

Data Structures

Topic: Graphs



By

Ravi Kant Sahu

Asst. Professor,

Lovely Professional University, Punjab



Contents

- Introduction
- Basic Terminology
- Sequential Representation of Graphs
 - Adjacency Matrix
 - Path Matrix
- Warshall's Algorithm: Shortest Path
- BFS and DFS



Introduction

- A Graph G is a collection of:
 1. A set V of elements called Nodes or Vertices.
 2. A set E of Edges such that each edge e in E is identified with a unique pair $[u, v]$ of nodes in V , denoted by $e = [u, v]$.

$$G = (V, E)$$

- Nodes u and v are called end points of edge e and also known as adjacent nodes or neighbors.



Basic Terminology

- **Degree of a node:** Degree of a node, $\deg(u)$, is the number of edges containing u .
- If $\deg(u) = 0$, then node u is called **Isolated Node**.
- A **Path** P of length n from node u to a node v is defined as a sequence of $n+1$ nodes.

$$P = (v_0, v_1, v_2, \dots, v_n)$$



Path

- **Simple Path:** The path is said to be simple if all the nodes are distinct.
- **Closed Path:** A path is said to be closed if first and last node are same i.e. $v_0 = v_n$.
- **Cycle:** A cycle is a closed simple path with length 3 or more.
- A cycle with length k is called k -cycle.



Graph

- **Connected Graph:** A graph G is connected iff there is a simple path between any two nodes in G .
- **Complete Graph:** A graph G is said to be complete if every node u in G is adjacent to every other node v in G . i.e. each node u is directly connected to all other nodes v in Graph G .
- A complete graph with n nodes will have $n(n-1)/2$ edges.



Labeled Graphs...

- A graph G is said to be labeled if its edges are assigned data.
- **Weighted Graph:** Graph G is said to be weighted if each edge e is assigned a non-negative numerical value $w(e)$ called the weight or length of edge.
- If no other information about weights are given in a graph, then assume the weight $w(e) = 1$ for each edge.



Multi-Graph

- **Multiple Edges:** Distinct edges e and e' are called multiple edges if they connect the same endpoints,

i.e. if $e = [u, v]$ and $e' = [u, v]$.

- **Loops:** An edge e is called a loop if it has identical endpoints ,

i.e. if $e = [u, u]$.

- **Note:** Definition of a graph does not allow any loop or multiple edge in Graph.

- A Graph with loops or multiple edges is called a Multi-graph.



Degree of Graph

- **Outdegree:** Outdegree of a node u in G is the number of edges beginning at u .
- **Indegree:** Indegree of a node u in G is the number of edges ending at u .
- **Source:** A node u is called a source if it has a positive outdegree but zero indegree.
- **Sink:** A node u is called a sink if it has a positive indegree but zero outdegree.



Sequential Representation

- There are two ways of representing a graph in memory:
 - **Sequential Representation**
 - Adjacency Matrix
 - Path Matrix
 - **Linked Representation**



Adjacency Matrix

- Let G is a simple directed graph with m nodes and the nodes of G have been ordered and are called v_1, v_2, \dots, v_m .
- The adjacency matrix $A = a_{ij}$ of graph G is the $m \times m$ matrix defined as below:

$a_{ij} = 1$, if v_i is adjacent to v_j , i.e. if there is an edge (v_i, v_j)

$a_{ij} = 0$, otherwise

- Suppose G is an undirected graph, then the adjacency matrix A of G will be a symmetric matrix i.e. one in which $a_{ij} = a_{ji}$.



Adjacency Matrix

- Let A be the adjacency matrix of a graph G . Then $a_K(i, j)$, the ij entry in the matrix A^K , gives the number of paths of length K from v_i to v_j .



Path Matrix

- Let G is a simple directed graph with m nodes v_1, v_2, \dots, v_m .
- The Path matrix or Reachability matrix $P = p_{ij}$ of graph G is the $m \times m$ matrix defined as below:

$p_{ij} = 1$, if there is a path from v_i to v_j

$p_{ij} = 0$, otherwise



Path Matrix...

- Let A be the adjacency matrix and P be the path matrix of a digraph G . Then $P_{ij} = 1$, iff there is a non-zero number in the ij entry of the matrix

$$B_m = A + A^2 + A^3 + \dots + A^m$$

- Path matrix is obtained by replacing the non-zero entries in B_m by 1.
- Graph G is strongly connected iff path matrix P of G has no zero entries.



Warshall's Algorithm: Path Matrix

- A directed graph G with M nodes is maintained in memory by its adjacency matrix A . This algorithm finds the path matrix P of the graph G .

1. Repeat for $i, j = 1, 2, \dots, M$:
 If $A[i, j] = 0$, then: Set $P[i, j] = 0$.
 Else: Set $P[i, j] = 1$.
2. Repeat Step 3 and 4 for $k = 1, 2, \dots, M$:
3. Repeat Step 4 for $i = 1, 2, \dots, M$:
4. Repeat for $j = 1, 2, \dots, M$:
 Set $P[i, j] = P[i, j] \vee (P[i, k] \wedge P[k, j])$
 [End of Step 4 Loop.]
 [End of Step 3 Loop.]
 [End of Step 2 Loop.]
5. Exit.



Work Space

Ravi Kant Sahu, Asst. Professor @ LPU Phagwara (Punjab) India



Floyd-Warshall Algorithm: Shortest Path

Floyd–Warshall algorithm is an algorithm for finding shortest paths in a weighted graph with positive or negative edge weights.

1. Repeat for $i, j = 1, 2, \dots, M$:
 IF: $W[i, j] = 0$, then Set $Q[i, j] = \infty$.
 Else: Set $Q[i, j] = W[i, j]$.
2. Repeat Step 3 and 4 for $k = 1, 2, \dots, M$:
3. Repeat Step 4 for $i = 1, 2, \dots, M$:
4. Repeat for $j = 1, 2, \dots, M$:
 Set $Q[i, j] = \text{Min} (Q[i, j], (Q[i, k] + Q[k, j]))$
 [End of Step 4 Loop.]
 [End of Step 3 Loop.]
 [End of Step 2 Loop.]
5. Exit.



Work Space

Ravi Kant Sahu, Asst. Professor @ LPU Phagwara (Punjab) India



Graph Traversal

- There are two different ways of Traversing a Graph.
 - Breadth First Search (BFS) : uses Queue
 - Depth First Search (DFS) : uses Stack
- During Traversal, each node N of G will be in one of the three states:
 - STATUS = 1: Ready State (initial state)
 - STATUS = 2: Waiting State (waiting in Queue/Stack)
 - STATUS = 3: Processed State



Breadth First Search

1. Initialize all nodes to Ready State (STATUS = 1).
 2. Put the starting node A in Queue and change its status to Waiting State (STATUS = 2).
 3. Repeat step 4 and 5 until Queue is empty:
 4. Remove the front node N of the Queue.
 Process N and set the status of N to STATUS=3.
 5. Add to the Rear of Queue all the neighbors of N that are in STATUS = 1. and change their status to STATUS = 2.
- [End of step 3 Loop.]
6. Exit.



Depth First Search

1. Initialize all nodes to Ready State (STATUS = 1).
2. Push the starting node A onto STACK and change its status to Waiting State (STATUS = 2).
3. Repeat step 4 and 5 until STACK is empty:
4. POP the TOP node N from the STACK.
Process N and set the status of N to STATUS=3.
5. PUSH onto STACK all the neighbors of N that are in STATUS = 1, and change their status to STATUS = 2.
[End of step 3 Loop.]
6. Exit.



Questions