

CODE:

```
hw.cpp x  leap.exe
Day 2 > hw.cpp > Robot > ~Robot()

1  #include<iostream>
2  using namespace std;
3
4  class Robot {
5      private:
6          string name;
7          int battery;
8
9      public:
10     Robot() {
11         name = "Alpha";
12         battery = 100;
13         cout<<"Robot " << name << " activated with battery " << battery << "% \n";
14     }
15
16     void performTask() {
17         if (battery>=10)
18         {
19             battery-=10;
20             cout<<"Robot "<<name<<" has performed the task and battery is now "<<battery<<"%\n";
21         }
22         else
23             cout<<"Not enough charge to perform task"<<endl;
24     }
25
26     void displayStatus() {
27         cout<<"The Robot "<<name<<" is currently active and is at "<<battery<<"%\n";
28     }
29
30     ~Robot() {
31         cout<<"The robot "<<name<<" deactivated \n";
32     }
33 };
34
35 int main()
36 {
37     Robot r;
38     r.performTask();
39     r.displayStatus();
40     return 0;
41 }
```

OUTPUT:

```
PS C:\Users\user\Desktop\Rajat_Robocon> & 'c:\Users\user\.vscode\extensions\ms-vscode.cpptools-1.26.3-win32-x64\deb
stdout=Microsoft-MIEngine-Out-0rrt5oyh.p3b' '--stderr=Microsoft-MIEngine-Error-bgmureyz.nep' '--pid=Microsoft-MIEngi
Robot Alpha activated with battery 100%
Robot Alpha has performed the task and battery is now 90%
The Robot Alpha is currently active and is at 90%
The robot Alpha deactivated
```