

**Preparation of Papers in a Two-Column Format for the 2018 18th
International Conference on Control, Automation and Systems (ICCAS 2018)**

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Abstract: It is recommended that your abstract contain 150-200 words.

Keywords: Selected keywords relevant to the subject.

1. INTRODUCTION

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[illegible][illegible]

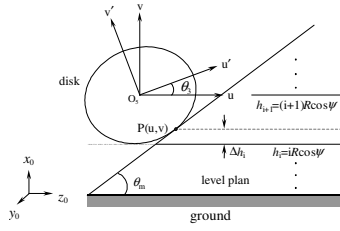


Fig. 1 The caption should be placed after the figure.

4.2 Equations

Equation numbers should be Arabic numerals enclosed in parentheses on the right-hand margin. They should be cited in the text as, for example, Eq. (1), or Eqs. (1) ~ (3). Equations start from the left on the column. Punctuate equations with commas or periods when they are part of a sentence. For example,

$$\dot{x} = Ax + bu, \quad (1)$$

$$y = Cx + Du. \quad (2)$$

4.3 References

References should appear in a separate bibliography at the end of the paper, with items referred to by numerals in square brackets [1, 4-5]. Times New Roman 10pt is used for references.

5. PAGE NUMBERS

Do not put a page number in the manuscript PDF.

REFERENCES

- [1] H. S. Lee, Y. H. Oh, and J. B. Song, "Torque sensor based robot arm control using disturbance observer," *Proc. of the International Conference on Control, Automation and Systems*, pp. 1697-1700, 2010.
- [2] R. C. Baker and B. Charlie, "Nonlinear unstable systems," *International Journal of Control, Automation, and Systems*, Vol. 23, No. 4, pp. 123-145, 1989.
- [3] M. Young, *The Technical Writer's Handbook*, Mill Valley, Seoul, 1989.