

Independent Component Analysis

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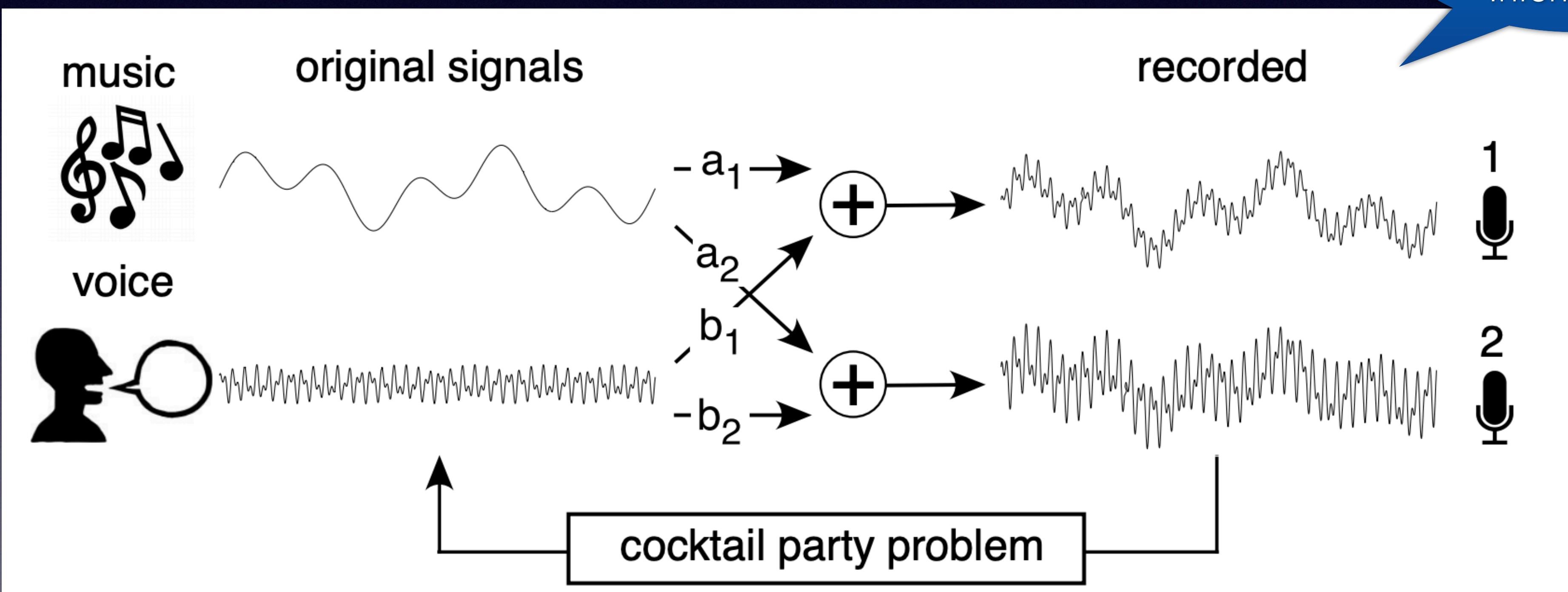
Cocktail Party Problem



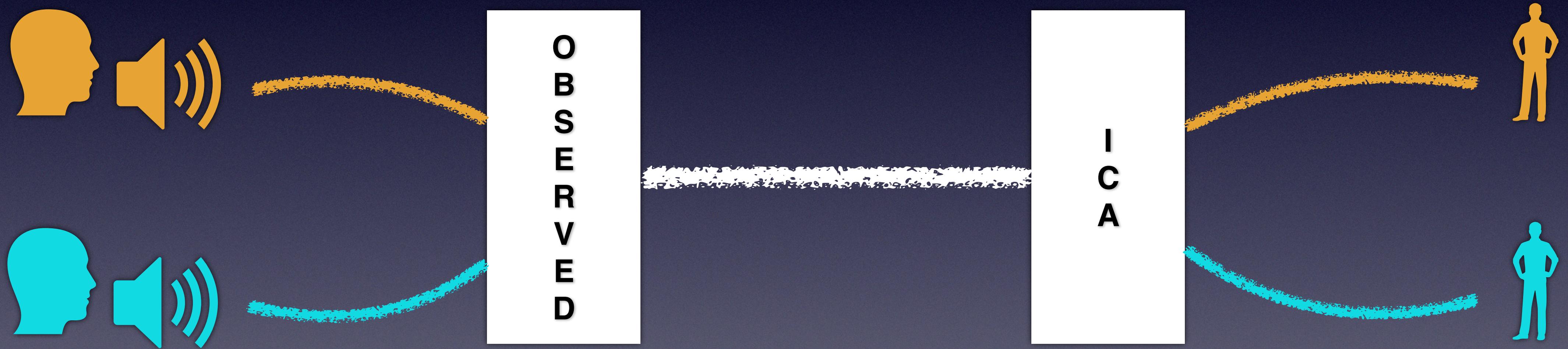
Ref: <https://jundurraga.github.io/COGS703/?print-pdf#/>

Blind Source Separation

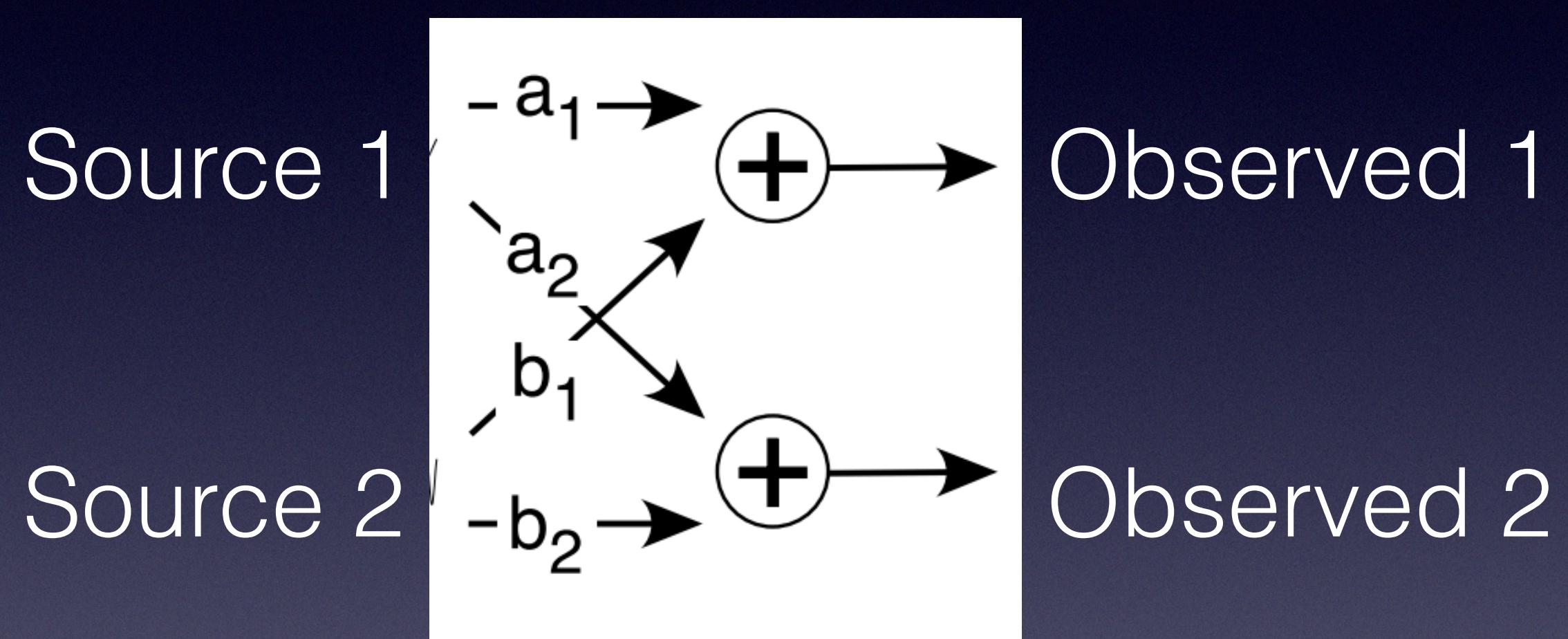
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Independent Component Analysis (ICA)



Mathematical Formation



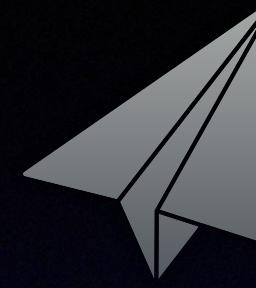
Linear Combinations

Intuition ?

Observed Signals
(Column Vector)

Mixing Matrix

Source Signals
(Column Vector)



GOAL

$$x = As$$

$$\text{Mixing Matrix, } A = \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix}$$

Linear Combinations of
Source 1 and Source 2

$$\hat{s} = Wx$$

Observed signal

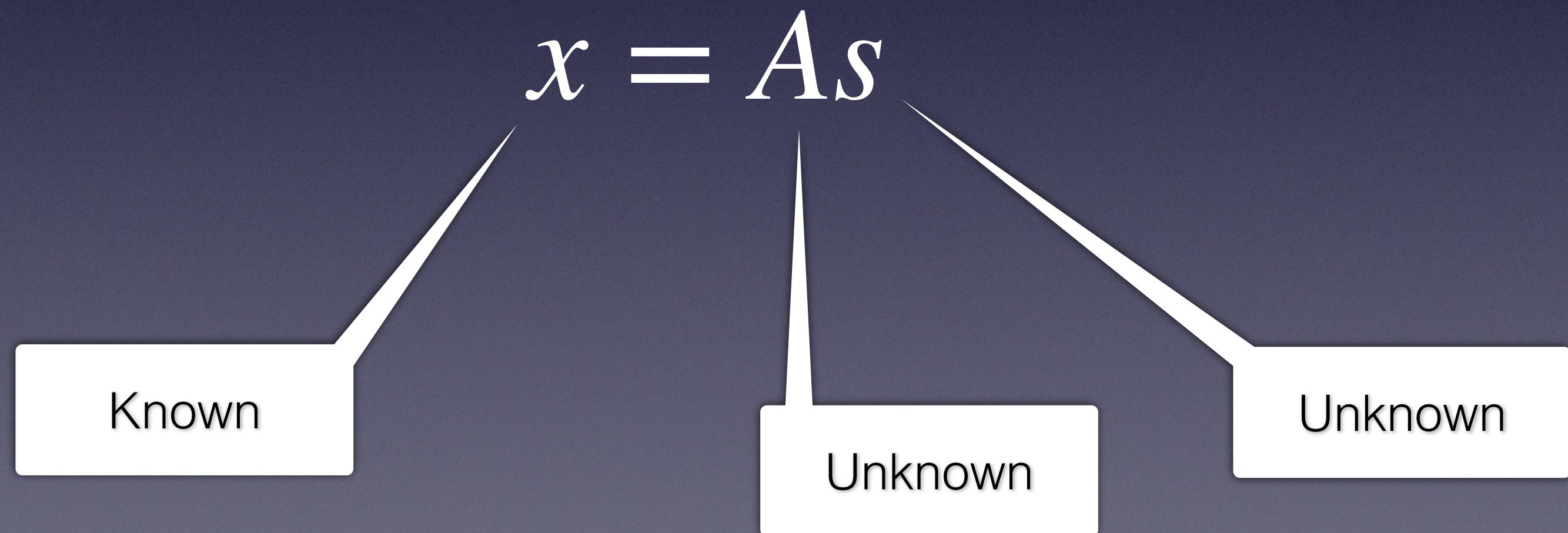
Independent signals

W is an
approximation of
 A^{-1} so that $\hat{s} \approx s$

Un-mixing Matrix

Impossible Problem?

Under constrained problem because number of unknown exceed the number of observations

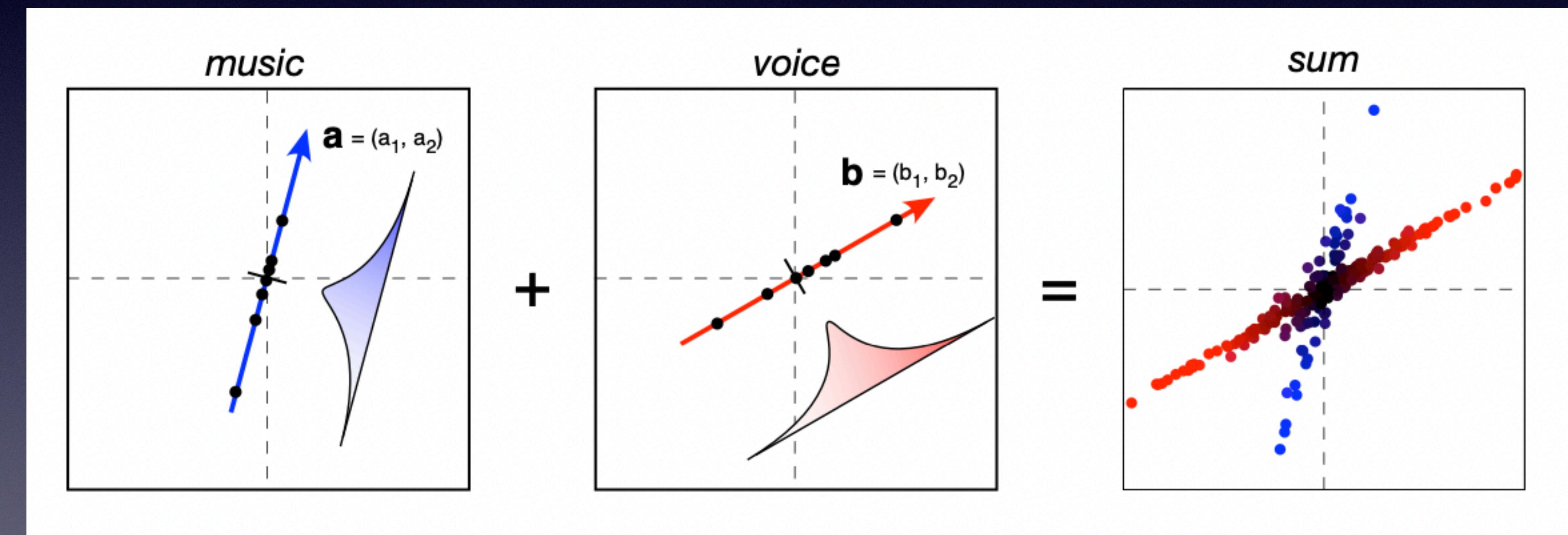


Assumptions

1. Sources are statistically Independent $p(x, y) = p(x)p(y)$
2. Independent components have Non Gaussian distribution
3. A is square and invertible

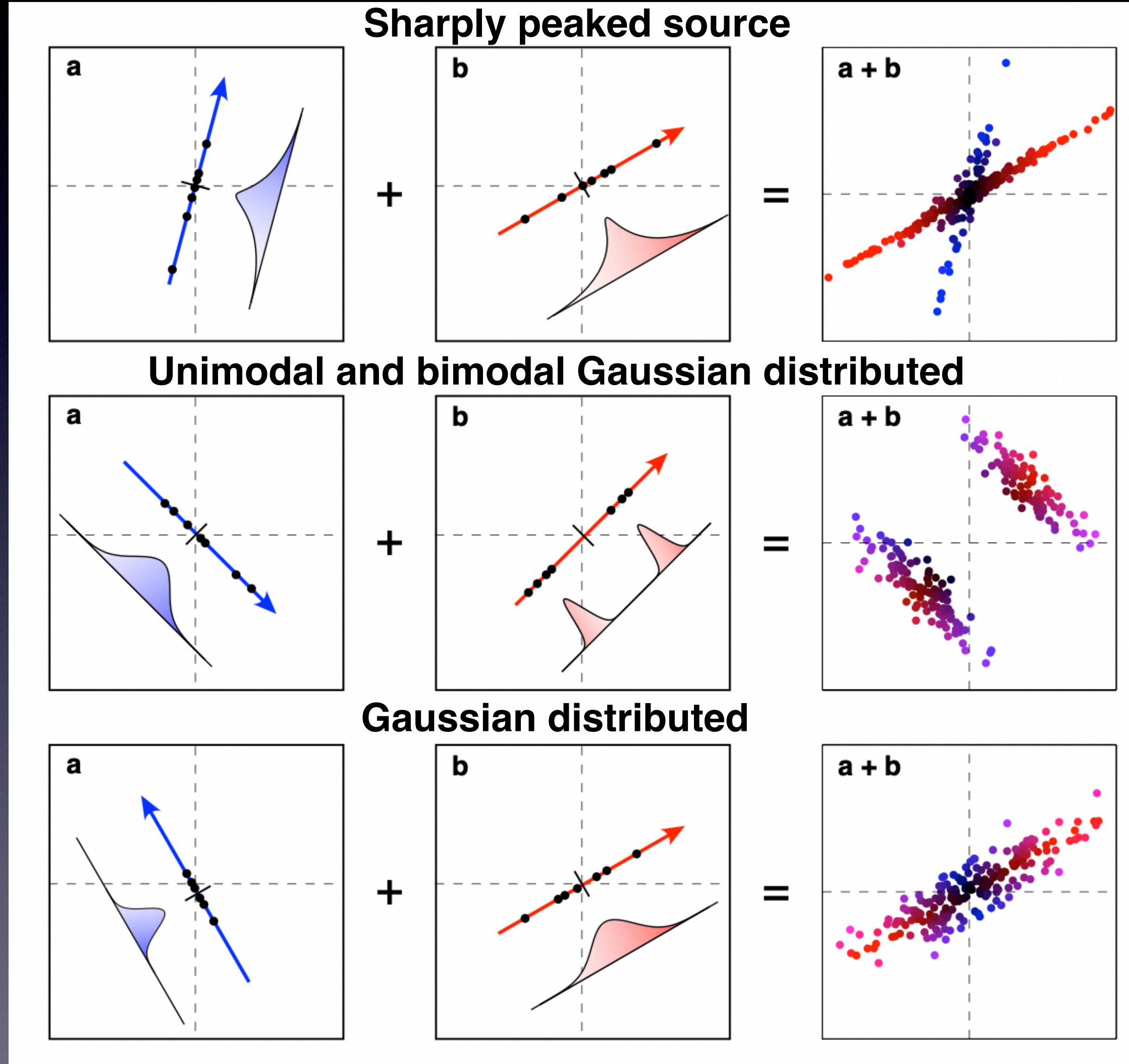
Why?

Visualisation of linear mixture

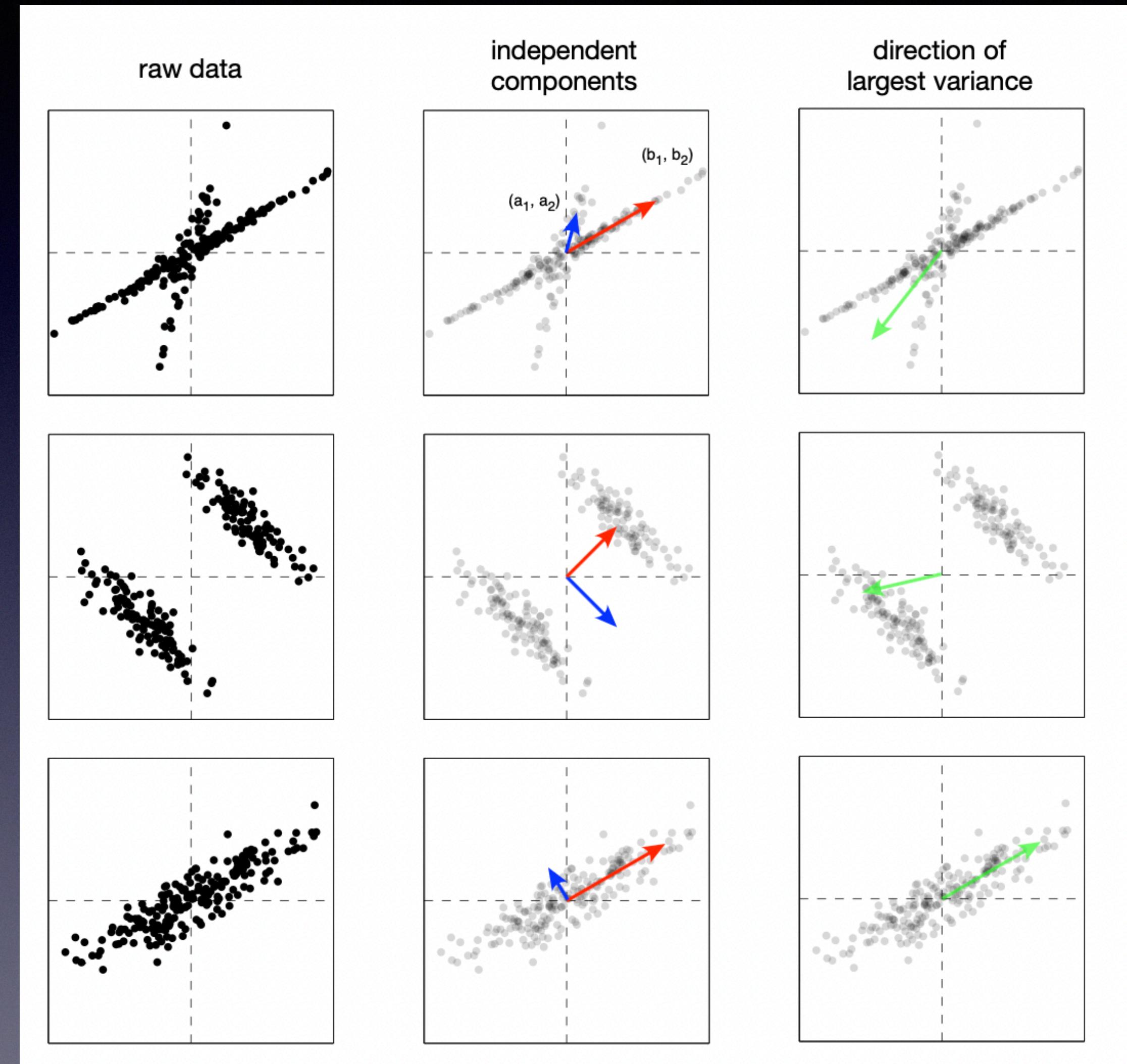


TYPES OF LINEAR MIXTURE

3



ANALYSIS OF LINEAR MIXTURE



Mathematical Preliminaries

Singular Value Decomposition

#1

$$A = U\Sigma V^\dagger$$

$$\begin{bmatrix} 3 & 0 \\ 4 & 5 \end{bmatrix} =$$

- Dimensionality Reduction
- Direction of maximum Stretching
- Rotation-Scale-Rotation

$$A = U\Sigma V^T$$

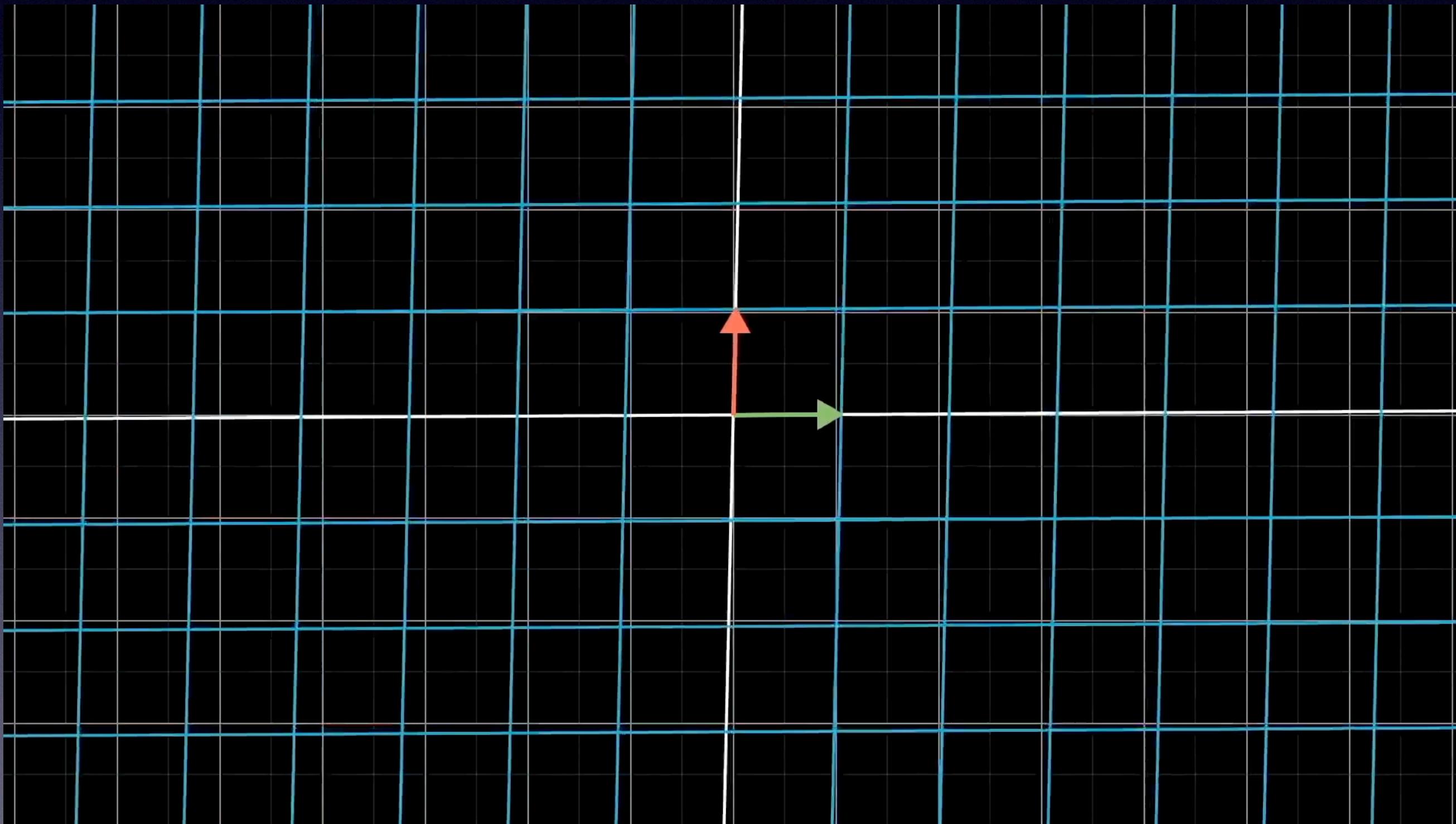
U = Eigen vectors of AA^T

V = Eigen vectors of $A^T A$

Mathematical Preliminaries

Covariance Matrix and PCA

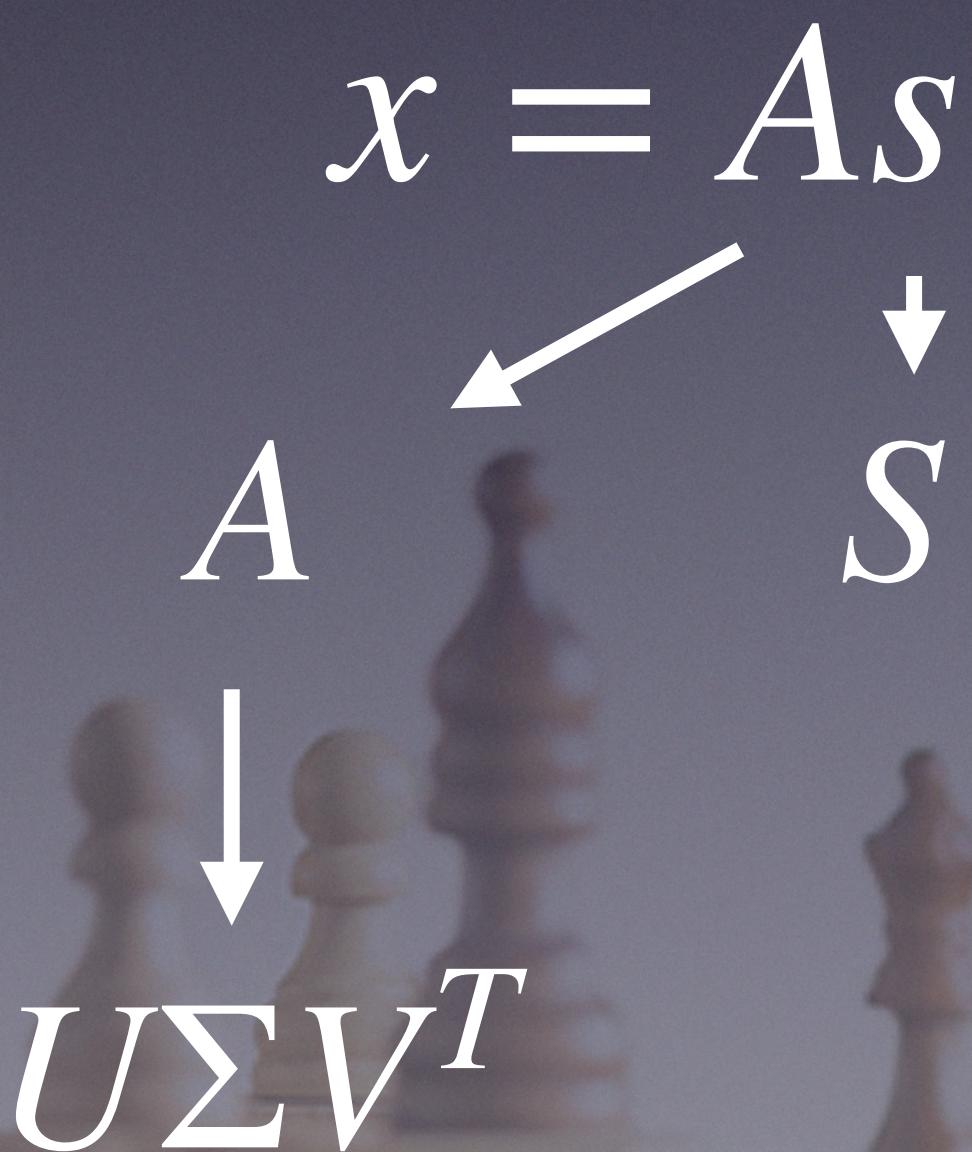
#2



- Transformation that rotate any vector into the direction of the greatest variance
- PCA uses greatest variance direction as principal component and does dimensionality reduction

Strategy!

Divide and Conquer

$$x = As$$
$$A \downarrow$$
$$U\Sigma V^T$$
$$S$$


$$\hat{s} = Wx$$

$$W = A^{-1} = (U\Sigma V^T)^{-1}$$

$$W = (V^T)^{-1}\Sigma^{-1}U^{-1}$$

$$W = V\Sigma^{-1}U^T$$

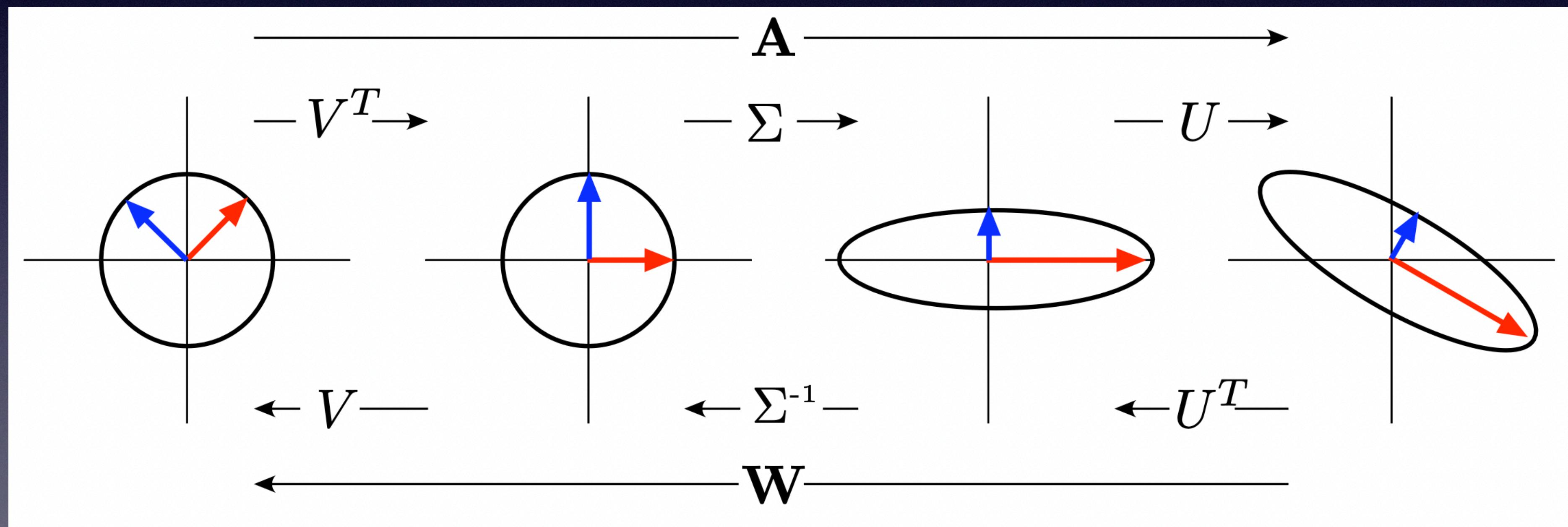
Solution

$$W = V\Sigma^{-1}U^T$$

Assumption of
independence of s to
solve for V

Examine the covariance of
the data x in order to
calculate U and Σ

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Covariance of data

Covariance = Expected value of the outer product of individual data points

$$E[xx^T] = \langle xx^T \rangle = E [(x_1 x_2 \dots x_n)(x_1 x_2 \dots x_n)^T]$$

Assumption!

- Zero mean
- Covariance of the source is whitened

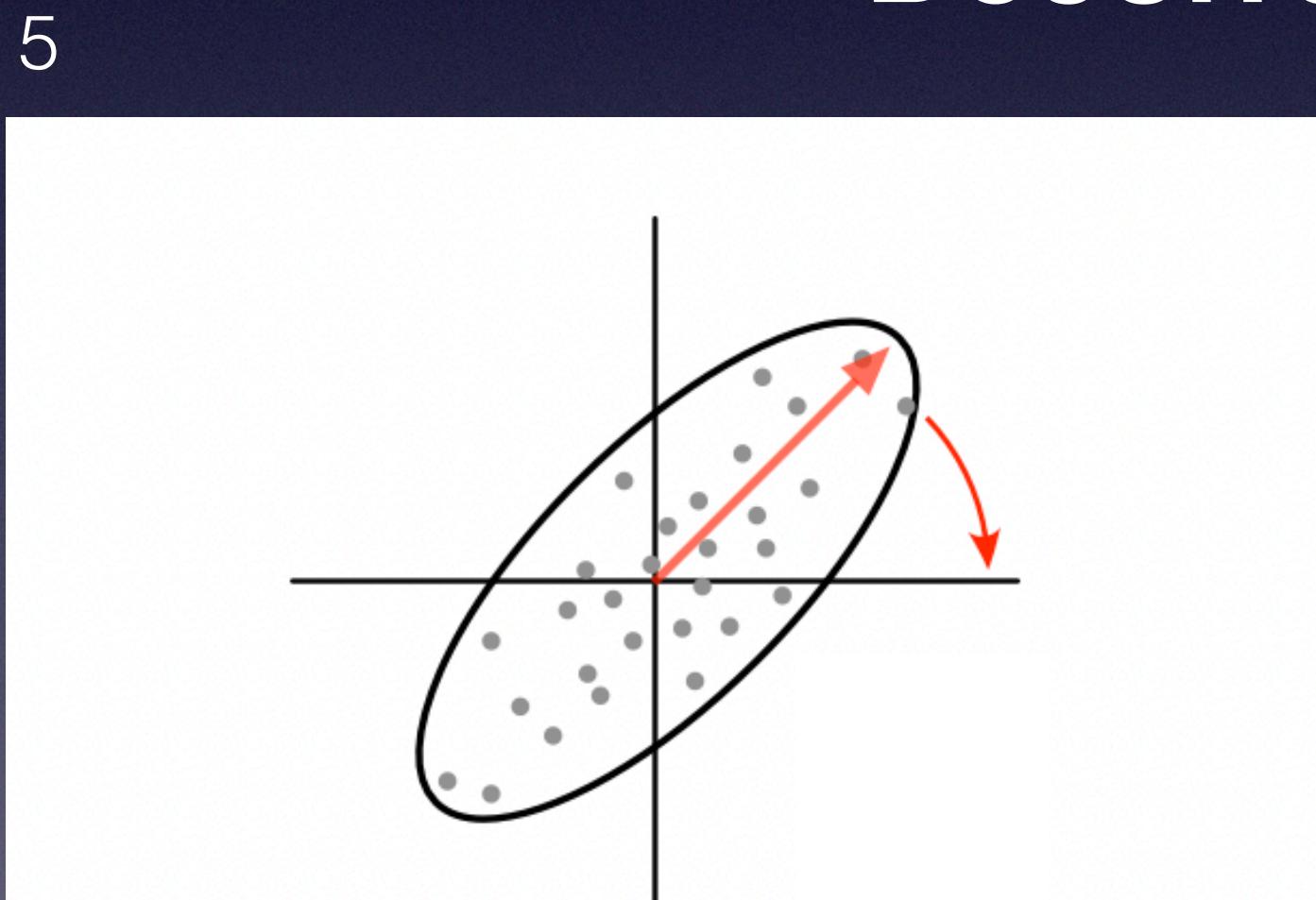
$$\langle ss^T \rangle = I$$

Identity Matrix

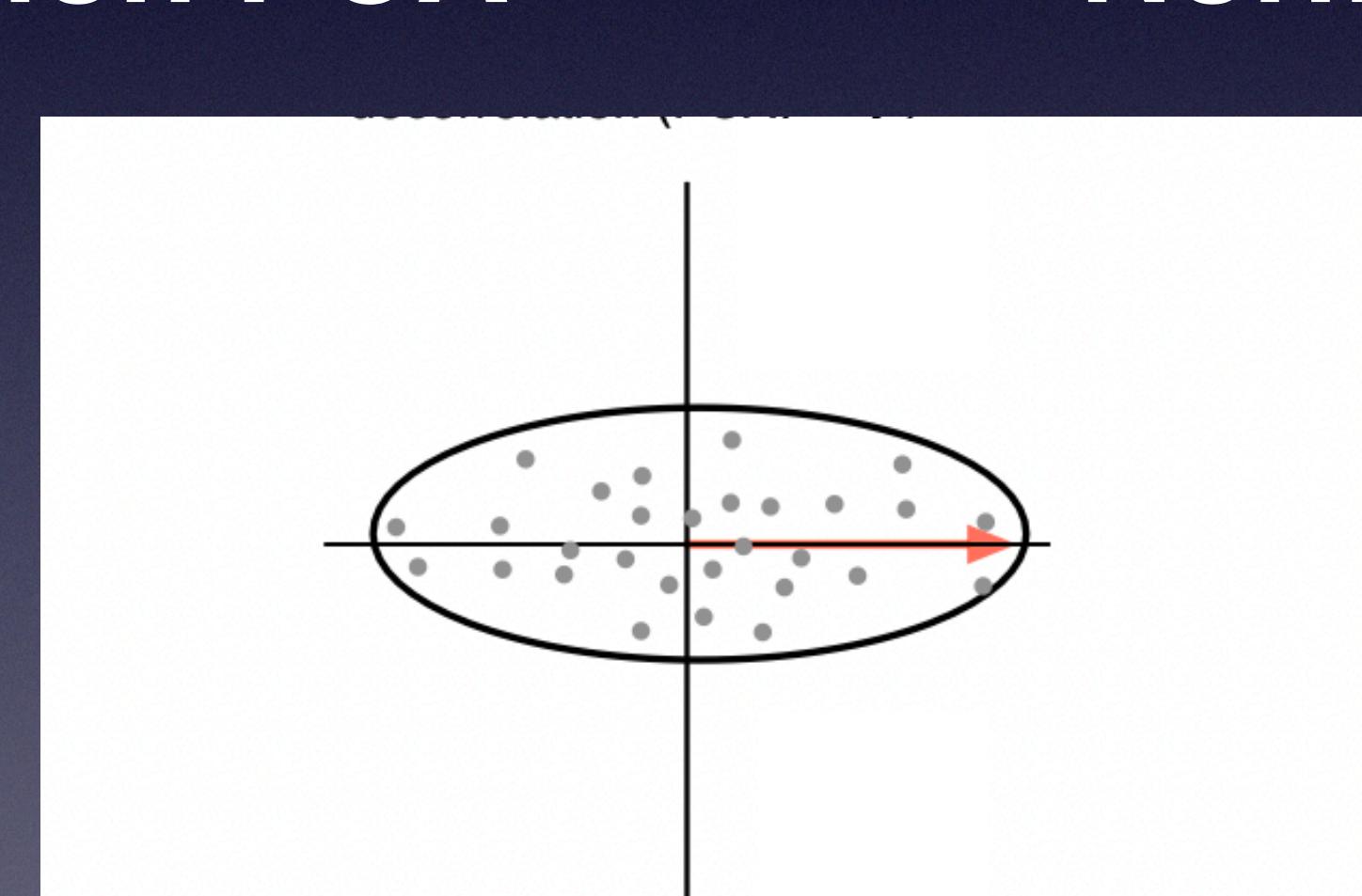
Whitening Intuition!

Operation that removes all linear dependencies in data set (second order correlations) & Normalise the variance among all dimensions

Decorrelation PCA



Normalisation



$$D^{-\frac{1}{2}}$$

Mathematically,

Decorrelation means the covariance of the transformed data is diagonalised

$$\langle xx^T \rangle = EDE^T$$

$$E^T \langle xx^T \rangle = E^T EDE^T$$

$$E^T \langle xx^T \rangle E = DE^T E$$

$$E^T \langle xx^T \rangle E = D$$

$$\langle (E^T x)(x^T E) \rangle = D$$

$$\langle (E^T x)(E^T x)^T \rangle = D$$

Covariance of data

$$\begin{aligned}\langle xx^T \rangle &= \langle (As)(As)^T \rangle \\&= \langle (U\Sigma V^T s)(U\Sigma V^T s)^T \rangle \\&= \langle U\Sigma V^T s s^T V\Sigma^T U^T \rangle \\&= U\Sigma V^T \langle s s^T \rangle V\Sigma U^T \\ \langle xx^T \rangle &= U\Sigma V^T V\Sigma U^T = U\Sigma^2 U^T\end{aligned}$$



Independent
of sources S as well
as V

Covariance of data

$$\langle xx^T \rangle = U\Sigma^2U^T$$

Familiar
form!

$$\langle xx^T \rangle = EDE^T$$

$$W = V\Sigma^{-1}U^T$$

$$W = VD^{-\frac{1}{2}}E^T$$

Only Unknown

Eigen value of
correlation data

Eigen vector of
correlation data

Defining x_w

$$x_w = (D^{-\frac{1}{2}} E^T) x$$

Whitened version of observed data such that $\langle x_w x_w^T \rangle = I$

$$W = V D^{-\frac{1}{2}} E^T$$

$$\hat{s} = W x$$

$$\hat{s} = V x_w$$

Statistics of Independence

Statistical independence is the strongest measure of dependency between random variables

$$p(a, b) = p(a)p(b)$$

$$p(s) = \prod_i P(s_i)$$

Why? Coz all second order correlations are removed

Solution using Information Theory

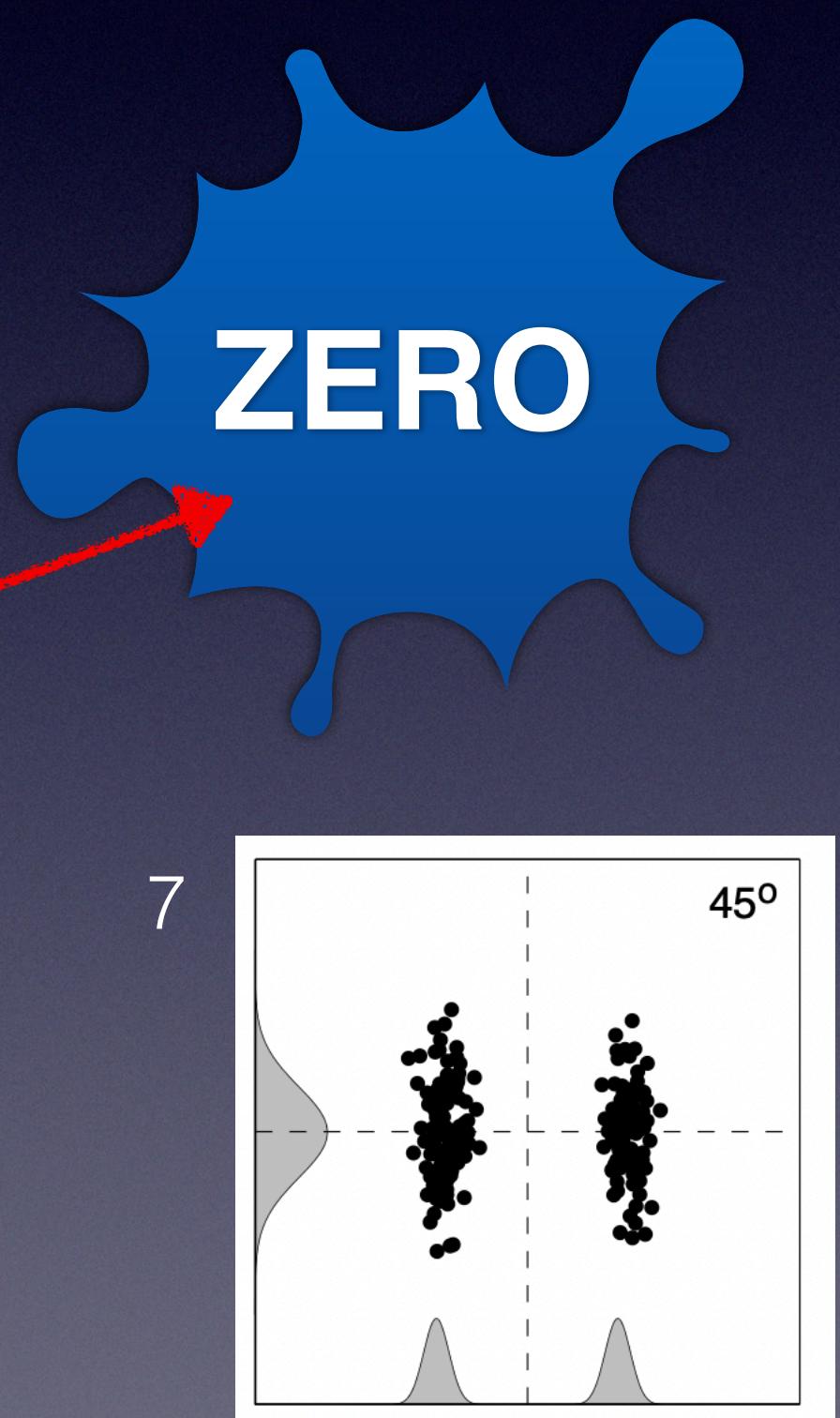
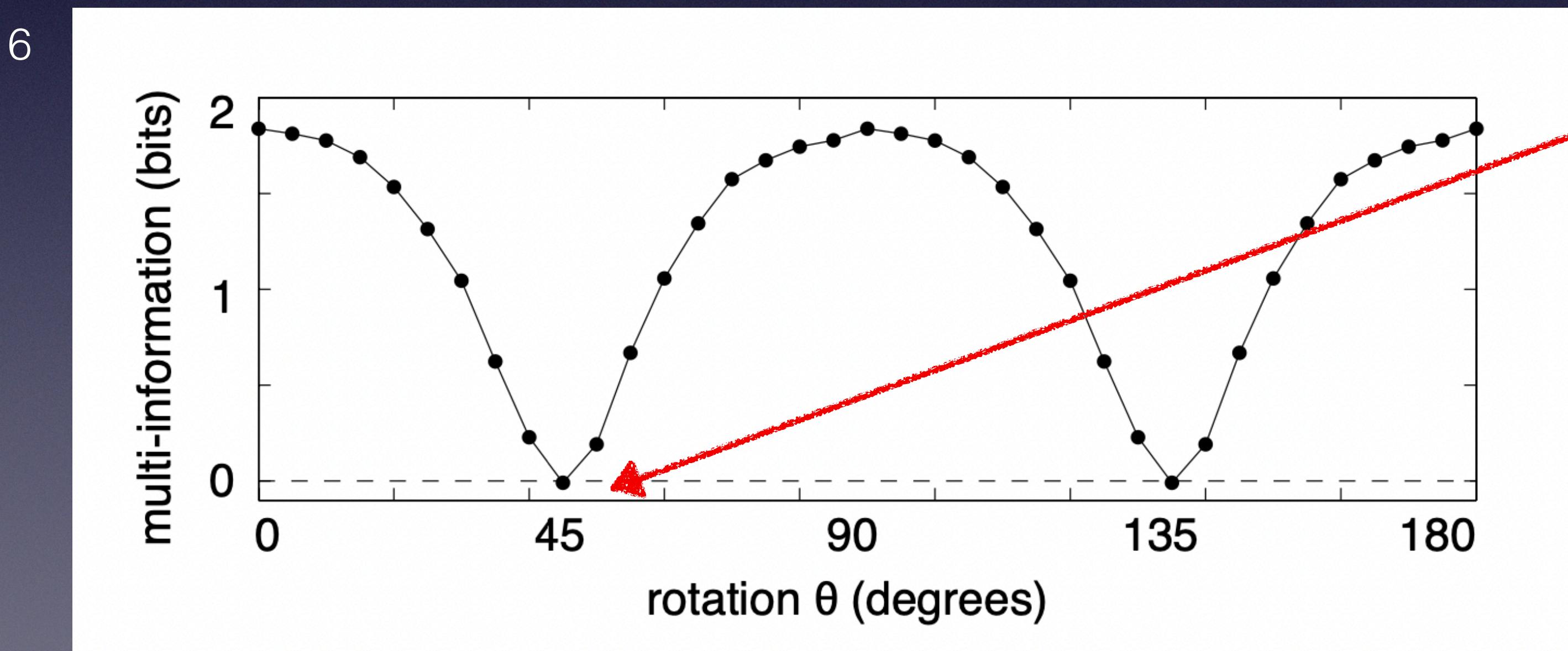
Multi information: $I(y) = \int p(y) \log_2 \left(\frac{p(y)}{\prod_i p(y_i)} \right) dy$

Non negative quantity that reaches minimum of zero only if all variables are statistically independent

If $p(y) = \prod_i p(y_i)$, then $\log_2(1) = 0$ so, $I(y) = 0$

Goal of ICA: Minimise the multi information until it reaches zero

$$V = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$



Entropy: Amount of uncertainty about a distribution $p(y)$

$$H(y) = - \int p(y) \log_2 p(y) dy$$

Multi information is given by:

$$I(y) = \sum_i H(y_i) - H(y)$$

Entropies of
marginal distribution

Entropies of joint
distribution

Towards rotation V

$$I(\hat{s}) = \sum_i H[(Vx_w)_i] - H(Vx_w)$$

For linear transformation V and random vector x_w ,

$$H(Vx_w) = H(x_w) + \log_2 |V|$$

$$I(\hat{s}) = \sum_i H[(Vx_w)_i] - H(x_w)$$

Determinant
of the rotation
matrix is 1

$$I(\hat{s}) = \sum_i H[(Vx_w)_i] - H(x_w)$$

Independent of V

Finding rotation matrix that minimises the sum of the marginal entropies of \hat{s}

$$V = \arg \min \sum_i H(Vx_w)_i$$

Maximize the statistical independence of \hat{s}

Many ICA strategy focus on approximating this



Summary

1. Subtract off the mean of the data in each dimension.
2. Whiten the data by calculating the eigenvectors of the covariance of the data.
3. Identify final rotation matrix that optimises statistical independence

Why Non-Gaussian?

Let $x = As$ where $s \sim N(0,1)$,
symmetric and rotation

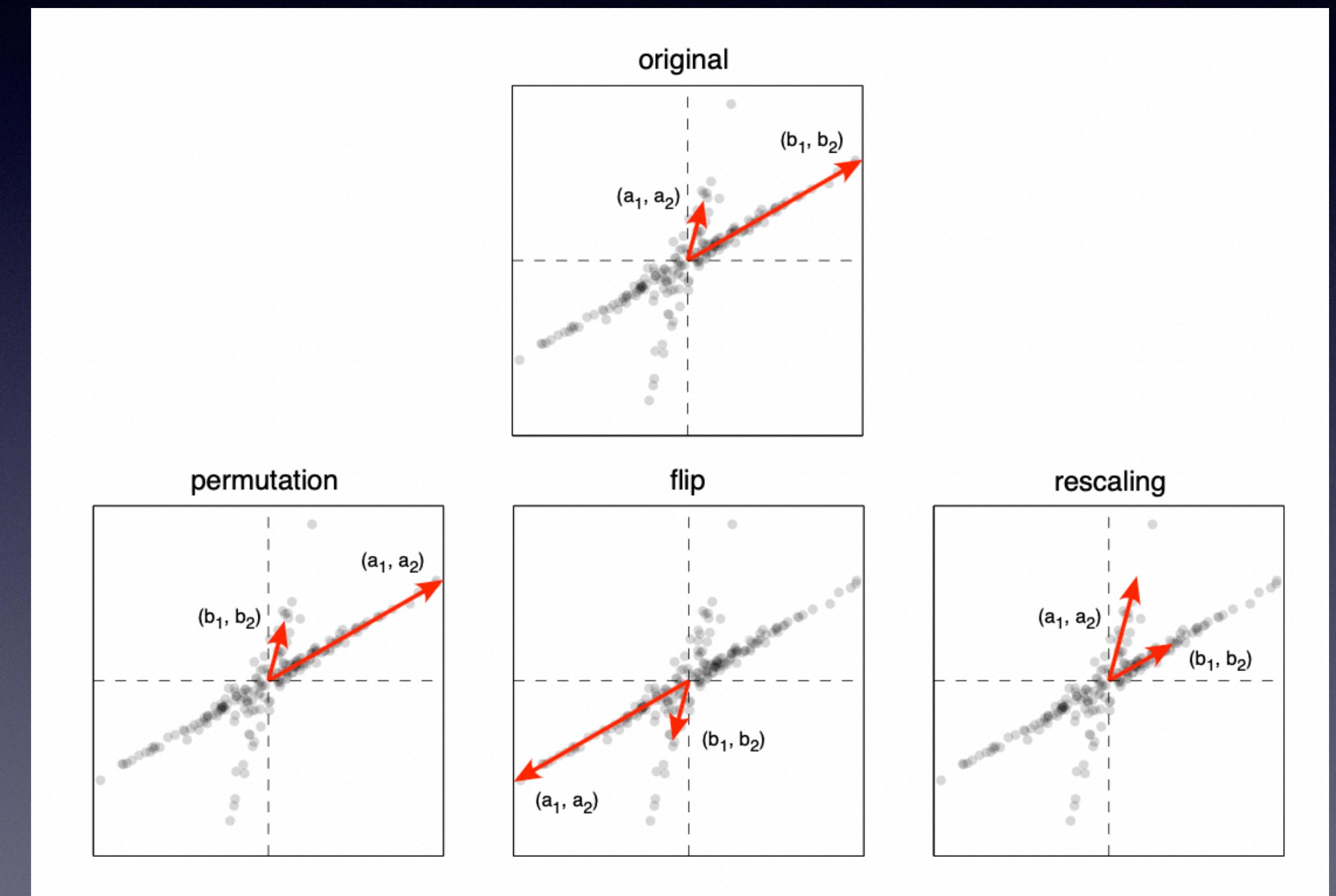
$$\begin{aligned} Cov(x) &= E[(x - 0)(x - 0)^T] \\ &= E[(As)(As)^T] \\ &= E[Ass^TA^T] \\ &= AE[ss^T]A^T \\ &= ACov(s)A^T \\ &= AA^T \end{aligned}$$

Now assume some arbitrary rotation
 R , $RR^T = I$

$$\begin{aligned} Cov(x) &= E[(x - 0)(x - 0)^T] \\ &= E[(ARs)(ARs)^T] \\ &= E[ARss^TR^TA^T] \\ &= ARE[ss^T]R^TA^T \\ &= ARR^TA^T \\ &= AA^T \end{aligned}$$

Ambiguities in Solution

1. Optimisation of V
2. Each a degree of freedom that provides an additional solution



ICA vs PCA

ICA provides a fairly unrestrictive linear basis for representing a data set

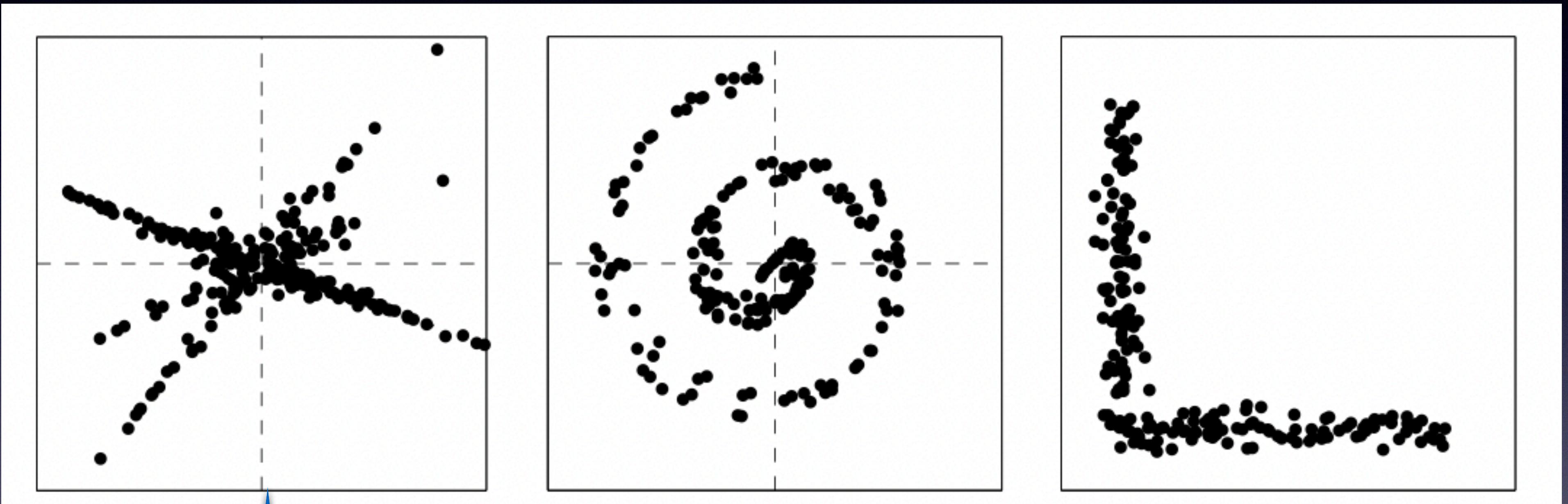
PCA identifies an orthogonal linear basis which maximises the variance of the data.

ICA is not restricted to an orthogonal basis because statistical independence makes no such requirement

PCA can identify the underlying sources only when data is distributed appropriately, such as a Gaussian distribution

Challenges

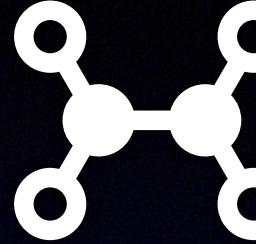
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number of independent
sources exceed the number of
measurements

Nonlinear manifold

Occlusion



Extensions

- Over complete problem
- Non linearity!

Python Implementation

FastICA Algorithm

Invented by **Aapo Hyvärinen**
at Helsinki University of Technology

<https://research.ics.aalto.fi/ica/software.shtml>

```
sklearn.decomposition.FastICA
```

```
class sklearn.decomposition.FastICA(n_components=None, *, algorithm='parallel', whiten=True, fun='logcosh', fun_args=None, max_iter=200, tol=0.0001, w_init=None, random_state=None)
```

[\[source\]](#)

<https://scikit-learn.org/stable/modules/generated/sklearn.decomposition.FastICA.html#sklearn.decomposition.FastICA.fit>



Independent Component Analysis (ICA) and Blind Source Separation (BSS)

Home Research Members Demos Software Links

The FastICA package for MATLAB

The FastICA package is a free (GPL) MATLAB program that implements the fast fixed-point algorithm for independent component analysis and projection pursuit. It features an easy-to-use graphical user interface, and a computationally powerful algorithm.

[Download software package](#)

Related software

[ICASSO: analysing and visualising the reliability of independent components](#)

[ISCTEST: principled statistical testing of independent components](#)

FastICA for other environments

[FastICA in R](#)

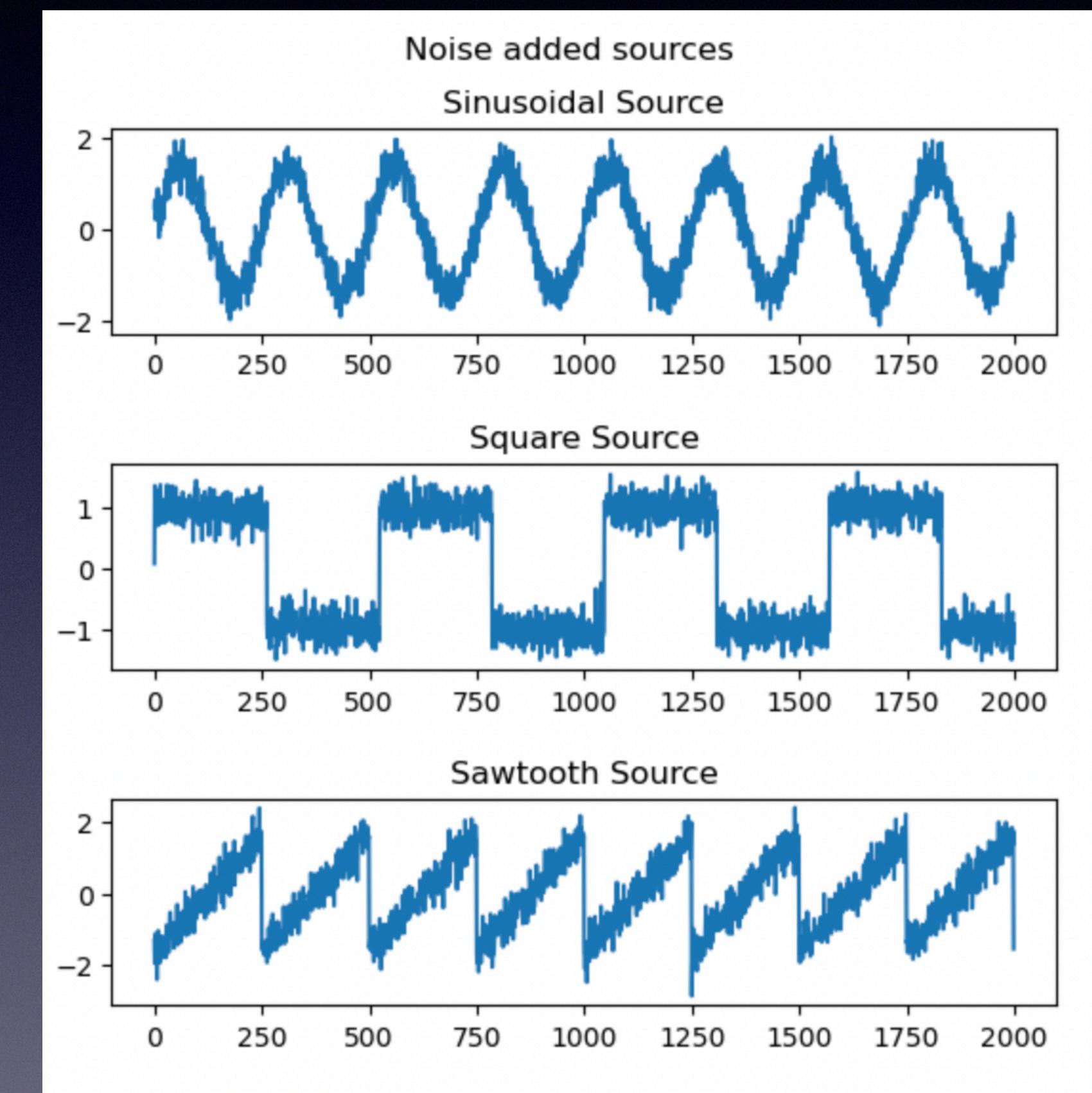
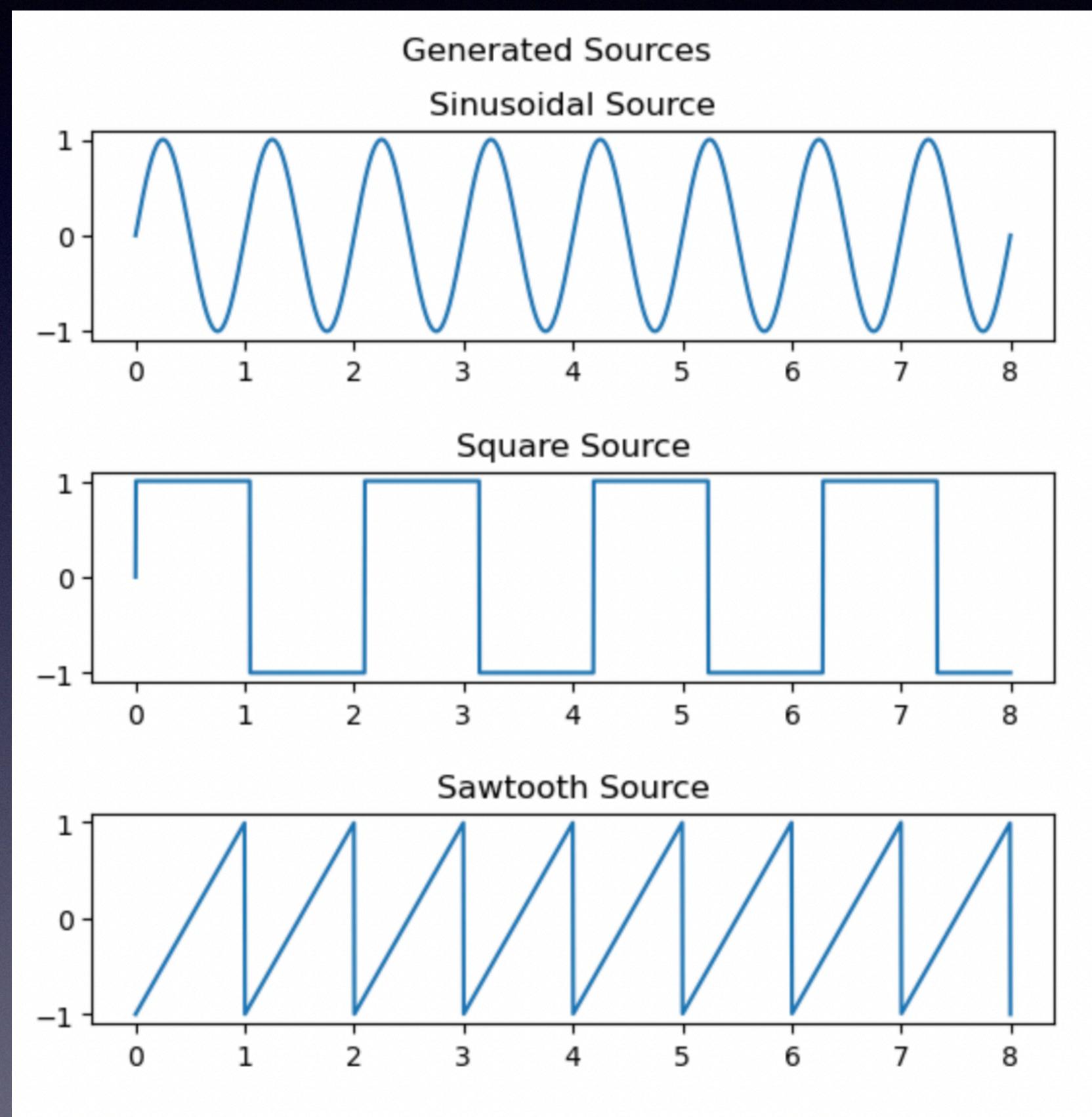
[FastICA in C++ \(part of IT++ package\)](#)

[FastICA in Python as part of MDP package](#)

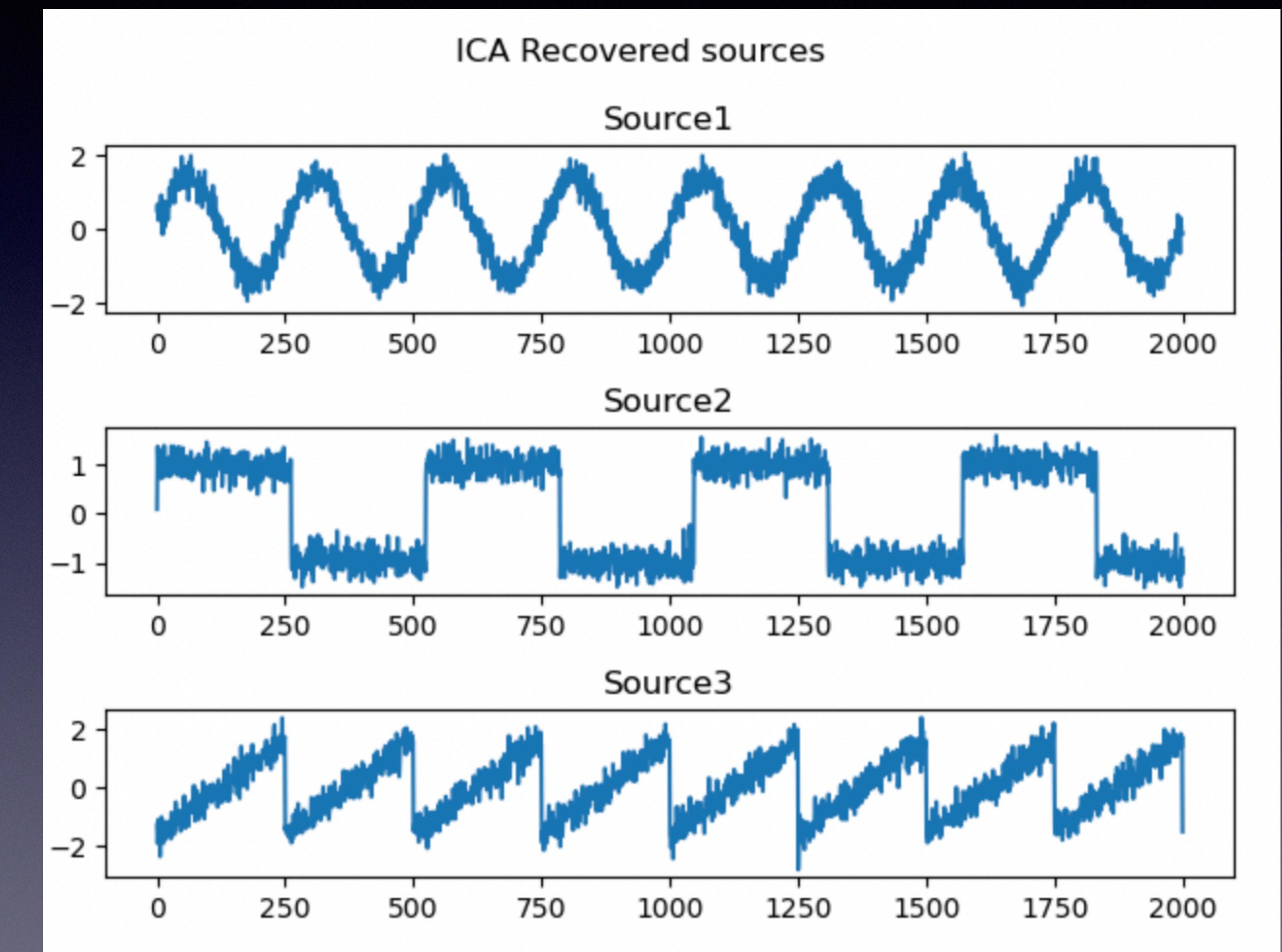
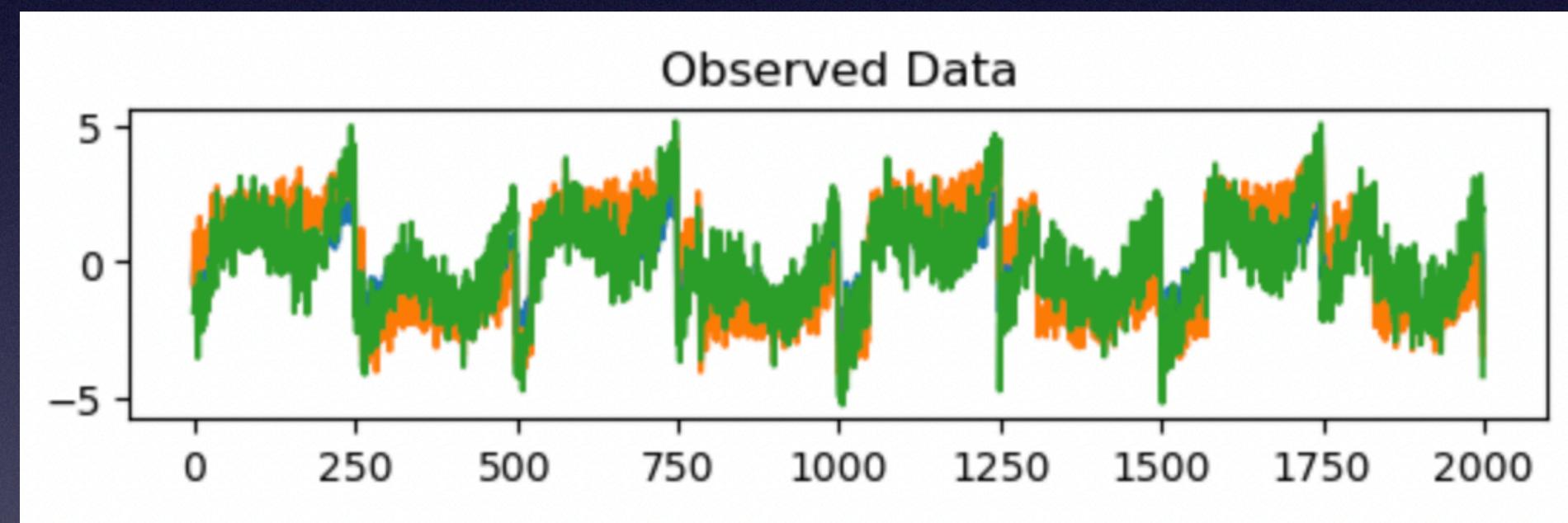
[FastICA in Python as part of scikit-learn package](#)



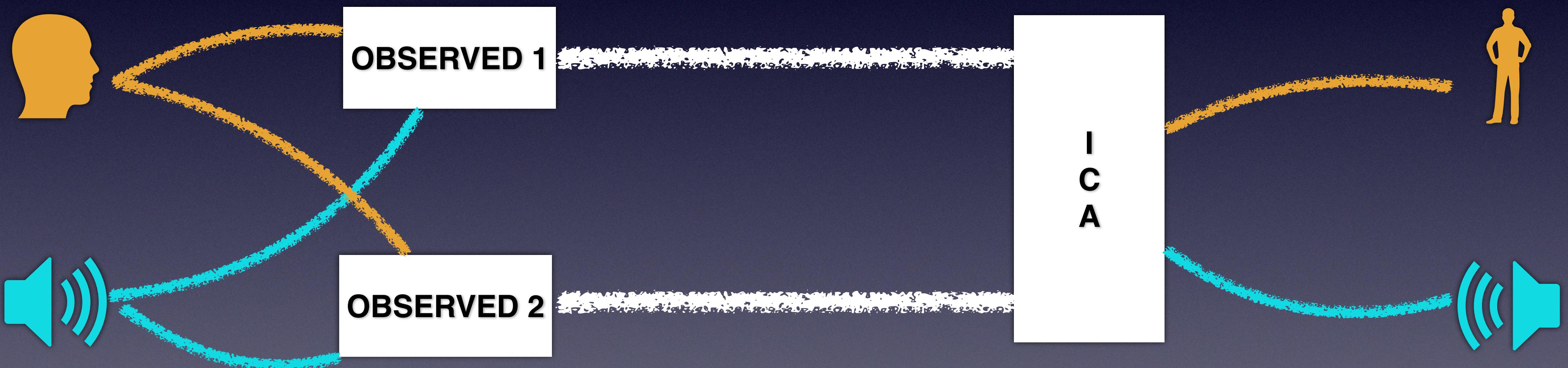
1. Basic signals



Gitlink: <https://github.com/Rajesh-Smartino/Independent-Component-Analysis>



2. Audios



References:

1. [1, 2, 3, 4, 5, 6, 7, 8, 9] A Tutorial on Independent Component Analysis **Jonathon Shlens** Google Research Mountain View, CA 94043
2. “*Independent Component Analysis*” book by **Aapo Hyvarinen**, Juha Karhunen, Erkki Oja.

Video credits:

1. [#2] Eigenvectors and eigenvalues | Chapter 14, Essence of linear algebra by **3Blue1Brown**. <https://youtu.be/PFDu9oVAE-g>
2. [#1] Singular Value Decomposition (SVD) and Image Compression by **Serrano.Academy**. <https://youtu.be/DG7YTIGnCEo>

Thank you