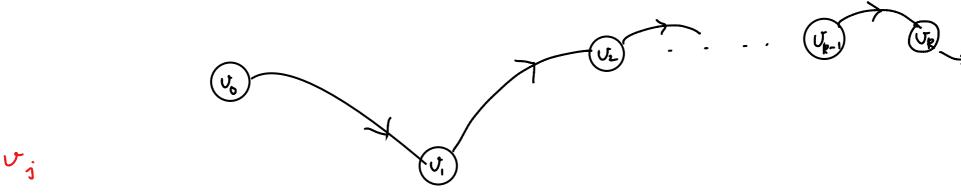
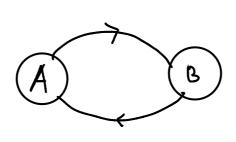
- · Dinected Graph G= (V,E) |V|
- . Eage weights w: E → R

w(u,v) is weight of eage (u,v)

. Path $\beta = \langle v_0, v_1, \dots, v_k \rangle$ $v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \cdots \qquad v_{k-1} \rightarrow v_k$



V= = V



just a

symbol

· Weight of a path p:

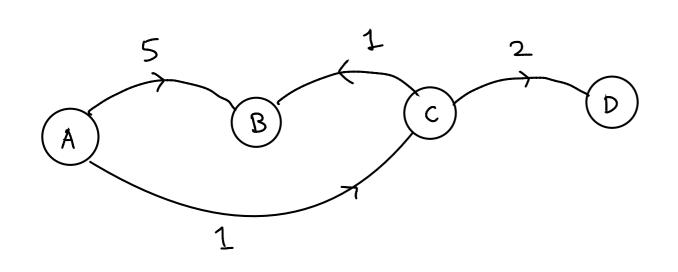
$$W(p) = \sum_{i=1}^{k} W(v_{i-1}, v_i) = \text{summation of weights}$$
 $i=1$

Shortest-Path weight between vertices u and r

etween vertice u and
$$v$$

$$S(u,v) = \begin{cases} min & w(p) \\ u & v \end{cases}, \quad if a path exists$$

$$\delta(u,v) = \begin{cases} min & w(p) \\ u & v \end{cases}, \quad if path does not exist$$



$$S(A,B) = 2$$

$$S(A,D) = 3$$

$$S(B,A) = \infty$$

$$S(B,C) = \infty$$

$$S(B,D) = \infty$$

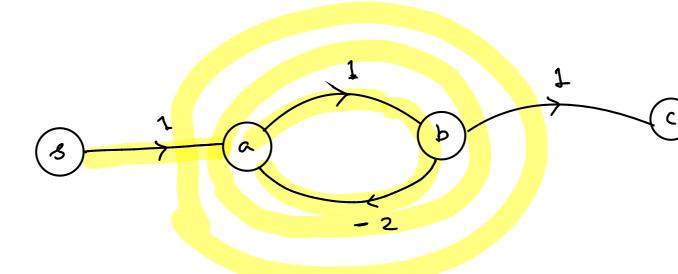
. We want to find the shortest path from a single source vertex stV bo each ventex v E V (i) single destribution: de V (from each ve V to Le V) Special Cares Flip/Reverse the eages and do single source sourcest path (Ii) Between a given pair (u, v)

Parperties Of Shortest Paths · Subpaths of shortest paths are shortest paths φ= < 5, 5, ..., \$ 7 1 < i < j < k p. = < v., ..., v, 7 V₁ P₁i V_i Pij V_j Pjk V_k Proof: $\omega(p) = \omega(p_{i,i}) + \omega(p_{i,j}) + \omega(p_{j,k})$ Pij was not shortest path between vi and vj , but pij wcpap) > wcpin) Je più vo più vo più vo pik $\omega(p_{1:}) + \omega(p'_{ij}) + \omega(p_{jk}) < \omega(p_{ii}) + \omega(p_{ij}) + \omega(p_{jk})$ hot snortest path

Shortest Path

- . Negative Edges are Okay (they are allowed in the graph)
 - Negative cycles are an





$$S(s,c) = -\infty$$

$$S(a,g) = -3$$

Shortest Paths Contain no the Oycles

(by removing this tre cycle we can always produce a shorter path)

1VI-1 distinct edges in an acyclic path

Predecessor +([v] = another vertex

PRINT- PATH (G, s, v)

ig v=s then point s

evse if H[V] = NILthen paint "no path from" of "exists"

Lext

else PRINT-PATH (G, 8, M[V])
print of

· Paedecessor Graph

I dealey, at termination of our algorithms, we want Git to Shortest. Path- Tree"

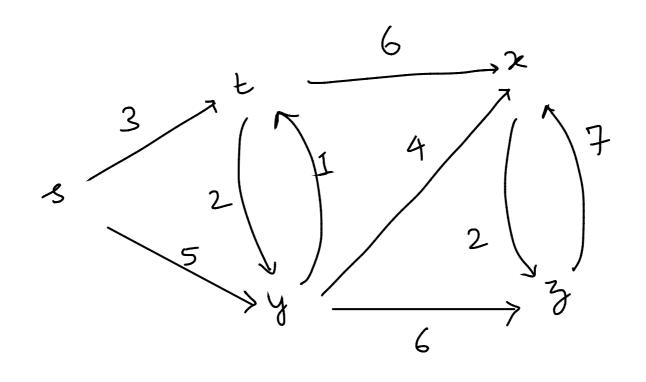
Shortest Path Tree: G'= (V', E')

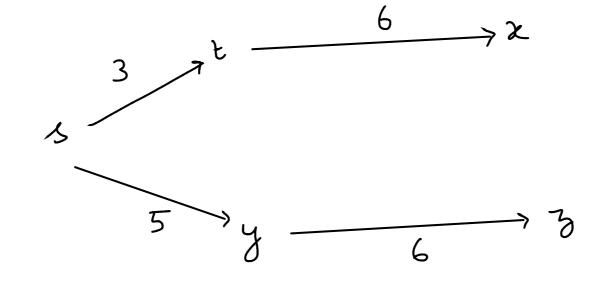
* V' S V is the set of vertices reachable from s in G

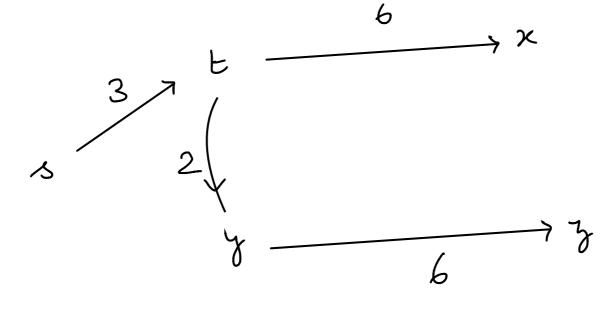
* 6' is a tree rooted at s

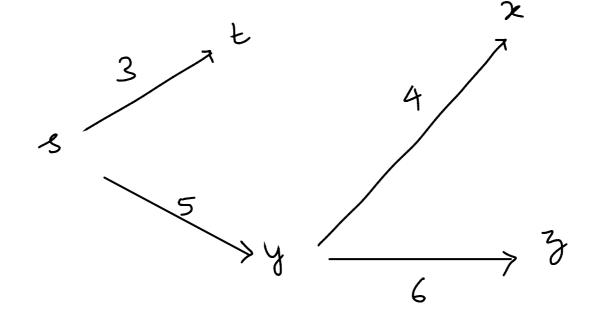
of for all vev; the simple path from s to v in G'
is the shortest path from s to v in G

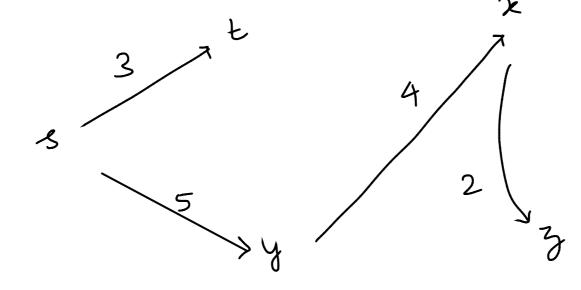
Shortest Path Tree Need Not be knique











Relaxation

d[v]: upper bound on weight of shortest path to u impercit)

> INIT - SINGLE - SOURCE (G, s) for each vertex $v \in V(G_1)$ do a [v] < 0 HEVJ 4 NIL

> > d [3] ← 0

Relax (u, o, w)

if d[v] > d[v] + w(v,v) then a [v] < d(u] + w(u,v) TCV] < u

Basically to heach v it seems a better" i dea to reach to u first and take edge (u,v)