Construction of trees with parameters in XGBoost

Based on: https://xgboost.readthedocs.io/en/latest/parameter.html

Input: training set

Feature_i

value 1

value_2

value_3

value_N

...

...



•••	Feature_i	•••
	value_1	
	value_2	
	value_3	
	value N	

colsample_bytree
also
colsample bylevel, colsample bynode

Initial prediction

	y_pred
	pred_1
	pred_2
	pred_3
ľ	pred_N

base_score

Parameters for one tree



gblinear: Generalized Linear Modelgbtree: Gradient Boosted Trees. Defaultdart: Dropout Additive Regression Trees

tree method

exact / gpu_exact: Exact greedy algorithm. No bins. Default for small & medium sets
approx: Approximate algorithm. With bins, uses sketch_eps. Default for big sets
hist / gpu_hist: Fast approximate algorithm. With bins, uses max_bin.

Uses **grow_policy** for adding new leaves:

depthwise: split at nodes closest to the root. Defaultlossguide: split at nodes with highest loss change, like LGBM.Uses max leaves

updater - an advanced parameter that is usually set automatically.

grow_histmaker: Row-based data splitting. Global histogram counting for bins
grow_local_histmaker: Row-based data splitting. Local histogram counting for bins
grow_colmaker: Column-based construction of trees. Default
prune: Prunes the splits where the best gain < gamma. Default</pre>

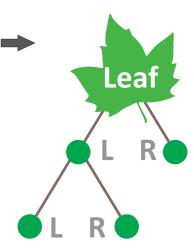
max_depth - maximum depth of a tree. 0 indicates no limit

scale_pos_weight - control the balance of positive and negative weights (binary classification)

Useful for unbalanced classes









Next tree if possible



Parameters for boosting

train(

num_boost_round - number of boosting iterations

early_stopping_rounds - validation error needs to decrease at least every such number of rounds to continue training.

pred_1	
pred_2	
pred_3	

pred N

y_pred

= learning_rate *

weigths
w_1
w_2
w_3

w N

w_i - weight for the leaf, corresponding i-th row of data



One-leaf calculation with parameters in XGBoost

Based on: https://arxiv.org/pdf/1603.02754.pdf https://github.com/dmlc/xgboost/blob/master/src/tree/param.h

Input: prediction from previous boosting iteration

y_pred

pred_1

pred_2

pred_3

pred_N'



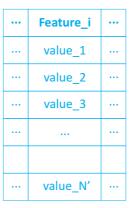
The first and second order gradient statistics on the loss(y_iter, y_pred)

Gradients	Hessians
grad_1	hess_1
grad_2	hess_2
grad_3	hess_3
grad_N'	hess_N'

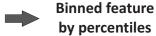
sum_grad sum_hess



Input: subset of features



If local binarization is used, binning is done here. If global binarization is used, each leaf gets binned features as input. If binarization is not used (Exact greedy algorithm), the features themselves will be splitted.





max_bin sketch_eps



Weight of leaf

Sorted bins with sums of statistics

	Feature_i	Gradients	Hessians
L subset	bin_i1	grads_i1	hess_i1
R subset	bin_i2	grads_i2	hess_i2



Outputs:

Weight of leaf **Best gain**

Feature with best gain L/R subsets for best gain

Best split

Gain split = Gain_L + Gain_R - Gain_All

Best gain = Max { Gain split : for each split on L/R subsets, for each feature

Best split = argMax { Gain split : for each split on L/R subsets,

for each feature



Construction of trees with parameters in LGBM

Based on: https://media.readthedocs.org/pdf/lightgbm/latest/lightgbm.pdf https://papers.nips.cc/paper/6907-lightgbm-a-highly-efficient-gradient-boosting-decision-tree.pdf



Input: training set Exclusive Feature Bundling (EFB) Random subset for tree



Initial prediction

•••	Feature_i	•••
	value_1	
	value_2	
	value_3	
	value_N	

Feature_i	Feature_k
0	value_1
value_2	0
0	0
0	value_N

	Bundle_j
	value_1
	value_2
	0
	value_N

 Bundle_j	 ion
 value_1	 fract
 value_2	 freq, bagging_fraction
 value_3	 , bag
	bagging <u>.</u>
 value N	 раg

y_pred
pred_1
pred_2
pred_3
pred_N

enable_bundle max_conflict_rate

feature_fraction

init score initscore_filename valid_data_initscores

Parameters for one tree

boosting

rf: Random Forest. Not boosting

gbdt: Gradient Boosted Decision Trees. Default

dart: Dropout Additive Regression Trees

goss: Gradient-based One-Side Sampling. Using "smart" subsampling with parameters: top_rate - sampling ratio of large gradient data. If 0, other rate ~ bagging fraction other_rate - sampling ratio of small gradient data

max_depth - maximum depth of a tree. <=0 indicates no limit

min_gain_to_split - prune by minimum loss requirement (post training regularization)

min_data_in_leaf - prune by minimum number of observations requirement

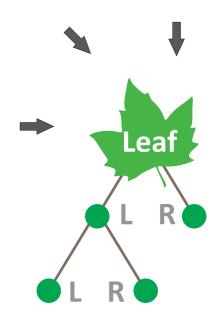
num_leaves - maximum number of leaves in one tree

scale_pos_weight - control the balance of positive and negative weights (binary classification). Useful for unbalanced classes.

Cannot be used at the same time with is_unbalance

is_unbalance - set this to true if training data are unbalanced (binary classification). Useful for unbalanced classes

Cannot be used at the same time with scale pos weight





Next tree if possible



Parameters for boosting

train(

num_iterations - number of boosting iterations

early_stopping_rounds - validation error needs to decrease at least every such number of rounds to continue training.

y_preu
pred_1
pred_2
pred_3
pred_N

v nred

learning_rate

weigths	
w_1	
w_2	١
w_3	f
	i

w N

w_i - weight for the leaf, corresponding -th row of data



One-leaf calculation with parameters in LGBM

Based on: https://media.readthedocs.org/pdf/lightgbm/latest/lightgbm.pdf https://papers.nips.cc/paper/6907-lightgbm-a-highly-efficient-gradient-boosting-decision-tree.pdf

Input: prediction from previous boosting iteration

y_pred

pred_1

pred_2

pred_3

pred_N'



The first and second order gradient statistics on the loss(y_iter, y_pred)

Gradients	Hessians	
grad_1	hess_1	
grad_2	hess_2	
grad_3	hess_3	
grad_N'	hess_N'	

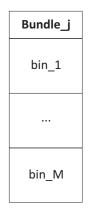
sum_grad sum_hess



Input: subset of bundles

 value_1	
 value_2	
 value_3	
 value_N'	

Binned bundles by percentiles



max_bin
min_data_in_bin
bin_construct_sample_cnt
max_cat_threshold
max_cat_to_onehot
cat 12



Weight of leaf

Sorted bins with sums of statistics

	Bundle_j	Gradients	Hessians
L subset	bin_i1	grads_i1	hess_i1
R subset	bin_i2	grads_i2	hess_i2



Outputs:

Weight of leaf Best gain

Bundle with best gain L/R subsets for best gain

Best split

Gain split = Gain_L + Gain_R

Best gain = Max { Gain split : for each split on L/R subsets,

for each bundle }

Best split = argMax { Gain split : for each split on L/R subsets,

for each bundle