

Honors Pledge Statement: "The writeup of this submission is my own work alone".

1.1

$$\begin{aligned}(3, -1) &= s(2, 1) + t(1, 3) \\ (3, -1) &= (2s + t, s + 3t)\end{aligned}$$

We turn this into a system of equations.

$$\begin{cases} 2s + t = 3 \\ s + 3t = -1 \end{cases}$$

Solving, we find that $s = 2, t = -1$.

1.4

$$\|\mathbf{x}\| = \sqrt{4^2 + 7^2 + (-4)^2 + 1^2 + 2^2 + (-2)^2} = 3\sqrt{10}$$

$$\|\mathbf{y}\| = \sqrt{2^2 + 1^2 + 2^2 + 2^2 + (-1)^2 + (-1)^2} = \sqrt{11}$$

$$\begin{aligned}\cos \theta &= \frac{\mathbf{x} \cdot \mathbf{y}}{\|\mathbf{x}\| \|\mathbf{y}\|} \\ &= \frac{4 \cdot 2 + 7 \cdot 1 + (-4) \cdot 2 + 1 \cdot (-1) + (-2) \cdot (-1)}{3\sqrt{10} \cdot \sqrt{11}} \\ &= \frac{8}{3\sqrt{110}} \\ &= \frac{4\sqrt{110}}{165} \\ \theta &\approx 1.314\end{aligned}$$

1.5

$$\|\mathbf{x}\| = \sqrt{4^2 + 7^2 + 4^2} = 9$$

$$\|\mathbf{y}\| = \sqrt{2^2 + 1^2 + 2^2} = 3$$

$$\begin{aligned}\cos \theta &= \frac{4 \cdot 2 + 7 \cdot 1 + 4 \cdot 2}{9 \cdot 3} \\ &= \frac{23}{27} \\ \theta &\approx 0.551\end{aligned}$$

1.7

a

$$\begin{aligned}\mathbf{u}_1 \cdot \mathbf{u}_2 &= \frac{1}{81} (1 \cdot 8 + (-4) \cdot 4 + (-8) \cdot (-1)) = 0 \\ \mathbf{u}_2 \cdot \mathbf{u}_3 &= \frac{1}{81} (8 \cdot 4 + 4 \cdot (-7) + (-1) \cdot 4) = 0 \\ \mathbf{u}_1 \cdot \mathbf{u}_3 &= \frac{1}{81} (1 \cdot 4 + (-4) \cdot (-7) + (-8) \cdot 4) = 0\end{aligned}$$

Therefore, $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthonormal basis of \mathbb{R}^3 .

$$\begin{aligned}\mathbf{u}_1 \times \mathbf{u}_2 &= \frac{1}{81} (1, -4, -8) \times (8, 4, -1) \\ &= \frac{1}{81} (36, -63, 36) \\ &= \frac{1}{9} (4, -7, 4) \\ &= \mathbf{u}_3\end{aligned}$$

Since $\mathbf{u}_1 \times \mathbf{u}_2 = \mathbf{u}_3$, $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is a right-handed orthonormal basis of \mathbb{R}^3 .

b

$$\begin{aligned}y_1 \mathbf{u}_1 + y_2 \mathbf{u}_2 + y_3 \mathbf{u}_3 &= (10, 11, -11) \\ y_1 (1, -4, -8) + y_2 (8, 4, -1) + y_3 (4, -7, 4) &= (90, 99, -99) \\ (y_1 + 8y_2 + 4y_3, -4y_1 + 4y_2 - 7y_3, -8y_1 - y_2 + 4y_3) &= (90, 99, -99)\end{aligned}$$

We can solve this system to find $\boxed{y_1 = 6, y_2 = 15, y_3 = -9}$.

$$\begin{aligned}\|(y_1, y_2, y_3)\| &= \sqrt{6^2 + 15^2 + (-9)^2} \\ &= \boxed{3\sqrt{38}} \\ \|(10, 11, -11)\| &= \sqrt{10^2 + 11^2 + (-11)^2} \\ &= \boxed{3\sqrt{38}}\end{aligned}$$

1.14

a

Let \mathbf{v}_1 be the vector that passes through \mathbf{a}_1 and \mathbf{a}_2 . Let \mathbf{v}_2 be the vector that passes through \mathbf{a}_2 and \mathbf{a}_3 . Let \mathbf{v}_3 be the vector that passes through \mathbf{b}_1 and \mathbf{b}_2 . Let \mathbf{v}_4 be the vector that passes through \mathbf{b}_2 and \mathbf{b}_3 .

$$\mathbf{v}_1 = (-2, 0, -4)$$

$$\mathbf{v}_2 = (3, -5, 1)$$

$$\mathbf{v}_3 = (0, -1, 1)$$

$$\mathbf{v}_4 = (-1, 1, 0)$$

Since $\mathbf{v}_1, \mathbf{v}_2$ lie in the plane P_1 , their cross product \mathbf{n}_1 is perpendicular to P_1 . Likewise for $\mathbf{v}_3, \mathbf{v}_4, P_2, \mathbf{n}_2$, respectively.

$$\mathbf{n}_1 = (20, -10, 10)$$

$$\mathbf{n}_2 = (1, 1, -1)$$

We substitute into the standard form equation for a plane:

$$P_1 : \mathbf{n}_1 \cdot \mathbf{r} + d_1 = 0$$

$$P_2 : \mathbf{n}_2 \cdot \mathbf{r} + d_2 = 0$$

Substituting \mathbf{a}_1 and \mathbf{b}_1 , respectively, we find that $d_1 = -10$ and $d_2 = -2$. After simplifying P_1 ,

$$P_1 : \boxed{2x - y + z - 1 = 0}$$

$$P_2 : \boxed{x + y - z - 2 = 0}$$

b

Adding the equations together, we see that the lines intersect at $x = 3$. Substituting this back, we find

$$z = y - 1$$

Putting these results back into vector notation,

$$\mathbf{r} = (3, y, y - 1) = (3, 0, -1) + y(1, 1, 1)$$

Parametrizing using $t \in \mathbb{R}$,

$$\mathbf{r}(t) = (3, 0, -1) + t(1, 1, 1), \quad t \in \mathbb{R}$$

The distance between this line and \mathbf{a}_1 is

$$\begin{aligned} \sqrt{\|(3, 0, -1) - (1, 2, 1)\|^2 - \left\|((3, 0, -1) - (1, 2, 1)) \times \frac{1}{\sqrt{3}}(1, 1, 1)\right\|^2} &= \sqrt{\|(2, -2, -2)\|^2 - \frac{1}{3}\|(3, -2, -2) \times (1, 1, 1)\|^2} \\ &= \sqrt{(2\sqrt{3})^2 - \frac{1}{3}\|(0, 5, 5)\|^2} \\ &= \sqrt{12 - \frac{1}{3}(50)} \\ &= \sqrt{12 - \frac{50}{3}} \end{aligned}$$

Something went wrong here...

c

$$\mathbf{r} = \mathbf{b}_1 + t\mathbf{a}$$

Suppose the line is at \mathbf{b}_1 when $t = 0$. In addition, at $t = 1$, suppose the line is at \mathbf{b}_2 . Then, $\mathbf{a} = \mathbf{b}_2 - \mathbf{b}_1 = (0, -1, 1)$. Therefore,

$$\mathbf{r} = (1, 1, 0) + t(0, -1, 1)$$

Recall that a line in \mathbb{R}^3 is simply the intersection of two nonparallel planes.

1.15

Let the orthonormal basis be composed of vectors $\mathbf{a}, \mathbf{b}, \mathbf{c}$. We let

$$\mathbf{c} := \frac{\mathbf{v}}{\|\mathbf{v}\|} = \frac{1}{\sqrt{26}}(1, 4, 3)$$

In addition, we define

$$\mathbf{w} := (-4, 1, 0)$$

Note that \mathbf{w} and \mathbf{c} are orthogonal. We normalize and let that be \mathbf{a} .

$$\mathbf{a} := \frac{1}{\sqrt{17}}(-4, 1, 0)$$

To make \mathbf{b} orthogonal to the other two vectors, we can compute the final vector:

$$\begin{aligned}
\mathbf{y} &= \mathbf{v} \times \mathbf{w} \\
&= (-3, -12, 15) \\
\mathbf{b} &= \frac{\mathbf{y}}{\|\mathbf{y}\|} \\
\mathbf{b} &= \frac{1}{\sqrt{378}} (-3, -12, 15)
\end{aligned}$$

1.16

Let the orthonormal basis be $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$.

$$\begin{aligned}
\mathbf{u}_1 &= \frac{\mathbf{a}}{\|\mathbf{a}\|} \\
&= \frac{1}{\sqrt{26}} (1, 4, 3) \\
\mathbf{u}_2 &= \frac{\mathbf{b}}{\|\mathbf{b}\|} \\
&= \frac{1}{\sqrt{14}} (3, 2, 1) \\
\mathbf{c} &= \mathbf{a} \times \mathbf{b} \\
&= (-2, 8, -10) \\
\mathbf{u}_3 &= \frac{\mathbf{c}}{\|\mathbf{c}\|} \\
&= \frac{1}{\sqrt{168}} (-2, 8, -10)
\end{aligned}$$

1.17

a

Let $(s, t) = (0, 0), (0, 1), (1, 0)$ correspond to $\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3$, respectively. We see that $\mathbf{x}_0 = \mathbf{p}_1 = (-2, 0, 2)$. Further, we also see that

$$\mathbf{v}_1 = \mathbf{p}_2 - \mathbf{p}_1 = (3, -2, 0)$$

and

$$\mathbf{v}_2 = \mathbf{p}_3 - \mathbf{p}_1 = (5, -1, -4)$$

$$\mathbf{x}(s, t) = (-2, 0, 2) + s(3, -2, 0) + t(5, -1, -4)$$

b

Let $t = 0$ at \mathbf{x}_0 , so $\mathbf{z}_0 = \mathbf{x}_0$.