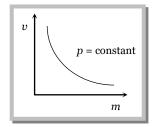
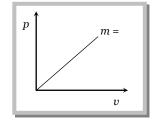
### Inertia :

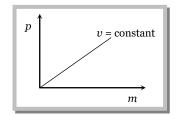
- 1. Inherent property of all the bodies by virtue of which they cannot change their state of rest or uniform motion along a straight line by their own is called inertia.
- 2. Inertia is not a physical quantity. It is only a property of the body which depends on mass of the body.
- 3. Inertia has no units and no dimensions
- 4. Two bodies of equal mass, one in motion and another is at rest, possess same inertia because it is a factor of mass only and does not depend upon the velocity.

### **Linear Momentum**

- 1. Linear momentum of a body is the quantity of motion contained in the body.
- 2. It is measured in terms of the force required to stop the body in unit time.
- 3. It is measured as the product of the mass of the body and its velocity *i.e.*, Momentum = mass  $\times$  velocity.
- 4. If a body of mass m is moving with velocity  $\vec{v}$  then its linear momentum  $\vec{p}$  is given by  $\vec{p} = m\vec{v}$
- 5. It is a vector quantity and it's direction is the same as the direction of velocity of the body.
- 6. Units : *kg-m/sec* [S.I.], *g-cm/sec* [C.G.S.]
- 7. Dimension :  $[MLT^{-1}]$







8. If two objects of different masses have same momentum, the lighter body possesses greater velocity.

$$p = m_1 v_1 = m_2 v_2 = \text{constant}$$

- $\therefore \frac{v_1}{v_2} = \frac{m_2}{m_1} \quad i.e. \quad v \propto \frac{1}{m}$  [As p is constant] This is shown in figure 1
- 9. For a given body  $p \propto v$  this is shown in fig 2
- **10.** For different bodies at same velocities  $p \propto m$  shown in figure 3

# Newton's First Law

A body continues to be in its state of rest or of uniform motion along a straight line, unless it is acted upon by some external force to change the state.

- (1) If no net force acts on a body, then the velocity of the body cannot change i.e. the body cannot accelerate.
  - $(2) \ Newton's \ first \ law \ defines \ inertia \ and \ is \ rightly \ called \ the \ law \ of \ inertia. \ Inertia \ are \ of \ three \ types:$

# Inertia of rest, Inertia of motion, Inertia of direction

(3) **Inertia of rest:** It is the inability of a body to change by itself, its state of rest. This means a body at rest remains at rest and cannot start moving by its own.

 ${\it Example}: (i) \ A \ person \ who \ is \ standing \ freely \ in \ bus, \ thrown \ backward, \ when \ bus \ starts \ suddenly.$ 

When a bus suddenly starts, the force responsible for bringing bus in motion is also transmitted to lower part of body, so this part of the body comes in motion along with the bus. While the upper half of body (say above the waist) receives no force to overcome inertia of rest and so it stays in its original position. Thus there

is a relative displacement between the two parts of the body and it appears as if the upper part of the body has been thrown backward.

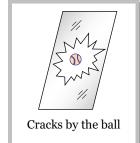
**Note**: 

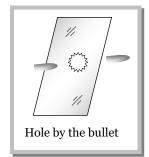
If the motion of the bus is slow, the inertia of motion will be transmitted to the body of the person uniformly and so the entire body of the person will come in motion with the bus and the person will not experience any jerk.

(ii) When a horse starts suddenly, the rider tends to fall backward on account of inertia of rest of upper part of the body as explained above.

(iii) A bullet fired on a window pane makes a clean hole through it while a stone breaks the whole window

because the bullet has a speed much greater than the stone. So its time of contact with glass is small. So in case of bullet the motion is transmitted only to a small portion of the glass in that small time. Hence a clear hole is created in the glass window, while in case of ball, the time and the area of contact is large. During this time the motion is transmitted to the entire window, thus creating the cracks in the entire window.

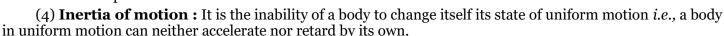




(iv) In the arrangement shown in the figure:

(a) If the string *B* is pulled with a sudden jerk then it will experience tension while due to inertia of rest of mass *M* this force will not be transmitted to the string *A* and so the string *B* will break.

- (b) If the string B is pulled steadily the force applied to it will be transmitted from string B to A through the mass M and as tension in A will be greater than in B by Mg (weight of mass M) the string A will break.
- (v) If we place a coin on smooth piece of card board covering a glass and strike the card board piece suddenly with a finger. The cardboard slips away and the coin falls into the glass due to inertia of rest.
- (vi) The dust particles in a durree falls off when it is beaten with a stick. This is because the beating sets the durree in motion whereas the dust particles tend to remain at rest and hence separate.



*Example*: (i) When a bus or train stops suddenly, a passenger sitting inside tends to fall forward. This is because the lower part of his body comes to rest with the bus or train but the upper part tends to continue its motion due to inertia of motion.

- (ii) A person jumping out of a moving train may fall forward.
- (iii) An athlete runs a certain distance before taking a long jump. This is because velocity acquired by running is added to velocity of the athlete at the time of jump. Hence he can jump over a longer distance.
  - (5) **Inertia of direction**: It is the inability of a body to change by itself direction of motion.

*Example*: (i) When a stone tied to one end of a string is whirled and the string breaks suddenly, the stone flies off along the tangent to the circle. This is because the pull in the string was forcing the stone to move in a circle. As soon as the string breaks, the pull vanishes. The stone in a bid to move along the straight line flies off tangentially.

- (ii) The rotating wheel of any vehicle throw out mud, if any, tangentially, due to directional inertia.
- (iii) When a car goes round a curve suddenly, the person sitting inside is thrown outwards.

### Newton's Second Law:

- (1) The rate of change of linear momentum of a body is directly proportional to the external force applied on the body and this change takes place always in the direction of the applied force.
- (2) If a body of mass m, moves with velocity  $\vec{v}$  then its linear momentum can be given by  $\vec{p} = m\vec{v}$  and if force  $\vec{F}$  is applied on a body, then

$$\vec{F} \propto \frac{d\vec{p}}{dt} \Rightarrow F = K \frac{d\vec{p}}{dt}$$

or 
$$\vec{F} = \frac{d\vec{p}}{dt}$$

(K = 1 in C.G.S. and S.I. units)

or 
$$\vec{F} = \frac{d}{dt}(m\vec{v})$$

 $\vec{F} = \frac{d}{dt}(m\vec{v}) = m\frac{d\vec{v}}{dt} = m\vec{a}$  (As  $a = \frac{d\vec{v}}{dt} =$ acceleration produced in the body)

$$\vec{F} = m\vec{a}$$

Force =  $mass \times acceleration$ 

# Sample problem based on Newton's first law

**Problem** 1. When a bus suddenly takes a turn, the passengers are thrown outwards because of

[AFMC 1999; CPMT 2000, 2001]

(a) Inertia of motion

(b) Acceleration of motion

(c) Speed of motion

(d) Both (b) and (c)

Solution: (a)

**Problem** 2. A person sitting in an open car moving at constant velocity throws a ball vertically up into air. The ball fall [EAMCET (Med.) 1995]

(a) Outside the car

- (b) In the car ahead of the person
- (c) In the car to the side of the person
- (d) Exactly in the hand which threw it up

Solution: (d) Because the horizontal component of velocity are same for both car and ball so they cover equal horizontal distances in given time interval.

# Sample problem based on Newton's second law

**Problem 3.** A train is moving with velocity 20 m/sec. on this, dust is falling at the rate of 50 kg/min. The extra force required to move this train with constant velocity will be

- (a) 16.66 N
- (b) 1000 N
- (c) 166.6 N
- (d) 1200 N

Solution: (a) Force  $F = v \frac{dm}{dt} = 20 \times \frac{50}{60} = 16.66 \, N$ 

**<u>Problem</u>** 4. A force of 10 Newton acts on a body of mass 20 kg for 10 seconds. Change in its momentum is

- (a)
- 5 kg m/s
- (b) 100 kg m/s
- (c) 200 kg m/s
- (d) 1000 kg m/s

### Force:

- (1) Force is an external effect in the form of a push or pulls which
  - (i) Produces or tries to produce motion in a body at rest.
  - (ii) Stops or tries to stop a moving body.
  - (iii) Changes or tries to change the direction of motion of the body.
- (2) Dimension : Force =  $mass \times acceleration$

$$[F] = [M][LT^{-2}] = [MLT^{-2}]$$

(3) Units: Absolute units: (i) Newton (S.I.) (ii) Dyne (C.G.S)

Gravitational units: (i) Kilogram-force (M.K.S.) (ii) Gram-force (C.G.S)

Newton: One Newton is that force which produces an acceleration of  $1m/s^2$  in a body of

mass 1 Kilogram.  $\therefore$  1  $Newton = 1kg m/s^2$ 

Dyne: One dyne is that force which produces an acceleration of  $1cm/s^2$  in a body of mass

1 gram. : 1  $Dyne = 1 gm cm / sec^2$ 

Relation between absolute units of force 1 Newton = 10 5 Dyne

*Kilogram-force*: It is that force which produces an acceleration of  $9.8m/s^2$  in a body of mass 1 kg.  $\therefore$  1 kg-f = 9.81 Newton

*Gram-force*: It is that force which produces an acceleration of  $980cm/s^2$  in a body of mass 1gm.  $\therefore$  1 gm-f = 980 Dyne

Relation between gravitational units of force : 1 kg-f = 10  $^{7}$  gm-f

- (4)  $\vec{F} = m\vec{a}$  formula is valid only if force is changing the state of rest or motion and the mass of the body is constant and finite.
  - (5) If *m* is not constant  $\vec{F} = \frac{d}{dt}(m\vec{v}) = m\frac{d\vec{v}}{dt} + \vec{v}\frac{dm}{dt}$
  - (6) If force and acceleration have three component along x, y and z axis, then

$$\vec{F} = F_x \hat{i} + F_y \hat{j} + F_z \hat{k}$$
 and  $\vec{a} = a_x \hat{i} + a_y \hat{j} + a_z \hat{k}$ 

From above it is clear that  $F_x = ma_x$ ,  $F_y = ma_y$ ,  $F_z = ma_z$ 

(7) No force is required to move a body uniformly along a straight line.

$$\vec{F} = ma$$
  $\therefore \vec{F} = 0$  (As  $a = 0$ )

(8) When force is written without direction then positive force means repulsive while negative force means attractive.

*Example : Positive force –* Force between two similar charges

Negative force – Force between two opposite charges

- (9) Out of so many natural forces, for distance  $10^{-15}$  metre, nuclear force is strongest while gravitational force weakest.  $F_{\rm nuclear} > F_{\rm electromagnetic} > F_{\rm gravitational}$ 
  - (10) Ratio of electric force and gravitational force between two electron  $F_e/F_g=10^{43}$  ::  $F_e>>F_g$
  - (11) Constant force : If the direction and magnitude of a force is constant. It is said to be a constant force.
  - (12) Variable or dependent force :
- (i)  $\it Time\ dependent\ force$ : In case of impulse or motion of a charged particle in an alternating electric field force is time dependent.
  - (ii) Position dependent force : Gravitational force between two bodies  $\frac{Gm_1m_2}{r^2}$

or

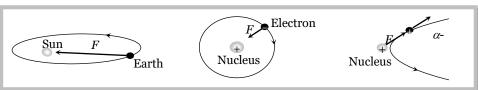
Force between two charged particles =  $\frac{q_1q_2}{4\pi\varepsilon_0r^2}$ .

(iii) *Velocity dependent force*: Viscous force(F)=  $(6\pi\eta rv)$ 

Force on charged particle in a magnetic field  $(qvB \sin \theta)$ 

(13) Central force: If a position dependent force is always directed towards or away from a fixed point it is said to be central otherwise non-central.

*Example*: Motion of earth around the sun. Motion of electron in an atom. Scattering of  $\alpha$ -particles from a nucleus



(14) Conservative or non conservative force: If under the action of a force the work done in a round trip is zero or the work is path independent, the force is said to be conservative otherwise non conservative.

Example: Conservative force: Gravitational force, electric force, elastic force.

Non conservative force: Frictional force, viscous force.

- (15) Common forces in mechanics:
- (i) *Weight*: Weight of an object is the force with which earth attracts it. It is also called the force of gravity or the gravitational force.
- (ii) *Reaction or Normal force*: When a body is placed on a rigid surface, the body experiences a force which is perpendicular to the surfaces in contact. Then force is called 'Normal force' or 'Reaction'.

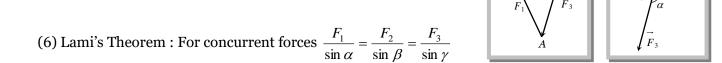


- (iii) *Tension*: The force exerted by the end of taut string, rope or chain against pulling (applied) force is called the tension. The direction of tension is so as to pull the body.
- (iv) *Spring force*: Every spring resists any attempt to change its length. This resistive force increases with change in length. Spring force is given by F = -Kx; where x is the change in length and K is the spring constant (unit N/m).

# F = -Kx $\downarrow \longrightarrow$ $\downarrow \longrightarrow$ $\downarrow \longrightarrow$ $\downarrow \longrightarrow$ $\downarrow \longrightarrow$

# **Equilibrium of Concurrent Force:**

- (1) If all the forces working on a body are acting on the same point, then they are said to be concurrent.
- (2) A body, under the action of concurrent forces, is said to be in equilibrium, when there is no change in the state of rest or of uniform motion along a straight line.
- (3) The necessary condition for the equilibrium of a body under the action of concurrent forces is that the vector sum of all the forces acting on the body must be zero.
  - (4) Mathematically for equilibrium  $\sum F_{\rm net} = 0$  or  $\sum F_x = 0$ ;  $\sum F_y = 0$ ; ,  $\sum F_z = 0$
- (5) Three concurrent forces will be in equilibrium, if they can be represented completely by three sides of a triangle taken in order.



NEWTON LAWS OF MOTION			
u = 0 $v = 0$	Body remains at rest. Here force is trying to change the state of rest.		
u = 0 $v > 0$	Body starts moving. Here force changes the state of rest.		
$\xrightarrow{F} \qquad \qquad \downarrow v > u$	In a small interval of time, force increases the magnitude of speed and direction of motion remains same.		
$F \longrightarrow U \\ \longrightarrow v < U$	In a small interval of time, force decreases the magnitude of speed and direction of motion remains same.		
	In uniform circular motion only direction of velocity changes, speed remains constant. Force is always perpendicular to velocity.		
V $F = mg$	In non-uniform circular motion, elliptical, parabolic or hyperbolic motion force acts at an angle to the direction of motion. In all these motions. Both magnitude and direction of velocity changes.		

# Sample problem based on force and equilibrium

- Three forces starts acting simultaneously on a particle moving with velocity  $\vec{v}$ . These forces are Problem 6. represented in magnitude and direction by the three sides of a triangle ABC (as shown). The particle will now move with velocity
  - (a)  $\vec{v}$  remaining unchanged
  - (b) Less than  $\vec{v}$
  - (c) Greater than  $\vec{v}$
  - (d)  $\overrightarrow{v}$  in the direction of the largest force BC
- Given three forces are in equilibrium i.e. net force will be zero. It means the particle will move with same Solution: (a) velocity.
- Problem 7. Two forces are such that the sum of their magnitudes is 18 N and their resultant is perpendicular to the smaller force and magnitude of resultant is 12. Then the magnitudes of the forces are
  - (a) 12 N, 6 N
- (b) 13 N, 5N
- (c) 10 N, 8 N
- (d) 16 N, 2 N

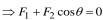
Solution: (b) Let two forces are  $F_1$  and  $F_2(F_1 < F_2)$ .

According to problem:  $F_1 + F_2 = 18$ 

....(i)

Angle between  $F_1$  and resultant (R) is 90°

$$\therefore \tan 90 = \frac{F_2 \sin \theta}{F_1 + F_2 \cos \theta} = \infty$$



$$\Rightarrow \cos \theta = -\frac{F_1}{F_2} \qquad \dots (ii)$$

and 
$$R^2 = F_1^2 + F_2^2 + 2F_1F_2\cos\theta$$

$$144 = F_1^2 + F_2^2 + 2F_1F_2\cos\theta \qquad .....(iii)$$

by solving (i), (ii) and (iii) we get  $F_1 = 5N$  and  $F_2 = 13N$ 

- **Problem** 8. The resultant of two forces, one double the other in magnitude, is perpendicular to the smaller of the two forces. The angle between the two forces is
  - (a) 60°

- (b) 120°
- (c) 150°
- (d) 90°
- *Solution*: (b) Let forces are F and 2F and angle between them is  $\theta$  and resultant makes an angle  $\alpha$  with the force F.

$$\tan \alpha = \frac{2F\sin\theta}{F + 2F\cos\theta} = \tan 90 = \infty$$

$$\Rightarrow F + 2F\cos\theta = 0$$

$$\therefore \cos \theta = -1/2 \text{ or } \theta = 120^{\circ}$$

- **Problem** 9. A weightless ladder, 20 *ft* long rests against a frictionless wall at an angle of 60° with the horizontal. A 150 pound man is 4 *ft* from the top of the ladder. A horizontal force is needed to prevent it from slipping. Choose the correct magnitude from the following
  - (a) 175 lb
- (b) 100 *lb*
- (c) 70 lb
- (d) 150 lb
- Solution: (c) Since the system is in equilibrium therefore  $\sum F_x = 0$  and  $\sum F_y = 0$  :.  $F = R_2$  and  $W = R_1$

Now by taking the moment of forces about point B.

$$F.(BC) + W.(EC) = R_1(AC)$$

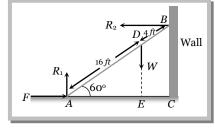
[from the figure  $EC= 4 \cos 60$ ]

$$F.(20\sin 60) + W(4\cos 60) = R_1(20\cos 60)$$

$$10\sqrt{3}F + 2W = 10R_1$$

$$\left[ \text{As } R_1 = W \right]$$

$$\therefore F = \frac{8W}{10\sqrt{3}} = \frac{8 \times 150}{10\sqrt{3}} = 70lb$$

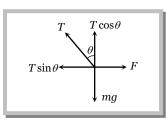


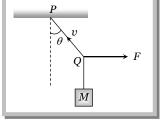
- **Problem** 10. A mass M is suspended by a rope from a rigid support at P as shown in the figure. Another rope is tied at the end Q, and it is pulled horizontally with a force F. If the rope PQ makes angle  $\theta$  with the vertical then the tension in the string PQ is
  - (a)  $F \sin \theta$
  - (b)  $F/\sin\theta$
  - (c)  $F\cos\theta$
  - (d)  $F/\cos\theta$
- Solution: (b) From the figure

For horizontal equilibrium

$$T\sin\theta = F$$

$$T = \frac{F}{\sin \theta}$$





- **Problem** 11. A spring balance A shows a reading of 2 kg, when an aluminium block is suspended from it. Another balance B shows a reading of 5 kg, when a beaker full of liquid is placed in its pan. The two balances are arranged such that the Al block is completely immersed inside the liquid as shown in the figure. Then
  - (a) The reading of the balance A will be more than 2 kg
  - (b) The reading of the balance B will be less than 5 kg
  - (c) The reading of the balance A will be less than 2 kg. and that of B will be more than 5 kg
  - (d) The reading of balance A will be 2 kq, and that of B will be 5 kq.

Solution: (c) Due to buoyant force on the aluminium block the reading of spring balance A will be less than 2 kg but it increase the reading of balance *B*.

In the following diagram, pulley  $P_1$  is movable and pulley  $P_2$  is fixed. The value of angle  $\theta$  will be Problem 12.

- (a) 60°
- (b) 30°
- (c)  $45^{\circ}$
- (d) 15°

Solution: (b) Free body diagram of pulley  $P_1$  is shown in the figure

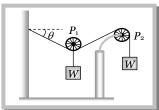
For horizontal equilibrium  $T_1 \cos \theta = T_2 \cos \theta$  ::  $T_1 = T_2$ 

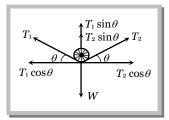
and 
$$T_1 = T_2 = W$$

For vertical equilibrium

$$T_1 \sin \theta + T_2 \sin \theta = W \implies W \sin \theta + W \sin \theta = W$$

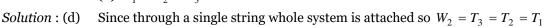
$$\therefore \sin \theta = \frac{1}{2} \text{ or } \theta = 30^{\circ}$$





In the following figure, the pulley is massless and frictionless. The relation between  $T_1$ ,  $T_2$  and  $T_3$  will be Problem 13.

- (a)  $T_1 = T_2 \neq T_3$
- (b)  $T_1 \neq T_2 = T_3$
- (c)  $T_1 \neq T_2 \neq T_3$
- (d)  $T_1 = T_2 = T_3$



**Problem** 14. In the above problem (13), the relation between  $W_1$  and  $W_2$  will be

(a) 
$$W_2 = \frac{W_1}{2\cos\theta}$$

(b) 
$$2W_1 \cos \theta$$
 (c)  $W_2 = W_1$ 

(c) 
$$W_2 = W_1$$

(d) 
$$W_2 = \frac{2\cos\theta}{W_1}$$

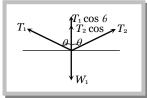
For vertical equilibrium Solution: (a)

$$T_1 \cos \theta + T_2 \cos \theta = W_1$$

$$[As T_1 = T_2 = W_2]$$

$$2W_2\cos\theta = W_1$$

$$\therefore W_2 = \frac{W_1}{2\cos\theta}.$$

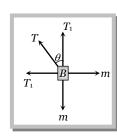


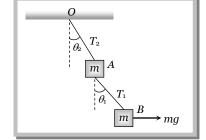
Problem 15. In the following figure the masses of the blocks A and B are same and each equal to m. The tensions in the strings OA and AB are  $T_2$  and  $T_1$  respectively. The system is in equilibrium with a constant horizontal

force mg on B. The  $T_1$  is

- (a) mg
- (b)  $\sqrt{2} mg$
- (c)  $\sqrt{3} mg$
- (d)  $\sqrt{5} mg$

From the free body diagram of block B Solution : (b)





$$T_1 \cos \theta_1 = mg \dots (i)$$

$$T_1 \sin \theta_1 = -mg$$
 .....(ii)

by squaring and adding  $T_1^2 \left( \sin^2 \theta_1 + \cos^2 \theta_1 \right) = 2(mg)^2$ 

$$T_1 = \sqrt{2}mg$$

**Problem 16.** In the above problem (15), the angle  $\theta_1$  is

(a) 30°

- (b) 45°
- (c)  $60^{\circ}$

(d)  $\tan^{-1} \left( \frac{1}{2} \right)$ 

Solution: (b) From the solution (15) by dividing equation(ii) by equation (i)

$$\frac{T_1 \sin \theta_1}{T_1 \cos \theta_1} = \frac{mg}{mg}$$

$$\therefore$$
 tan  $\theta_1 = 1$  or  $\theta_1 = 45^{\circ}$ 

**Problem** 17. In the above problem (15) the tension  $T_2$  will be

(a) mg

- (b)  $\sqrt{2} mg$
- (c)  $\sqrt{3}$  mg
- (d)  $\sqrt{5} mg$

 $T_2 \cos$ 

 $T_2 \sin$ 

From the free body diagram of block ASolution: (d)

For vertical equilibrium  $T_2 \cos \theta_2 = mg + T_1 \cos \theta_1$ 

$$T_2\cos\theta_2 = mg + \sqrt{2}mg\cos45^\circ$$

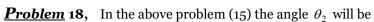
$$T_2\cos\theta_2 = 2mg$$

For horizontal equilibrium  $T_2 \sin \theta_2 = T_1 \sin \theta_1 = \sqrt{2}mg \sin 45^\circ$ 

$$T_2 \sin \theta_2 = mg$$

by squaring and adding (i) and (ii) equilibrium

$$T_2^2 = 5(mg)^2$$
 or  $T_2 = \sqrt{5}mg$ 



(a) 30°

- (b) 45°
- (c)  $60^{\circ}$
- (d)  $\tan^{-1} \left( \frac{1}{2} \right)$

 $T_1 \cos$ 

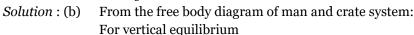
From the solution (17) by dividing equation(ii) by equation (i) Solution: (d)

$$\frac{\sin \theta_2}{\cos \theta_2} = \frac{mg}{2mg} \Rightarrow \tan \theta_2 = \frac{1}{2} \qquad \therefore \theta_2 = \tan^{-1} \left[ \frac{1}{2} \right]$$

$$\therefore \ \theta_2 = \tan^{-1} \left[ \frac{1}{2} \right]$$

**<u>Problem</u>** 19. A man of mass m stands on a crate of mass M. He pulls on a light rope passing over a smooth light pulley. The other end of the rope is attached to the crate. For the system to be in equilibrium, the force exerted by the men on the rope will be

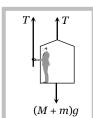
- (a) (M + m)q
- (b)  $\frac{1}{2}(M+m)g$
- (c) Mg
- (d) mg



$$2T = (M+m)g$$

$$\therefore T = \frac{(M+m)g}{2}$$





- **<u>Problem</u>** 20. Two forces, with equal magnitude F, act on a body and the magnitude of the resultant force is  $\frac{F}{2}$ . The angle between the two forces is
  - (a)  $\cos^{-1}\left(-\frac{17}{18}\right)$  (b)  $\cos^{-1}\left(-\frac{1}{3}\right)$  (c)  $\cos^{-1}\left(\frac{2}{3}\right)$  (d)  $\cos^{-1}\left(\frac{8}{9}\right)$

- Resultant of two vectors A and B, which are working at an angle  $\theta$ , can be given by Solution: (a)

$$R = \sqrt{A^2 + B^2 + 2AB\cos\theta}$$

[As 
$$A = B = F$$
 and  $R = \frac{F}{3}$ ]

$$\left(\frac{F}{3}\right)^2 = F^2 + F^2 + 2F^2 \cos\theta$$

$$\frac{F^2}{9} = 2F^2 + 2F^2 \cos \theta \implies \frac{-17}{9}F^2 = 2F^2 \cos \theta \implies \cos \theta = \left(\frac{-17}{18}\right) \text{ or } \theta = \cos^{-1}\left(\frac{-17}{18}\right)$$

- **Problem 21.** A cricket ball of mass 150 gm is moving with a velocity of 12 m/s and is hit by a bat so that the ball is turned back with a velocity of 20 m/s. The force of blow acts for 0.01s on the ball. The average force exerted by the bat on the ball is
- (c) 500 N
- (d) 400 N
- Solution: (a)  $v_1 = -12m/s$  and  $v_2 = +20m/s$  [because direction is reversed]

$$m = 150 \, gm = 0.15 \, kg$$
,  $t = 0.01 \, \text{sec}$ 

Force exerted by the bat on the ball  $F = \frac{m[v_2 - v_1]}{t} = \frac{0.15[20 - (-12)]}{0.01} = 480 \text{ Newton}$ 

### **Newton's Third Law**

To every action, there is always an equal (in magnitude) and opposite (in direction) reaction.

- (1) When a body exerts a force on any other body, the second body also exerts an equal and opposite force on the first.
  - (2) Forces in nature always occurs in pairs. A single isolated force is not possible.
- (3) Any agent, applying a force also experiences a force of equal magnitude but in opposite direction. The force applied by the agent is called 'Action' and the counter force experienced by it is called 'Reaction'.
- (4) Action and reaction never act on the same body. If it were so the total force on a body would have always been zero i.e. the body will always remain in equilibrium.
- (5) If  $\vec{F}_{AB}$  = force exerted on body A by body B (Action) and  $\vec{F}_{BA}$  = force exerted on body B by body A (Reaction)

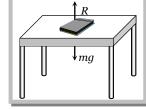
Then according to Newton's third law of motion  $\vec{F}_{AB} = -\vec{F}_{BA}$ 

(6) Example: (i) A book lying on a table exerts a force on the table which is equal to the weight of the book. This is the force of action.

The table supports the book, by exerting an equal force on the book. This is the force of reaction.

As the system is at rest, net force on it is zero. Therefore force of action and reaction must be equal and opposite.

- (ii) Swimming is possible due to third law of motion.
- (iii) When a gun is fired, the bullet moves forward (action). The gun recoils backward (reaction).
  - (iv) Rebounding of rubber ball takes place due to third law of motion.
- (v) While walking a person presses the ground in the backward direction (action) by his feet. The ground pushes the person in forward direction with an equal force (reaction). The component of reaction in horizontal direction makes the person move forward.
  - (vi) It is difficult to walk on sand or ice.





# Sample problem based on Newton's third law

**Problem 22.** You are on a frictionless horizontal plane. How can you get off if no horizontal force is exerted by pushing against the surface

(a) By jumping

(b) By splitting or sneezing

(c) By rolling your body on the surface

(d) By running on the plane

Solution: (b) By doing so we can get push in backward direction in accordance with *Newton's* third law of motion.

### Frame of Reference

- (1) A frame in which an observer is situated and makes his observations is known as his 'Frame of reference'.
- (2) The reference frame is associated with a co-ordinate system and a clock to measure the position and time of events happening in space. We can describe all the physical quantities like position, velocity, acceleration etc. of an object in this coordinate system.
- (3) Frame of reference are of two types: (i) Inertial frame of reference (ii) Non-inertial frame of reference.

### (i) Inertial frame of reference:

- (a) A frame of reference which is at rest or which is moving with a uniform velocity along a straight line is called an inertial frame of reference.
  - (b) In inertial frame of reference Newton's laws of motion holds good.
- (c) Inertial frame of reference are also called un accelerated frame of reference or Newtonian or Galilean frame of reference.
- (d) Ideally no inertial frame exists in universe. For practical purpose a frame of reference may be considered as inertial if it's acceleration is negligible with respect to the acceleration of the object to be observed.
  - (e) To measure the acceleration of a falling apple, earth can be considered as an inertial frame.
- (f) To observe the motion of planets, earth cannot be considered as an inertial frame but for this purpose the sun may be assumed to be an inertial frame.

*Example*: The lift at rest, lift moving (up or down) with constant velocity, car moving with constant velocity on a straight road.

### (ii) Non inertial frame of reference:

- (a) Accelerated frame of references are called non-inertial frame of reference.
- (b) Newton's laws of motion are not applicable in non-inertial frame of reference.

*Example:* Car moving in uniform circular motion, lift which is moving upward or downward with some acceleration, plane which is taking off.

# Impulse

(1) When a large force works on a body for very small time interval, it is called impulsive force.

An impulsive force does not remain constant, but changes first from zero to maximum and then from maximum to zero. In such case we measure the total effect of force.

(2) Impulse of a force is a measure of total effect of force.

(3) 
$$\vec{I} = \int_{t_1}^{t_2} \vec{F} \, dt$$
.

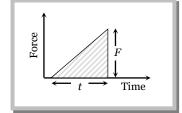
- (4) Impulse is a vector quantity and its direction is same as that of force.
- (5) Dimension : [ *MLT* <sup>-1</sup> ]
- (6) Units: Newton-second or Kg-m- $s^{-1}$  (S.I.) and Dyne-second or gm-cm- $s^{-1}$  (C.G.S.)
- (7) Force-time graph : Impulse is equal to the area under F-t curve.

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If we plot a graph between force and time, the area under the curve and time axis gives the value of impulse.

I =Area between curve and time axis

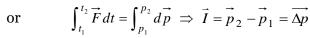
$$= \frac{1}{2} \times \text{ Base} \times \text{ Height}$$
$$= \frac{1}{2} F t$$



(8) If  $F_{av}$  is the average magnitude of the force then

$$I = \int_{t_1}^{t_2} F \, dt = F_{av} \int_{t_1}^{t_2} dt = F_{av} \Delta t$$

(9) From Newton's second law  $\overrightarrow{F} = \frac{d\overrightarrow{p}}{dt}$ 



*i.e.* The impulse of a force is equal to the change in momentum.

This statement is known as *Impulse momentum theorem*.

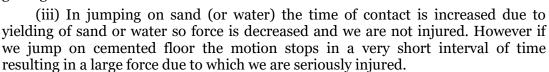
(10) Examples: Hitting, kicking, catching, jumping, diving, collision etc.

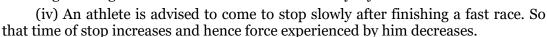
In all these cases an impulse acts.  $I = \int F dt = F_{av}$ .  $\Delta t = \Delta p = \text{constant}$ 

So if time of contact  $\Delta t$  is increased, average force is decreased (or diluted) and vice-versa.

(i) In hitting or kicking a ball we decrease the time of contact so that large force acts on the ball producing greater acceleration.

(ii) In catching a ball a player by drawing his hands backwards increases the time of contact and so, lesser force acts on his hands and his hands are saved from getting hurt.





(v) China wares are wrapped in straw or paper before packing.



# $oldsymbol{S}$ ample problem based on Impulse

**Problem 23.** A ball of mass 150q moving with an acceleration  $20m/s^2$  is hit by a force, which acts on it for 0.1 sec. The impulsive force is [AFMC 1999]

- (a) 0.5 N-s
- (b) 0.1 *N-s*
- (c) 0.3 N-s
- (d) 1.2 N-s

Solution: (c) Impulsive force =  $force \times time$ 

 $= m a \times t = 0.15 \times 20 \times 0.1 = 0.3 N-s$ 

<u>Problem 24.</u> A force of 50 dynes is acted on a body of mass 5 g which is at rest for an interval of 3 seconds, then impulse is

- (a)  $0.15 \times 10^{-3} N s$  (b)  $0.98 \times 10^{-3} N s$  (c)  $1.5 \times 10^{-3} N s$  (d)  $2.5 \times 10^{-3} N s$

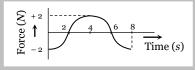
Solution: (c)

Impulse = force × time =  $50 \times 10^{-5} \times 3 = 1.5 \times 10^{-3} N$  - s

**Problem 25.** The force-time (F - t) curve of a particle executing linear motion is as shown in the figure. The momentum acquired by the particle in time interval from zero to 8 *second* will be

(a) 
$$-2 N-s$$

(b) 
$$+ 4 N-s$$



Solution: (d) Momentum acquired by the particle is numerically equal to the area enclosed between the *F-t* curve and time Axis. For the given diagram area in a upper half is positive and in lower half is negative (and equal to the upper half). So net area is zero. Hence the momentum acquired by the particle will be zero.

### Law of Conservation of Linear Momentum

If no external force acts on a system (called isolated) of constant mass, the total momentum of the system remains constant with time.

(1) According to this law for a system of particles  $\vec{F} = \frac{d\vec{p}}{dt}$ 

In the absence of external force  $\vec{F} = 0$  then  $\vec{p} = \text{constant}$ 

*i.e.*, 
$$\vec{p} = \vec{p}_1 + \vec{p}_2 + \vec{p}_3 + ... = \text{constant}.$$

or 
$$m_1 \stackrel{\rightarrow}{v_1} + m_2 \stackrel{\rightarrow}{v_2} + m_3 \stackrel{\rightarrow}{v_3} + \dots = \text{constant}$$

This equation shows that in absence of external force for a closed system the linear momentum of individual particles may change but their sum remains unchanged with time.

(2) Law of conservation of linear momentum is independent of frame of reference though linear momentum depends on frame of reference.

(3) Conservation of linear momentum is equivalent to Newton's third law of motion.

For a system of two particles in absence of external force by law of conservation of linear momentum.

$$\vec{p}_1 + \vec{p}_2 = \text{constant}.$$

$$m_1\vec{v}_1 + m_2\vec{v}_2 = \text{constant.}$$

Differentiating above with respect to time

$$m_1 \frac{d\vec{v}_1}{dt} + m_2 \frac{d\vec{v}_2}{dt} = 0 \implies m_1 \vec{a}_1 + m_2 \vec{a}_2 = 0 \implies \vec{F}_1 + \vec{F}_2 = 0$$

$$\vec{F}_2 = -\vec{F}_1$$

i.e. for every action there is equal and opposite reaction which is Newton's third law of motion.

(4) Practical applications of the law of conservation of linear momentum

(i) When a man jumps out of a boat on the shore, the boat is pushed slightly away from the shore.

(ii) A person left on a frictionless surface can get away from it by blowing air out of his mouth or by throwing some object in a direction opposite to the direction in which he wants to move.

(iii) **Recoiling of a gun:** For bullet and gun system, the force exerted by trigger will be internal so the momentum of the system remains unaffected.

Let  $m_G = \text{mass of gun}$ ,  $m_B = \text{mass of bullet}$ ,

$$v_G$$
 = velocity of gun,  $v_B$  = velocity of bullet

Initial momentum of system = 0

Final momentum of system =  $m_G \vec{v}_G + m_B \vec{v}_B$ 

By the law of conservation linear momentum

$$m_G \vec{v}_G + m_B \vec{v}_B = 0$$



So recoil velocity 
$$\vec{v}_G = -\frac{m_B}{m_G} \vec{v}_B$$

- (a) Here negative sign indicates that the velocity of recoil  $\vec{v}_G$  is opposite to the velocity of the bullet.
- (b)  $v_G \propto \frac{1}{m_G}$  i.e. higher the mass of gun, lesser the velocity of recoil of gun.
- (c) While firing the gun must be held tightly to the shoulder, this would save hurting the shoulder because in this condition the body of the shooter and the gun behave as one body. Total mass become large and recoil velocity becomes too small.

$$v_G \propto \frac{1}{m_G + m_{\rm man}}$$

(iv) **Rocket propulsion :** The initial momentum of the rocket on its launching pad is zero. When it is fired from the launching pad, the exhaust gases rush downward at a high speed and to conserve momentum, the rocket moves upwards.

Let  $m_0$  = initial mass of rocket,

m = mass of rocket at any instant 't' (instantaneous mass)

 $m_r$  = Residual mass of empty container of the rocket

u =velocity of exhaust gases,

v = velocity of rocket at any instant 't' (instantaneous velocity)

 $\frac{dm}{dt}$  = Rate of change of mass of rocket = rate of fuel consumption

= rate of ejection of the fuel.

(a) Thrust on the rocket : 
$$F = -u \frac{dm}{dt} - mg$$

Here negative sign indicates that direction of thrust is opposite to the direction of escaping gases.

$$F = -u \frac{dm}{dt}$$
 (if effect of gravity is neglected)

(b) Acceleration of the rocket: 
$$a = \frac{u}{m} \frac{dm}{dt} - g$$

and if effect of gravity is neglected 
$$a = \frac{u}{m} \frac{dm}{dt}$$

(c) Instantaneous velocity of the rocket : 
$$v = u \log_{e} \left(\frac{m_0}{m}\right) - gt$$

and if effect of gravity is neglected 
$$v = u \log_e \left(\frac{m_0}{m}\right) = 2.303 u \log_{10} \left(\frac{m_0}{m}\right)$$

(d) Burnt out speed of the rocket : 
$$v_b = v_{\text{max}} = u \log_e \left(\frac{m_0}{m_r}\right)$$

The speed attained by the rocket when the complete fuel gets burnt is called burnt out speed of the rocket. It is the maximum speed acquired by the rocket.

# Sample Problem based on conservation of momentum

- **Problem 26.** A wagon weighing 1000 kg is moving with a velocity 50 km/h on smooth horizontal rails. A mass of 250 kg is dropped into it. The velocity with which it moves now is
  - (a) 12.5 km/hour
- (b) 20 km/hour
- (d) 50 km/hour
- Initially the wagon of mass 1000 kq is moving with velocity of 50 km/hSolution: (c)

So its momentum =  $1000 \times 50 \frac{kg \times km}{h}$ 

When a mass 250kg is dropped into it. New mass of the system = 1000 + 250 = 1250kg

Let v is the velocity of the system.

By the conservation of linear momentum : Initial momentum = Final momentum  $1000 \times 50 = 1250 \times v$ 

 $v = \frac{50,000}{1250} = 40 \, km \, / h.$ 

- **Problem 27.** The kinetic energy of two masses  $m_1$  and  $m_2$  are equal. The ratio of their linear momentum will be
  - (a)  $m_1/m_2$
- (b)  $m_2/m_1$
- (c)  $\sqrt{m_1/m_2}$
- (d)  $\sqrt{m_2/m_1}$
- Relation between linear momentum (P), man (m) and kinetic energy (E)Solution: (c)

 $P = \sqrt{2mE}$   $\Rightarrow P \propto \sqrt{m}$  [as E is constant]  $\therefore \frac{P_1}{P_2} = \sqrt{\frac{m_1}{m_2}}$ 

- **Problem 28.** Which of the following has the maximum momentum
  - (a) A 100 kg vehicle moving at 0.02  $ms^{-1}$  (b) A 4 g weight moving at 10000  $cms^{-1}$
  - (c) A 200 q weight moving with kinetic energy 10<sup>-6</sup> J (d) kilometre
- A 20 q weight after falling 1

- Solution : (d) Momentum of body for given options are :
  - (a)  $P = mv = 100 \times 0.02 = 2kgm / sec$
- (b)  $P = mv = 4 \times 10^{-3} \times 100 = 0.4 kgm / sec$
- (c)  $P = \sqrt{2mE} = \sqrt{2 \times 0.2 \times 10^{-6}} = 6.3 \times 10^{-4} \, \text{kgm/sec}$
- (d)  $P = m\sqrt{2gh} = 20 \times 10^{-3} \times \sqrt{2 \times 10 \times 10^{3}} = 2.82 kgm / sec$

So for option (d) momentum is maximum.

- **Problem 29.** A rocket with a lift-off mass  $3.5 \times 10^4$  kg is blasted upwards with an initial acceleration of  $10m/s^2$ . Then the initial thrust of the blast is
  - (a)  $1.75 \times 10^5 N$

- (b)  $3.5 \times 10^5 N$  (c)  $7.0 \times 10^5 N$  (d)  $14.0 \times 10^5 N$
- Initial thrust on the rocket  $F = m(g + a) = 3.5 \times 10^4 (10 + 10) = 7.0 \times 10^5 N$ Solution: (c)
- **Problem 30.** In a rocket of mass 1000 kg fuel is consumed at a rate of 40 kg/s. The velocity of the gases ejected from the rocket is  $5 \times 10^4 \, m \, / \, s$ . The thrust on the rocket is
  - (a)  $2 \times 10^3 N$
- (b)  $5 \times 10^4 N$
- (c)  $2 \times 10^6 N$  (d)  $2 \times 10^9 N$

- Thrust on the rocket  $F = \frac{udm}{dt} = 5 \times 10^4 (40) = 2 \times 10^6 N$ Solution: (c)
- **Problem 31.** If the force on a rocket moving with a velocity of 300 m/s is 210 N, then the rate of combustion of the fuel
  - (a) 0.7 kg/s
- (b)  $1.4 \, kg/s$
- (c)  $0.07 \, kg/s$
- Solution: (a) Force on the rocket  $=\frac{udm}{dt}$  :. Rate of combustion of fuel  $\left(\frac{dm}{dt}\right) = \frac{F}{u} = \frac{210}{300} = 0.7 kg/s$ .
- **Problem 32.** A rocket has a mass of 100 kg. 90% of this is fuel. It ejects fuel vapours at the rate of 1 kg/sec with a velocity of 500 m/sec relative to the rocket. It is supposed that the rocket is outside the gravitational field. The initial upthrust on the rocket when it just starts moving upwards is
- (b) 500 N
- (c) 1000 N

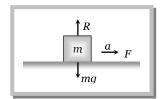
Free Body Diagram:					
Condition	Figure	Velocity	Acceleration		Conclusion
				Reaction	
Lift is at rest	LIFT  R  Spring Balance  mg	v = 0	<i>a</i> = 0	R - mg = 0 $\therefore R = mg$	Apparent weight = Actual weight
Lift moving upward or downward with constant velocity	LIFT  R  Spring Balance  mg	v = constant	<i>a</i> = 0	R - mg = 0 $\therefore R = mg$	Apparent weight = Actual weight
Lift accelerating upward at the rate of 'a'	LIFT  R  a  Spring Balance  mg	v = variable	a < g	$R - mg = ma$ $\therefore R = m(g + a)$	Apparent weight > Actual weight
Lift accelerating upward at the rate of 'g'	LIFT  R  Spring Balance	v = variable	a = g	R - mg = mg $R = 2mg$	Apparent weight = 2 Actual weight
Lift accelerating downward at the rate of 'a'	LIFT  R  a  Spring Balance  mg	v = variable	a < g	mg - R = ma $\therefore R = m(g - a)$	Apparent weight < Actual weight
Lift accelerating downward at the rate of 'g'	LIFT  R  Spring Balance  mg	v = variable	a = g	mg - R = mg R = 0	Apparent weight = Zero (weightlessness)
Lift accelerating downward at the rate of a(>g)	LIFT  R  a > g  mg	v = variable	a > g	mg - R = ma R = mg - ma R = -ve	Apparent weight negative means the body will rise from the floor of the lift and stick to the ceiling of the lift.

### **Acceleration of Block on Horizontal Smooth Surface:**

# (1) When a pull is horizontal

$$R = mg$$
 and 
$$F = ma$$

$$\therefore a = F/m$$



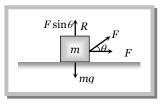
### (2) When a pull is acting at an angle ( $\theta$ ) to the horizontal (upward)

$$R + F \sin \theta = mg$$

$$\Rightarrow$$
  $R = mq - F\sin\theta$ 

and 
$$F\cos\theta = ma$$

$$\therefore \qquad a = \frac{F\cos\theta}{m}$$

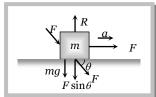


# (3) When a push is acting at an angle ( $\theta$ ) to the horizontal (downward)

$$R = mg + F\sin\theta$$

and 
$$F\cos\theta = ma$$

$$a = \frac{F\cos\theta}{m}$$



### **Acceleration of Block on Smooth Inclined Plane**

# (1) When inclined plane is at rest

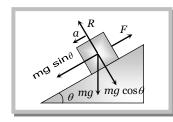
Normal reaction  $R = mg \cos \theta$ 

Force along a inclined plane

$$F = mg \sin \theta$$

$$ma = mg \sin \theta$$

$$\therefore \qquad a = g \sin \theta$$



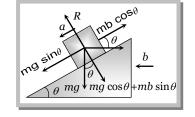
# (2) When a inclined plane given a horizontal acceleration ' $\boldsymbol{b}$ '

Since the body lies in an accelerating frame, an inertial force (mb) acts on it in the opposite direction.

Normal reaction  $R = mg \cos \theta + mb \sin \theta$ 

and 
$$ma = mg \sin \theta - mb \cos \theta$$

$$\therefore \qquad a = q \sin \theta - b \cos \theta$$



**Note**:  $\square$  The condition for the body to be at rest relative to the inclined plane:  $a = g \sin \theta - b \cos \theta = 0$ 

$$\therefore \qquad b = g \tan \theta$$

# **Motion of Blocks in Contact:**

Condition	Free body diagram	Equation	Force and acceleration
BA	$\xrightarrow{F} \xrightarrow{m_1 a} \xrightarrow{f}$	$F - f = m_1 a$	$a = \frac{F}{m_1 + m_2}$
$\xrightarrow{F} \boxed{m_1} \qquad m_2$	$ \begin{array}{c}  m_2 a \\  \hline  m_2 \end{array} $	$f = m_2 a$	$f = \frac{m_2 F}{m_1 + m_2}$
$ \begin{array}{c c} B \\ \hline A \\ \hline m_1 \end{array} $ $m_2$ $F$	$m_1a \leftarrow f$	$f = m_1 a$	$a = \frac{F}{m_1 + m_2}$
$m_1$ $m_2$ $\stackrel{1}{\longleftarrow}$	$ \xrightarrow{f}  \xrightarrow{m_2 a}  \xrightarrow{F} $	$F - f = m_2 a$	$f = \frac{m_1 F}{m_1 + m_2}$
	$\xrightarrow{F} \boxed{m_1 a} \leftarrow f_1$	$F - f_1 = m_1 a$	$a = \frac{F}{m_1 + m_2 + m_3}$
$F \longrightarrow \boxed{\begin{array}{c c} & & C \\ \hline m_1 & m_2 & m_3 \end{array}}$	$ \xrightarrow{f_1}  \xrightarrow{m_2 a}  \xrightarrow{f_2}  $	$f_1 - f_2 = m_2 a$	$f_1 = \frac{(m_2 + m_3)F}{m_1 + m_2 + m_3}$
		$f_2 = m_3 a$	$f_2 = \frac{m_3 F}{m_1 + m_2 + m_3}$
	$m_1a$ $m_1$ $m_1$	$f_1 = m_1 a$	$a = \frac{F}{m_1 + m_2 + m_3}$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\xrightarrow{f_1} \xrightarrow{m_2 a} \xrightarrow{f_2}$	$f_2 - f_1 = m_2 a$	$f_1 = \frac{m_1 F}{m_1 + m_2 + m_3}$
	$ \begin{array}{c}  & \xrightarrow{m_3 a} \\  & \xrightarrow{f_2} & \xrightarrow{m_3} & F \end{array} $	$F - f_2 = m_3 a$	$f_2 = \frac{(m_1 + m_2)F}{m_1 + m_2 + m_3}$

# **Motion of Blocks Connected by Mass Less String**

Condition	Free body diagram	Equation	Tension and acceleration
$egin{array}{cccccccccccccccccccccccccccccccccccc$	$m_1a$ $m_1$ $T$	$T = m_1 a$	$a = \frac{F}{m_1 + m_2}$
$m_1$ $m_2$	$ \begin{array}{c}  & \xrightarrow{m_2 a} \\  & \xrightarrow{T} & \xrightarrow{m_2} & F \end{array} $	$F - T = m_2 a$	$T = \frac{m_1 F}{m_1 + m_2}$
B A	$ \begin{array}{c}  & m_1 a \\  & F \\ \hline  & m_1 \end{array} $	$F - T = m_1 a$	$a = \frac{F}{m_1 + m_2}$
$F$ $m_1$ $T$ $m_2$	$T \qquad m_2 a \qquad m_2 a \qquad m_2$	$T = m_2 a$	$T = \frac{m_2 F}{m_1 + m_2}$
	$\xrightarrow{m_1 a} \xrightarrow{T_1}$	$T_1 = m_1 a$	$a = \frac{F}{m_1 + m_2 + m_3}$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c}                                     $	$T_2 - T_1 = m_2 a$	$T_1 = \frac{m_1 F}{m_1 + m_2 + m_3}$
	$ \begin{array}{c c}  & \underline{m_3a} \\ \hline  & T_2 \\ \hline  & m_3 \end{array} $	$F - T_2 = m_3 a$	$T_2 = \frac{(m_1 + m_2)F}{m_1 + m_2 + m_3}$
	$ \begin{array}{c c} \hline  & m_1 a \\ \hline  & m_1 \end{array} $	$F - T_1 = m_1 a$	$a = \frac{F}{m_1 + m_2 + m_3}$
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c c} \hline  & m_2 a \\ \hline  & m_2 \\ \hline  & m_2 \end{array} $	$T_1 - T_2 = m_2 a$	$T_1 = \frac{(m_2 + m_3)F}{m_1 + m_2 + m_3}$
	$T_2$ $m_3a$ $m_3$	$T_2 = m_3 a$	$T_2 = \frac{m_3 F}{m_1 + m_2 + m_3}$

# **Motion of Connected Block Over a Pulley**

Condition	Free body diagram	Equation	Tension and acceleration
$P$ $T_1$	$\uparrow T_1 \\ m_1 \uparrow m_1 a$ $\downarrow m_1 g$	$m_1 a = T_1 - m_1 g$	$T_1 = \frac{2m_1 m_2}{m_1 + m_2} g$
$a \uparrow \boxed{\begin{array}{c} T_1 \\ m_1 \end{array}} \downarrow T_1$ $A \boxed{\begin{array}{c} m_2 \\ B \end{array}} \downarrow a$	$\uparrow T_1$ $m_2 \downarrow m_2 a$ $\downarrow m_2 g$	$m_2 a = m_2 g - T_1$	$T_2 = \frac{4m_1m_2}{m_1 + m_2}g$
В	$T_1$ $T_1$	$T_2 = 2T_1$	$a = \left[\frac{m_2 - m_1}{m_1 + m_2}\right] g$
$T_3$	$T_1$ $m_1$ $m_1$ $m_1g$	$m_1 a = T_1 - m_1 g$	$T_1 = \frac{2m_1[m_2 + m_3]}{m_1 + m_2 + m_3} g$
$p$ $T_1$ $M_1$ $T_1$ $M_2$	$ \uparrow T_1  m_2 \downarrow m_2 a  \downarrow m_2 g + T_2 $	$m_2 a = m_2 g + T_2 - T_1$	$T_2 = \frac{2m_1 m_3}{m_1 + m_2 + m_3} g$
$B \downarrow T_2$ $m_3 \downarrow a$ $C$	$ \begin{array}{c} \uparrow T_2 \\ m_3 \downarrow m_3 a \\ \downarrow m_3 g \end{array} $	$m_3 a = m_3 g - T_2$	$T_3 = \frac{4m_1[m_2 + m_3]}{m_1 + m_2 + m_3} g$
	$T_3$ $T_1$ $T_1$	$T_3 = 2T_1$	$a = \frac{[(m_2 + m_3) - m_1]g}{m_1 + m_2 + m_3}$

# $oldsymbol{S}$ ample problems based on lift

- **Problem 33.** A man weighs 80kg. He stands on a weighing scale in a lift which is moving upwards with a uniform acceleration of  $5m/s^2$ . What would be the reading on the scale.  $(g = 10m/s^2)$ 
  - (a) 400 N
- (b) 800 N
- (c) 1200 N
- (d) Zero
- Solution: (c) Reading of weighing scale = m(g + a) = 80(10 + 5) = 1200 N
- **Problem 34.** A body of mass 2 kg is hung on a spring balance mounted vertically in a lift. If the lift descends with an acceleration equal to the acceleration due to gravity 'g', the reading on the spring balance will be
  - (a) 2 kg
- (b)  $(4 \times g) kg$
- (c)  $(2 \times g) kg$
- (d) Zero

- Solution : (d)
- R = m(g a) = (g g) = 0
- [because the lift is moving downward with a = g]
- **Problem 35.** In the above problem, if the lift moves up with a constant velocity of 2 *m/sec*, the reading on the balance will Be

(a) 2 kg

(b) 4 kg

(c) Zero

(d) 1 kg

Solution: (a) R = mg = 2g Newton or 2kg [because the lift is moving with the zero acceleration]

Condition	Free body diagram	Equation	Tension and acceleration
When pulley have a finite mass <i>M</i> and radius <i>R</i> then tension in two segments of string are different	$ \uparrow T_1 \\ m_1 \downarrow m_1 a $ $ \downarrow m_1 g$	$m_1 a = m_1 g - T_1$	$a = \frac{m_1 - m_2}{m_1 + m_2 + \frac{M}{2}}$
$T_2$	$egin{pmatrix} igwedge T_2 \ m_2 \ igwedge m_2 g \ \end{pmatrix} m_2 a$	$m_2 a = T_2 - m_2 g$	$T_1 = \frac{m_1 \left[ 2m_2 + \frac{M}{2} \right]}{m_1 + m_2 + \frac{M}{2}} g$
$T_2$ $M_2$ $T_1$ $B$ $M_1$ $A$	$T_2$ $T_1$	Torque = $(T_1 - T_2)R = I\alpha$ $(T_1 - T_2)R = I\frac{a}{R}$ $(T_1 - T_2)R = \frac{1}{2}MR^2\frac{a}{R}$ $T_1 - T_2 = \frac{Ma}{2}$	$T_2 = \frac{m_2 \left[ 2m_1 + \frac{M}{2} \right]}{m_1 + m_2 + \frac{M}{2}} g$
$A \longrightarrow T \longrightarrow P$	$ \begin{array}{c} m_1 a \\ \longrightarrow \\ m_1 \end{array} $	$T = m_1 a$	$a = \frac{m_2}{m_1 + m_2} g$
$T$ $m_2$ $\downarrow a$ $B$	$\uparrow T$ $m_2$ $\downarrow m_2 a$ $\downarrow m_2 g$	$m_2 a = m_2 g - T$	$T = \frac{m_1 m_2}{m_1 + m_2} g$
T $T$ $T$ $T$	$m_1 a$ $m_1 g \sin \theta$ $m_1 \theta$	$m_1 a = T - m_1 g \sin \theta$	$a = \left[\frac{m_2 - m_1 \sin \theta}{m_1 + m_2}\right] g$
$m_1$ $\theta$ $m_2$ $d$ $d$	$T$ $m_2$ $\downarrow m_2 a$ $\downarrow m_2 g$	$m_2a = m_2g - T$	$T = \frac{m_1 m_2 (1 + \sin \theta)}{m_1 + m_2} g$
	$m_1 a$ $m_1$ $m_1 g \sin \alpha$ $m_2$ $m_3$ $m_4$ $m_5$ $m_5$ $m_5$ $m_6$ $m_6$ $m_7$ $m_8$ $m_$	$T - m_1 g \sin \alpha = m_1 a$	$a = \frac{(m_2 \sin \beta - m_1 \sin \alpha)}{m_1 + m_2} g$
	$m_2$ $m_3$ $m_4$ $m_2$ $m_3$ $m_4$ $m_4$ $m_5$	$m_2 a = m_2 g \sin \beta - T$	$T = \frac{m_1 m_2 (\sin \alpha + \sin \beta)}{m_1 + m_2} g$

Condition	Free body diagram	Equation	Tension and acceleration
	$m_1g\sin\theta$ $m_1$ $m_2$ $m_3$	$m_1 g \sin \theta - T = m_1 a$	$a = \frac{m_1 g \sin \theta}{m_1 + m_2}$
a $B$ $T$ $B$	$m_2a$ $T$ $m_2$	$T = m_2 a$	$T = \frac{2m_1m_2}{4m_1 + m_2}g$
$A \xrightarrow{a_1} P$ $T \xrightarrow{P} T$	$ \begin{array}{c} m_1 a \\ \longrightarrow \\ m_1 \longrightarrow T \end{array} $	$T = m_1 a$	$a_1 = a = \frac{2m_2g}{4m_1 + m_2}$
As $\frac{d^2(x_2)}{dt^2}$ $= \frac{1}{2} \frac{d^2(x_1)}{dt^2}$ $\therefore a_2 = \frac{a_1}{2}$ $a_1 = \text{acceleration of block}$ $A$ $a_2 = \text{acceleration of block}$ $B$	$ \uparrow_{m_2}^{2T} \downarrow_{m_2(a/2)} $ $ \downarrow_{m_2g}$	$m_2 \frac{a}{2} = m_2 g - 2T$	$a_2 = \frac{m_2 g}{4m_1 + m_2}$ $T = \frac{2m_1 m_2 g}{4m_1 + m_2}$
$C \longrightarrow M \longrightarrow T_1$	$T_1$ $m_1$ $m_1$ $m_1$	$m_1 a = m_1 g - T_1$	$a = \frac{(m_1 - m_2)}{[m_1 + m_2 + M]}g$
$T_2$ $a \uparrow m_2$ $B$ $T_1$ $M_1 \downarrow a$	$\uparrow^{T_2}$ $m_2$ $\uparrow$ $m_2a$ $\downarrow$ $m_2g$	$m_2 a = T_2 - m_2 g$	$T_1 = \frac{m_1(2m_2 + M)}{[m_1 + m_2 + M]} g$
	$T_2 \longleftrightarrow M \longrightarrow T_1$	$T_1 - T_2 = Ma$	$T_2 = \frac{m_2(2m_2 + M)}{[m_1 + m_2 + M]}g$

- **Problem 36.** If the lift in problem, moves up with an acceleration equal to the acceleration due to gravity, the reading on the spring balance will be
  - (a) 2 kg
- (b)  $(2 \times q) kq$
- (c)  $(4 \times g) kg$
- (d) 4 kg

- Solution: (d)
- R = m(g+a) = m(g+g)
- [because the lift is moving upward with a = g]

=2mg  $R=2\times 2g$  N=4g N or 4kg

- **Problem 37.** A man is standing on a weighing machine placed in a lift, when stationary, his weight is recorded as 40 kg. If the lift is accelerated upwards with an acceleration of  $2m/s^2$ , then the weight recorded in the machine will be  $(g = 10 \, m \, / \, s^2)$ 
  - (a) 32 kg
- (b) 40 kg
- (c) 42 kg
- (d) 48 kg

R = m(g + a) = 40(10 + 2) = 480 N or 48kgSolution : (d)

- **Problem 38.** An elevator weighing 6000 kg is pulled upward by a cable with an acceleration of  $5ms^{-2}$ . Taking g to be  $10ms^{-2}$ , then the tension in the cable is [Manipal MEE 1995]
  - (a) 6000 N
- (b) 9000 N
- (c) 60000 N
- (d) 90000 N

T = m(g + a) = 6000 (10 + 5) T = 90,000 NSolution: (d)

- **Problem 39.** The ratio of the weight of a man in a stationary lift and when it is moving downward with uniform acceleration 'a' is 3:2. The value of 'a' is (g- Acceleration due to gravity on the earth)
  - (a)  $\frac{3}{2}g$

- (c)  $\frac{2}{3}g$
- (d) g

 $\frac{\text{weight of a man in stationary lift}}{\text{weight of a man in downward moving lift}} = \frac{mg}{m(g-a)} = \frac{3}{2}$ Solution: (b)

$$\therefore \frac{g}{g-a} = \frac{3}{2} \implies 2g = 3g - 3a \text{ or } a = \frac{g}{3}$$

- **Problem 40.** A 60 kg man stands on a spring scale in the lift. At some instant he finds, scale reading has changed from 60 kg to 50 kg for a while and then comes back to the original mark. What should we conclude
  - (a) The lift was in constant motion upwards
  - (b) The lift was in constant motion downwards
  - (c) The lift while in constant motion upwards, is stopped suddenly
  - (d) The lift while in constant motion downwards, is suddenly stopped
- For retarding motion of a lift R = m(g + a) for downward motion Solution: (c)

$$R = m(g - a)$$
 for upward motion

Since the weight of the body decrease for a while and then comes back to original value it means the lift was moving upward and stops suddenly.

**Note**:  $\square$  Generally we use R = m(g + a) for upward motion

R = m(g - a) for downward motion

here a= acceleration, but for the given problem a= retardation

- A bird is sitting in a large closed cage which is placed on a spring balance. It records a weight placed on a spring balance. It records a weight of 25 N. The bird (mass = 0.5kq) flies upward in the cage with an acceleration of  $2m/s^2$ . The spring balance will now record a weight of
- (b) 25 N
- (c) 26 N
- Solution: (b) Since the cage is closed and we can treat bird cage and air as a closed (Isolated) system. In this condition the force applied by the bird on the cage is an internal force due to this reading of spring balance will not change.

- **Problem 42.** A bird is sitting in a wire cage hanging from the spring balance. Let the reading of the spring balance be  $W_1$ . If the bird flies about inside the cage, the reading of the spring balance is  $W_2$ . Which of the following is true
  - (a)  $W_1 = W_2$

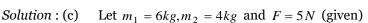
(b)  $W_1 > W_2$ 

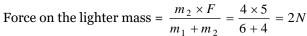
(c)  $W_1 < W_2$ 

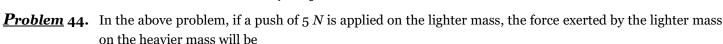
- (d) Nothing definite can be predicted
- In this problem the cage is wire-cage the momentum of the system will not be conserved and due to this Solution: (b) the weight of the system will be lesser when the bird is flying as compared to the weight of the same system when bird is resting is  $W_2 < W_1$ .

# Sample problems based on motion of blocks in contact

- **<u>Problem</u>** 43. Two blocks of mass 4 kg and 6 kg are placed in contact with each other on a frictionless horizontal surface. If we apply a push of 5 N on the heavier mass, the force on the lighter mass will be
  - (a) 5 N
  - (b) 4 N
  - (c) 2N
  - (d) None of the above







- (a) 5N
- (c) 2N

(d) None of the above

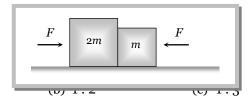
Solution: (d) Force on the heavier mass  $=\frac{m_1F}{m_1+m_2}=\frac{6\times 5}{6+4}=3N$ 

**Problem** 45. In the above problem, the acceleration of the lighter mass will be

- (b)  $\frac{5}{4} ms^{-2}$  (c)  $\frac{5}{6} ms^{-2}$
- (d) None of the above

(a)  $0.5 \, ms^{-2}$  (b)  $\frac{5}{4} \, ms^{-2}$  (c)  $\frac{5}{6}$ Acceleration =  $\frac{\text{Net force on the system}}{\text{Total mass of the system}} = \frac{5}{10} = 0.5 \, m/s^2$ Solution: (a)

**Problem** 46. Two blocks are in contact on a frictionless table one has a mass m and the other 2 m as shown in figure. Force F is applied on mass 2m then system moves towards right. Now the same force F is applied on m. The ratio of force of contact between the two blocks will be in the two cases respectively.



(a) 1:1

(d) 1:4

When the force is applied on mass 2m contact force  $f_1 = \frac{m}{m+2m}g = \frac{g}{3}$ Solution: (b)

When the force is applied on mass m contact force  $f_2 = \frac{2m}{m+2m}g = \frac{2}{3}g$ 

Ratio of contact forces  $\frac{f_1}{f_2} = \frac{1}{2}$ 

# $oldsymbol{S}$ ample problems based on motion of blocks connected by mass less string

- **Problem** 47. A monkey of mass 20 kg is holding a vertical rope. The rope will not break when a mass of 25 kg is suspended from it but will break if the mass exceeds 25 kg. What is the maximum acceleration with which the monkey can climb up along the rope  $(g = 10m/s^2)$ 
  - (a)  $10 \, m \, / \, s^2$
- (b)  $25 m/s^2$
- (c)  $2.5m/s^2$
- (d)  $5m/s^2$
- Solution: (c) Maximum tension that string can bear  $(T_{max}) = 25 \times g N = 250 N$

Tension in rope when the monkey climb up T = m(g + a)

Tension in tope when the monkey emilioup T = m(g + u)

For limiting condition  $T = T_{\text{max}} \implies m(g+a) = 250 \implies 20 (10+a) = 250$   $\therefore a = 2.5 \, \text{m/s}^2$ 

- **Problem** 48. Three blocks of masses 2 kg, 3 kg and 5 kg are connected to each other with light string and are then placed on a frictionless surface as shown in the figure. The system is pulled by a force F = 10N, then tension  $T_1 = 0$ 
  - (a) 1N

- (b) 5 N
- (c) 8N

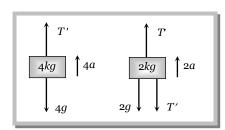
- (d) 10 N
- Solution: (c) By comparing the above problem with general expression.  $T_1 = \frac{(m_2 + m_3)F}{m_1 + m_2 + m_3} = \frac{(3+5)10}{2+3+5} = 8$  Newton
- **Problem** 49. Two blocks are connected by a string as shown in the diagram. The upper block is hung by another string. A force F applied on the upper string produces an acceleration of  $2m/s^2$  in the upward direction in both the blocks. If T and T' be the tensions in the two parts of the string, then [AMU (Engg.) 2000]
  - (a) T = 70.8 N and T' = 47.2 N
  - (b) T = 58.8N and T' = 47.2N
  - (c) T = 70.8N and T' = 58.8N
  - (d) T = 70.8N and T' = 0
- Solution: (a) From F.B.D. of mass 4 kg 4a = T 4g .....(i)
  - From F.B.D. of mass 2 kg 2a = T T 2g .....(ii)

For total system upward force

$$F = T = (2+4)(g+a) = 6(18+2)N = 70.8 \text{ N}$$

by substituting the value of T in equation (i) and (ii)

and solving we get T' = 47.2N



- **Problem 50.** Three masses of 15 kg. 10 kg and 5 kg are suspended vertically as shown in the fig. If the string attached to the support breaks and the system falls freely, what will be the tension in the string between 10 kg and 5 kg masses. Take  $g = 10 \text{ ms}^{-2}$ . It is assumed that the string remains tight during the motion
  - (a) 300 N
- (b) 250 N
- (c) 50 N
- (d) Zero

- Solution: (d) In the condition of free fall, tension becomes zero.
- **Problem** 51. A sphere is accelerated upwards with the help of a cord whose breaking strength is five times its weight. The maximum acceleration with which the sphere can move up without cord breaking is
  - (a) 4g

- (b) 3q
- (c) 2q

- (d) q
- Solution: (a) Tension in the cord = m(q + a) and breaking strength = 5 mq

For critical condition  $m(g+a)=5mg \implies a=4g$ 

This is the maximum acceleration with which the sphere can move up with cord breaking.

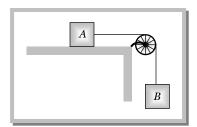
# Sample problems based on motion of blocks over pulley

- A light string passing over a smooth light pulley connects two blocks of masses  $m_1$  and  $m_2$  (vertically). If the acceleration of the system is g/8 then the ratio of the masses is
  - (a) 8:1

(d) 5:3

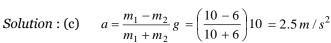
Solution: (b) 
$$a = \left(\frac{m_2 - m_1}{m_1 + m_2}\right)g = \frac{g}{8};$$
 by solving  $\frac{m_2}{m_1} = 9/7$ 

- **Problem** 53. A block A of mass 7 kg is placed on a frictionless table. A thread tied to it passes over a frictionless pulley and carries a body B of mass 3 kg at the other end. The acceleration of the system is (given  $g = 10 \, ms^{-2}$ )
  - (a)  $100 \text{ ms}^{-2}$
  - (b)  $3ms^{-2}$
  - (c)  $10ms^{-2}$
  - (d)  $30ms^{-2}$
- Solution: (b)  $a = \left(\frac{m_2}{m_1 + m_2}\right) g = \left(\frac{3}{7 + 3}\right) 10 = 3m / s^2$



 $m_2 \mid 6 kq$ 

- **Problem** 54. Two masses  $m_1$  and  $m_2$  are attached to a string which passes over a frictionless smooth pulley. When  $m_1 = 10 \, kg$ ,  $m_2 = 6 \, kg$ , the acceleration of masses is
  - (a)  $20 m/s^2$
  - (b)  $5m/s^2$
  - (c)  $2.5 m/s^2$
  - (d)  $10 \, m \, / \, s^2$



- **Problem** 55. Two weights  $W_1$  and  $W_2$  are suspended from the ends of a light string passing over a smooth fixed pulley. If the pulley is pulled up with an acceleration g, the tension in the string will be
  - (a)  $\frac{4W_1W_2}{W_1 + W_2}$
- (b)  $\frac{2W_1W_2}{W_1 + W_2}$  (c)  $\frac{W_1W_2}{W_1 + W_2}$

 $10 kg m_1$ 

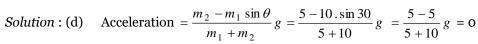
- (d)  $\frac{W_1W_2}{2(W_1+W_2)}$
- When the system is at rest tension in string  $T = \frac{2m_1m_2}{(m_1 + m_2)}g$ Solution: (a)

If the system moves upward with acceleration g then  $T = \frac{2m_1m_2}{m_1 + m_2}(g + g) = \frac{4m_1m_2}{m_1 + m_2}g$  or  $T = \frac{4w_1w_2}{w_1 + w_2}$ 

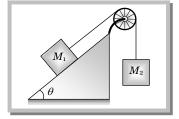
**Problem 56.** Two masses  $M_1$  and  $M_2$  are attached to the ends of a string which passes over a pulley attached to the top of an inclined plane. The angle of inclination of the plane in  $\theta$ . Take  $q = 10 \text{ ms}^{-2}$ .

If  $M_1 = 10 \text{ kg}$ ,  $M_2 = 5 \text{ kg}$ ,  $\theta = 30^\circ$ , what is the acceleration of mass  $M_2$ 

- (a)  $10ms^{-2}$
- (b)  $5ms^{-2}$
- (c)  $\frac{2}{3}ms^{-2}$



- **Problem** 57. In the above problem, what is the tension in the string
  - (a) 100 N



- (b) 50 N

- $T = \frac{m_1 m_2 (1 + \sin \theta)}{m_1 + m_2} g = \frac{10 \times 5 (1 + \sin 30).10}{10 + 5} = 50 N$ Solution: (b)
- **Problem** 58. In the above problem, given that  $M_2 = 2M_1$  and  $M_2$  moves vertically downwards with acceleration a. If the position of the masses are reversed the acceleration of  $M_2$  down the inclined plane will be
  - (a) 2 a

(b) a

- (c) a/2
- (d) None of the above
- If  $m_2 = 2m_1$ , then  $m_2$  moves vertically downward with acceleration Solution: (d)

$$a = \frac{m_2 - m_1 \sin \theta}{m_1 + m_2} g = \frac{2m_1 - m_1 \sin 30}{m_1 + 2m_1} g = g/2$$

If the position of masses are reversed then  $m_2$  moves downward with acceleration

$$a' = \frac{m_2 \sin \theta - m_1}{m_1 + m_2} g = \frac{2m_1 \sin 30 - m_1}{m_1 + 2m_1} . g = 0$$
 [As  $m_2 = 2m_1$ ]

*i.e.* the  $m_2$  will not move.

- **Problem** 59. In the above problem, given that  $M_2 = 2M_1$  and the tension in the string is T. If the positions of the masses are reversed, the tension in the string will be

- (c) T

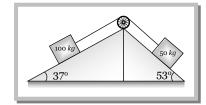
(d) T/2

Tension in the string  $T = \frac{m_1 m_2 (1 + \sin \theta)}{m_1 + m_2} g$ Solution: (c)

If the position of the masses are reversed then there will be no effect on tension.

- **Problem 60.** In the above problem, given that  $M_1 = M_2$  and  $\theta = 30^\circ$ . What will be the acceleration of the system
  - (a)  $10ms^{-2}$
- (b)  $5ms^{-2}$
- (c)  $2.5ms^{-2}$
- (d) Zero
- $a = \frac{m_2 m_1 \sin \theta}{m_1 + m_2} g = \frac{1 \sin 30}{2} g = \frac{g}{4} = 2.5 \, m / s^2 \qquad [\text{As } m_1 = m_2]$ Solution: (c)
- **Problem** 61. In the above problem, given that  $M_1 = M_2 = 5 kg$  and  $\theta = 30^{\circ}$ . What is tension in the string
- (c) 12.5 N
- (d) Zero

- Solution: (a)  $T = \frac{m_1 m_2 (1 + \sin \theta)}{m_1 + m_2} g = \frac{5 \times 5 (1 + \sin 30)}{5 + 5} \times 10 = 37.5 N$
- **Problem** 62. Two blocks are attached to the two ends of a string passing over a smooth pulley as shown in the figure. The acceleration of the block will be (in  $m/s^2$ ) (sin  $37^\circ = 0.60$ , sin  $53^\circ = 0.80$ )
  - (a) 0.33
  - (b) 0.133
  - (c) 1
  - (d) 0.066
- $a = \frac{m_2 \sin \beta m_1 \sin \alpha}{m_1 + m_2} g = \frac{50 \sin 53^\circ 100 \sin 37^\circ}{100 + 50} g = -0.133 \, m / s^2$ Solution: (b)



- **Problem** 63. The two pulley arrangements shown in the figure are identical. The mass of the rope is negligible. In (a) the mass m is lifted up by attaching a mass 2m to the other end of the rope. In (b), m is lifted up by pulling the other end of the rope with a constant downward force of 2mg.
  - The ratio of accelerations in two cases will be
  - (a) 1:1
- (b) 1:2
- (c) 1:3
- For first case  $a_1 = \frac{m_2 m_1}{m_1 + m_2} g = \frac{2m m}{m + 2m} = \frac{g}{3}$ Solution: (c)

from free body diagram of m







$$ma_2 = T - mg$$

$$ma_2 = 2mg - mg$$

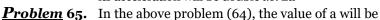
[As 
$$T=2mq$$
]

 $a_2 = g$  ......(ii)

From (i) and (ii)  $\frac{a_1}{a_2} = \frac{g/3}{g} = 1/3$ 

- **Problem** 64. In the adjoining figure  $m_1 = 4m_2$ . The pulleys are smooth and light. At time t = 0, the system is at rest. If the system is released and if the acceleration of mass  $m_1$  is a, then the acceleration of  $m_2$  will be
  - (a) g
  - (b) *a*
  - (c)  $\frac{a}{2}$
  - (d) 2a

Solution : (d) Since the mass  $m_2$  travels double distance in comparison to mass  $m_1$  therefore its acceleration will be double *i.e.* 2a



(a) g

- (b)  $\frac{g}{2}$
- (c)  $\frac{g}{4}$

(d)  $\frac{g}{8}$ 

 $m_1 \uparrow m_1 a$ 

Solution : (c) By drawing the FBD of  $m_1$  and  $m_2$ 

$$m_1 a = m_1 g - 2T$$

....(i)

$$m_2(2a) = T - m_2 g$$

....(ii)

by solving these equation a = g/4

**Problem 66.** In the above problem, the tension *T* in the string will be

- (a)  $m_2g$
- (b)  $\frac{m_2 g}{2}$
- (c)  $\frac{2}{3}m_2g$
- (d)  $\frac{3}{2}m_2g$

 $m_2$   $m_2(2a)$ 

Solution: (d) From the solution (65) by solving equation

$$T = \frac{3}{2}m_2g$$

**Problem** 67. In the above problem, the time taken by  $m_1$  in coming to rest position will be

- (a) 025
- (b) 0.4 s
- (c) 0.6 s
- (d) 0.8 s

Solution: (b) Time taken by mass  $m_2$  to cover the distance 20 cm

$$t = \sqrt{\frac{2h}{a}} = \sqrt{\frac{2 \times 0.2}{g/4}} = \sqrt{\frac{2 \times 0.2}{2.5}} = 0.4 \text{ sec}$$

**Problem 68.** In the above problem, the distance covered by  $m_2$  in 0.4 s will be

- (a) 40 cm
- (b) 20 cm
- (c) 10 cm
- (d) 80 cm

Solution: (a) Since the  $m_2$  mass cover double distance therefore  $S = 2 \times 20 = 40$  cm

**Problem 69.** In the above problem, the velocity acquired by  $m_2$  in 0.4 second will be

- (a) 100 cm/s
- (b) 200 cm/s
- (c)  $300 \, cm/s$
- (d) 400 cm/s

Solution: (b) Velocity acquired by mass  $m_2$  in 0.4 sec

From 
$$v = u + at$$

[As 
$$a = g/2 = \frac{10}{2} = 5 m/s^2$$
]

$$v = 0 + 5 \times 0.4 = 2m / s = 200 cm / sec.$$

**Problem** 70. In the above problem, the additional distance traversed by  $m_2$  in coming to rest position will be

- (a) 20 cm
- (b) 40 cm
- (c) 60 cm
- (d) 80 cm

Solution: (a) When  $m_2$  mass acquired velocity 200 cm/sec it will move upward till its velocity becomes zero.

$$H = \frac{u^2}{2g} = \frac{(200)^2}{2 \times 100} = 20 \ cm$$

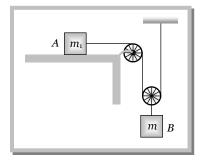
Problem 71. The acceleration of block B in the figure will be

(a) 
$$\frac{m_2 g}{(4m_1 + m_2)}$$

(b) 
$$\frac{2m_2g}{(4m_1+m_2)}$$

(c) 
$$\frac{2m_1g}{(m_1+4m_2)}$$

(d) 
$$\frac{2m_1g}{(m_1+m_2)}$$



When the block  $m_2$  moves downward with acceleration a, the acceleration of mass  $m_1$  will be 2a because Solution: (a) it covers double distance in the same time in comparison to  $m_2$ .

Let *T* is the tension in the string.

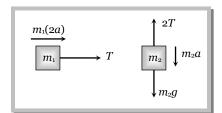
By drawing the free body diagram of A and B

$$T = m_1 2a$$

$$m_2g - 2T = m_2a$$
 ......(ii)

by solving (i) and (ii)

$$a = \frac{m_2 g}{\left(4m_1 + m_2\right)}$$



Constrained motion will be continued in class notes

# **Motion of Massive String**

Condition	Free body diagram	Equation	Tension and acceleration
$ \begin{array}{c} m \\ M \end{array} \longrightarrow F $	$ \begin{array}{c} \xrightarrow{a} \\ M \longrightarrow T_1 \end{array} $ $ T_1 = \text{force applied by the string on the block} $	$F = (M + m)a$ $T_1 = Ma$	$a = \frac{F}{M+m}$ $T_1 = M \frac{F}{(M+m)}$
	$T_2 = \text{Tension at mid point}$ of the rope	$T_2 = \left(M + \frac{m}{2}\right)a$	$T_2 = \frac{(2M+m)}{2(M+m)}F$
$ \begin{array}{ccc} & L & \longrightarrow \\ & & \downarrow & \downarrow \\ & & \downarrow & \downarrow & \downarrow \end{array} $	$ \begin{array}{c} m \\ a \\ \rightarrow \end{array} $	F = ma	a = F/m
n = Mass of string T = Tension in string at a distance x from the end where the force is applied	$m\left[(L-x)/L\right] \longrightarrow T$	$T = m \left(\frac{L - x}{L}\right) a$	$T = \left(\frac{L - x}{L}\right) F$
$F_2 \longleftrightarrow L \longrightarrow F_1$ $A \leftarrow X \rightarrow B$	$T \xleftarrow{A \xrightarrow{(M/L)x} B} \longrightarrow F_1$ $\xrightarrow{a} \longrightarrow$	$F_1 - T = \frac{Mxa}{L}$	$a = \frac{F_1 - F_2}{M}$
M = Mass of uniform rod L = Length of rod	$ \begin{array}{cccc} F_2 & M & F_1 \\ & & & & \\ & & & & \\ & & & & \\ & & & & $	$F_1 - F_2 = Ma$	$T = F_1 \left( 1 - \frac{x}{L} \right) + F_2 \left( \frac{x}{L} \right)$
		$T = \left(\frac{L - x}{L}\right) F$	$T = \left(\frac{L - x}{L}\right) F$
Mass of segment $BC$ $= \left(\frac{M}{L}\right) x$			