

EDUCATION

M.Sc.- Robotics and Autonomous Systems	University of Lübeck , Germany	Oct 2020 - Aug 2022
B.Tech - Mechanical Engineering	Indian Institute of Information Technology Jabalpur , India	Jul 2015 – Aug 2019

SKILLS

<i>Programming/Script Languages:</i>	Python, MATLAB, C, bash, Java(basic)
<i>DL Frameworks and Libraries:</i>	PyTorch, TensorFlow, Detectron2, MMDetection, OpenCV, Streamlit
<i>Robotics:</i>	ROS Gazebo, Linux, Simulink, Siemens TIA portal

WORK EXPERIENCE

Robert Bosch GmbH Renningen, Germany	Master Thesis <i>Few-Shot Object Detection</i>	July '22 – Present
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- Topic: Investigation of Class Prototyping and Feature Fusion for Dense Meta-Detectors.
- Working with the RetinaNet to improve the performance on few-shot novel dataset (5-10 samples per category).
- One of the first works to focus on computing class prototypes and feature fusion methods – *work in progress*.

Robert Bosch GmbH Renningen, Germany	Internship Topic: <i>Few-Shot Object Detection</i>	March '22 – June '22
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- Literature review of object detection and meta-learning research papers.
- Implemented YoloX in the few-shot setting using the Detectron2 framework.

Institute of Medical Informatics , University of Lübeck, Germany	Deep Learning Intern Topic: <i>Monocular Depth Estimation</i>	Sep '21 – March' 22 Link
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- Depth estimation for Bronchoscopy Navigation (navigation inside the lungs).
- Implemented U-net and Pix2Pix GAN network for generating depth images from monocular RGB images.
- Devised a new loss function, the images are being predicted with a SSIM metric of around 95%

University of Lübeck	Hiwi / Student Assistant	Oct '21 – Feb '22
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- Worked as a student assistant for Learn2Trust project (designing AI course for medical students).
- Developed a software plugin using streamlit, to upload a medical image and to produce masks automatically once the boundary is drawn around the region of interest.

PROJECTS

Object detection for Autonomous Driving	Link
• Implemented state-of-the-art YOLOv3 neural network in TensorFlow for object detection. Achieved a mAP score of 70% without any data augmentation.	

Exploration Strategies in Deep Reinforcement Learning

- Conducted literature survey on all the existing exploration strategies involved in deep reinforcement learning.

Camera-based Vehicle Tracking	Link
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- Used Histogram of Oriented Gradients (HOG) as feature descriptor and linear SVM as the classifier.
- Trained classifier is used to track the preceding vehicles with the traditional sliding window approach.

Medical Device for Dementia (Forgetfulness)	Link
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- A wearable device which used deep learning to aid human memory to recall the location of day-to-day objects.
- Out of 5049 teams, our team is one among the 70 selected teams to exhibit the prototype.

ADDITIONAL INFORMATION

References	: Available upon request
Languages	: English, German (beginner), Hindi, Telugu
Hobbies	: Reading Novels (avid reader of Agatha Christi books), Gardening, Crafting (Wall decors)
Interests	: Mathematics and Machine Learning, Cricket, Apple products
First & Last Name	: Rakesh Reddy; Kondeti