

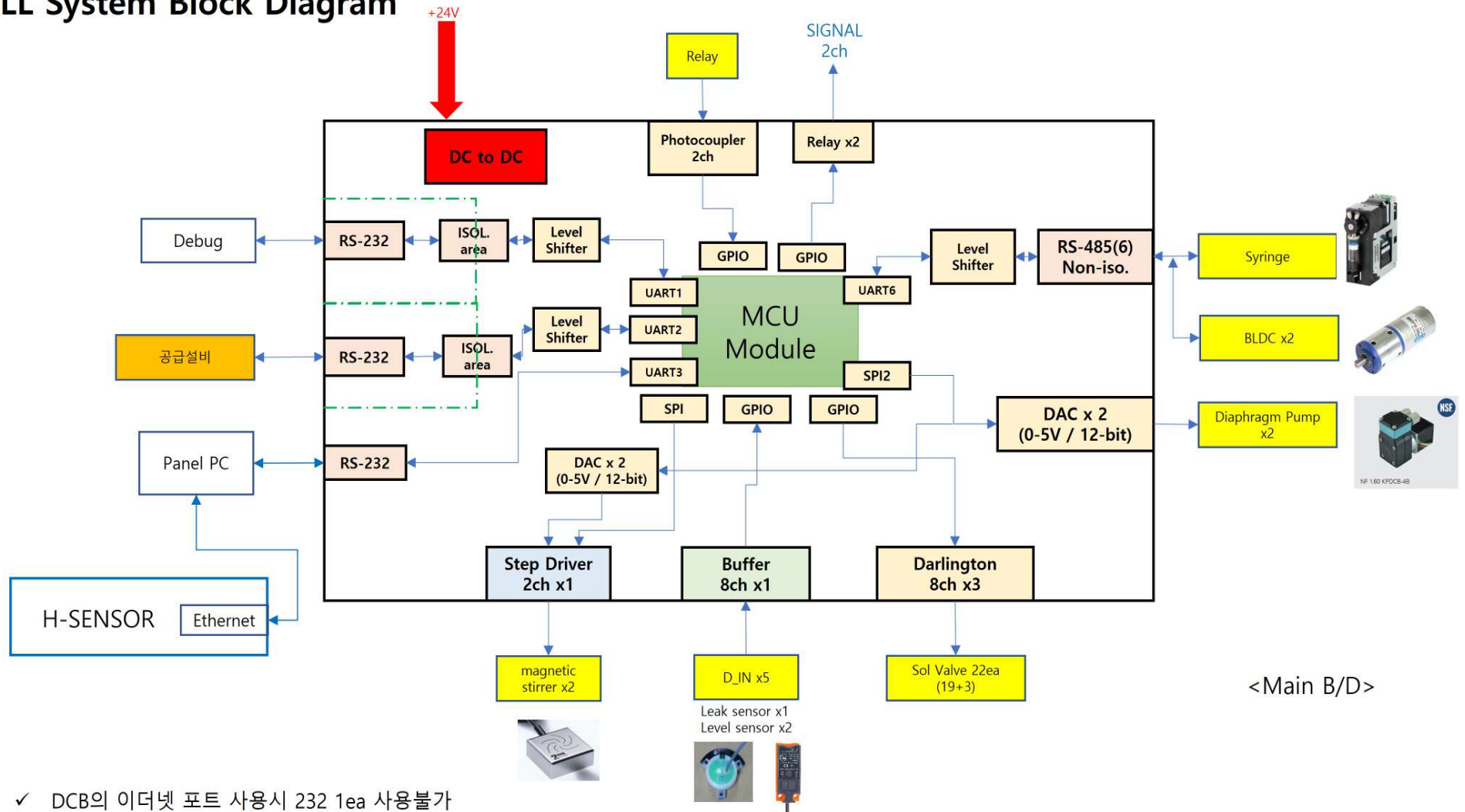
L-L MAIN BOARD

Version 0.1

Revision History

REVISION	DESCRIPTION
Main_V0.1_20230831A	new design

LL System Block Diagram

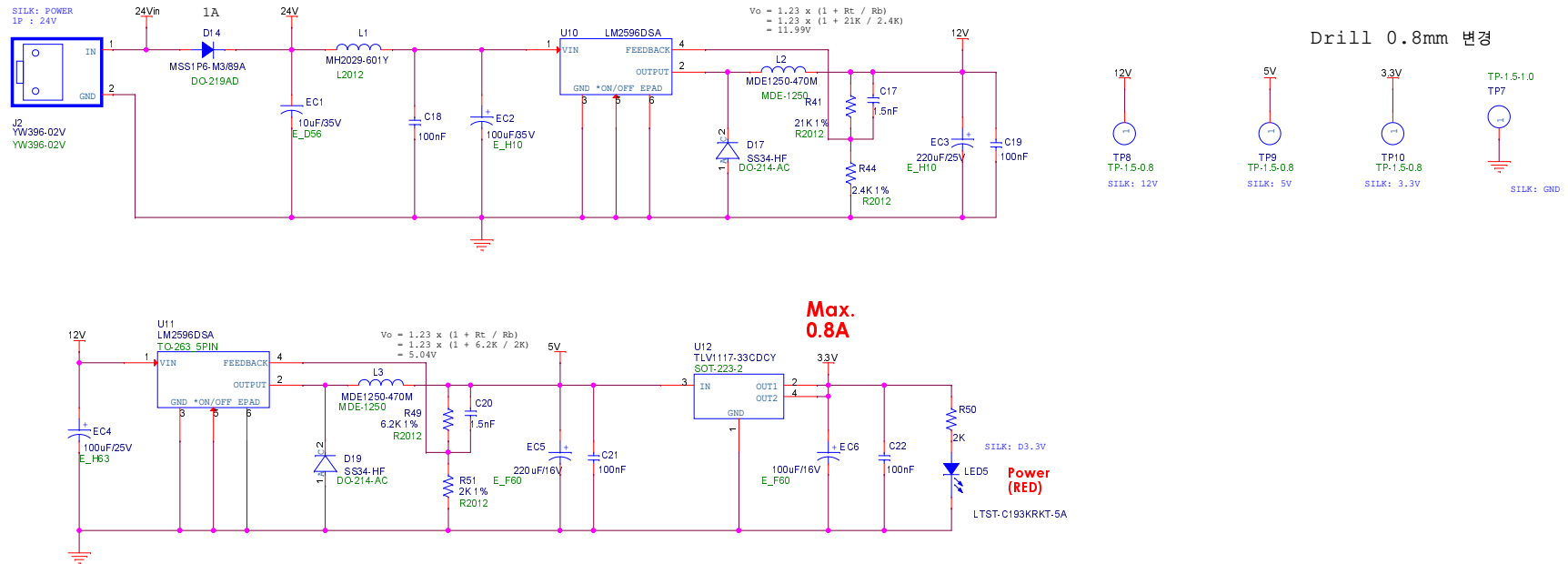


<Main B/D>

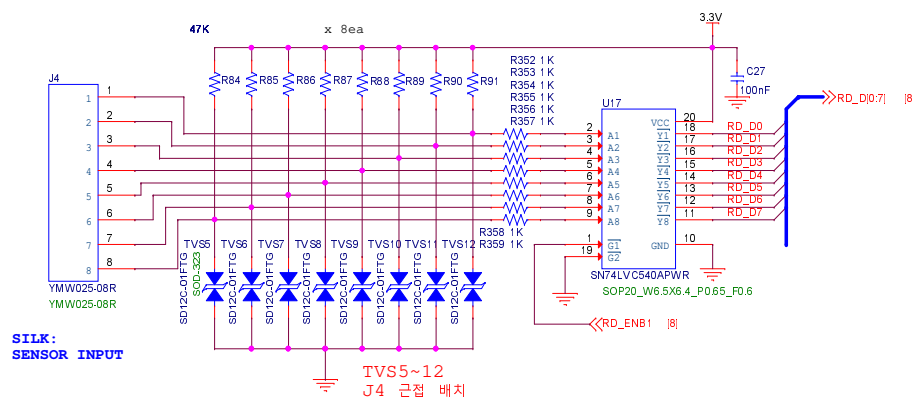
✓ DCB의 이더넷 포트 사용시 232 1ea 사용불가

File			
L-L Main Board			
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POWER SUPPLY

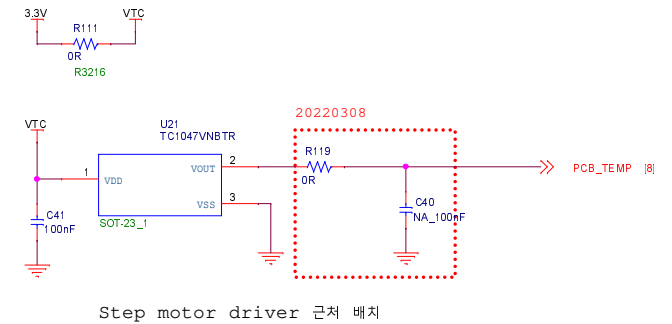


SENSOR INPUT



PCB TEMP.

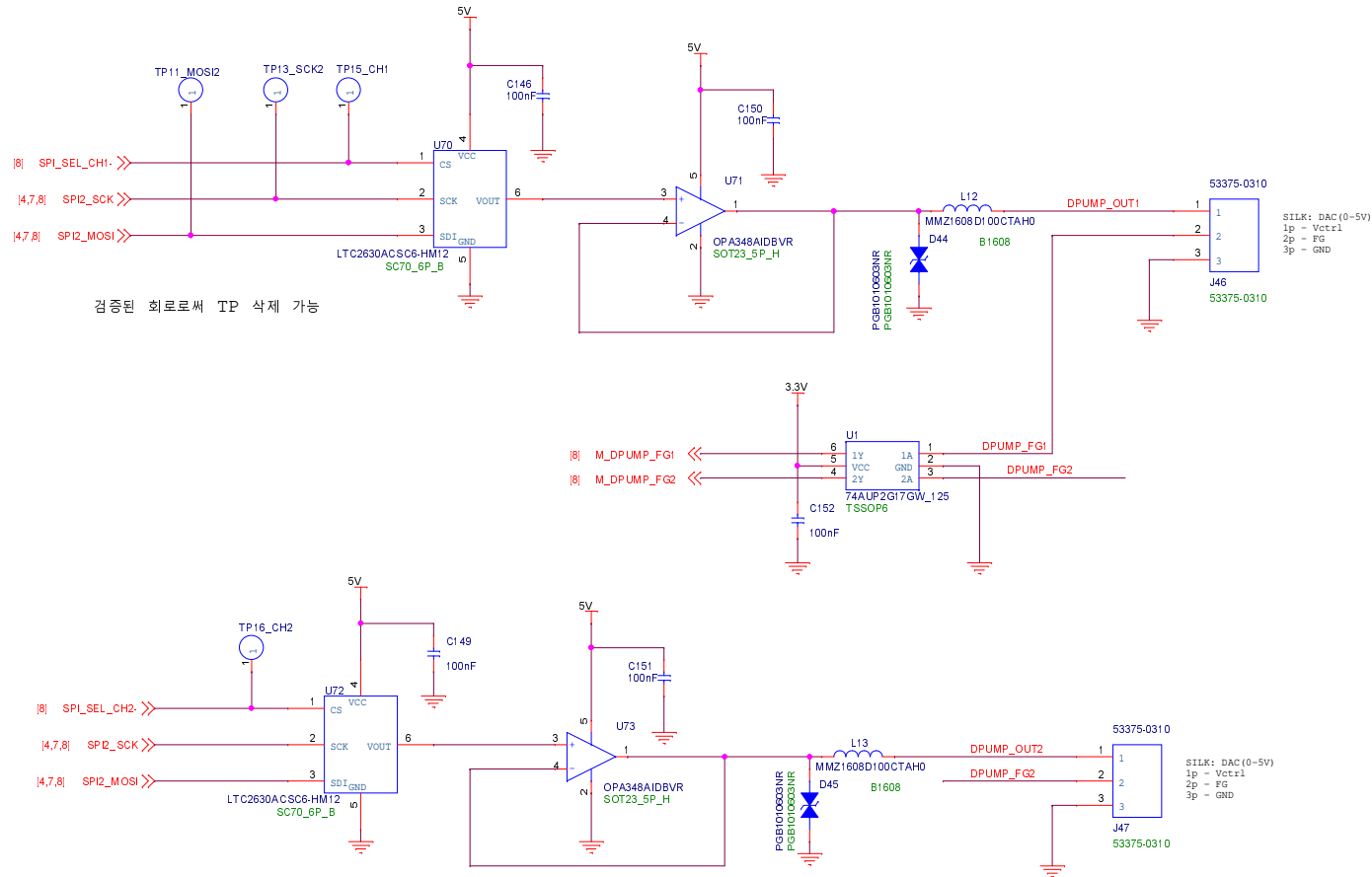
J7 근처 배치 및 U21.3번핀 R117 GND 근처배치



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DAC out (Diaphragm Pump)

0~5V Output ch #1~ #2



ELECTRIC SPECIFICATIONS

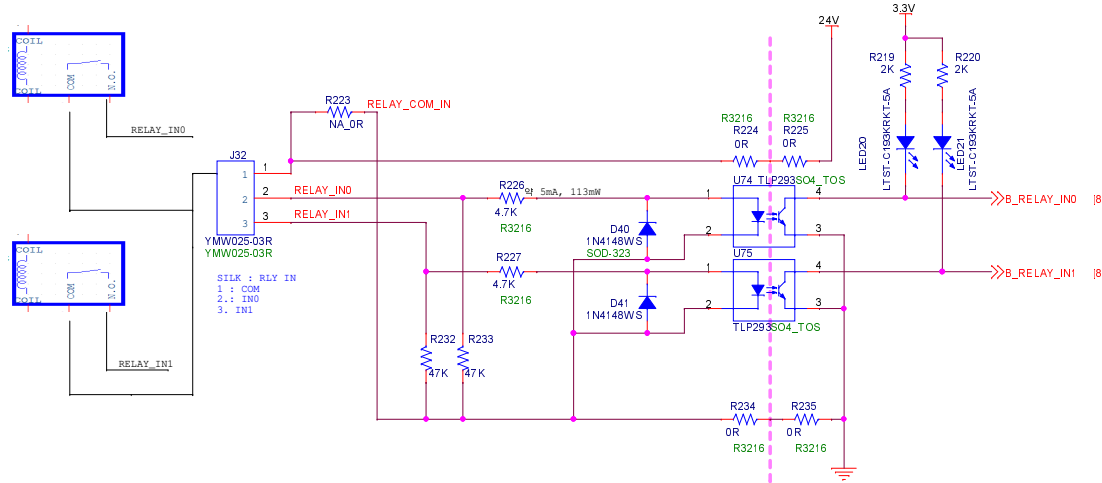
Wires	AWG 24
Wires assignment	red = +VS black = - VS/GND white = Vctrl-input green = FG-output
Input signal	0-5 V



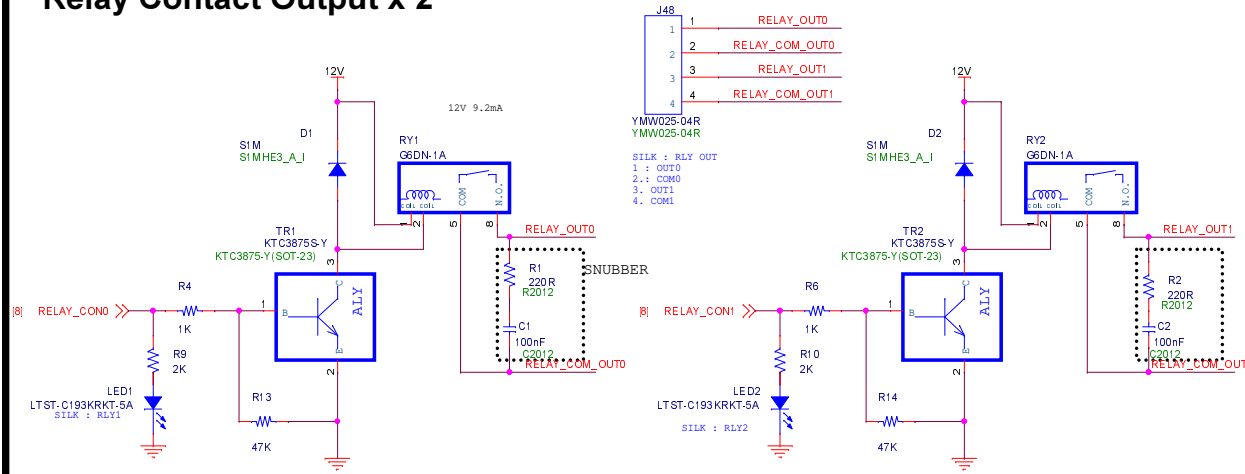
R, L, C, LED 사이즈 미표기 --> 1608 (Metric)

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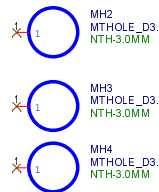
Relay Contact Input x 2



Relay Contact Output x 2



Dia : 3.5mm , Drill : 3.5mm
KEEP OUT Area : 8mm

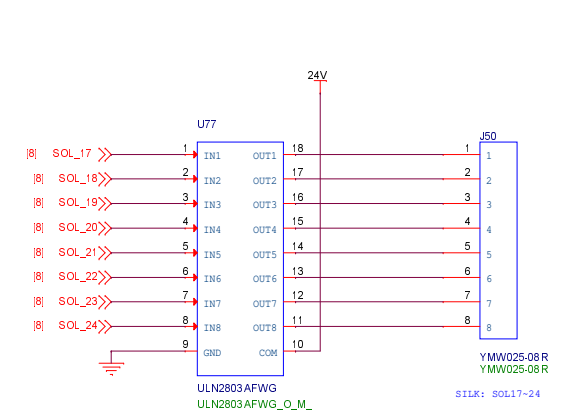
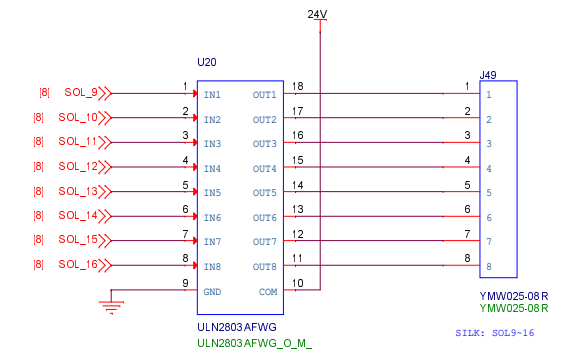
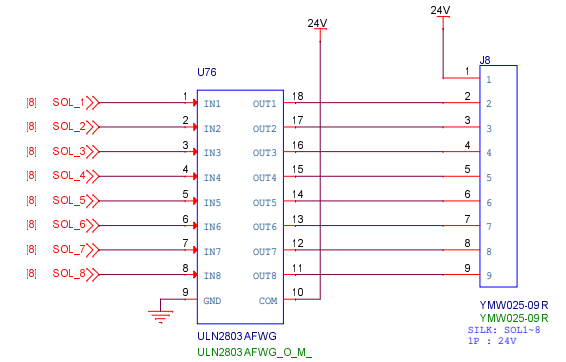


MCU module 연결
Dia : 3.5mm , Drill : 3.5mm
KEEP OUT Area : 8mm

주후 사이즈에 따라 추가/삭제 필요

24V out 8ch x3

전장부에서 분기

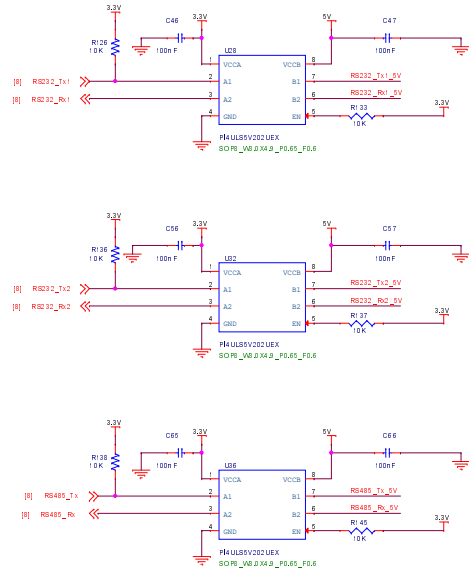


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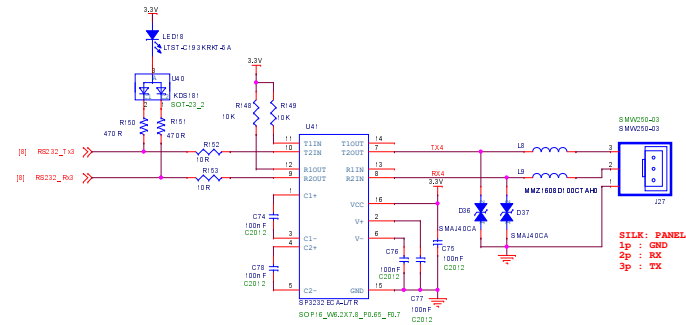
R, L, C 사이즈 미표기 --> 1608 (Metric)

RS-232/RS-485

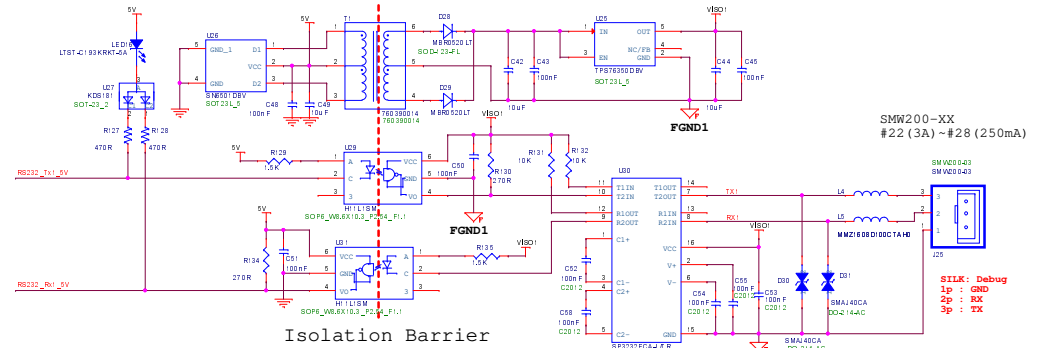
LEVEL SHIFTER (3.3V <=> 5V)



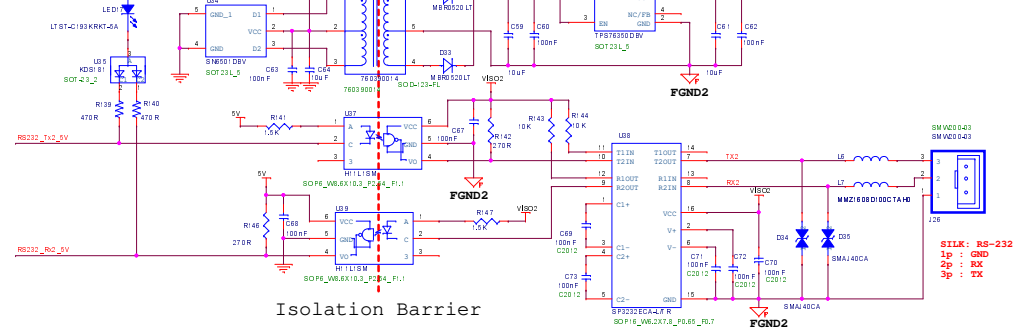
UART #3 RS232 -> panel PC 연결



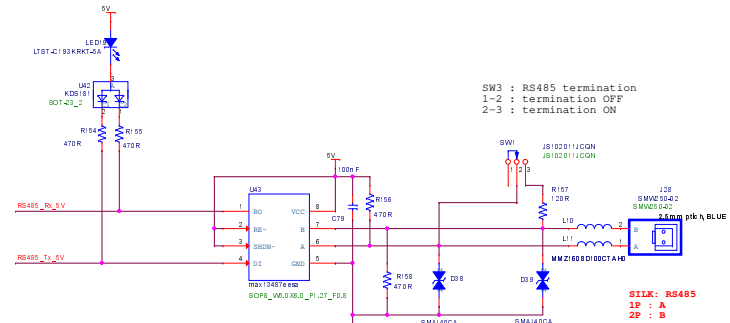
UART #1



UART #2

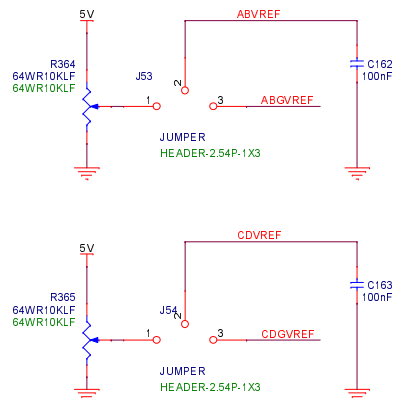
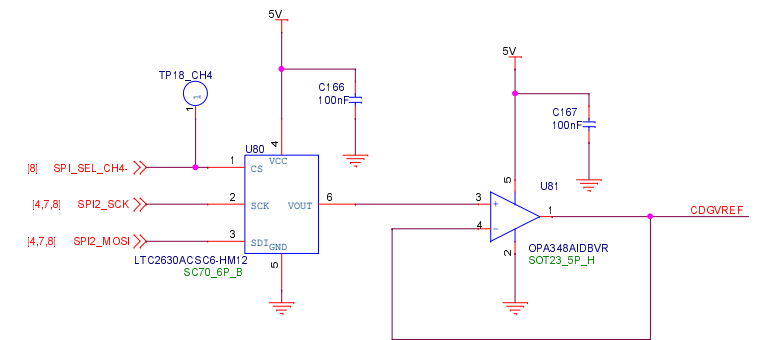
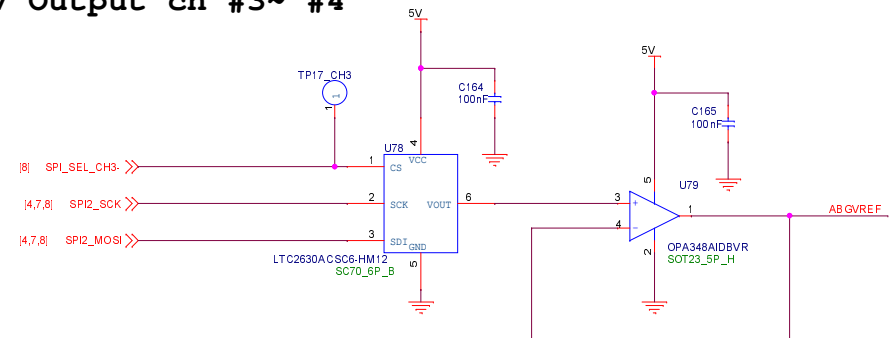
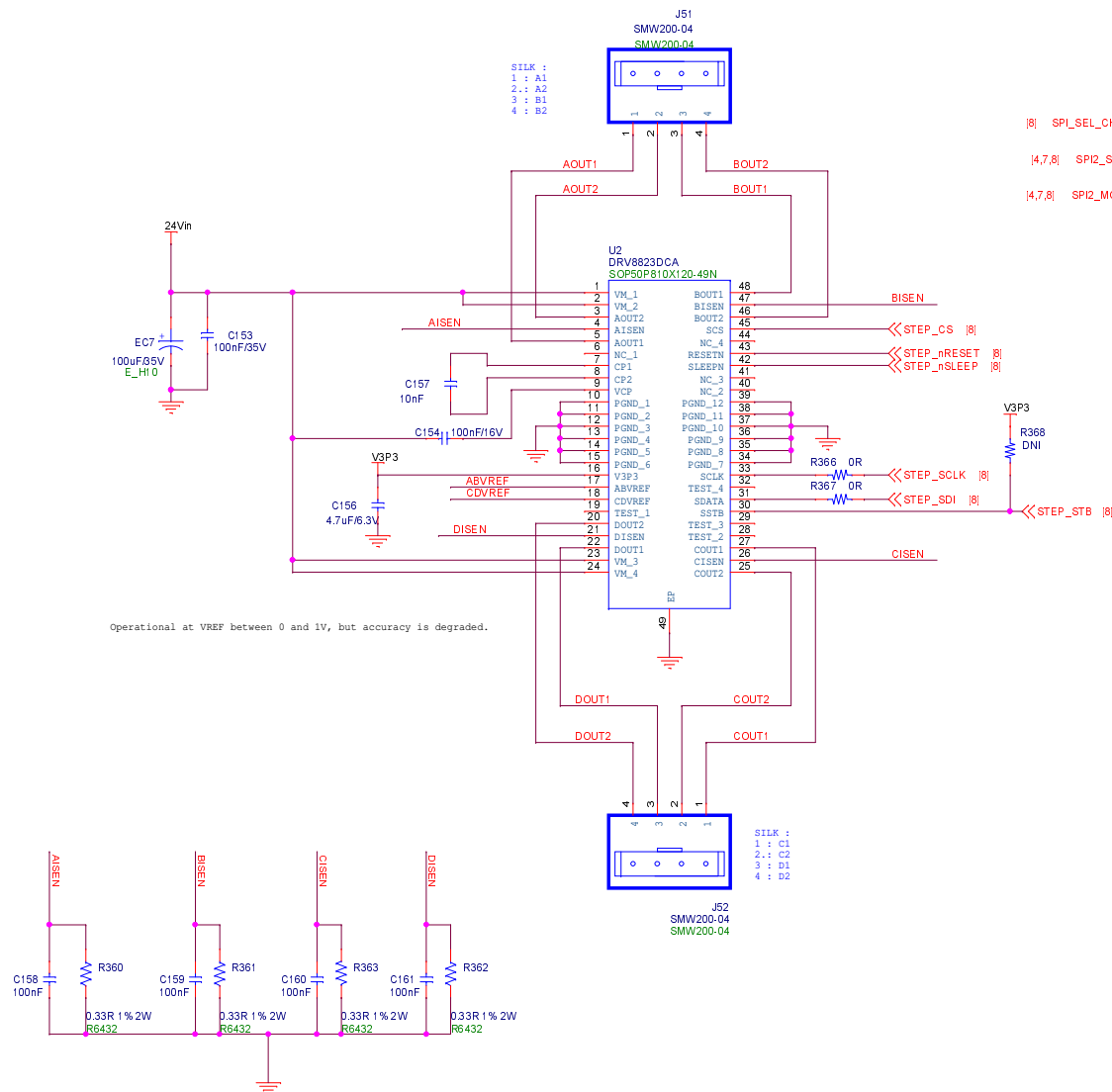


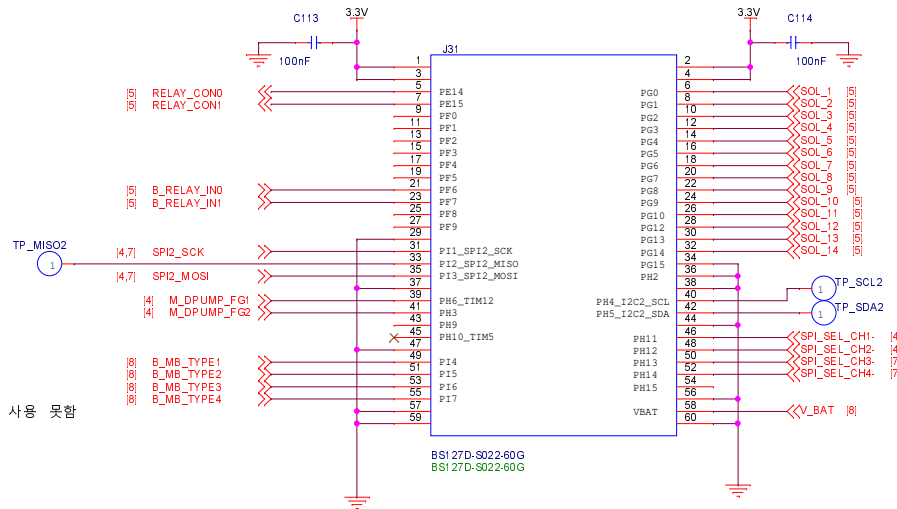
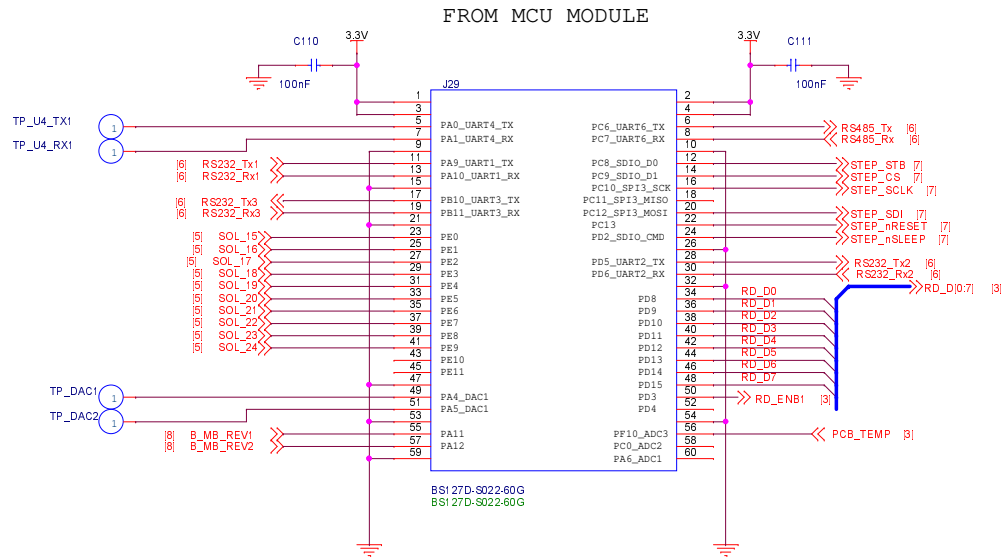
UART #6 RS485 -> 해밀턴 실린지 펌프 사용 (iso1 X)



DUAL STEP MOTOR DRIVER

0~5V Output ch #3~ #4





PH2,10
PI2,10
EXT. INT. 사용 못함

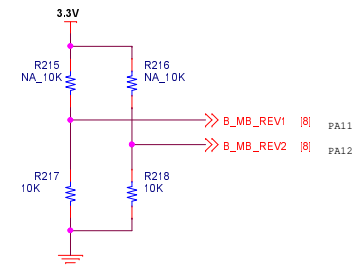
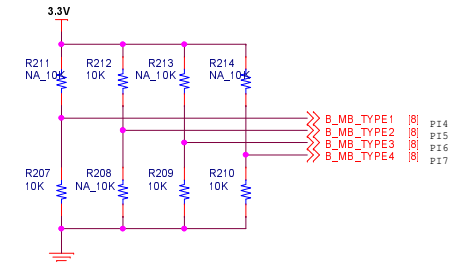
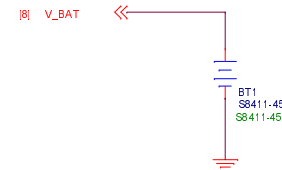
TYPE1~4 (0001~1111)
MAIN TYPE 15종류 지정

SILK: M/B TYPE

PI7	PI6	PI5	PI4	Type
0	0	0	1	L-T
0	0	1	0	L-L
1	1	1	1	ATIK_JIG

PA12	PA11	PCB Issue
0	0	Rev 0.1
0	1	Rev 0.2
1	0	Rev 1.0
1	1	Rev 1.1

SILK: M/B Rev.



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