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$$\begin{aligned}
 1. \quad \nabla_{\omega(l)} \hat{y}_k &= \nabla_{\omega(l)} \frac{\exp(z_k)}{\sum_{k'=1}^C \exp(z_{k'})} \quad k=1 \\
 &= \frac{\sum_{k'=1}^C \exp(z_{k'}) \cdot \frac{\partial \exp(z_k)}{\partial \omega} - \exp(z_k) \cdot \frac{\partial \sum_{k'=1}^C \exp(z_{k'})}{\partial \omega}}{\left(\sum_{k'=1}^C \exp(z_{k'})\right)^2} \\
 &= \frac{\sum_{k'=1}^C \exp(x^T \omega^{(l)} + b_{k'}) \cdot \exp(x^T \omega^{(l)} + b_k) \cdot x^T - \exp(x^T \omega^{(l)} + b_k) \cdot \exp(z_k) x^T}{\left(\sum_{k'=1}^C \exp(x^T \omega^{(l)} + b_{k'})\right)^2} \\
 &= \frac{\exp(z_k) x^T - x^T \exp(z_k)}{\sum_{k'=1}^C \exp(z_{k'}) \left(\sum_{k'=1}^C \exp(z_{k'})\right)^2} \\
 &= x^{(i)} \hat{y}_l - x^{(i)} \hat{y}_l^2 \\
 &= x^{(i)} \hat{y}_l (1 - \hat{y}_l)
 \end{aligned}$$

$$\begin{aligned}
 \nabla_{\omega(l)} &= \nabla_{\omega(l)} \frac{\exp(z_k)}{\sum_{k'=1}^C \exp(z_{k'})} \quad l \neq k \\
 &= \frac{\sum_{k'=1}^C \exp(z_{k'}) \cdot \frac{\partial \exp(z_k)}{\partial \omega} - \exp(z_k) \cdot \frac{\partial \sum_{k'=1}^C \exp(z_{k'})}{\partial \omega}}{\left(\sum_{k'=1}^C \exp(z_{k'})\right)^2} \\
 &= \frac{\sum_{k'=1}^C \exp(z_{k'}) \cdot 0 - \exp(z_k) \cdot \exp(z_k) x^T}{\left(\sum_{k'=1}^C \exp(z_{k'})\right)^2} \\
 &= -\hat{y}_k \cdot \hat{y}_l \cdot x^T \\
 &= -x^{(i)} \hat{y}_k (1 - \hat{y}_l)
 \end{aligned}$$

$$\begin{aligned}
 \nabla_{\omega(l)} J_{CE}(\omega, b) &= -\frac{1}{n} \sum_{i=1}^n \sum_{k=1}^C y_k^{(i)} \nabla_{\omega(l)} \log \hat{y}_k^{(i)} \\
 &= -\frac{1}{n} \sum_{i=1}^n \sum_{k=1}^C y_k^{(i)} \frac{1}{\hat{y}_k^{(i)}} \cdot \nabla_{\omega(l)} \hat{y}_k^{(i)} \\
 &= -\frac{1}{n} \sum_{i=1}^n \frac{y_i^{(i)}}{\hat{y}_k^{(i)}} \cdot (x^{(i)} \hat{y}_l^{(i)} (1 - \hat{y}_l^{(i)}) - \sum_{k \neq l} x^{(i)} \hat{y}_k^{(i)} \hat{y}_l^{(i)}) \\
 &= -\frac{1}{n} \sum_{i=1}^n (y_l^{(i)} + \sum_{k \neq l} y_k^{(i)}) \cdot (x^{(i)} (1 - \hat{y}_l^{(i)}) - \sum_{k \neq l} x^{(i)} \hat{y}_k^{(i)} \hat{y}_l^{(i)}) \\
 &= -\frac{1}{n} \sum_{i=1}^n y_l^{(i)} x^{(i)} (1 - \hat{y}_l^{(i)}) - \sum_{k \neq l} y_k^{(i)} x^{(i)} \hat{y}_l^{(i)} \\
 &= -\frac{1}{n} \sum_{i=1}^n \hat{y}_l^{(i)} x^{(i)} (1 - \hat{y}_l^{(i)}) - x^{(i)} \hat{y}_l^{(i)} (1 - \hat{y}_l^{(i)}) \\
 &= -\frac{1}{n} \sum_{i=1}^n x^{(i)} (y_l^{(i)} - y_l^{(i)} \hat{y}_l^{(i)} - \hat{y}_l^{(i)} + y_l^{(i)} \hat{y}_l^{(i)}) \\
 &= -\frac{1}{n} \sum_{i=1}^n x^{(i)} (y_l^{(i)} - \hat{y}_l^{(i)})
 \end{aligned}$$

$$\begin{aligned}
 2. \quad -\log P(D|\omega, b) &= -\log \sum_{i=1}^n P(y_i|x_i, \omega, b), \text{ where } n \text{ is the number of } x, y \text{ pairs in } D \\
 &= -\log \sum_{i=1}^n \left(\prod_{k=1}^C \hat{y}_k^{y_k} \right) \\
 &= -\sum_{i=1}^n \sum_{k=1}^C \log(\hat{y}_k^{y_k}) \\
 &= -\sum_{i=1}^n \sum_{k=1}^C y_k \log \hat{y}_k
 \end{aligned}$$

$$4. a. f\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \left[x_1 - 2x_2 + \frac{x_3}{4}\right]$$

$$x_1 - 2x_2 + \frac{x_3}{4} = \begin{bmatrix} w_{21} & w_{22} & w_{23} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + b_2$$

$$\boxed{w_2 = \begin{bmatrix} 1 & -2 & \frac{1}{4} \end{bmatrix}} \\ b_2 = 0$$

$$g\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 + 2x_2 \\ x_2 \\ -x_1 + 3 \end{bmatrix}$$

$$\begin{bmatrix} x_1 + 2x_2 \\ x_2 \\ -x_1 + 3 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix}$$

$$\boxed{w_1 = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ -1 & 0 \end{bmatrix}} \\ b_1 = \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix}$$

$$c. \boxed{\frac{\partial z_2}{\partial \text{vec}(w_2)} \cdot \frac{\partial w_2}{\partial z_1} \quad \frac{\partial z_2}{\partial b_2} \cdot \frac{\partial b_2}{\partial z_1}}$$

$$f. f(g(x)) = w_2 g(x), \text{ so } z_1 = g(x)$$

$$\frac{\partial (f \circ g)}{\partial z_1}(x) = \boxed{w_2}$$

$$g. \frac{\partial (f \circ g)}{\partial b_1} = \boxed{\frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial b_1}}$$

$$\nabla_{w_1} (f \circ g)(x) = \boxed{\frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial w_1}}$$