Rains in Bharat - II

Ву

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Bachelor Thesis submitted to

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Bachelor of Technology

in

Computer Science and Engineering

May, 2021

Certificate

This is to certify that the thesis entitled "Rains in Bharat" being submitted by Rajnish Maurya (CSE 18067/378), Subham Pal (CSE 18093/404) and Subrata Kumar Biswas (CSE 18094/405), undergraduate students, in the Department of Computer Science and Engineering, Indian Institute of Information Technology Kalyani, West Bengal 741235, India, for the award of Bachelors of Technology in Computer Science Engineering is an original research work carried by them under my supervision and guidance. The thesis has fulfilled all the requirements as per the regulation of Indian Institute of Information Technology Kalyani and in my opinion, has reached the standards needed for submission. The works, techniques and the results presented have not been submitted to any other university or Institute for the award of any other degree or diploma.

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Declaration

I hereby declare that the work which being presented in the thesis entitled "Rains of Bharat" is submitted to Indian Institute of Information Technology Kalyani in partial fulfillment for the award of the degree of **Bachelor of Technology** in Computer Science and Engineering does not contain any classified information during the period from **January**, 2021 to May, 2021 under the supervision of Dr. Uma Das, Department of Physics, Indian Institute of Information Technology Kalyani, West Bengal 741235, India.

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Abstract

A climate change project to forecast precipitation rate in the country in each and every coordinate with 0.25 degree resolution by training with data 1998 to 2019. We will attempt to predict the expected rainfall for one more year for a particular Latitude and Longitude by using various models.

Chapter 1: Introduction

We have collected the data containing the rainfall rate in mm/hour from Huffman et al [1]. This daily accumulated precipitation product is generated from the research-quality 3-hourly TRMM Multi-Satellite Precipitation Analysis TMPA (**3B42**). It is produced at the **NASA** GES DISC, as a value added product. Simple summation of valid retrievals in a grid cell is applied for the data day. The TRMM Microwave Imager (TMI) measured microwave **energy** emitted by the Earth and its atmosphere to quantify the water vapor, the cloud water, and the rainfall intensity in the atmosphere. These terminologies are defined in the website of NASA linked in the references [2]. The size of the folder is 1.29GB containing individual records for 8031 days starting from 01-01-1998 with precipitation rates in mm/hour.

Problem Statement

Make a model to forecast precipitation given in mm/hour for one more year after 2019. Data is present from 1998-2019. In order to implement LSTM and other models there is a need to rearrange the data in a proper manner.

Models Involved

- 1. Facebook Prophet. (Only for Reference)
- 2. LSTM
- 3. ARIMA/SARIMAX

Chapter 2: Data and Methods

Description of Data

Data we received was 3B42 global data in csv format. Each file contains two dimensional arrays of data - $161 \times 121 = \text{longitudes}$ and latitudes. For each day there is one individual csv file. Filename contains data in yyyymmdd format.

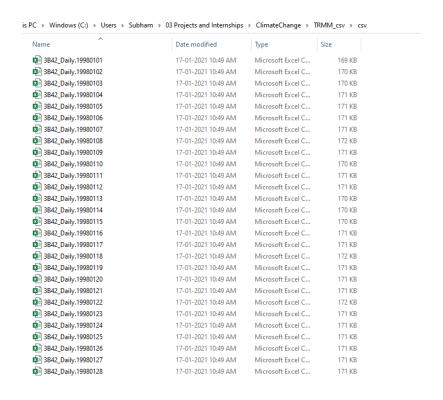


Figure 2.1.
3B42 Daily Data from 1980 to 2019.

4	Α	В	С	D	E	F	G	H	1	J	K	L	M	N	0	P	Q	R	S	T	U
1	21.69	28.26	33.75	37.95	47.1	34.5	28.8	36.6	23.07	25.23	26.37	29.61	38.52	33.48	37.56	29.79	30.66	24	24.3	31.95	3
2	17.79	27.18	37.17	37.8	38.82	42.69	46.47	38.85	38.04	41.04	35.49	31.17	31.29	29.43	23.64	27.12	26.4	25.5	25.08	34.77	3
3	10.92	18.51	24.15	26.28	31.29	34.53	53.19	46.26	45.21	42.03	39.18	26.1	24.75	20.37	18.57	23.67	25.62	32.34	31.29	38.1	4
1	6.24	13.23	16.11	18.99	27.81	40.38	42.87	42.33	39.42	32.79	27.78	22.35	17.79	21.66	21.27	21.21	23.52	32.58	38.4	54.93	7
5	14.52	27.27	31.68	26.97	26.01	32.34	37.11	32.55	27.72	20.46	26.28	30.69	18.42	20.55	21.57	19.56	22.56	30.15	35.73	48.84	6
5	20.67	31.83	34.26	28.98	20.07	17.31	23.7	21.6	14.25	14.55	28.53	24.66	20.13	25.44	24.93	22.92	24.51	32.91	48.75	49.02	8
7	17.73	25.98	28.95	22.68	16.35	17.28	20.76	18.75	21.69	26.52	33	35.55	34.74	29.76	31.83	22.44	31.32	33.3	35.73	45.84	6
3	9.09	11.1	17.49	15.39	15.18	15.3	20.73	20.07	28.29	43.23	47.58	46.2	49.44	35.97	32.34	37.53	41.1	37.77	35.4	45.36	4
)	6.75	5.52	5.37	5.46	11.79	13.8	16.62	23.07	30.6	38.28	35.25	49.89	51.39	43.47	38.37	43.65	48.69	48.99	45.3	35.76	4
0	6.27	3.45	2.19	6.96	9.03	8.1	10.08	19.77	32.4	42.03	36.48	39.87	50.79	47.31	38.34	35.49	36.72	36.99	32.82	20.16	
1	10.17	2.67	3.96	3.81	9.09	12.81	15.24	15.75	22.05	38.76	37.62	30.96	46.53	51.3	40.44	35.73	35.13	37.41	22.35	19.29	- :
2	6.75	4.89	5.16	4.59	5.1	6.84	11.31	13.47	17.82	32.76	36.78	34.05	29.91	31.92	30.39	30.69	36.48	30.84	25.83	17.58	- 2
3	8.22	6.66	7.47	7.05	5.7	4.89	9.18	15.78	18.54	21.18	35.22	29.82	30.69	31.05	28.08	30.87	67.86	49.02	30.99	24.75	
4	7.86	6.72	8.31	7.47	8.97	5.4	5.88	11.82	11.79	10.71	12.09	17.01	26.67	46.02	63.87	66.51	63.63	69.48	44.1	39.81	
5	9.48	6.57	6.36	4.47	5.22	6.09	5.64	6.72	6.69	8.61	9.09	11.49	34.38	38.13	66.72	84.06	90.33	84.18	60.78	45.12	
6	2.37	3.42	2.61	1.83	2.34	6.63	5.88	5.13	3.81	9.69	16.8	24.51	34.47	40.62	56.07	78.57	93.99	73.5	77.73	61.65	
7	2.31	2.31	1.35	1.08	1.95	3.72	5.34	5.73	5.55	12.18	19.71	17.91	23.43	15.84	39.09	43.53	57.18	50.73	44.34	27.21	4
8	0.12	1.35	1.83	1.95	2.43	2.82	2.49	2.16	4.14	8.94	11.46	10.11	6.75	17.19	23.85	20.76	25.17	23.97	17.07	9.93	- :
9	0.48	0.45	1.68	1.95	2.58	3.93	2.16	1.65	1.62	3.75	5.82	7.68	9.15	17.55	16.08	14.88	31.62	20.52	15.45	11.28	
0	2.49	1.14	0.72	0.33	1.02	4.65	3.3	2.34	2.07	3.84	4.26	8.64	11.49	16.32	12.93	12.09	33.27	27	23.52	18.3	
1	4.14	2.31	0.24	0.99	1.95	3.12	5.19	5.94	4.32	4.74	4.14	3.63	4.53	10.11	10.98	14.43	23.7	31.47	33.99	23.19	:
4	þ.	3B42 Dai	ily.1998010	01 (-	F)								: 4								

Figure 2.2.

3B42 Daily Data Sample with $161 \times 121 = longitudes \times latitudes$.

Instructions Provided for Extracting Information

IDL> help, lon1								
LON1	FLOAT = A	Array[161]						
IDL> print, lon1								
59.8750	60.1250	60.3750	60.6250	60.8750	61.1250	61.3750	61.6250	61.8750
62.1250								
62.3750	62.6250	62.8750	63.1250	63.3750	63.6250	63.8750	64.1250	64.3750
64.6250								
64.8750	65.1250	65.3750	65.6250	65.8750	66.1250	66.3750	66.6250	66.8750
67.1250								
67.3750	67.6250	67.8750	68.1250	68.3750	68.6250	68.8750	69.1250	69.3750
69.6250								
69.8750	70.1250	70.3750	70.6250	70.8750	71.1250	71.3750	71.6250	71.8750
72.1250								
72.3750	72.6250	72.8750	73.1250	73.3750	73.6250	73.8750	74.1250	74.3750
74.6250								
74.8750	75.1250	75.3750	75.6250	75.8750	76.1250	76.3750	76.6250	76.8750
77.1250								
77.3750	77.6250	77.8750	78.1250	78.3750	78.6250	78.8750	79.1250	79.3750
79.6250								
79.8750	80.1250	80.3750	80.6250	80.8750	81.1250	81.3750	81.6250	81.8750
82.1250								
82.3750	82.6250	82.8750	83.1250	83.3750	83.6250	83.8750	84.1250	84.3750
84.6250								
84.8750	85.1250	85.3750	85.6250	85.8750	86.1250	86.3750	86.6250	86.8750
87.1250								
87.3750	87.6250	87.8750	88.1250	88.3750	88.6250	88.8750	89.1250	89.3750
89.6250								
89.8750	90.1250	90.3750	90.6250	90.8750	91.1250	91.3750	91.6250	91.8750
92.1250								
92.3750	92.6250	92.8750	93.1250	93.3750	93.6250	93.8750	94.1250	94.3750
94.6250	05 4050	05 0550	05 5050	05 0550	0.5 4.050	0.0.0000	0.6. 6050	0.5 0.550
94.8750	95.1250	95.3750	95.6250	95.8750	96.1250	96.3750	96.6250	96.8750
97.1250	05 6050	07 0750	00 1050	00 0750	0. 6050	00 0750	00 1050	00 0750
97.3750	97.6250	97.8750	98.1250	<u>98</u> .37€2	+ 98.6250	98.8750	99.1250	99.3750
99.6250				`				
99.8750								

Figure 2.3.

Rows of the data represent 161 Longitudes starting from 59.8750 to 99.8750 degrees with 0.25 degree resolution. Refer to Figure 3 to understand the context.

LAT1 F	LOAT = A1	rray[121]						
IDL> print, lat1		_						
	5.12500	5.37500	5.62500	5.87500	6.12500	6.37500	6.62500	6.87500
7.12500								
7.37500	7.62500	7.87500	8.12500	8.37500	8.62500	8.87500	9.12500	9.37500
9.62500								
	10.1250	10.3750	10.6250	10.8750	11.1250	11.3750	11.6250	11.8750
12.1250	10 6050	10 0750	12 1250	10 0750	12 (25)	12 0750	14 1050	14 2750
12.3750 14.6250	12.6230	12.8750	13.1250	13.3750	13.6250	13.8750	14.1250	14.3750
	15.1250	15.3750	15.6250	15.8750	16.1250	16.3750	16.6250	16.8750
17.1250	13.1230	13.3730	13.6230	13.6730	10.1230	10.3730	10.0230	10.0750
	17.6250	17.8750	18.1250	18.3750	18.6250	18.8750	19.1250	19.3750
19.6250								
19.8750	20.1250	20.3750	20.6250	20.8750	21.1250	21.3750	21.6250	21.8750
22.1250								
22.3750	22.6250	22.8750	23.1250	23.3750	23.6250	23.8750	24.1250	24.3750
24.6250								
	25.1250	25.3750	25.6250	25.8750	26.1250	26.3750	26.6250	26.8750
27.1250								
	27.6250	27.8750	28.1250	28.3750	28.6250	28.8750	29.1250	29.3750
29.6250								
29.8750	30.1250	30.3750	30.6250	30.8750	31.1250	31.3750	31.6250	31.8750
32.1250	22 6250	22 0750	22 1252	22 2752	22 6252	22 0750	24 1250	04 0750
34.6250	32.6250	32.8/50	33.1250	33.3/50	33.6250	33.8/50	34.1250	34.3750
34.8750								
IDL> help, data								
	LOAT = A	ray[161, 121	1					
IDL>	LORI - AI	LLUY (LVI) IZI	1					

Figure 2.4.

Columns of the data represent 121 Latitudes starting from 4.8750 to 34.8750 degrees with 0.25 degree resolution. Refer to Figure 3 to understand the context.

Reshaping the daily 3B42

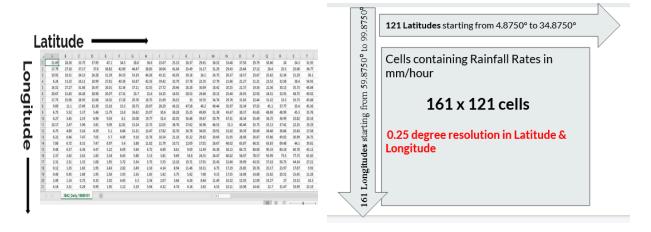


Figure 2.5

Latitude and Longitude is arranged in this manner. Refer to Figure 2.3 and 2.4.

We can see how Latitude and Longitudes are mapped. In order to get precipitation rate for a particular day it is possible to find out from here. But generating an entire time series is still not possible.

In Figure 2.5, we have seen data in nxm matrix format. Now we are going to squeeze the entire thing and make it 1-D.

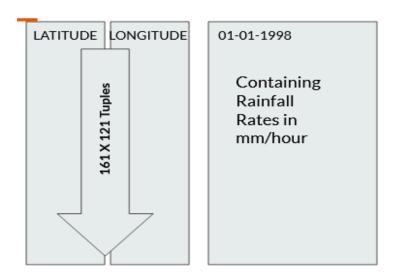


Figure 2.6

Reshaping Data.

Merging CSV Files to a single one

As we know, training a LSTM model takes time, so arranging the data in a proper way is necessary to make a robust model. So far, we can see that data is arranged in separate CSV files for a particular day. In Figure 4 and Figure 5, we received the key to access any coordinate of that particular csv file to give us the rainfall rate for that day. But, in order to get a time series data for a particular location, we need to gather data for that coordinate from all the files. Iterating this process everytime will make the process slow.



Figure 2.7

Process of making a single Global.csv

We made an attempt to merge all the individual csv files to a single one.

```
: lat = [59.875 + 0.25*x for x in range(161)]
lon = [4.875 + 0.25*x for x in range(121)]
```

```
lat_lon = []
for i in lat:
    for j in lon:
        lat_lon.append((i,j))
lat_lon

[(59.875, 4.875),
    (59.875, 5.125),
    (59.875, 5.375),
    (59.875, 5.625),
    (59.875, 5.875),
```

Figure 2.8.

Generating all possible combinations of Latitude and Longitude.

Figure 2.9.

Creating Global.csv with the latitude-longitude as index as created in Figure 5.

Merging all the individual files to a single csv file.

		1998-01-01	1998-01-02	1998-01-03	1998-01-04	1998-01-05	1998-01-06	1998-01-07	1998-01-08	1998-01-09	1998-01-10	 2019-12-21
59.875	4.875	21.69	2.550000	0.0	2.34	93.72	27.30	1.38	15.00	22.14	53.220000	 46.05
	5.125	17.79	6.750000	0.0	0.84	64.62	25.41	4.20	7.41	7.35	52.380000	 39.69
	5.375	10.92	5.880000	0.0	0.00	31.59	24.87	7.08	2.88	4.17	45.300000	 20.85
	5.625	6.24	9.600000	0.0	0.00	28.95	26.64	10.56	1.44	3.84	31.470000	 40.38
	5.875	14.52	18.660000	0.0	0.00	24.78	29.46	10.29	0.00	7.44	22.680000	 34.77
99.875	33.875	0.00	0.000000	0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.000000	 0.00
	34.125	0.00	0.008728	0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.000000	 0.00
	34.375	0.00	0.000000	0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.000000	 0.00
	34.625	0.00	0.000000	0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.000000	 0.00
	34.875	0.00	0.000000	0.0	0.00	0.00	0.00	0.00	0.00	0.00	0.027414	 0.00

Figure 2.10

Merged Global csv file. The multi-index gives

all possible coordinates and we get columns for each day.

Now getting time series data for a particular coordinate is very easy, we no longer need to peek into individual csv files as all data is available in the Global.csv. Moreover the data can be retrieved by knowing the coordinates of that place.

```
## Find data for lat-lon
Global.loc[(59.875,4.875)]
1998-01-01
            21.69
             2.55
1998-01-02
1998-01-03
             0.00
1998-01-04
             2.34
1998-01-05
             93.72
2019-12-26
             0.00
2019-12-27
             0.00
2019-12-28
             0.00
2019-12-29
             0.00
           0.48
2019-12-30
Name: (59.875, 4.875), Length: 8031, dtype: float64
```

Figure 2.11.

Extracting Time Series from Global.csv

Automatic Latitude Longitude Generation System

With the help of the **geopy** module we can get the coordinates of a particular place upon providing the name of the place. In case it fails to recognize the location, then we made it flexible to take manual input.

```
def get_city_coordinates():
    from geopy.geocoders import Nominatim
    geolocator = Nominatim(user_agent="my_user_agent")
    city =input('**HIT ENTER for Manual Mode **OR**\nEnter Location As "City" or "City, Country" format: ')
    country =""
    loc = geolocator.geocode(city+','+ country)
    print("latitude is " ,loc.latitude,"&longtitude is " ,loc.longitude)
    return loc.latitude,loc.longitude
```

Figure 2.12.

Returns coordinate on providing the location name.

Timeseries Generator and Validator

In the previous section, we managed to get the coordinate location. Now we need to find out the nearest location according to our dataset. We designed one algorithm for the same task. If we fail to get the nearest coordinate then it will prompt us to take another location. If we are able to match the coordinates then we generate a time series dataframe.

```
## Findout closest coordinates wrt to available data

def closest(pos):
    latitude = pos[0]
    longitude = pos[1]
    lon = [59.875 + 0.25*x for x in range(161)]
    lat = [4.875 + 0.25*x for x in range(121)]
    LAT = lat[min(range(len(lat)), key = lambda i: abs(lat[i]-latitude))]
    LON = lon[min(range(len(lon)), key = lambda i: abs(lon[i]-longitude))]
    if (abs(latitude-LAT) > 1) or (abs(longitude-LON)>1):
        return 0
    return (LON, LAT)
```

Figure 2.13.

Code to find the closest coordinate.

```
## Run this function to create DataFrame
df = GetLocation()
df.plot(figsize=(25,5))
**HIT ENTER for Manual Mode **OR**
Enter Location As "City" or "City, Country" format: kolkata
latitude is 22.5414185 &longtitude is 88.35769124388872
Table Created with nearest co-ordinates: (88.375, 22.625)
            Rainfall
1998-01-01
              0.0000
 1998-01-02
              0.0000
1998-01-03
              0.0000
 1998-01-04
              4 8600
 1998-01-05
              0.0000
2019-12-26
              0.0000
2019-12-27
              0.0000
2019-12-28
              0.0000
2019-12-29
              5.0818
```

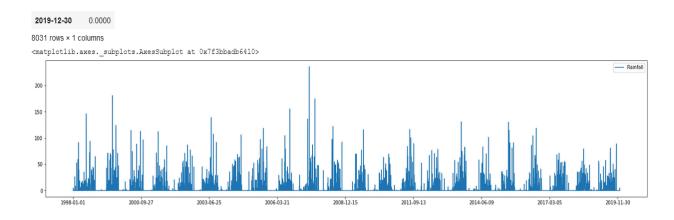


Figure 2.14.

Generation of time series data frame along with plot for location Kolkata

All the models are made with respect to Kolkata as its location as given in Figure 14.

Model Using Facebook Prophet

Facebook Prophet is an open source library for univariate time series forecasting. The model takes very less time yet a robust one. We created this model only for reference to LSTM and ARIMAX.

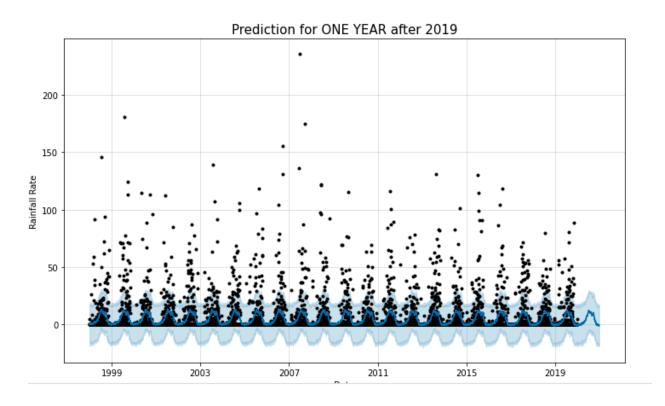


Figure 2.15.

FB Prophet Prediction of Rainfall Rate (mm/hr).

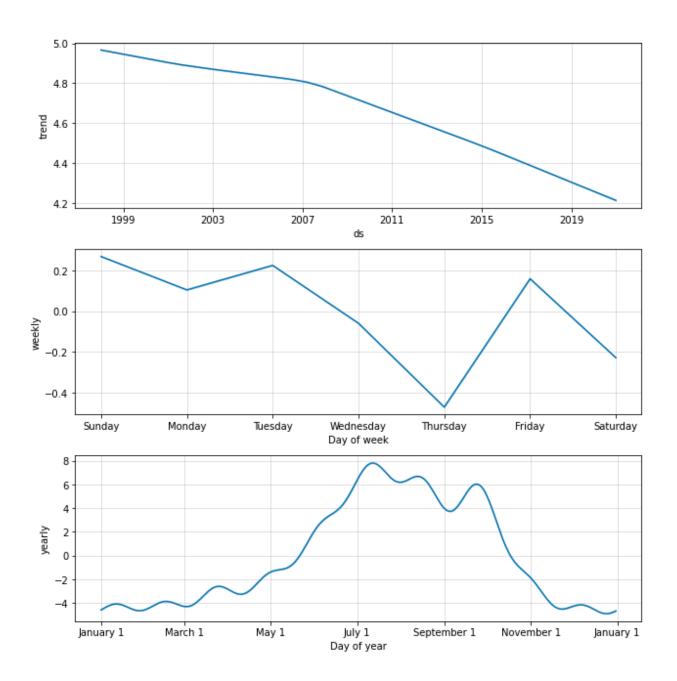


Figure 2.16.
Trend Analysis of Rainfall Rate (mm/hr)

Model Using LSTM

Long short-term memory network

Long short-term memory network(LSTM) is a particular form of recurrent neural network(RNN), which is the general term of a series of neural networks capable of processing sequential data. LSTM is a special type of network structure with three "gates" structures. Three gates in an LSTM unit are input gate, forgetting gate and output gate. While information enters the LSTM network, it can be selected by rules, only the information confirmed to the algorithm will be left, and the information that does not confirm will be forgotten through the forgetting gate.

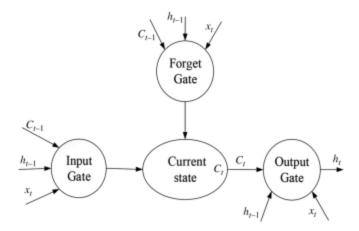


Figure 2.17.

Gates in LSTM

The LSTM can add and delete information for neurons through the gating unit. To determine selectively whether information passes or not, it consists of a sigmoid neural network layer and a pair of multiplication operations. Each element output by the Sigmoid layer is a real number between [0, 1], representing the weight through which the corresponding information . LSTM unit structure passes. In the LSTM neural network, there is also a layer containing tanh activation function which is used for updating the state of neurons.

$$\sigma(x) = (1)/(1 + e^{x}-x)$$

$$tanh(x) = (e^x - e^-x)/(e^x + e^-x)$$

The forgetting gate of the LSTM neural network determines what information needs to be discarded, which reads h_{t-1} and x_t , gives the neuron state C_{t-1} a value of 0-1. The calculation method of forgetting probability is given below:

$$f_{t=\sigma}(W_{f} \cdot [h_{t-1}, x_{t}] + b_{f})$$

where h_{t-1} represents the output of the previous neuron and x_t is the input of the current neuron. σ is the sigmoid function.

The input gate determines how much new information is added to the neuron state. First, the input layer containing the sigmoid activation function determines which information needs to be updated, and then a tanh layer generates candidate vectors c_t , an update is made to the state of the neuron.

$$Ct = ft * Ct-1 + it * Ct$$

where the calculation method of it and ct are shown below:

it =
$$\sigma$$
 (Wi · [ht-1, xt]+ bi)
ct = tanh(Wc · [ht-1, xt]+ bc)

The output gate is used to control how many current neural united state are filtered and how many controlling units state are filtered which are shown below:

ot =
$$\sigma$$
(Wo · [ht-1, xt] + bo)
ht = ot * tanh(Ct)

LSTM Model Building, training and Evaluation

The first step is to define the model of the LSTM network as a Sequential class. Sequential class is a sequence of layers in a neural network. We create layers and add them in the order that they should be connected. A fully connected layer that often follows LSTM layers and is used for outputting a prediction called Dense. In a layer the first hidden layer in the network must define the number of inputs to expect, e.g the shape of the input layer. Input must be three-dimensional, consisting of samples, time steps and features in that order.

- **Samples** These are the rows in our data. One sample may be one sequence.
- **Time steps** These are the past observation for a feature, such as lag variable.
- **Features** These are columns in our data.

We create our 2D dataset to a 3D dataset using reshape() function in NumPy. The model assumes one or more samples to define the number of time steps and features. Here, Sequential model works as a pipeline in which our raw data fed in at one end and predictions that come at the other end. Sequential layer helps in transforming the data from input to prediction. For example, activation functions that transform a

summed signal from each neuron in a layer can be extracted and added to the Sequential as a layer-like object called Activation. The choice of activation function is most important for the output layer as it will define the format that predictions will take. So, we have used logistic activation function (sigmoid-function).

Once we have defined our network, we must compile it because compilation is an efficient step.

Compilation requires a number of parameters to be specified, specifically tailored to training the network. The **stochastic gradient descent(sgd)** optimization algorithm was used to train the network to find the model parameters that correspond to the best fit between predicted and actual outputs and the **mean squared error(mse)** loss function is used to evaluate the network that is minimized by the optimization algorithm.

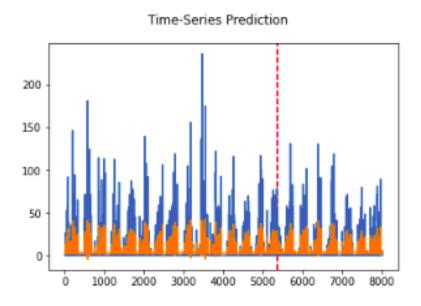


Figure 2.18.

Right side shows the predicted output.

Before the data were used to train the LSTM Network, they were split into a training set and a test set. The data were split by assigning the first 80% to the training set and the last 20% to the testing set. Finally, the training and testing set were split into an input and targeted array. The network is trained using the **Backpropagation Through Time algorithm** and optimized according to the optimization algorithm and the loss function specified when compiling the model. The backpropagation algorithms requires that the network should be trained for a specified number of epochs to all the sequences in the training dataset. Each epoch is partitioned into groups of input-output pattern pairs called batches.

Epoch: One passes through all samples in the training dataset and updates the network weights. LSTMs may be trained for tens, hundreds, or thousands of epochs.

Batch: A pass through a subset of samples in the training dataset after which the network weights are updated. One epoch consists of one or more batches.

Our model is fitted with a 32 batch size and 2000 epochs. The model evaluates the loss function across all of the test patterns. When error values are reduced due to back-propagation, then the deviation of predicted output with actual output is minimized, which in turn is defined as loss. Errors are reduced gradually by achieving stability, and the gradient persists through the proposed model, which leads to minimal losses. The global minimum loss was found to be 0.00334 at around 1800 epochs and remains within 0.00334 until the 1900 epochs, which shows the stability of the proposed model.

Model with ARIMA / SARIMAX

There are two popular models while dealing with time series datasets. One is the Auto-regressive model and the other is the Moving Average model. The basic difference between them is that the moving average (MA) model does not use the past forecasts to predict the future values whereas it uses the errors from the past forecasts. While, the autoregressive model (AR) uses the past forecasts to predict future values.

But, while making accurate predictions, we need both of the models altogether and thus ARIMA was introduced which is abbreviated as Auto-regressive Integrated Moving Average model. It uses both models over a time series dataset. But the problem with ARIMA is that it does not support seasonal data. That is a time series with a repeating cycle. ARIMA expects data that is either not seasonal or has the seasonal component removed.

Seasonal Autoregressive Integrated Moving Average, SARIMA or Seasonal ARIMA, is an extension of ARIMA that explicitly supports univariate time series data with a seasonal component. (Method name is SARIMAX where 'X' stands for exogenous variable support). It added four seasonal elements to ARIMA i.e. P,D,Q & m that stands for Seasonal autoregressive order, Seasonal difference order, Seasonal moving average order and the number of time steps for a single seasonal period respectively.

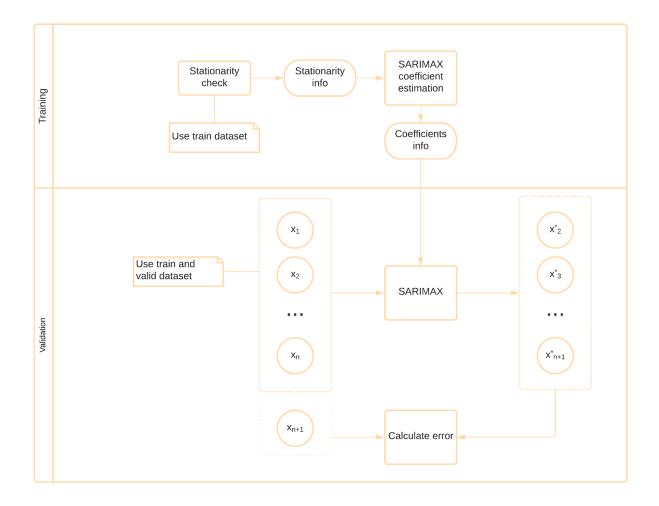


Figure 2.19
Architecture of SARIMAX

Given time series data X_t where t is an integer index and the X_t are real numbers, an ARIMA model output is given by,

$$\left(1-\sum_{i=1}^p arphi_i L^i
ight)(1-L)^d X_t = \left(1+\sum_{i=1}^q heta_i L^i
ight)arepsilon_t$$

Where L is the lag operator. ε_t is the error term.

Firstly, we create a monthly distribution of our data for seasonality analysis. Visualisation of data helps in tracing seasonality more easily.

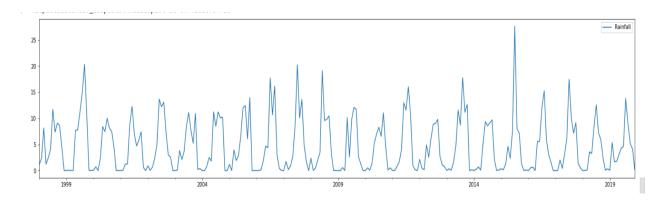


Figure 2.20

Monthly Distribution

Firstly, let's try to make predictions using the ARIMA model.

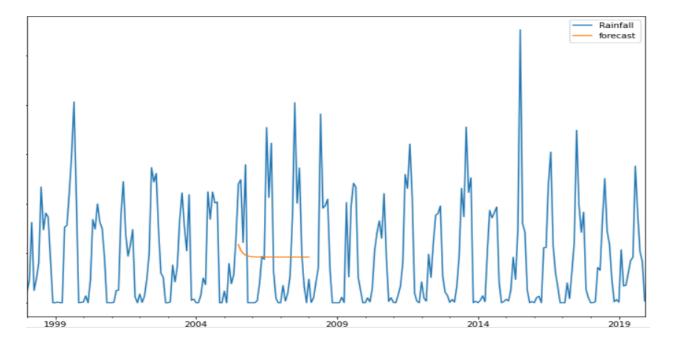


Figure 2.21

ARIMA (train-test split)

Here, it is clearly visible that there is no seasonality in our prediction. The reason is the absence of seasonality factors in our model. Therefore, ARIMA is not recommended for predicting seasonal variations. For the purpose, we will use the SARIMAX model.

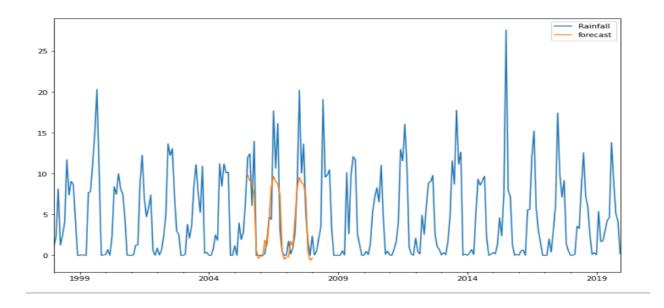


Figure 2.22
SARIMAX - Seasonality Verification (train-test split)

We just verified the presence of seasonality in our predictions by using 'train-test split' of our original data. Therefore, it is verified that the SARIMAX model can make predictions on seasonal datasets. Now, it's time to make our predictions.

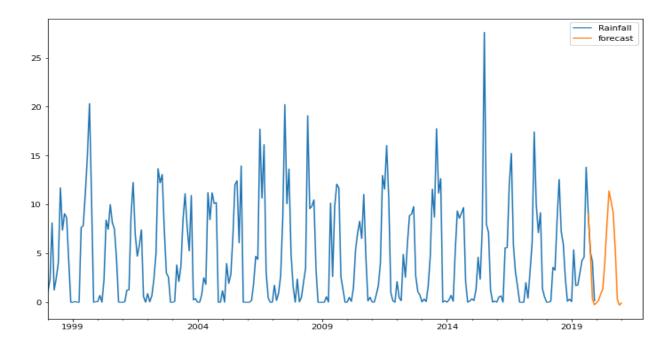


Figure 2.23
SARIMAX Predictions

Chapter 3: Results and Discussion

Model selection is an important factor in predicting satisfactory results. Out of ARIMA and LSTM, LSTM yields better data-fitting and overfitting in long term modelling. In different random training of the model, it was found 84-87% of reduction in error rates while data-fitting as compared to ARIMA model claiming the superiority of LSTM over ARIMA in long term modelling. While predicting, LSTM modelling has the advantage of better error handling when it comes to presence of huge deviation in seasonal dataset. The reason is the possibility of learning noisy and nonlinear relationships with every step and explicit handling of ordered observations by adapting itself.

But, ARIMA/SARIMAX model out-performs machine learning and deep learning methods in both one-step and multi-step forecasting on univariate datasets given that there shouldn't be much errors and deviations other than the seasonality itself.

Chapter 4: Future Work

In the future we will try to put some natural calamities like Cyclones and its effect on the monsoon winds resulting in irregularities. There is also a trend of extreme rainfall in some pockets and drought in other parts of the country. We will try to study the effect of rainfall on the rainfed rivers as most of them are dying. We will deploy the model with FB Prophet in the near future.

References

- Huffman, G.J., D.T. Bolvin, E.J. Nelkin, and R.F. Adler (2016), TRMM (TMPA) Precipitation L3 1 day 0.25 degree x 0.25 degree V7, Edited by Andrey Savtchenko, Goddard Earth Sciences Data and Information Services Center (GES DISC), Accessed: [Data Access Date], 10.5067/TRMM/TMPA/DAY/7
- 2. NASA, https://gpm.nasa.gov/category/keywords/tmpa

Appendix

Notebook 1: https://nbviewer.jupyter.org/github/subhmm/rainGLOBAL/blob/main/GlobalRainfall.ipynb

Notebook 2:

https://colab.research.google.com/drive/1mieY6EY DpAiVapjmxw8NtwqlXWq5B6T?usp=sharing