```
# Code originally written on kaggle
!pip install torch-scatter torch-sparse torch-cluster torch-spline-
conv -f https://data.pyg.org/whl/torch-2.5.0+cu121.html
!pip install torch-geometric
!pip install torch-cluster -f https://data.pyg.org/whl/torch-
2.5.0+cu121.html
import h5py
import numpy as np
import torch
import random
from tgdm import tgdm
from torch geometric.data import Data
from torch geometric.nn import knn_graph
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
print(f"Using device: {device}")
file path = "/kaggle/input/quark-gluon/quark-gluon data-
set n139306.hdf5"
output file = "/kaggle/working/graph gae dataset.pt"
H, W = 125, 125
x coords np, y coords np = np.meshgrid(np.linspace(0, 1, W),
np.linspace(0, 1, H))
x coords = torch.tensor(x coords np, dtype=torch.float32,
device=device)
y coords = torch.tensor(y coords np, dtype=torch.float32,
device=device)
with h5py.File(file path, "r") as f:
    X_{jets} = f["X_{jets}"]
    m0 = f["m0"]
    pt = f["pt"]
    y = f["y"]
    total_events = X_jets.shape[0]
    num samples = min(50000, total events)
    random.seed(42)
    selected indices = sorted(random.sample(range(total events),
num samples))
    print(f"Processing {num samples} randomly selected samples out of
{total events} available.")
    graph dataset = []
    batch size = 5000
```

```
for start in tgdm(range(0, num samples, batch size),
desc="Processing Batches"):
        end = min(start + batch_size, num_samples)
        batch indices = selected indices[start:end]
        X_batch = torch.tensor(X_jets[batch_indices],
dtype=torch.float32, device=device)
        m0 batch = torch.tensor(m0[batch indices],
dtype=torch.float32, device=device)
        pt batch = torch.tensor(pt[batch indices],
dtype=torch.float32, device=device)
        y batch = torch.tensor(y[batch indices], dtype=torch.float32,
device=device)
        for i in range(end - start):
            nonzero mask = torch.any(X batch[i] > 0, dim=-1)
            nonzero x = x coords[nonzero mask]
            nonzero y = y coords[nonzero mask]
            nonzero features = X batch[i][nonzero mask]
            if nonzero x.numel() == 0:
                continue
            num points = nonzero x.shape[0]
            node features = torch.stack([
                nonzero_x, nonzero_y,
                nonzero_features[:, 0], nonzero_features[:, 1],
nonzero features[:, 2],
                torch.full((num points,), m0 batch[i],
dtype=torch.float32, device=device),
                torch.full((num points,), pt batch[i],
dtype=torch.float32, device=device)
            ], dim=1)
            k = 8
            edge index = knn graph(node features[:, :5], k=k)
            data = Data(x=node features, edge index=edge index,
y=y_batch[i])
            graph_dataset.append(data)
torch.save(graph dataset, output file)
print(f"Graph dataset saved to '{output file}'.")
Looking in links: https://data.pyg.org/whl/torch-2.5.0+cu121.html
Collecting torch-scatter
  Downloading
https://data.pyg.org/whl/torch-2.5.0%2Bcu121/torch_scatter-
2.1.2%2Bpt25cu121-cp310-cp310-linux x86 64.whl (10.9 MB)
```

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packages (from torch-sparse) (1.13.1)
Requirement already satisfied: numpy<2.3,>=1.22.4 in
/usr/local/lib/python3.10/dist-packages (from scipy->torch-sparse)
(1.26.4)
Requirement already satisfied: mkl fft in
/usr/local/lib/python3.10/dist-packages (from numpy<2.3,>=1.22.4-
>scipy->torch-sparse) (1.3.8)
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>scipy->torch-sparse) (1.2.4)
Requirement already satisfied: mkl umath in
/usr/local/lib/python3.10/dist-packages (from numpy<2.3,>=1.22.4-
>scipy->torch-sparse) (0.1.1)
Requirement already satisfied: mkl in /usr/local/lib/python3.10/dist-
packages (from numpy<2.3,>=1.22.4->scipy->torch-sparse) (2025.0.1)
Requirement already satisfied: tbb4py in
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>scipy->torch-sparse) (2024.2.0)
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/usr/local/lib/python3.10/dist-packages (from mkl->numpy<2.3,>=1.22.4-
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Requirement already satisfied: tcmlib==1.* in
/usr/local/lib/python3.10/dist-packages (from tbb==2022.*->mkl-
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/usr/local/lib/python3.10/dist-packages (from mkl umath-
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Requirement already satisfied: intel-cmplr-lib-ur==2024.2.0 in
/usr/local/lib/python3.10/dist-packages (from intel-openmp>=2024->mkl-
>numpy<2.3,>=1.22.4->scipy->torch-sparse) (2024.2.0)
Installing collected packages: torch-spline-conv, torch-scatter,
torch-sparse, torch-cluster
Successfully installed torch-cluster-1.6.3+pt25cu121 torch-scatter-
2.1.2+pt25cu121 torch-sparse-0.6.18+pt25cu121 torch-spline-conv-
```

```
1.2.2+pt25cu121
Collecting torch-geometric
  Downloading torch geometric-2.6.1-py3-none-any.whl.metadata (63 kB)
                                   ---- 63.1/63.1 kB 2.0 MB/s eta
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ent already satisfied: aiohttp in /usr/local/lib/python3.10/dist-
packages (from torch-geometric) (3.11.12)
Requirement already satisfied: fsspec in
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(2024.12.0)
Requirement already satisfied: jinja2 in
/usr/local/lib/python3.10/dist-packages (from torch-geometric) (3.1.4)
Requirement already satisfied: numpy in
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Requirement already satisfied: psutil>=5.8.0 in
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Requirement already satisfied: aiohappyeyeballs>=2.3.0 in
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geometric) (2.4.6)
Requirement already satisfied: aiosignal>=1.1.2 in
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geometric) (1.3.2)
Requirement already satisfied: async-timeout<6.0,>=4.0 in
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Requirement already satisfied: attrs>=17.3.0 in
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geometric) (25.1.0)
Requirement already satisfied: frozenlist>=1.1.1 in
/usr/local/lib/python3.10/dist-packages (from aiohttp->torch-
geometric) (1.5.0)
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/usr/local/lib/python3.10/dist-packages (from aiohttp->torch-
geometric) (6.1.0)
Requirement already satisfied: propcache>=0.2.0 in
/usr/local/lib/python3.10/dist-packages (from aiohttp->torch-
geometric) (0.2.1)
Requirement already satisfied: yarl<2.0,>=1.17.0 in
/usr/local/lib/python3.10/dist-packages (from aiohttp->torch-
geometric) (1.18.3)
Requirement already satisfied: MarkupSafe>=2.0 in
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/usr/local/lib/python3.10/dist-packages (from jinja2->torch-geometric)
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Requirement already satisfied: mkl fft in
/usr/local/lib/python3.10/dist-packages (from numpy->torch-geometric)
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Requirement already satisfied: charset-normalizer<4,>=2 in
/usr/local/lib/python3.10/dist-packages (from requests->torch-
geometric) (3.4.1)
Requirement already satisfied: idna<4,>=2.5 in
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geometric) (3.10)
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geometric) (2.3.0)
Requirement already satisfied: certifi>=2017.4.17 in
/usr/local/lib/python3.10/dist-packages (from requests->torch-
geometric) (2025.1.31)
Requirement already satisfied: typing-extensions>=4.1.0 in
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>aiohttp->torch-geometric) (4.12.2)
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/usr/local/lib/python3.10/dist-packages (from intel-openmp>=2024->mkl-
>numpy->torch-geometric) (2024.2.0)
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                                       - 1.1/1.1 MB 21.7 MB/s eta
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Successfully installed torch-geometric-2.6.1
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Requirement already satisfied: torch-cluster in
/usr/local/lib/python3.10/dist-packages (1.6.3+pt25cu121)
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/usr/local/lib/python3.10/dist-packages (from numpy<2.3,>=1.22.4-
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Requirement already satisfied: intel-cmplr-lib-rt in
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>numpy<2.3,>=1.22.4->scipy->torch-cluster) (2024.2.0)
Requirement already satisfied: intel-cmplr-lib-ur==2024.2.0 in
/usr/local/lib/python3.10/dist-packages (from intel-openmp>=2024->mkl-
>numpy<2.3,>=1.22.4->scipy->torch-cluster) (2024.2.0)
Using device: cuda
Processing 50000 randomly selected samples out of 139306 available.
Processing Batches: 100% | 10/10 [12:08<00:00, 72.81s/it]
```

```
Graph dataset saved to '/kaggle/working/graph gae dataset.pt'.
import torch
import torch.nn as nn
import torch.nn.functional as F
from torch geometric.nn import GCNConv, GAE
from torch geometric.loader import DataLoader
import torch geometric.utils as pyg utils
from tgdm import tgdm
import time
from torch.cuda.amp import autocast, GradScaler
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
print(f"Using device: {device}")
trv:
    graph dataset = torch.load("/kaggle/working/graph gae dataset.pt")
    print(f"Dataset loaded successfully with {len(graph dataset)}
samples")
except Exception as e:
    raise RuntimeError(f"Error loading dataset: {e}")
if not graph dataset or not isinstance(graph dataset, list):
    raise ValueError("Error: Loaded dataset is empty or incorrectly
formatted!")
graph dataset = [data.to('cpu') for data in graph dataset]
in channels = graph dataset[0].x.shape[1]
print(f"Node feature dimensions: {in channels}")
train_size = int(0.8 * len(graph_dataset))
train dataset = graph dataset[:train size]
val dataset = graph dataset[train size:]
print(f"Training samples: {len(train dataset)}, Validation samples:
{len(val dataset)}")
train loader = DataLoader(train dataset, batch size=256, shuffle=True,
num workers=4,
                         pin memory=(device.type == "cuda"))
val loader = DataLoader(val dataset, batch size=256, shuffle=False,
num workers=2,
                       pin memory=(device.type == "cuda"))
class GraphAutoencoder(nn.Module):
    def __init__(self, in_channels, hidden_dim=128, latent_dim=64):
        super(GraphAutoencoder, self). init ()
        # Encoder
        self.conv1 = GCNConv(in channels, hidden dim)
        self.bn1 = nn.BatchNorm1d(hidden dim)
```

```
self.conv2 = GCNConv(hidden dim, hidden dim)
        self.bn2 = nn.BatchNorm1d(hidden dim)
        self.conv3 = GCNConv(hidden dim, latent dim)
    def encode(self, x, edge index):
        x = self.conv1(x, edge index)
        x = self.bn1(x)
        x = F.relu(x)
        x = F.dropout(x, p=0.2, training=self.training)
        x = self.conv2(x, edge index)
        x = self.bn2(x)
        x = F.relu(x)
        x = F.dropout(x, p=0.2, training=self.training)
        x = self.conv3(x, edge index)
        return x
    def decode(self, z, edge index):
        score = (z[edge_index[0]] * z[edge_index[1]]).sum(dim=1)
        return torch.clamp(score, -10, 10)
    def forward(self, x, edge index):
        return self.encode(x, edge index)
model = GAE(GraphAutoencoder(in channels)).to(device)
optimizer = torch.optim.Adam(model.parameters(), lr=0.003,
weight decay=1e-5)
scheduler = torch.optim.lr scheduler.ReduceLROnPlateau(optimizer,
'min', factor=0.5, patience=3, verbose=True)
scaler = GradScaler()
def train(epoch):
    model.train()
    total loss = 0
    total examples = 0
    start time = time.time()
    for batch in tqdm(train loader, desc=f"Epoch {epoch}/{num epochs}
[Train]", leave=False):
        batch = batch.to(device)
        optimizer.zero grad()
        with autocast(enabled=device.type == "cuda"):
            # Encode graph
            z = model.encode(batch.x, batch.edge index)
            pos edge index = batch.edge index
```

```
neg edge index = pyg utils.negative sampling(
                edge index=pos edge index.cpu(),
                num nodes=batch.x.size(0),
                num neg samples=pos edge index.shape[1]
            ).to(device)
            edge index = torch.cat([pos edge index, neg edge index],
dim=1)
            edge_label = torch.cat([
                torch.ones(pos edge index.shape[1]),
                torch.zeros(neg edge index.shape[1])
            1).to(device)
            # Decode
            edge_pred = model.decode(z, edge_index)
            # BCE loss
            loss = F.binary_cross_entropy_with_logits(edge_pred,
edge label)
        scaler.scale(loss).backward()
        scaler.unscale (optimizer)
        torch.nn.utils.clip grad norm (model.parameters(),
max norm=1.0)
        scaler.step(optimizer)
        scaler.update()
        total_loss += loss.item() * batch.num_graphs
        total examples += batch.num graphs
    epoch time = time.time() - start time
    return total loss / total examples, epoch time
def validate():
    model.eval()
    total loss = 0
    total examples = 0
    with torch.no grad():
        for batch in tqdm(val loader, desc="Validation", leave=False):
            batch = batch.to(device)
            with autocast(enabled=device.type == "cuda"):
                # Encode graph
                z = model.encode(batch.x, batch.edge index)
                pos edge_index = batch.edge_index
```

```
neg edge index = pyg utils.negative sampling(
                    edge_index=pos_edge_index.cpu(),
                    num nodes=batch.x.size(0),
                    num neg samples=pos edge index.shape[1]
                ).to(device)
                edge index = torch.cat([pos edge index,
neg edge index], dim=1)
                edge label = torch.cat([
                    torch.ones(pos edge index.shape[1]),
                    torch.zeros(neg_edge_index.shape[1])
                1).to(device)
                # Decode
                edge pred = model.decode(z, edge index)
                # BCE loss
                loss = F.binary cross entropy with logits(edge pred,
edge_label)
            total loss += loss.item() * batch.num graphs
            total examples += batch.num graphs
    return total loss / total_examples
num epochs = 20
best val loss = float('inf')
patience = 5
counter = 0
print(f"Starting training with mixed precision {'enabled' if
device.type == 'cuda' else 'disabled (CUDA required)'}")
for epoch in range(1, num_epochs + 1):
    train loss, epoch time = train(epoch)
    val loss = validate()
    print(f"Epoch {epoch}/{num_epochs} - Train Loss: {train_loss:.4f},
Val Loss: {val loss:.4f}, Time: {epoch time:.2f}s")
    scheduler.step(val loss)
    if val loss < best val loss:</pre>
        best val loss = val loss
        torch.save(model.state dict(),
"/kaggle/working/gae model best.pt")
        print(f"New best model saved with validation loss:
{best_val_loss:.4f}")
```

```
counter = 0
    else:
        counter += 1
    if counter >= patience:
        print(f"Early stopping after {epoch} epochs without
improvement")
        break
torch.save(model.state_dict(), "/kaggle/working/gae_model_final.pt")
print("Training completed. Final model saved.")
model.load state dict(torch.load("/kaggle/working/gae model best.pt"))
val loss = validate()
print(f"Best model validation loss: {val loss:.4f}")
Using device: cuda
<ipython-input-3-108ed1b82b94>:16: FutureWarning: You are using
`torch.load` with `weights only=False` (the current default value),
which uses the default pickle module implicitly. It is possible to
construct malicious pickle data which will execute arbitrary code
during unpickling (See
https://github.com/pytorch/pytorch/blob/main/SECURITY.md#untrusted-
models for more details). In a future release, the default value for
`weights only` will be flipped to `True`. This limits the functions
that could be executed during unpickling. Arbitrary objects will no
longer be allowed to be loaded via this mode unless they are
explicitly allowlisted by the user via
`torch.serialization.add safe globals`. We recommend you start setting
`weights only=True` for any use case where you don't have full control
of the loaded file. Please open an issue on GitHub for any issues
related to this experimental feature.
  graph dataset = torch.load("/kaggle/working/graph gae dataset.pt")
Dataset loaded successfully with 50000 samples
Node feature dimensions: 7
Training samples: 40000, Validation samples: 10000
<ipython-input-3-108ed1b82b94>:86: FutureWarning:
`torch.cuda.amp.GradScaler(args...)` is deprecated. Please use
`torch.amp.GradScaler('cuda', args...)` instead.
  scaler = GradScaler()
Starting training with mixed precision enabled
Epoch 1/20 [Train]: 0%|
                                  | 0/157 [00:00<?, ?it/s]<ipython-
input-3-108ed1b82b94>:100: FutureWarning:
`torch.cuda.amp.autocast(args...)` is deprecated. Please use
`torch.amp.autocast('cuda', args...)` instead.
```

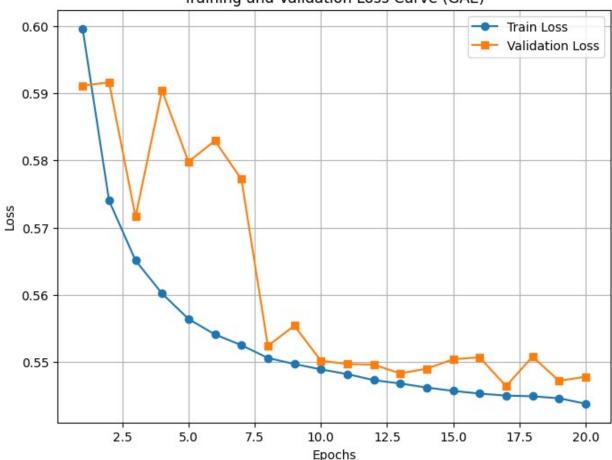
```
with autocast(enabled=device.type == "cuda"):
                           | 0/40 [00:00<?, ?it/s]
Validation:
              0%|
<ipython-input-3-108ed1b82b94>:155: FutureWarning:
`torch.cuda.amp.autocast(args...)` is deprecated. Please use
`torch.amp.autocast('cuda', args...)` instead.
 with autocast(enabled=device.type == "cuda"):
Epoch 1/20 - Train Loss: 0.5996, Val Loss: 0.5911, Time: 329.24s
New best model saved with validation loss: 0.5911
Epoch 2/20 - Train Loss: 0.5740, Val Loss: 0.5916, Time: 318.55s
Epoch 3/20 - Train Loss: 0.5651, Val Loss: 0.5716, Time: 319.09s
New best model saved with validation loss: 0.5716
Epoch 4/20 - Train Loss: 0.5602, Val Loss: 0.5904, Time: 319.35s
Epoch 5/20 - Train Loss: 0.5564, Val Loss: 0.5798, Time: 319.93s
Epoch 6/20 - Train Loss: 0.5541, Val Loss: 0.5829, Time: 317.25s
Epoch 7/20 - Train Loss: 0.5525, Val Loss: 0.5772, Time: 321.21s
Epoch 8/20 - Train Loss: 0.5506, Val Loss: 0.5524, Time: 318.57s
New best model saved with validation loss: 0.5524
Epoch 9/20 - Train Loss: 0.5497, Val Loss: 0.5554, Time: 332.44s
Epoch 10/20 - Train Loss: 0.5489, Val Loss: 0.5502, Time: 334.55s
New best model saved with validation loss: 0.5502
Epoch 11/20 - Train Loss: 0.5482, Val Loss: 0.5497, Time: 335.07s
New best model saved with validation loss: 0.5497
```

Epoch 12/20 - Train Loss: 0.5473, Val Loss: 0.5496, Time: 335.31s New best model saved with validation loss: 0.5496 Epoch 13/20 - Train Loss: 0.5468, Val Loss: 0.5483, Time: 337.69s New best model saved with validation loss: 0.5483 Epoch 14/20 - Train Loss: 0.5462, Val Loss: 0.5490, Time: 338.61s Epoch 15/20 - Train Loss: 0.5457, Val Loss: 0.5504, Time: 334.22s Epoch 16/20 - Train Loss: 0.5453, Val Loss: 0.5507, Time: 337.97s Epoch 17/20 - Train Loss: 0.5450, Val Loss: 0.5464, Time: 333.34s New best model saved with validation loss: 0.5464 Epoch 18/20 - Train Loss: 0.5449, Val Loss: 0.5508, Time: 331.72s Epoch 19/20 - Train Loss: 0.5446, Val Loss: 0.5472, Time: 337.77s <ipython-input-3-108ed1b82b94>:227: FutureWarning: You are using `torch.load` with `weights\_only=False` (the current default value), which uses the default pickle module implicitly. It is possible to construct malicious pickle data which will execute arbitrary code during unpickling (See https://github.com/pytorch/pytorch/blob/main/SECURITY.md#untrustedmodels for more details). In a future release, the default value for `weights only` will be flipped to `True`. This limits the functions that could be executed during unpickling. Arbitrary objects will no longer be allowed to be loaded via this mode unless they are explicitly allowlisted by the user via `torch.serialization.add\_safe\_globals`. We recommend you start setting `weights only=True` for any use case where you don't have full control of the loaded file. Please open an issue on GitHub for any issues related to this experimental feature.

model.load\_state\_dict(torch.load("/kaggle/working/gae\_model\_best.pt"))

```
Epoch 20/20 - Train Loss: 0.5438, Val Loss: 0.5478, Time: 336.24s
Training completed. Final model saved.
Best model validation loss: 0.5464
import matplotlib.pyplot as plt
# Training and validation loss values from the logs
epochs = list(range(1, 21))
train loss = [0.5996, 0.5740, 0.5651, 0.5602, 0.5564, 0.5541, 0.5525,
0.550\overline{6}, 0.5497, 0.5489, 0.5482, 0.5473, 0.5468, 0.5462, 0.5457,
0.5453, 0.5450, 0.5449, 0.5446, 0.5438]
val_loss = [0.5911, 0.5916, 0.5716, 0.5904, 0.5798, 0.5829, 0.5772,
0.5\overline{5}24, 0.5554, 0.5502, 0.5497, 0.5496, 0.5483, 0.5490, 0.5504,
0.5507, 0.5464, 0.5508, 0.5472, 0.5478]
plt.figure(figsize=(8, 6))
plt.plot(epochs, train_loss, label="Train Loss", marker="o")
plt.plot(epochs, val loss, label="Validation Loss", marker="s")
plt.xlabel("Epochs")
plt.ylabel("Loss")
plt.title("Training and Validation Loss Curve (GAE)")
plt.legend()
plt.grid(True)
plt.show()
```





```
import torch
import matplotlib.pyplot as plt
import networkx as nx
from torch_geometric.utils import to_networkx

model_path = "/kaggle/working/gae_model_best.pt"
model.load_state_dict(torch.load(model_path, map_location=device))
model.eval()

sample_idx = torch.randint(0, len(val_dataset), (1,)).item()

data = val_dataset[sample_idx].to(device)

with torch.no_grad():
    z = model.encode(data.x, data.edge_index)
    reconstructed_edge_scores = model.decode(z,
data.edge_index).cpu().numpy()

original_graph = to_networkx(data, to_undirected=True)

threshold = 0
```

```
edges = [(u, v) \text{ for } (u, v), \text{ score in }
zip(data.edge index.t().cpu().numpy(), reconstructed edge scores) if
score > threshold]
reconstructed graph = nx.Graph()
reconstructed graph.add edges from(edges)
fig, axes = plt.subplots(1, 2, figsize=(12, 6))
# Plot Original Graph
ax = axes[0]
ax.set title("Original Graph")
nx.draw(original graph, pos=nx.spring layout(original graph),
node_size=30, edge_color='gray', ax=ax)
# Plot Reconstructed Graph
ax = axes[1]
ax.set title("Reconstructed Graph")
nx.draw(reconstructed graph,
pos=nx.spring layout(reconstructed graph), node size=30,
edge color='blue', ax=ax)
plt.tight layout()
plt.show()
<ipython-input-23-468b46e6cb67>:7: FutureWarning: You are using
`torch.load` with `weights_only=False` (the current default value),
which uses the default pickle module implicitly. It is possible to
construct malicious pickle data which will execute arbitrary code
during unpickling (See
https://github.com/pytorch/pytorch/blob/main/SECURITY.md#untrusted-
models for more details). In a future release, the default value for
`weights only` will be flipped to `True`. This limits the functions
that could be executed during unpickling. Arbitrary objects will no
longer be allowed to be loaded via this mode unless they are
explicitly allowlisted by the user via
`torch.serialization.add safe globals`. We recommend you start setting
`weights only=True` for any use case where you don't have full control
of the loaded file. Please open an issue on GitHub for any issues
related to this experimental feature.
  model.load state dict(torch.load(model path, map location=device))
```

