```
# Code originally written on kaggle
import h5py
import numpy as np
import torch
import random
from tqdm import tqdm
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
print(f"Using device: {device}")
# Paths
file_path = "/kaggle/input/quark-gluon/quark-gluon_data-
set_n139306.hdf5"
output_file = "/kaggle/working/point cloud dataset.pt"
# Image dimensions
H, W = 125, 125
x coords np, y coords np = np.meshgrid(np.linspace(0, 1, W),
np.linspace(0, 1, H))
x coords = torch.tensor(x coords np, dtype=torch.float32,
device=device)
y coords = torch.tensor(y coords np, dtype=torch.float32,
device=device)
with h5py.File(file path, "r") as f:
    X_{jets} = f["X_{jets}"]
    m0 = f["m0"]
    pt = f["pt"]
    y = f["y"]
    total events = X jets.shape[0]
    num samples = min(50000), total events) # Limiting to 50,000
samples
    random.seed(42)
    selected indices = sorted(random.sample(range(total events),
num samples))
    print(f"Processing {num samples} randomly selected samples out of
{total events} available.")
    dataset = {"point clouds": [], "labels": []}
    batch size = 5000
    for start in tqdm(range(0, num samples, batch size),
desc="Processing Batches"):
        end = min(start + batch size, num samples)
        batch indices = selected indices[start:end]
```

```
X batch = torch.tensor(X jets[batch indices],
dtype=torch.float32, device=device)
        m0 batch = torch.tensor(m0[batch indices],
dtype=torch.float32, device=device)
        pt batch = torch.tensor(pt[batch indices],
dtype=torch.float32, device=device)
        y batch = torch.tensor(y[batch indices], dtype=torch.float32,
device=device)
        for i in range(end - start):
            nonzero mask = torch.any(X batch[i] > 0, dim=-1)
            nonzero_x = x_coords[nonzero mask]
            nonzero_y = y_coords[nonzero_mask]
            nonzero features = X batch[i][nonzero mask]
            if nonzero x.numel() == 0:
                continue # Skip empty point clouds
            num points = nonzero x.shape[0]
            jet features = torch.stack([
                nonzero_x, nonzero_y,
                nonzero_features[:, 0], nonzero_features[:, 1],
nonzero_features[:, 2],
                torch.full((num points,), m0 batch[i],
dtype=torch.float32, device=device),
                torch.full((num points,), pt batch[i],
dtype=torch.float32, device=device)
            ], dim=1)
            dataset["point clouds"].append(jet features.cpu())
            dataset["labels"].append(y batch[i].cpu())
   torch.save(dataset, output file)
   print(f"Point cloud dataset saved to '{output file}'.")
Using device: cuda
Processing 50000 randomly selected samples out of 139306 available.
Processing Batches: 100% | 10/10 [10:13<00:00, 61.36s/it]
Point cloud dataset saved to '/kaggle/working/point cloud dataset.pt'.
# □ STEP 2: Convert Point Clouds to Graph Dataset
!pip install torch-scatter torch-sparse torch-cluster torch-spline-
conv -f https://data.pyg.org/whl/torch-2.5.0+cu121.html
!pip install torch-geometric
!pip install torch-cluster -f https://data.pyg.org/whl/torch-
2.5.0+cu121.html
import torch
```

```
from torch geometric.data import Data, InMemoryDataset
from torch geometric.nn import knn graph
from tqdm.notebook import tqdm
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
print(f"Using device: {device}")
# Paths
input file = "/kaggle/working/point cloud dataset.pt"
output file = "/kaggle/working/graph dataset.pt"
# Load point cloud dataset
dataset = torch.load(input file)
graph data list = []
for i in tqdm(range(len(dataset["point clouds"])), desc="Processing
Graphs"):
    point cloud = dataset["point clouds"][i]
    label = dataset["labels"][i]
    if point cloud.numel() == 0:
        continue # Skip empty point clouds
    # k-NN Graph Construction (use only spatial features `x, y`)
    k = 8
    edge index = knn graph(point cloud[:, :2], k=k) # Use only (x, y)
for graph structure
    data = Data(x=point_cloud, edge index=edge index, y=label)
    graph data list.append(data)
# □ Define InMemoryDataset wrapper
class GraphDataset(InMemoryDataset):
    def init (self, root=None, data list=None):
        super(). __init__(root)
        if data list:
            self.data, self.slices = self.collate(data list)
    def len (self):
        return len(self.slices["x"]) - 1
# □ Save dataset correctly
graph_dataset = GraphDataset(data_list=graph_data_list)
torch.save(graph dataset, output file)
print(f"Graph dataset saved to '{output file}'.")
Looking in links: https://data.pyg.org/whl/torch-2.5.0+cu121.html
Collecting torch-scatter
  Downloading
```

```
https://data.pvg.org/whl/torch-2.5.0%2Bcu121/torch scatter-
2.1.2%2Bpt25cu121-cp310-cp310-linux x86 64.whl (10.9 MB)
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Requirement already satisfied: intel-cmplr-lib-rt in
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>numpy<2.3,>=1.22.4->scipy->torch-sparse) (2024.2.0)
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/usr/local/lib/python3.10/dist-packages (from intel-openmp>=2024->mkl-
>numpy<2.3,>=1.22.4->scipy->torch-sparse) (2024.2.0)
Installing collected packages: torch-spline-conv, torch-scatter,
torch-sparse, torch-cluster
```

```
Successfully installed torch-cluster-1.6.3+pt25cu121 torch-scatter-
2.1.2+pt25cu121 torch-sparse-0.6.18+pt25cu121 torch-spline-conv-
1.2.2+pt25cu121
Collecting torch-geometric
  Downloading torch geometric-2.6.1-py3-none-any.whl.metadata (63 kB)
                                       - 63.1/63.1 kB 2.9 MB/s eta
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ent already satisfied: aiohttp in /usr/local/lib/python3.10/dist-
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Requirement already satisfied: jinja2 in
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Requirement already satisfied: psutil>=5.8.0 in
/usr/local/lib/python3.10/dist-packages (from torch-geometric) (5.9.5)
Requirement already satisfied: pyparsing in
/usr/local/lib/python3.10/dist-packages (from torch-geometric) (3.2.0)
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/usr/local/lib/python3.10/dist-packages (from torch-geometric)
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Requirement already satisfied: aiohappyeyeballs>=2.3.0 in
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geometric) (25.1.0)
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/usr/local/lib/python3.10/dist-packages (from aiohttp->torch-
geometric) (1.5.0)
Requirement already satisfied: multidict<7.0,>=4.5 in
/usr/local/lib/python3.10/dist-packages (from aiohttp->torch-
geometric) (6.1.0)
Requirement already satisfied: propcache>=0.2.0 in
/usr/local/lib/python3.10/dist-packages (from aiohttp->torch-
geometric) (0.2.1)
Requirement already satisfied: yarl<2.0,>=1.17.0 in
/usr/local/lib/python3.10/dist-packages (from aiohttp->torch-
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geometric) (1.18.3)
Requirement already satisfied: MarkupSafe>=2.0 in
/usr/local/lib/python3.10/dist-packages (from jinja2->torch-geometric)
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(2022.0.0)
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(2.4.1)
Requirement already satisfied: charset-normalizer<4,>=2 in
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Requirement already satisfied: certifi>=2017.4.17 in
/usr/local/lib/python3.10/dist-packages (from requests->torch-
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>numpy->torch-geometric) (2024.2.0)
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Requirement already satisfied: torch-cluster in
/usr/local/lib/python3.10/dist-packages (1.6.3+pt25cu121)
Requirement already satisfied: scipy in
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Requirement already satisfied: numpy<2.3,>=1.22.4 in
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>scipy->torch-cluster) (1.3.8)
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>scipy->torch-cluster) (1.2.4)
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Requirement already satisfied: intel-cmplr-lib-ur==2024.2.0 in
/usr/local/lib/python3.10/dist-packages (from intel-openmp>=2024->mkl-
>numpy<2.3,>=1.22.4->scipy->torch-cluster) (2024.2.0)
Using device: cuda
```

```
<ipython-input-2-ebd000c1c252>:19: FutureWarning: You are using
`torch.load` with `weights only=False` (the current default value),
which uses the default pickle module implicitly. It is possible to
construct malicious pickle data which will execute arbitrary code
during unpickling (See
https://github.com/pytorch/pytorch/blob/main/SECURITY.md#untrusted-
models for more details). In a future release, the default value for
`weights_only` will be flipped to `True`. This limits the functions
that could be executed during unpickling. Arbitrary objects will no
longer be allowed to be loaded via this mode unless they are
explicitly allowlisted by the user via
`torch.serialization.add_safe_globals`. We recommend you start setting
`weights_only=True` for any use case where you don't have full control
of the loaded file. Please open an issue on GitHub for any issues
related to this experimental feature.
  dataset = torch.load(input file)
{"model id": "b75f42077d434e4681d1cbe48ecc2bc0", "version major": 2, "vers
ion minor":0}
Graph dataset saved to '/kaggle/working/graph dataset.pt'.
dataset = torch.load("/kaggle/working/graph dataset.pt",
map location="cpu")
print(dataset) # Should print dataset details
# Check dataset samples
print(len(dataset))
print(dataset[0]) # Check a sample graph
<ipython-input-3-300146acecel>:1: FutureWarning: You are using
`torch.load` with `weights only=False` (the current default value),
which uses the default pickle module implicitly. It is possible to
construct malicious pickle data which will execute arbitrary code
during unpickling (See
https://github.com/pytorch/pytorch/blob/main/SECURITY.md#untrusted-
models for more details). In a future release, the default value for
`weights only` will be flipped to `True`. This limits the functions
that could be executed during unpickling. Arbitrary objects will no
longer be allowed to be loaded via this mode unless they are
explicitly allowlisted by the user via
`torch.serialization.add safe globals`. We recommend you start setting
`weights only=True` for any use case where you don't have full control
of the loaded file. Please open an issue on GitHub for any issues
related to this experimental feature.
  dataset = torch.load("/kaggle/working/graph dataset.pt",
map location="cpu")
```

```
GraphDataset(50000)
50000
Data(x=[515, 7], edge index=[2, 4120], y=[1])
import torch
import torch.nn.functional as F
from torch geometric.nn import GINConv, global mean pool
from torch geometric.data import DataLoader, InMemoryDataset
from sklearn.preprocessing import StandardScaler
from sklearn.model selection import StratifiedShuffleSplit
from sklearn.utils.class weight import compute class weight
from tgdm import tgdm
import numpy as np
from sklearn.metrics import roc auc score
import ac
# Ensure GPU Memory is Cleared
torch.cuda.empty cache()
gc.collect()
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
print(f"Using device: {device}")
# Load Dataset
dataset path = "/kaggle/working/graph dataset.pt"
dataset = torch.load(dataset path, map location="cpu")
# Remove Empty Graphs
dataset = [data for data in dataset if data.edge index.numel() > 0 and
data.x.numel() > 0
assert len(dataset) > 0, "All graphs were found empty after
filtering."
# Split Dataset with Stratification
labels = np.array([data.y.item() for data in dataset])
splitter = StratifiedShuffleSplit(n splits=1, test size=0.2,
random state=42)
train idx, temp idx = next(splitter.split(np.zeros(len(labels)),
labels))
temp labels = labels[temp idx]
splitter = StratifiedShuffleSplit(n splits=1, test size=0.5,
random state=42)
val idx, test idx = next(splitter.split(np.zeros(len(temp labels)),
temp labels))
train dataset = [dataset[i] for i in train idx]
val dataset = [dataset[i] for i in val_idx]
test_dataset = [dataset[i] for i in test_idx]
```

```
# Feature Normalization (Only Fit on Train Data)
scaler = StandardScaler()
train_features = np.vstack([data.x.cpu().numpy().astype(np.float32)
for data in train dataset])
scaler.fit(train features)
for data in dataset:
    data.x = torch.tensor(scaler.transform(data.x.cpu().numpy()),
dtype=torch.float32)
# Compute Class Weights
class weights = compute class weight("balanced",
classes=np.unique(labels), y=labels)
class weights = torch.tensor(class weights,
dtype=torch.float32).to(device)
# Data Loaders
batch size = 16
train loader = DataLoader(train dataset, batch size=batch size,
shuffle=True, num_workers=2, pin_memory=True)
val loader = DataLoader(val dataset, batch size=batch size,
num_workers=2, pin_memory=True)
test_loader = DataLoader(test_dataset, batch_size=batch_size,
num workers=2, pin memory=True)
# GIN Model
class GIN(torch.nn.Module):
    def init (self, in channels, hidden channels=128,
out_channels=1, num_layers=3):
        super(GIN, self). init ()
        self.convs = torch.nn.ModuleList()
        self.batch norms = torch.nn.ModuleList()
        self.dropouts = torch.nn.ModuleList()
        nn1 = torch.nn.Sequential(
            torch.nn.Linear(in channels, hidden channels),
            torch.nn.LeakyReLU(0.1),
            torch.nn.Linear(hidden channels, hidden channels)
        self.convs.append(GINConv(nn1))
        self.batch norms.append(torch.nn.BatchNorm1d(hidden channels))
        self.dropouts.append(torch.nn.Dropout(0.2))
        for _ in range(num layers - 1):
            nn layer = torch.nn.Sequential(
                torch.nn.Linear(hidden channels, hidden channels),
                torch.nn.LeakyReLU(0.1),
                torch.nn.Linear(hidden channels, hidden channels)
            self.convs.append(GINConv(nn layer))
```

```
self.batch norms.append(torch.nn.BatchNorm1d(hidden channels))
            self.dropouts.append(torch.nn.Dropout(0.2))
        self.fc = torch.nn.Linear(hidden channels, out channels)
    def forward(self, x, edge index, batch):
        for conv, bn, do in zip(self.convs, self.batch norms,
self.dropouts):
            x = conv(x, edge index)
            x = bn(x)
            x = F.leaky relu(x, negative slope=0.1)
            x = do(x)
        x = global mean pool(x, batch)
        return self.fc(x).squeeze()
# Initialize Model
model = GIN(in channels=7).to(device)
optimizer = torch.optim.AdamW(model.parameters(), lr=0.0015,
weight decay=5e-5)
scheduler = torch.optim.lr scheduler.ReduceLROnPlateau(optimizer,
mode="max", factor=0.5, patience=5, verbose=True)
criterion = torch.nn.BCEWithLogitsLoss(pos weight=class weights[1])
# Training Function
def train():
    model.train()
    total loss = 0
    pbar = tqdm(train loader, desc="Training", leave=False)
    for data in pbar:
        data = data.to(device)
        optimizer.zero grad()
        output = model(data.x, data.edge index, data.batch)
        loss = criterion(output, data.y.float().view(-1))
        loss.backward()
        torch.nn.utils.clip grad norm (model.parameters(),
max norm=1.0) # Dynamic Gradient Clipping
        optimizer.step()
        total loss += loss.item()
        pbar.set postfix(loss=loss.item())
    return total loss / len(train loader)
# Evaluation Function
def evaluate(loader):
    model.eval()
```

```
total loss = 0
    preds, labels = [], []
    with torch.inference mode():
        pbar = tgdm(loader, desc="Evaluating", leave=False)
        for data in pbar:
            data = data.to(device)
            output = model(data.x, data.edge index, data.batch)
            loss = criterion(output, data.y.float().view(-1))
            total loss += loss.item()
            preds.append(output.sigmoid().cpu())
            labels.append(data.y.cpu())
    if not preds:
        return total loss / len(loader), None, None
    preds = torch.cat(preds).numpy()
    labels = torch.cat(labels).numpy()
    acc = ((preds > 0.5) == labels).mean()
    try:
        auc = roc auc score(labels, preds) if len(set(labels)) > 1
else 0.5
    except ValueError:
        auc = 0.5
    return total loss / len(loader), acc, auc
# Training Loop
num epochs = 50
best val auc = 0
patience = 5
no improve epochs = 0
for epoch in range(num epochs):
    train loss = train()
    val loss, val acc, val auc = evaluate(val loader)
    print(f"Epoch {epoch+1}/{num epochs} - Train Loss:
{train_loss:.4f} - Val Loss: {val_loss:.4f} - Val Acc: {val_acc:.4f} -
Val AUC: {val auc:.4f}")
    scheduler.step(val auc)
    if val auc and val auc > best val auc:
        best val auc = val auc
        torch.save(model.state dict(),
"/kaggle/working/best gin model.pt")
        no improve epochs = 0
    else:
        no improve epochs += 1
    if no improve epochs >= patience:
```

```
print("Early stopping triggered")
        break
torch.cuda.empty cache()
Using device: cuda
<ipython-input-3-856d2b5040e3>:22: FutureWarning: You are using
`torch.load` with `weights only=False` (the current default value),
which uses the default pickle module implicitly. It is possible to
construct malicious pickle data which will execute arbitrary code
during unpickling (See
https://github.com/pytorch/pytorch/blob/main/SECURITY.md#untrusted-
models for more details). In a future release, the default value for
`weights_only` will be flipped to `True`. This limits the functions
that could be executed during unpickling. Arbitrary objects will no
longer be allowed to be loaded via this mode unless they are
explicitly allowlisted by the user via
`torch.serialization.add safe globals`. We recommend you start setting
`weights only=True` for any use case where you don't have full control
of the loaded file. Please open an issue on GitHub for any issues
related to this experimental feature.
  dataset = torch.load(dataset path, map location="cpu")
/usr/local/lib/python3.10/dist-packages/torch geometric/deprecation.py
:26: UserWarning: 'data.DataLoader' is deprecated, use
'loader.DataLoader' instead
 warnings.warn(out)
/usr/local/lib/python3.10/dist-packages/torch/optim/lr scheduler.py:62
: UserWarning: The verbose parameter is deprecated. Please use
get last lr() to access the learning rate.
 warnings.warn(
Epoch 1/50 - Train Loss: 0.5895 - Val Loss: 0.5887 - Val Acc: 0.7094 -
Val AUC: 0.7759
Epoch 2/50 - Train Loss: 0.5812 - Val Loss: 0.5852 - Val Acc: 0.7140 -
Val AUC: 0.7780
Epoch 3/50 - Train Loss: 0.5771 - Val Loss: 0.5867 - Val Acc: 0.7076 -
Val AUC: 0.7791
Epoch 4/50 - Train Loss: 0.5737 - Val Loss: 0.5742 - Val Acc: 0.7128 -
Val AUC: 0.7812
```

- Epoch 5/50 Train Loss: 0.5720 Val Loss: 0.5723 Val Acc: 0.7182 Val AUC: 0.7830
- Epoch 6/50 Train Loss: 0.5693 Val Loss: 0.5704 Val Acc: 0.7140 Val AUC: 0.7812
- Epoch 7/50 Train Loss: 0.5675 Val Loss: 0.5714 Val Acc: 0.7176 Val AUC: 0.7817
- Epoch 8/50 Train Loss: 0.5665 Val Loss: 0.5759 Val Acc: 0.7188 Val AUC: 0.7832
- Epoch 9/50 Train Loss: 0.5661 Val Loss: 0.5646 Val Acc: 0.7174 Val AUC: 0.7858
- Epoch 10/50 Train Loss: 0.5647 Val Loss: 0.7402 Val Acc: 0.5184 Val AUC: 0.7588
- Epoch 11/50 Train Loss: 0.5639 Val Loss: 0.5735 Val Acc: 0.7184 Val AUC: 0.7825
- Epoch 12/50 Train Loss: 0.5637 Val Loss: 0.5710 Val Acc: 0.7178 Val AUC: 0.7843
- Epoch 13/50 Train Loss: 0.5624 Val Loss: 0.5646 Val Acc: 0.7208 Val AUC: 0.7880
- Epoch 14/50 Train Loss: 0.5603 Val Loss: 0.5627 Val Acc: 0.7246 Val AUC: 0.7874
- Epoch 15/50 Train Loss: 0.5612 Val Loss: 0.5644 Val Acc: 0.7248 Val AUC: 0.7884

```
Epoch 16/50 - Train Loss: 0.5603 - Val Loss: 0.5621 - Val Acc: 0.7256 - Val AUC: 0.7883
```

Epoch 17/50 - Train Loss: 0.5602 - Val Loss: 0.5664 - Val Acc: 0.7202 - Val AUC: 0.7886

Epoch 18/50 - Train Loss: 0.5594 - Val Loss: 0.5691 - Val Acc: 0.7216 - Val AUC: 0.7882

Epoch 19/50 - Train Loss: 0.5580 - Val Loss: 0.5685 - Val Acc: 0.7240 - Val AUC: 0.7878

Epoch 20/50 - Train Loss: 0.5587 - Val Loss: 0.5680 - Val Acc: 0.7270 - Val AUC: 0.7881

Epoch 21/50 - Train Loss: 0.5578 - Val Loss: 0.5591 - Val Acc: 0.7236 - Val AUC: 0.7904

Epoch 22/50 - Train Loss: 0.5578 - Val Loss: 0.5654 - Val Acc: 0.7226 - Val AUC: 0.7880

Epoch 23/50 - Train Loss: 0.5570 - Val Loss: 0.5590 - Val Acc: 0.7236 - Val AUC: 0.7905

Epoch 24/50 - Train Loss: 0.5577 - Val Loss: 0.5613 - Val Acc: 0.7214 - Val AUC: 0.7905

Epoch 25/50 - Train Loss: 0.5565 - Val Loss: 0.5645 - Val Acc: 0.7216 - Val AUC: 0.7898

Epoch 26/50 - Train Loss: 0.5565 - Val Loss: 0.5634 - Val Acc: 0.7268 - Val AUC: 0.7880

```
Epoch 27/50 - Train Loss: 0.5564 - Val Loss: 0.5647 - Val Acc: 0.7268
- Val AUC: 0.7915
Epoch 28/50 - Train Loss: 0.5561 - Val Loss: 0.5603 - Val Acc: 0.7274
- Val AUC: 0.7901
Epoch 29/50 - Train Loss: 0.5560 - Val Loss: 0.5628 - Val Acc: 0.7206
- Val AUC: 0.7892
Epoch 30/50 - Train Loss: 0.5554 - Val Loss: 0.5637 - Val Acc: 0.7138
- Val AUC: 0.7869
Epoch 31/50 - Train Loss: 0.5554 - Val Loss: 0.5619 - Val Acc: 0.7254
- Val AUC: 0.7925
Epoch 32/50 - Train Loss: 0.5556 - Val Loss: 0.5612 - Val Acc: 0.7246
- Val AUC: 0.7909
Epoch 33/50 - Train Loss: 0.5552 - Val Loss: 0.5621 - Val Acc: 0.7260
- Val AUC: 0.7910
Epoch 34/50 - Train Loss: 0.5555 - Val Loss: 0.5575 - Val Acc: 0.7288
- Val AUC: 0.7922
Epoch 35/50 - Train Loss: 0.5556 - Val Loss: 0.5559 - Val Acc: 0.7254
- Val AUC: 0.7915
Epoch 36/50 - Train Loss: 0.5542 - Val Loss: 0.5660 - Val Acc: 0.7238
- Val AUC: 0.7901
Early stopping triggered
import matplotlib.pyplot as plt
import numpy as np
epochs = np.arange(1, 37)
```

```
train loss = [0.5895, 0.5812, 0.5771, 0.5737, 0.5720, 0.5693, 0.5675,
0.5665, 0.5661, 0.5647,
              0.5639, 0.5637, 0.5624, 0.5603, 0.5612, 0.5603, 0.5602,
0.5594, 0.5580, 0.5587,
              0.5578, 0.5578, 0.5570, 0.5577, 0.5565, 0.5565, 0.5564,
0.5561, 0.5560, 0.5554,
              0.5554, 0.5556, 0.5552, 0.5555, 0.5556, 0.5542]
val loss = [0.5887, 0.5852, 0.5867, 0.5742, 0.5723, 0.5704, 0.5714,
0.5759, 0.5646, 0.7402,
            0.5735, 0.5710, 0.5646, 0.5627, 0.5644, 0.5621, 0.5664,
0.5691, 0.5685, 0.5680,
            0.5591, 0.5654, 0.5590, 0.5613, 0.5645, 0.5634, 0.5647,
0.5603, 0.5628, 0.5637,
            0.5619, 0.5612, 0.5621, 0.5575, 0.5559, 0.5660
val acc = [0.7094, 0.7140, 0.7076, 0.7128, 0.7182, 0.7140, 0.7176,
0.7188, 0.7174, 0.5184,
           0.7184, 0.7178, 0.7208, 0.7246, 0.7248, 0.7256, 0.7202,
0.7216, 0.7240, 0.7270,
           0.7236, 0.7226, 0.7236, 0.7214, 0.7216, 0.7268, 0.7268,
0.7274, 0.7206, 0.7138,
           0.7254, 0.7246, 0.7260, 0.7288, 0.7254, 0.7238]
val auc = [0.7759, 0.7780, 0.7791, 0.7812, 0.7830, 0.7812, 0.7817,
0.7832, 0.7858, 0.7588,
           0.7825, 0.7843, 0.7880, 0.7874, 0.7884, 0.7883, 0.7886,
0.7882, 0.7878, 0.7881,
           0.7904, 0.7880, 0.7905, 0.7905, 0.7898, 0.7880, 0.7915,
0.7901, 0.7892, 0.7869,
           0.7925, 0.7909, 0.7910, 0.7922, 0.7915, 0.7901
plt.figure(figsize=(12, 6))
plt.subplot(1, 2, 1)
plt.plot(epochs, train loss, label="Train Loss", marker='o',
linestyle='dashed')
plt.plot(epochs, val loss, label="Val Loss", marker='s',
linestyle='dashed')
plt.xlabel("Epochs")
plt.ylabel("Loss")
plt.title("Training and Validation Loss")
plt.legend()
plt.grid()
plt.subplot(1, 2, 2)
plt.plot(epochs, val acc, label="Val Accuracy", marker='o',
linestyle='dashed')
plt.plot(epochs, val auc, label="Val AUC", marker='s',
linestyle='dashed')
plt.xlabel("Epochs")
```

```
plt.ylabel("Metrics")
plt.title("Validation Accuracy & AUC")
plt.legend()
plt.grid()

plt.tight_layout()
plt.show()
```

