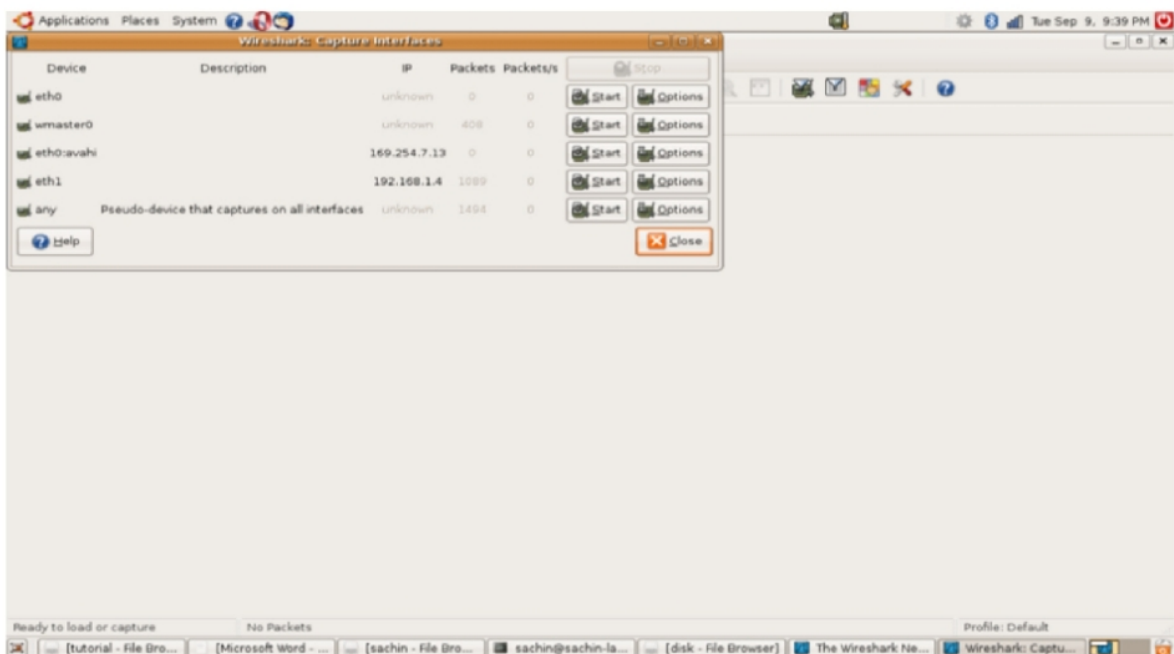
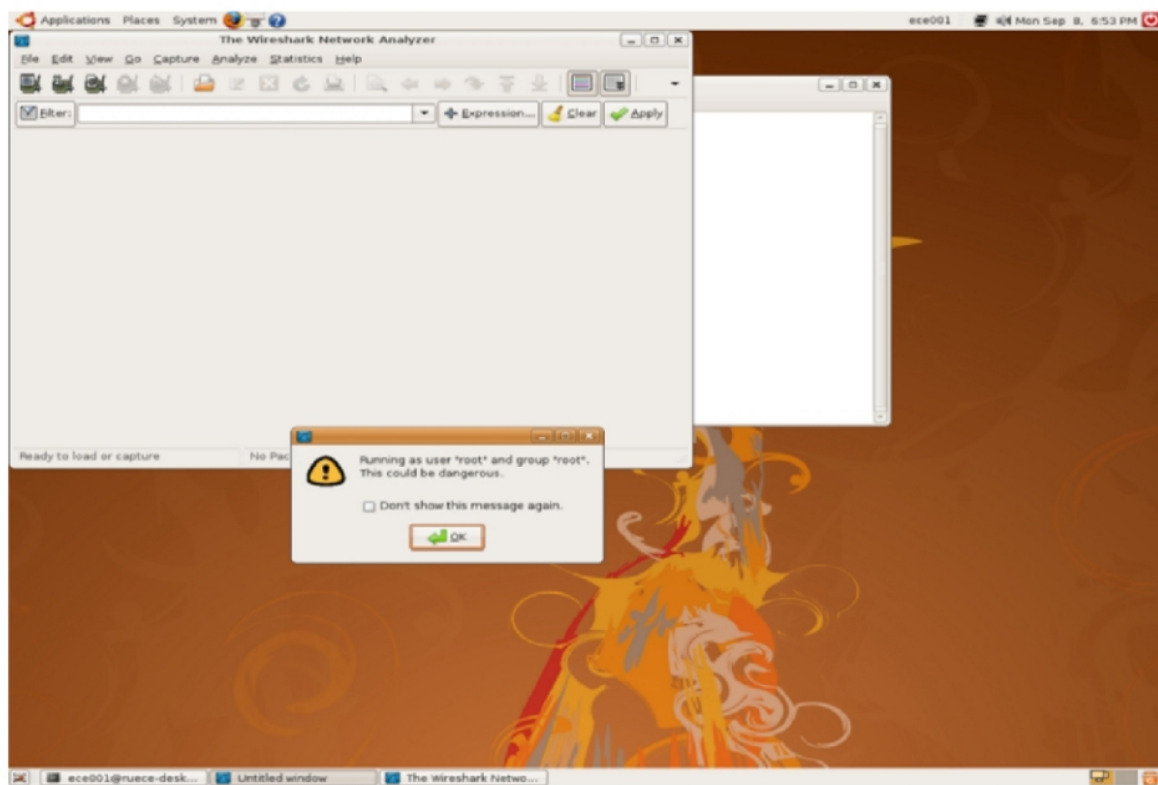


Figure 5: Wireshark display after step 9



This will install nam and ns2 on your Linux. Now let's check if everything is functional by executing a small TCL/Tk simulation script.

```
#Create a simulator object
set ns [new Simulator]
#Define different colors for data flows
$ns color 1 Blue
$ns color 2 Red

#Open the nam trace file
set nf [open out.nam w]
$ns namtrace-all $nf

#Define a 'finish' procedure
proc finish {} {
    global ns nf
    $ns flush-trace
    #Close the trace file
    close $nf
}

#Execute nam on the trace file
exec nam out.nam &
exit 0
}

#Create four nodes
set n0 [$ns node]
set n1 [$ns node]
set n2 [$ns node]
set n3 [$ns node]

#Create links between the nodes
$ns duplex-link $n0 $n2 1Mb 10ms DropTail
$ns duplex-link $n1 $n2 1Mb 10ms DropTail
$ns duplex-link $n3 $n2 1Mb 10ms SFQ

$ns duplex-link-op $n0 $n2 orient right-down
$ns duplex-link-op $n1 $n2 orient right-up
$ns duplex-link-op $n2 $n3 orient right
```

```
#Monitor the queue for the link between node 2 and node 3
```

```
$ns duplex-link-op $n2 $n3 queuePos 0.5
```

```
#Create a UDP agent and attach it to node n0
```

```
set udp0 [new Agent/UDP]
```

```
$udp0 set class_ 1
```

```
$ns attach-agent $n0 $udp0
```

```
# Create a CBR traffic source and attach it to udp0
```

```
set cbr0 [new Application/Traffic/CBR]
```

```
$cbr0 set packetSize_ 500
```

```
$cbr0 set interval_ 0.005
```

```
$cbr0 attach-agent $udp0
```

```
#Create a UDP agent and attach it to node n1
```

```
set udp1 [new Agent/UDP]
```

```
$udp1 set class_ 2
```

```
$ns attach-agent $n1 $udp1
```

```
# Create a CBR traffic source and attach it to udp1
```

```
set cbr1 [new Application/Traffic/CBR]
```

```
$cbr1 set packetSize_ 500
```

```
$cbr1 set interval_ 0.005
```

```
$cbr1 attach-agent $udp1
```

```
#Create a Null agent (a traffic sink) and attach it to node n3
```

```
set null0 [new Agent/Null]
```

```
$ns attach-agent $n3 $null0
```

```
#Connect the traffic sources with the traffic sink
```

```
$ns connect $udp0 $null0 &nbsp;
```

```
$ns connect $udp1 $null0
```

```
#Schedule events for the CBR agents
```

```
$ns at 0.5 "$cbr0 start"
```

```
$ns at 1.0 "$cbr1 start"
```

```
$ns at 4.0 "$cbr1 stop"
```

```
$ns at 4.5 "$cbr0 stop"
```

```
#Call the finish procedure after 5 seconds of simulation time
```

```
$ns at 5.0 "finish"
```

```
#Run the simulation
```

```
$ns run
```

Save it into example.tcl and run the following command:

```
ns example.tcl
```

if everything goes fine, which shows the animator network on nam as shown in figure 12.1

