A Real Time Application to Identify Alcoholics from ECG Signals

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STATUS – since synopsis (21st Jan)

- Raspberry Pi
- ▶ Feature Extraction
- ► Circuit Simulation
- Classifier

RASPBERRY PI

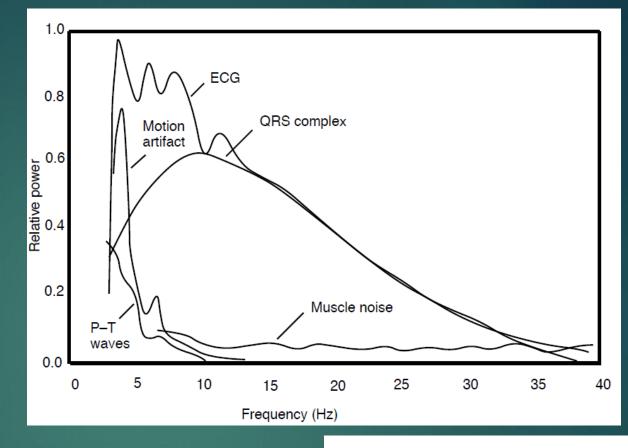
- ▶ Installed the OS
- Enabled ssh to accessed terminal
- Set static IP cmdline.txt was used IP and netmask provided

FEATURE EXTRATION

- ▶ Time domain
- ▶ Frequency domain
- ▶ Non-linear techniques

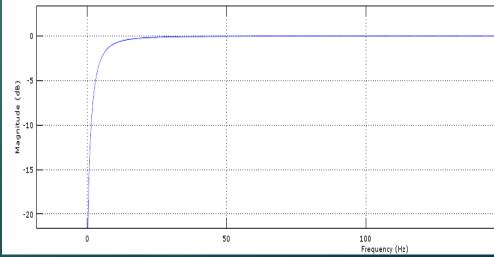
TIME DOMAIN

Based on PSD of generic ECG signal, an IIR HPF filter was designed to remove the low frequency baseline wandering

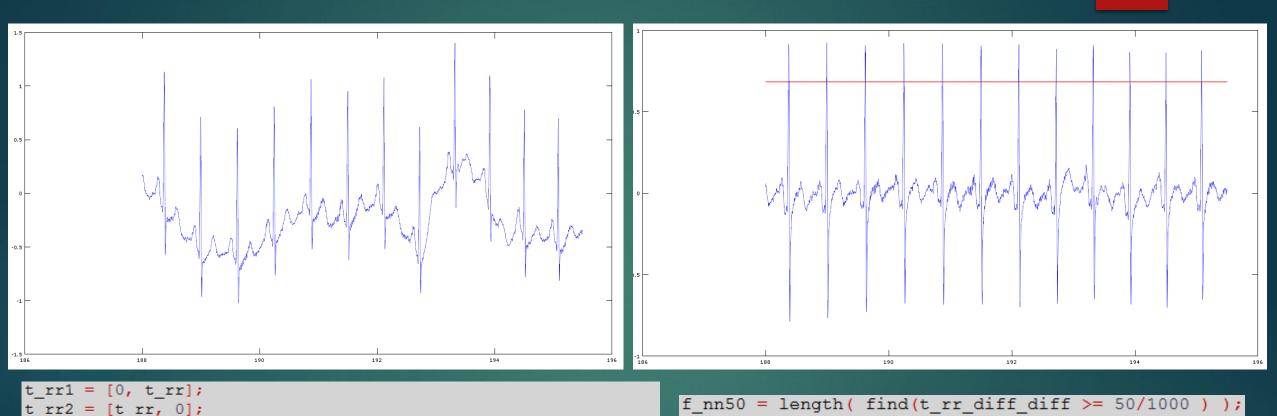


```
>> iir_butt
package loaded ...
Step 1 of 2: Reading requested records. (This may take a few minutes.)...
Step 2 of 2: Parsing data...
signal loaded ...

Filter characteristics...
1.00000 0.98574 -0.98574 1.00000 -0.97147
```



TIME DOMAIN



```
t_rr_diff = [t_rr2 - t_rr1](2: end-1); % HOLDS THE RR INTERVALS

f_pnn50 = 100*(f_nn50/length(t_rr_diff));

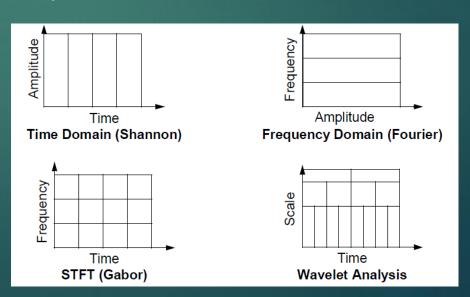
t_rr_diff1 = [0, t_rr_diff];
t_rr_diff2 = [t_rr_diff, 0];
t_rr_diff2 = [t_rr_diff2 - t_rr_diff1](2: end-1);

f_mean_min = mean(t_rr_diff)(1000*60)); % SAME AS: t_mean/(1000*60);
f_std = sqrt(var(t_rr_diff));

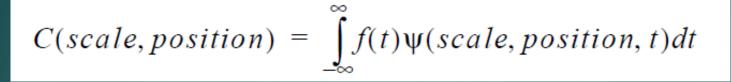
f_std_min = sqrt(var(t_rr_diff)(1000*60))); % SAME AS: f_std/(1000*60);
f_mean_HR = 1/f_mean_min;
f_std_HR = 1/f_std_min;
f_rms = sqrt( 1/length(t_rr_diff)*sum( (t_rr_diff).^2 ) );
```

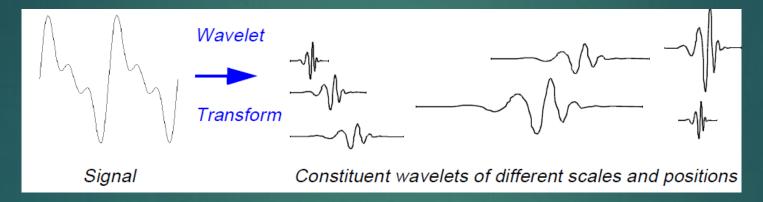
FREQUENCY DOMAIN

- Techniques possible:
 - ► Fourier Analysis time information is lost
 - ▶ Short Time Fourier Analysis limited precision based on window size
 - Wavelet Transform



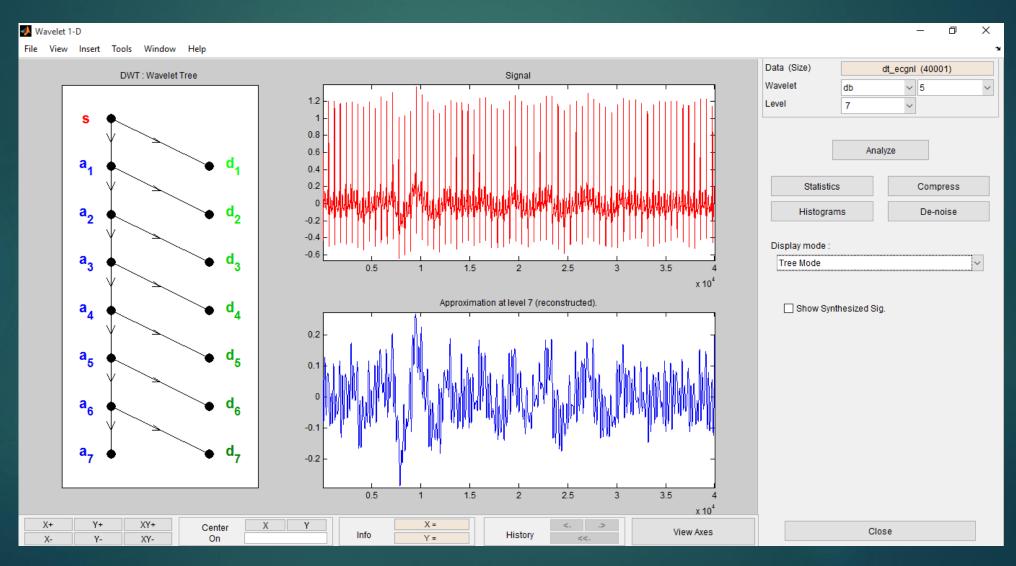
WHY WAVELET

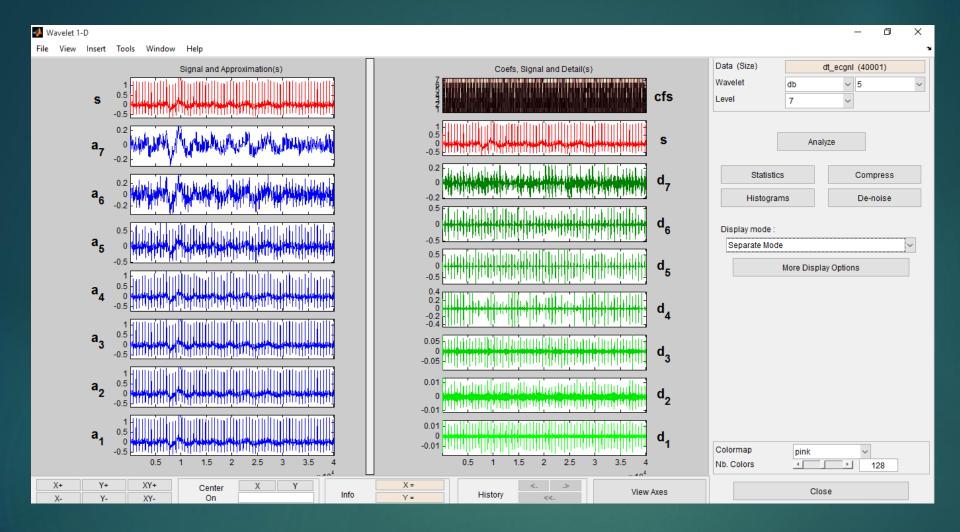




- Contains both frequency and time domain information
- Splits parent signal to different freq components, allowing isolation of low frequency baseline wandering
- R peak detection and RR interval calculation done

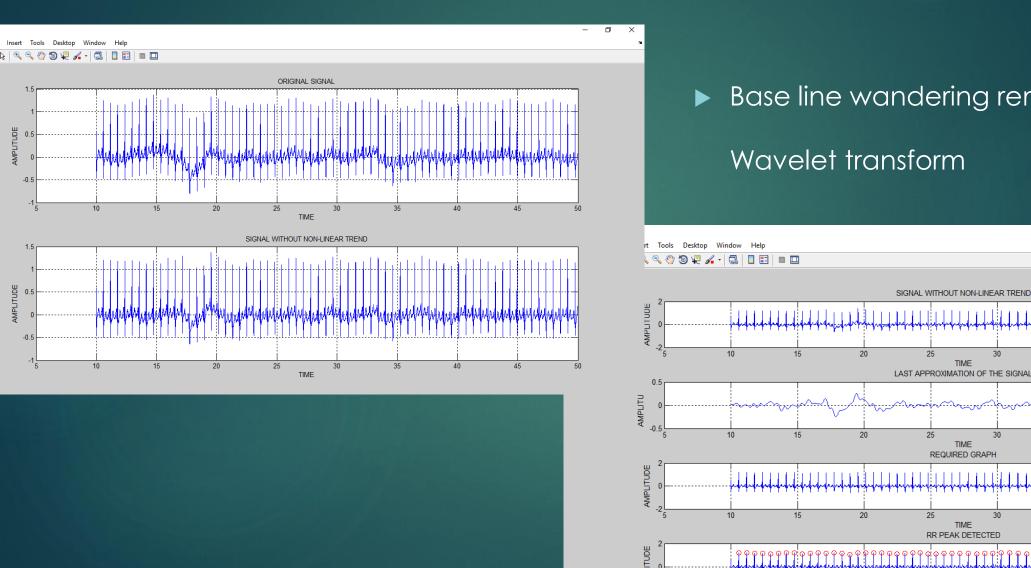
GRAPHS – MATLAB WAVELET TOOLBOX





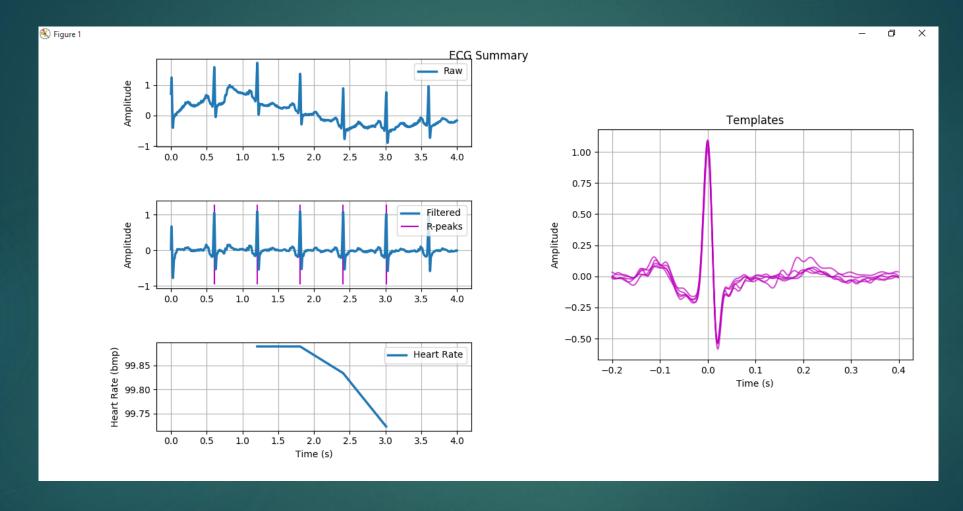
- Wavelet Toolbox of Matlab
- Daubechies (dB5) wavelet considered as mother wavelet
- Scale level used was 7

GRAPHS FOR ECG SAMPLE - MATLAB



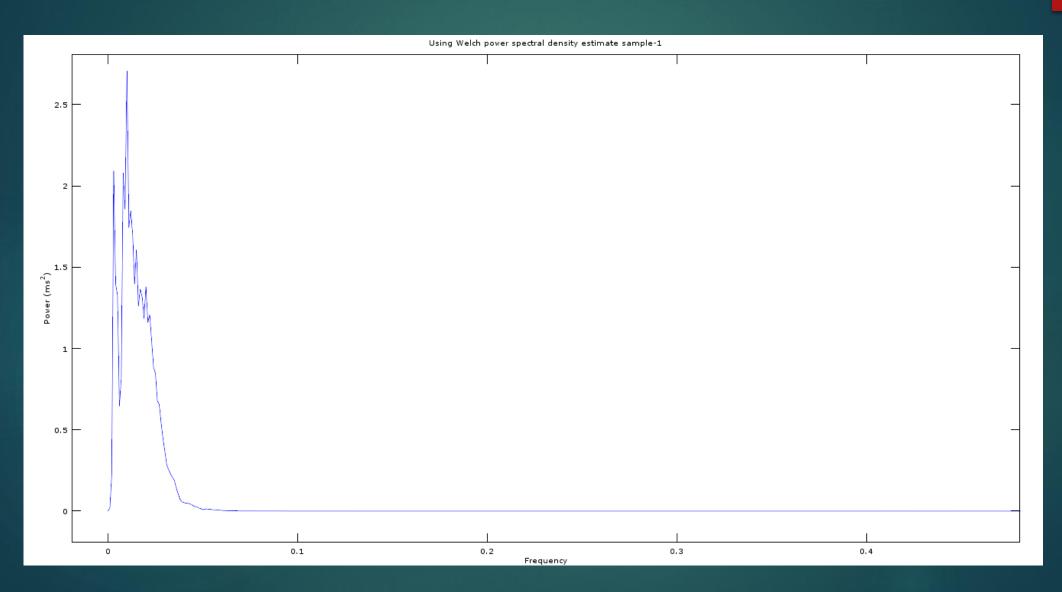
Base line wandering removed using

GRAPHS - PYTHON

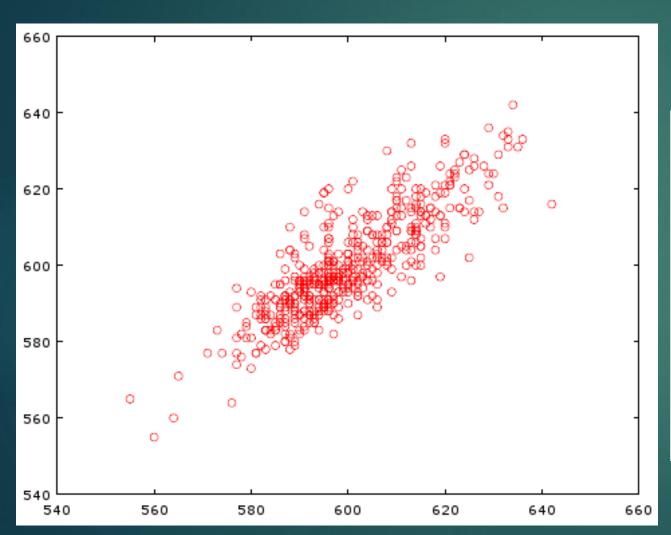


▶ De-trending the signal and RR peak detection was also implemented on Python

PSD OF RR INTERVAL SERIES



NON-LINEAR: POINCARE PLOT



```
%line x = y
for p = 1:size(points)(1)
 d = abs((a*points(i, 1) + b*points(i, 2)) / (sqrt(a*a + b*b)));
 dist = [dist, d];
sd1 = sgrt(var(dist));
%line x = -v
for p = 1:size(points)(1)
 d = abs((a*points(i, 1) + b*points(i, 2)) / (sqrt(a*a + b*b)));
 dist = [dist, d];
sd2 = sgrt(var(dist));
```

NON LINEAR: APPROX & SAMPLE ENTROPY

$$u_j = (RR_j, RR_{j+1}, \dots, RR_{j+m-1}), \quad j = 1, 2, \dots N - m + 1$$

$$d(u_j, u_k) = \max\{|RR_{j+n} - RR_{k+n}| | n = 0, ..., m-1\}$$

$$C_j^m(r) = \frac{\text{nbr of } \{u_k \mid d(u_j, u_k) \le r\}}{N - m + 1} \quad \forall k.$$

$$\Phi^{m}(r) = \frac{1}{N-m+1} \sum_{j=1}^{N-m+1} \ln C_{j}^{m}(r).$$

$$\Phi^{m}(r) = \frac{1}{N-m+1} \sum_{i=1}^{N-m+1} \ln C_{j}^{m}(r). \qquad \text{ApEn}(m,r,N) = \Phi^{m}(r) - \Phi^{m+1}(r).$$

FEATURES EXTRACTED

- ▶ Time Domain
 - mean_rr, STD_rr, mean_hr, STD_hr, RMS_rr, rr_50, p_rr_50
- Frequency Domain
 - pk_freq, abs_pow, rel_pow, norm_pow, LF_pow/HF_pow
- Non-Linear
 - ▶ Poincare plot's SD, ApEn, SamEn

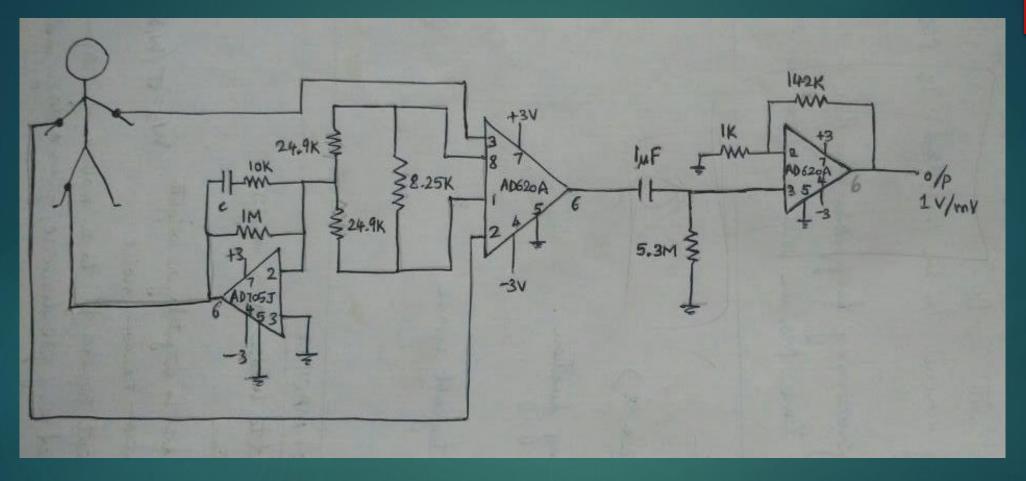
FEATURES WHICH CAN BE EXTRACTED

- Based on need as per classifier performance, following features can be added:
 - ▶ Time Domain
 - rr_hist, baseline_width_rr_hist
 - ▶ Frequency Domain
 - Sample Entropy different 'r', 'm'
 - Non-linear
 - ▶ DFA (Detrended Fluctuation Analysis), RPA (Recurrence Plot Analysis)

HARDWARE/CIRCUIT

- Studied various circuit designs available to acquire ECG Signals
- Met senior who had designed the circuit for his device
- Simulated circuits designed using sample base designs provided in AD620 Data-sheet, as well as circuits used by senior.
- Made modifications to circuit design as per requirements and issues faced.

ECG CIRCUIT FROM AD620 DATASHEET



- Simulated on MultiSim. The leg circuit to provide virtual ground did not work as expected.
- Erroneous outputs resulted in abandoning the circuit for other options.

MODIFIED CIRCUIT

- ► The circuit designed by senior was interfaced with a bluetooth module.
 We will not be using bluetooth.
- ▶ It also contained an integrator circuit in the second stage. We did not understand the use of such a part of the circuit, and resulted in erroneous output.
- Certain values of components (Resistors and Capacitors) were changed in order to obtain the necessary gain required.

OVERALL IDEA OF CIRCUIT

Virtual ground:

- A. To provide a reference with respect to which the voltage at the fingertips can be measured.
- B. The virtual ground will be provided to the thumb, so that the device can be hand held.

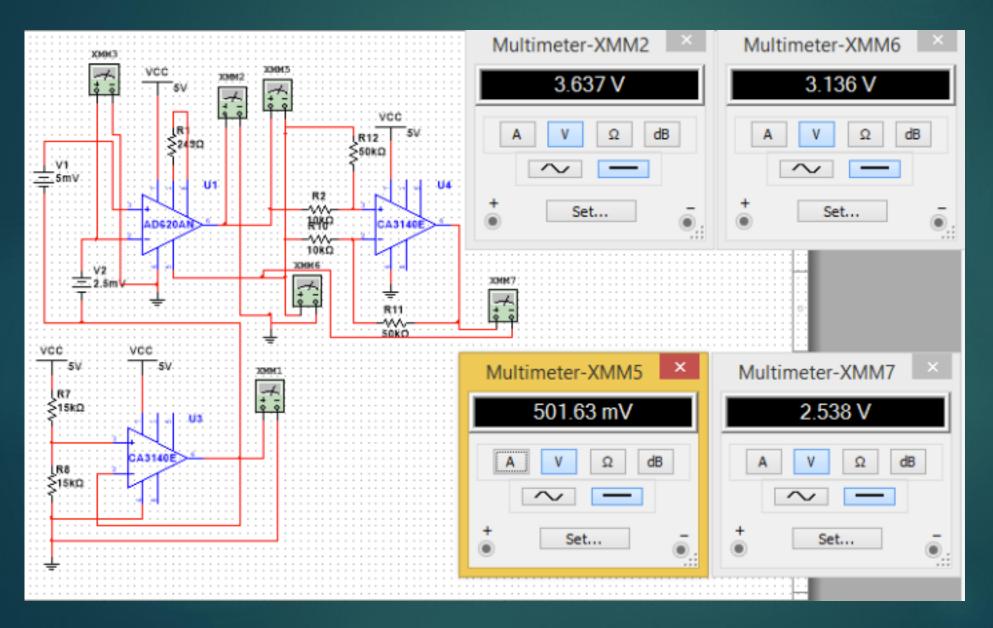
Instrumentation amplifier:

- A. Used to measure the differential voltage between the two fingertips on both hands with respect to the virtual ground (thumb).
- B. This stage provides most of the amplification.

Regular amp:

A. To provide secondary amplification after the instrumentation amplifier, i.e., to spread out the gains.

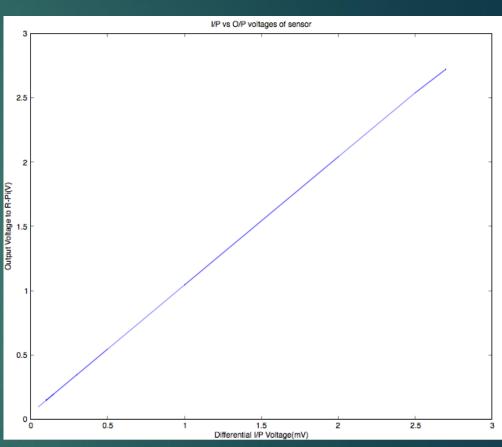
MODIFIED CIRCUIT



- ▶ R_G=249Ohm
- \blacktriangleright G₁=200
- V_{offset1}=3.167mV
- V_{offset2}=45.8mV
- \blacktriangleright G₂=5

CIRCUIT DESIGN FOR R-PI COMPATIBILITY

- Max Differential I/P voltage=2.7mV
- ▶ Leads to saturated output of 2.78V
- ► Max I/P to each electrode=10.2mV
- R-Pi does not have analog I/Ps
- External ADC required (MPC3008)
- ▶ 10 bit ADC[0-1023]
- ▶ R-Pi can take I/P from 0-3.3V
- ▶ Resolution of R-Pi=3.22mV
- ▶ If we increase supply voltage from 5V, we can increase range of I/P



CLASSIFIER

- ► Found ELM documentation by developer.
- Currently understanding ELM in order to implement it.
- ► Algorithm:

$$\mathbf{\hat{Y}} = \mathbf{W}_2 \sigma(\mathbf{W}_1 x)$$

W1 is the matrix of input-to-hidden-layer weights, σ is some activation function

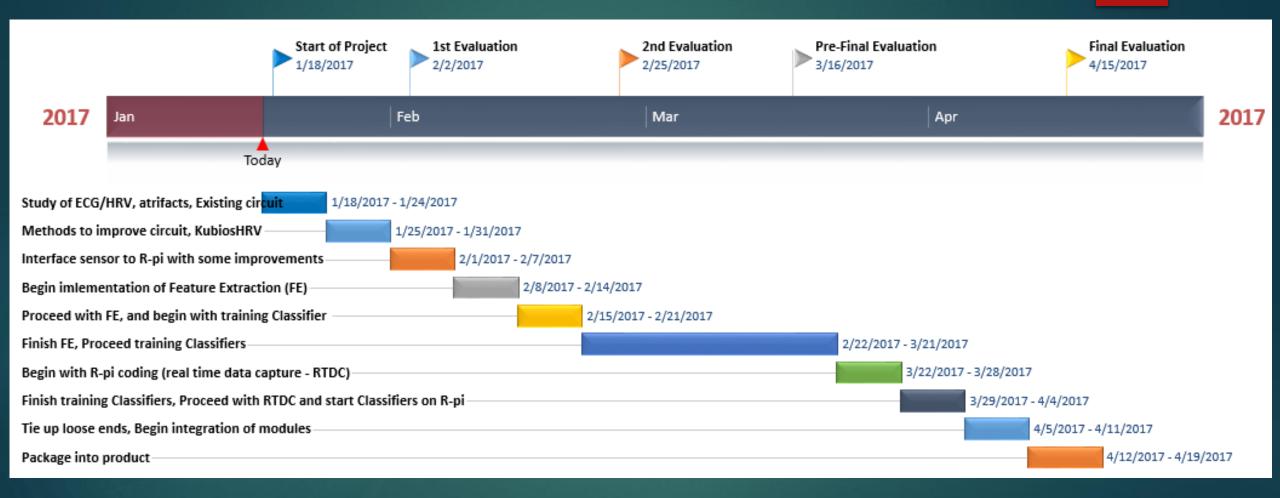
W2 is the matrix of hidden-to-output-layer weights

- 1. Fill W1 with Gaussian random noise;
- 2. Estimate W2 by least-squares fit to a matrix of response variables Y, computed using the pseudoinverse, given a design matrix X: $\mathbf{W}_2 = \sigma(\mathbf{W}_1\mathbf{X})^+\mathbf{Y}$
- Need to explore SVM
- Additional classifers to explore
 - ► RVM
 - parametric and non-parametric models, System Identification

WORK DONE

- RAKSHITH
 - ▶ Time domain feature extraction
 - ▶ Non linear feature extraction
- ▶ APOORV
 - ► Raspberry pi setup
 - Frequency domain feature extraction
- AKARSH
 - ▶ Circuit design/simulation
 - ▶ Introduction to ELM classifier

TIMELINE



On schedule as per expected timeline

TARGETS FOR THE NEXT REVIEW

RAKSHITH

- Consolidate Features to CSV file
- Explore SVM as a classifier
- Construct and test circuit on breadboard

APOORV

- ▶ Port all MATLAB code to R-PI to remove toolbox dependency
- Construct and test circuit on breadboard

AKARSH

- ▶ Train ELM classifier for consolidated features file
- Construct and test circuit on breadboard