6 En el caso 30 tenemos que si deir define un sistema de coordenadas (dextogino) no necesariamente ortigonal, entonces demuestre que:

Q)  $e^{i} = \frac{e_{i} \times e_{k}}{e_{i} \cdot (e_{j} \times e_{k})}$ ,  $i_{i}j_{i}k = 1,2,3$  y sus permutacions ciclicas. por definicion tenemos e: e'= difoiti er es perpendicular a e; y ex: ei=x(e; x ex) e'. e; = 1 (e).e' = x(e;xex)(e;) 1 = dei(e;xex); 1(e; xex) = x(e; xex) ei. (e, xex)

 $\frac{(e_j \times e_k)}{e_i \cdot (e_j \times e_k)_i} = e^i \qquad i, j, k = 1, 2, 3.$ 

(a) volumenes 
$$V = e_1 \cdot (e_2 \times e_3)$$
 y  $V = e_1 \cdot (e^2 \times e^3)$   
whonce  $VV = 1$   
 $(e_1 \cdot (e_2 \times e_3)) \cdot (e_1 \cdot (e^2 \times e^3)) = 1$   
 $(e_1 \cdot (\frac{1}{4})e^1) \cdot (e^1 \cdot (\frac{1}{4})e_1) = 1$   $d = 1$   
 $(e_1 \cdot e^1) \cdot (e^1 \cdot e_1) = 1$   
 $1 \cdot 1 = 1$ 

© Que vector satisface a.e =1? Demuestre que a es unico.

$$a \cdot e^{i} = 1$$
  
 $a^{i}(e_{j} \cdot e^{i}) = 1$   
 $a^{i} \delta_{j}^{i} = 1$   $\delta_{j}^{i} A^{i} = 1$   
 $a^{i} = 1$   
 $a^{i} e_{j} \cdot e^{i} = 1$   
 $i = j$   $a^{i} = 1$ 

$$i = j \cdot 0^{i} = 1$$
 $e_i \cdot e^i = 1$ 

The eventre of products vectorial de dos vectores a y b que estan representados en un sistema de coordenadas obliquo: Dada la base  $w_1 = 41 + 23 + k$ ,  $w_2 = 31 + 33$ ,  $w_3 = 2k$ 

Entonces encuentro:

Itas bases reciprocas je's  $w_1 \cdot w_2 = 18$ ,  $w_1 \cdot w_3 = 2$ ,  $w_2 \cdot w_3 = 0$ 

no es pase otogonal

$$w^{i} = \frac{w_{j} \times w_{k}}{w_{i} \cdot (w_{j} \times w_{k})}$$
  $i_{j} i_{j} k = 1, 2, 3$ .

 $W' = \frac{W_2 \times W_3}{W_1 \cdot (W_2 \times W_3)} \Rightarrow W' = \frac{(3,3,0) \times (0,0,2)}{(4,2,1) \cdot ((3,3,0) \times (0,0,2))}$ 

$$W' = \frac{(6,6,0)}{(4,2,1)\cdot(6,6,0)}$$

$$W' = \frac{1}{36}(6,6,0) = W_1 = (\frac{1}{6},\frac{1}{6},0)$$

$$W^{2} = \frac{\omega_{3} \times \omega_{1}}{\omega_{1}(\omega_{3} \times \omega_{1})} \Rightarrow W^{2} = \frac{(o, 0, 2) \times (4, 2, 1)}{(3, 3, 0) \cdot ((o, 0, 2) \times (4, 2, 1))}$$

$$W^{2} = \frac{(-4, 8, 0)}{(3, 3, 0) \cdot (-4, 8, 0)}$$

$$W^{2} = \frac{1}{12} (-4, 8, 0) \Rightarrow W^{2} = (-\frac{1}{3}, \frac{2}{3}, 10)$$

$$W^{3} = \frac{\omega_{1} \times \omega_{2}}{\omega_{3} \cdot (\omega_{1} \times \omega_{2})} \Rightarrow W^{3} = \frac{(4,2,1) \times (3,3,0)}{(0,0,2) \cdot ((4,2,1) \times (3,3,0))}$$

$$W^{3} = \frac{(-3,3,6)}{(0,0,2) \cdot (-3,3,6)}$$

$$W^{3} = \frac{1}{12} (-3,3,6) \Rightarrow W^{3} = (-\frac{3}{12},\frac{3}{12},\frac{1}{2})$$

$$W_{1} = (4,2,1) - W' = (\frac{1}{6},\frac{1}{6},0)$$

$$W_{2} = (3,3,0) - W^{2} = (-\frac{1}{3},\frac{2}{3},0)$$

$$W_{3} = (0,0,2) - W^{3} = (-\frac{3}{12},\frac{3}{12},\frac{1}{2})$$

$$\forall e_{i} \}$$
covariante
$$(3,3,0) - W^{3} = (-\frac{3}{12},\frac{3}{12},\frac{1}{2})$$

$$\forall e_{i} \}$$
contravariante

II components covariantes y contravariantes de

$$Proy_{\omega_i} = \left(\frac{a \cdot \omega_i}{|\omega_i|^2}\right) \omega_i$$

$$Proy_{\omega_{i}}Q = \left(\frac{(1,2,3)\cdot(4,2,1)}{((4,2,1))^{2}}\right)(4,2,1) \qquad Proy_{\omega_{3}}Q = \left(\frac{(1,2,3)\cdot(0,0,2)}{((0,0,2))^{2}}\right)(0,0,2)$$

$$= \left(\frac{4+4+3}{(4^{2}+2^{2}+1^{2})^{2}}\right)(4,2,1) \qquad = \left(\frac{3}{4}\right)(0,0,2)$$

$$= \left(\frac{11}{21}(4,2,1)\right) \qquad = \left(\frac{3}{2}(0,0,2)\right)$$

$$PNY_{w_2}Q = \left(\frac{(1,2,3)\cdot(3,3,0)}{|(3,3,0)|^2}\right)(3,3,0)$$

$$= \left(\frac{3+6}{|(3^2+3^2)^2|}\right)(3,3,0)$$

$$= \frac{9}{18}(3,3,0) = \frac{1}{2}(3,3,0)$$

$$Proy_{\omega^{1}} Q = \left(\frac{Q \cdot \omega^{1}}{|\omega|^{2}}\right) \omega^{1}$$

$$= \left(\frac{(1,2,3) \cdot (\frac{1}{6}, \frac{1}{6}, 0)}{|(\frac{1}{6}, \frac{1}{6}, 0)|^{2}}\right) \left(\frac{1}{6}, \frac{1}{6}, 0\right)$$

$$= \left(\frac{\frac{1}{6} + \frac{2}{6} + 0}{|\sqrt{(\frac{1}{6})^{2} + (\frac{1}{6})^{2}}|^{2}}\right) \left(\frac{1}{6}, \frac{1}{6}, 0\right)$$

$$= \left(\frac{3}{6}\right) \left(\frac{1}{6}, \frac{1}{6}, 0\right) = \left(\frac{1}{6}, \frac{1}{6}, 0\right)$$

$$= \frac{(\frac{3}{6})}{\frac{2}{36}} \left(\frac{1}{6}, \frac{1}{6}, 0\right) = \left(\frac{1}{6}, \frac{1}{6}, 0\right)$$

$$Proy_{\omega^{2}} Q = \left(\frac{(1,2,3) \cdot (\frac{1}{3}, \frac{2}{3}, 0)}{|(\frac{1}{3}, \frac{2}{3}, 0)|^{2}}\right) \left(\frac{1}{3}, \frac{2}{3}, 0\right)$$

$$Provi_{\omega^{2}}Q = \left(\frac{(1,2,3)\cdot(\frac{1}{3},\frac{1}{3},0)}{|(\frac{1}{3},\frac{1}{3},0)|^{2}}\right)(\frac{1}{3},\frac{1}{3},0)$$

$$= \frac{-\frac{1}{3}+\frac{1}{3}}{(\sqrt{(-\frac{1}{3})^{2}+(\frac{1}{3})^{2}})^{2}} \left(-\frac{1}{3},\frac{1}{3},0\right)$$

$$= \frac{\frac{1}{3}+\frac{1}{3}}{(\sqrt{(-\frac{1}{3})^{2}+(\frac{1}{3})^{2}})^{2}}$$

$$= \frac{\frac{1}{3}}{\frac{1}{3}} \left(-\frac{1}{3},\frac{1}{3},0\right) = \left(\frac{1}{3},\frac{1}{3},0\right)$$

$$Proy \omega^{3} \mathbf{Q} = \left(\frac{(\lambda_{1} 2, 3) \cdot (-\frac{3}{12} 1 \frac{3}{12} 1 \frac{1}{2})}{|(-\frac{3}{12} 1 \frac{3}{12} 1 \frac{1}{2})|^{2}}\right) \left(-\frac{3}{12} 1 \frac{3}{12} 1 \frac{1}{2}\right)$$

$$= -\frac{3}{12} + \frac{6}{12} + \frac{3}{2} - \left(-\frac{3}{12} 1 \frac{3}{12} 1 \frac{1}{2}\right)$$

$$= \frac{7}{4} - \left(-\frac{3}{12} 1 \frac{3}{12} 1 \frac{1}{2}\right) = \boxed{14 \cdot \left(-\frac{3}{12} 1 \frac{3}{12} 1 \frac{1}{2}\right)}$$

$$= \frac{7}{4} - \left(-\frac{3}{12} 1 \frac{3}{12} 1 \frac{1}{2}\right) = \boxed{14 \cdot \left(-\frac{3}{12} 1 \frac{3}{12} 1 \frac{1}{2}\right)}$$

Finali y dado un vector genérico en el espació de la matrica hermíticar 2x2 con la definición de producto interno definida en la secubí 2,2.4, encuentre también si 1-porma asociada.

Hatrices de Pauli:

$$\sigma_{1} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_{2} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_{3} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \sigma_{0} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Para hallar su base dual usamos la definición de wi-wi=1

$$\begin{aligned}
& \sigma_1 \cdot \sigma^1 = 1 \\
& \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} a_2 & b_2 \\ c_1 & d_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\
& \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}
\end{aligned}$$

$$\begin{aligned}
& \sigma_{3} \cdot \sigma^{3} = 1 \\
& \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}
\end{aligned}$$