **voronoi diagram are segments, or half lines**(which may terminate at useful border).
- The number of vertices in a voronoi diagram of a set of n points is at most **$2n-5$** and the number of edges are **at most $3n-6$** .
- Voronoi cells or voronoi partitions are **convex**.
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Applications

- **Nearest neighbor search:** For a query point ,
 - finding its nearest neighbor from a fixed set of points is simply a matter of determining which cell in the Voronoi diagram of contains .
- **Facility location:** Suppose McDonald's wanted to open another restaurant.
 - To minimize interference with existing McDonald's, it should be located as far away from the closest restaurant as possible.
 - This location is always at a vertex of the Voronoi diagram, and it can be found in a linear-time search through all the Voronoi vertices.
- **Largest empty circle:** Suppose you needed to obtain a large,
 - contiguous, undeveloped piece of land on which to build a factory.
 - The same condition used for picking McDonald's locations is appropriate for other undesirable facilities, namely that it be as far as possible from any relevant sites of interest.
 - A Voronoi vertex defines the center of the largest empty circle among the points.
- **Path planning:** If the sites of are the centers of obstacles we seek to avoid,
 - the edges of the Voronoi diagram define the possible channels that maximize the distance to the obstacles.
 - Thus in planning paths among the sites, it will be safest to stick to the edges of the Voronoi diagram.