

Method of Maximum Likelihood

15.11. Method of Maximum Likelihood Estimation. From theoretical point of view, the most general method of estimation known is the method of *Maximum Likelihood Estimators* (M.L.E.) which was initially formulated by C.F. Gauss but as a general method of estimation was first introduced by Prof. R.A. Fisher and later on developed by him in a series of papers. Before introducing the method we will first define *Likelihood Function*.

Likelihood Function. *Definition.* Let x_1, x_2, \dots, x_n be a random sample of size n from a population with density function $f(x, \theta)$. Then the likelihood function of the sample values x_1, x_2, \dots, x_n , usually denoted by $L = L(\theta)$ is their joint density function, given by

$$L = f(x_1, \theta) f(x_2, \theta) \dots f(x_n, \theta) = \prod_{i=1}^n f(x_i, \theta). \quad \dots(15.53)$$

L gives the relative likelihood that the random variables assume a particular set of values x_1, x_2, \dots, x_n . For a given sample x_1, x_2, \dots, x_n , L becomes a function of the variable θ , the parameter.

The principle of maximum likelihood consists in finding an estimator for the unknown parameter $\theta = (\theta_1, \theta_2, \dots, \theta_k)$, say, which maximises the likelihood function $L(\theta)$ for variations in parameter i.e., we wish to find $\hat{\theta} = (\hat{\theta}_1, \hat{\theta}_2, \dots, \hat{\theta}_k)$ so that

$$L(\hat{\theta}) > L(\theta) \quad \forall \theta \in \Theta$$

$$\text{i.e.,} \quad L(\hat{\theta}) = \text{Sup } L(\theta) \quad \forall \theta \in \Theta.$$

Thus if there exists a function $\hat{\theta} = \hat{\theta}(x_1, x_2, \dots, x_n)$ of the sample values which maximises L for variations in θ , then $\hat{\theta}$ is to be taken as an estimator of θ . $\hat{\theta}$ is usually called *Maximum Likelihood Estimator (M.L.E.)*. Thus $\hat{\theta}$ is the solution, if any, of

$$\frac{\partial L}{\partial \theta} = 0 \quad \text{and} \quad \frac{\partial^2 L}{\partial \theta^2} < 0 \quad \dots(15.54)$$

Since $L > 0$, and $\log L$ is a non-decreasing function of L ; L and $\log L$ attain their extreme values (maxima or minima) at the same value of $\hat{\theta}$. The first of the two equations in (15.54) can be rewritten as

$$\frac{1}{L} \cdot \frac{\partial L}{\partial \theta} = 0 \quad \Rightarrow \quad \frac{\partial \log L}{\partial \theta} = 0, \quad \dots(15.54a)$$

a form which is much more convenient from practical point of view.

If θ is vector valued parameter, then $\hat{\theta} = (\hat{\theta}_1, \hat{\theta}_2, \dots, \hat{\theta}_k)$, is given by the solution of simultaneous equations :

$$\frac{\partial}{\partial \theta_i} \log L = \frac{\partial}{\partial \theta_i} \log L (\theta_1, \theta_2, \dots, \theta_k) = 0 ; i = 1, 2, \dots, k$$

...(15.54b)

Equations (15.54a) and (15.54b) are usually referred to as the *Likelihood Equations* for estimating the parameters.

Remark. For the solution $\hat{\theta}$ of the likelihood equations, we have to see that the second derivative of L w.r. to θ is negative. If θ is vector valued, then for L to be maximum, the matrix of derivatives

$$\left(\frac{\partial^2 \log L}{\partial \theta_i \partial \theta_j} \right)_{\theta = \hat{\theta}} \text{ should be negative definite.}$$

15.11.1. Properties of Maximum Likelihood Estimators.

We make the following assumptions, known as the *Regularity Conditions* :

(i) The first and second order derivatives, viz., $\frac{\partial \log L}{\partial \theta}$ and $\frac{\partial^2 \log L}{\partial \theta^2}$ exist and are continuous functions of θ in a range R (including the true value θ_0 of the parameter) for almost all x . For every θ in R

$$\left| \frac{\partial}{\partial \theta} \log L \right| < F_1(x) \text{ and } \left| \frac{\partial^2}{\partial \theta^2} \log L \right| < F_2(x)$$

where $F_1(x)$ and $F_2(x)$ are integrable functions over $(-\infty, \infty)$.

(ii) The third order derivative $\frac{\partial^3}{\partial \theta^3} \log L$ exists such that

$$\left| \frac{\partial^3}{\partial \theta^3} \log L \right| < M(x)$$

where $E[M(x)] < K$, a positive quantity.

(iii) For every θ in R ,

$$\begin{aligned} E \left(- \frac{\partial^2}{\partial \theta^2} \log L \right) &= \int_{-\infty}^{\infty} \left(- \frac{\partial^2}{\partial \theta^2} \log L \right) L dx \\ &= I(\theta), \end{aligned}$$

is finite and non-zero.

(iv) The range of integration is independent of θ . But if the range of integration depends on θ , then $f(x, \theta)$ vanishes at the extremes depending on θ .

This assumption is to make the differentiation under the integral sign valid.

Under the above assumptions M.L.E. possesses a number of important properties, which will be stated in the form of theorems.

Theorem 15.11. (Cramer-Rao Theorem). *"With probability approaching unity as $n \rightarrow \infty$, the likelihood equation $\frac{\partial}{\partial \theta} \log L = 0$, has a solution which converges in probability to the true value θ_0 ". In other words M.L.E.'s are consistent.*

Remark. *M.L.E.'s are always consistent estimators but need not be unbiased. For example in sampling from $N(\mu, \sigma^2)$ population, [c.f. Example 15.31],*

$\text{MLE}(\mu) = \bar{x}$ (sample mean), which is both unbiased and consistent estimator of μ .

$\text{MLE}(\sigma^2) = s^2$ (sample variance), which is consistent but not unbiased estimator of σ^2 .

Theorem 15.12. (Hazoor Bazar's Theorem). Any consistent solution of the likelihood equation provides a maximum of the likelihood with probability tending to unity as the sample size (n) tends to infinity.

Theorem 15.13. (Asymptotic Normality of MLE's). A consistent solution of the likelihood equation is asymptotically normally distributed about the true value θ_0 . Thus, $\hat{\theta}$ is asymptotically $N\left(\theta_0, \frac{I}{I(\theta_0)}\right)$ as $n \rightarrow \infty$.

Remark. Variance of M.L.E. is given by

$$V(\hat{\theta}) = \frac{1}{I(\theta)} = \frac{1}{\left[E \left(- \frac{\partial^2}{\partial \theta^2} \log L \right) \right]} \quad \dots(15.55)$$

Theorem 15.14. *If M.L.E. exists, it is the most efficient in the class of such estimators.*

Theorem 15.15. *If a sufficient estimator exists, it is a function of the Maximum Likelihood Estimator.*

Proof. If $t = t(x_1, x_2, \dots, x_n)$ is a sufficient estimator of θ , then Likelihood Function can be written as (c.f. Theorem 15.7)

$$L = g(t, \theta) h(x_1, x_2, x_3, \dots, x_n | t)$$

where $g(t, \theta)$ is the density function of t and $h(x_1, x_2, \dots, x_n | t)$ is the density function of the sample, given t , and is independent of θ .

$$\therefore \log L = \log g(t, \theta) + \log h(x_1, x_2, \dots, x_n | t)$$

Differentiating w.r.t. θ , we get

$$\frac{\partial \log L}{\partial \theta} = \frac{\partial}{\partial \theta} \log g(t, \theta) = \psi(t, \theta), \text{ (say),} \quad \dots(15.56)$$

which is a function of t and θ only.

M.L.E. is given by

$$\frac{\partial \log L}{\partial \theta} = 0 \Rightarrow \psi(t, \theta) = 0$$

$$\therefore \hat{\theta} = \eta(t) = \text{Some function of sufficient statistic.}$$

$$\Rightarrow \hat{t} = \psi(\theta) = \text{Some function of M.L.E.}$$

Hence the theorem.

Theorem 15.17. (Invariance Property of MLE). *If T is the MLE of θ and $\psi(\theta)$ is one to one function of θ , then $\psi(T)$ is the MLE of $\psi(\theta)$.*

Example 15.31. *In random sampling from normal population $N(\mu; \sigma^2)$, find the maximum likelihood estimators for*

- (i) μ when σ^2 is known,*
- (ii) σ^2 when μ is known, and*
- (iii) the simultaneous estimation of μ and σ^2 .*

Solution. $X \sim N(\mu, \sigma^2)$ then

$$\begin{aligned} L &= \prod_{i=1}^n \left[\frac{1}{\sigma\sqrt{2\pi}} \exp \left\{ -\frac{1}{2\sigma^2} (x_i - \mu)^2 \right\} \right] \\ &= \left(\frac{1}{\sigma\sqrt{2\pi}} \right)^n \exp \left\{ -\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 \right\} \end{aligned}$$

$$\log L = -\frac{n}{2} \log(2\pi) - \frac{n}{2} \log \sigma^2 - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2$$

Case (i). When σ^2 is known, the likelihood equation for estimating μ is

$$\frac{\partial}{\partial \mu} \log L = 0 \Rightarrow -\frac{1}{2\sigma^2} \sum_{i=1}^n 2(x_i - \mu)(-1) = 0$$

or
$$\sum_{i=1}^n (x_i - \mu) = 0 \Rightarrow \sum_{i=1}^n x_i - n\mu = 0$$

$$\Rightarrow \hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i = \bar{x} \quad \dots (*)$$

Hence M.L.E. for μ is the sample mean \bar{x} .

Case (ii). When μ is known, the likelihood equation for estimating σ^2 is

$$\frac{\partial}{\partial \sigma^2} \log L = 0 \Rightarrow -\frac{n}{2} \times \frac{1}{\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^n (x_i - \mu)^2 = 0$$

$$\Rightarrow n - \frac{1}{\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 = 0, \quad i.e., \quad \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2 \quad \dots(**)$$

Case (iii). The likelihood equations for simultaneous estimation of μ and σ^2 are

$$\frac{\partial}{\partial \mu} \log L = 0 \quad \text{and} \quad \frac{\partial}{\partial \sigma^2} \log L = 0, \text{ thus giving}$$

$$\hat{\mu} = \bar{x} \quad \text{[From (*)]}$$

and
$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{\mu})^2 \quad \text{[From (**)]}$$

$$= \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2 = s^2, \text{ the sample variance.}$$

Remark. Since M.L.E. is the most efficient, we conclude that in sampling from a normal population, the sample mean \bar{x} is the most efficient estimator of the population mean μ .

Example 15.32. Prove that the maximum likelihood estimate of the parameter α of a population having density function :

$$\frac{2}{\alpha^2} (\alpha - x), 0 < x < \alpha$$

for a sample of unit size is $2x$, x being the sample value. Show also that the estimate is biased.

Solution. For a random sample of unit size ($n = 1$), the likelihood function is :

$$L(\alpha) = f(x, \alpha) = \frac{2}{\alpha^2} (\alpha - x) ; 0 < x < \alpha$$

Likelihood equation gives :

$$\frac{d}{d\alpha} \log L = \frac{d}{d\alpha} [\log 2 - 2 \log \alpha + \log (\alpha - x)] = 0$$

$$\Rightarrow -\frac{2}{\alpha} + \frac{1}{\alpha - x} = 0 \Rightarrow 2(\alpha - x) - \alpha = 0 \Rightarrow \alpha = 2x$$

Hence MLE of α is given by $\hat{\alpha} = 2x$.

$$\begin{aligned} E(\hat{\alpha}) &= E(2X) = 2 \int_0^{\alpha} x \cdot f(x, \alpha) dx \\ &= \frac{4}{\alpha^2} \int_0^{\alpha} x(\alpha - x) dx = \frac{4}{\alpha^2} \left[\frac{\alpha x^2}{2} - \frac{x^3}{3} \right]_0^{\alpha} = \frac{2}{3} \alpha \end{aligned}$$

Since $E(\hat{\alpha}) \neq \alpha$, $\hat{\alpha} = 2x$ is not an unbiased estimate of α .

Example 15.33. (a) Find the maximum likelihood estimate for the parameter λ of a Poisson distribution on the basis of a sample of size n . Also find its variance.

Solution. The probability function of the Poisson distribution with parameter λ is given by

$$P(X = x) = f(x, \lambda) = \frac{e^{-\lambda} \lambda^x}{x!}; x = 0, 1, 2, \dots$$

Likelihood function of random sample x_1, x_2, \dots, x_n of n observations from this population is

$$L = \prod_{i=1}^n f(x_i, \lambda) = \frac{e^{-n\lambda} \lambda^{\sum_{i=1}^n x_i}}{x_1! x_2! \dots x_n!}$$

$$\therefore \log L = -n\lambda + \left(\sum_{i=1}^n x_i \right) \log \lambda - \sum_{i=1}^n \log (x_i!)$$

$$= -n\lambda + n\bar{x} \log \lambda - \sum_{i=1}^n \log (x_i!)$$

The likelihood equation for estimating λ is

$$\frac{\partial}{\partial \lambda} \log L = 0 \quad \Rightarrow \quad -n + \frac{n\bar{x}}{\lambda} = 0 \quad \Rightarrow \quad \lambda = \bar{x}$$

Thus the M.L.E. for λ is the sample mean \bar{x} .

