Ram Padmanabhan

360 Coordinated Science Laboratory, Urbana, IL 61801, USA
ramp3@illinois.edu | Google Scholar | Website

Education

University of Illinois Urbana-Champaign — Urbana, IL, USA
Ph.D. Electrical and Computer Engineering — *August 2023 — Present*
Advisor: Prof. Melkior Ornik

University of Michigan — Ann Arbor, MI, USA
M.S. Electrical and Computer Engineering — *August 2021 — April 2023*
Advisor: Prof. Peter Seiler

PES University — Bengaluru, India
B. Tech Electronics and Communication Engineering — *August 2017 — June 2021*
Advisors: Prof. Rajini Makam and Prof. Koshy George
Capstone Project: *Adaptive Iterative Learning Control*

Publications

Preprints:

[1] **R. Padmanabhan** and M. Ornik, "Energetic Resilience of Linear Driftless Systems," *arXiv:2410.00323* [math.OC], Oct. 2024.

Journal Articles:

[2] **R. Padmanabhan** and P. Seiler, "Analysis of Gradient Descent with Varying Step Sizes using Integral Quadratic Constraints," accepted to *IEEE Transactions on Automatic Control*, 2024.

[3] **R. Padmanabhan**, R. Makam, and K. George, "Multiple Estimation Models for Discrete-time Adaptive Iterative Learning Control," *International Journal of Systems Science*, 55(10), pp. 2154–2171, 2024.

[4] **R. Padmanabhan**, M. Shetty, and T. S. Chandar, "Discrete Robust Control of Robot Manipulators using an Uncertainty and Disturbance Estimator," *Journal of Dynamic Systems, Measurement and Control*, 145(5): 051022, May 2023.

[5] **R. Padmanabhan**, M. Shetty, and T. S. Chandar, "Discrete-Time Design and Applications of Uncertainty and Disturbance Estimator," *International Journal of Robust and Nonlinear Control*, 31(10), pp. 4994–5015, Jul. 2021.

Conference Papers:

[6] **R. Padmanabhan**, C. Bakker, S. A. Dinkar, and M. Ornik, "How Much Reserve Fuel: Quantifying the Maximal Energy Cost of System Disturbances," in *63rd IEEE Conference on Decision and Control (CDC)*, Milan, Italy, Dec. 2024.

[7] **R. Padmanabhan**, M. Bhushan, K. K. Hebbar, R. Makam, and K. George, "Second-Level Adaptation and Optimization for Multiple Model Adaptive Iterative Learning Control," in *Seventh Indian Control Conference (ICC)*, Mumbai, India, Dec. 2021, pp. 289–294.

[8] S. Damodaran, **R. Padmanabhan**, R. Maahin, and S. Gurugopinath, "A Copula-Driven Unsupervised Learning Framework for Anomaly Detection with Multivariate Heterogeneous Data," in *IEEE 31st International Workshop on Machine Learning for Signal Processing*, Gold Coast, Queensland, Australia, Oct. 2021.

[9] **R. Padmanabhan**, M. Bhushan, K. K. Hebbar, R. Makam, and K. George, "A Novel Strategy with Multiple Models to Improve Performance of Adaptive Iterative Learning Control," in *IEEE International Conference on Electronics, Computing and Communication Technologies (CONECCT)*, Bengaluru, India, Jul. 2021.

[10] **R. Padmanabhan**, S. Damodaran, V. N. Batra, and S. Gurugopinath, "A Convolutional Neural Network Architecture for Camera Model Identification with Small Datasets," in *IEEE International Conference on Electronics, Computing and Communication Technologies (CONECCT)*, Bengaluru, India, Jul. 2020.

Awards and Fellowships

Joan and Lalit Bahl Fellowship — *August 2024 — May 2025*
Prof. CNR Rao Merit Scholarship — *August 2017 — May 2020*
Prof. MRD Merit Scholarship — *August 2017 — May 2020*

Teaching

Graduate Student Instructor, University of Michigan — Ann Arbor, MI, USA
EECS 460 — Control System Analysis and Design — *January — April 2023*
Held two discussion sessions each week, with teaching evaluations among the University's highest.

Graduate Student Instructor, University of Michigan — Ann Arbor, MI, USA
EECS 301 — Probabilistic Methods in Engineering — *August — December 2022*
Held two discussion sessions each week, with teaching evaluations among the University's highest.

Mentoring

Undergraduate Research Apprenticeship Program (URAP) — *August 2024 — May 2025*

Promoting Undergraduate Research in Engineering (PURE) — *August — December 2023*
Mentored a group of three undergraduates at UIUC in investigating the performance of different nonlinear Kalman filters on the problem of battery state-of-charge estimation.
(One student subsequently joined our primary research group.)

Experience

Research Intern, Indian Institute of Technology, Bombay — Mumbai, India
Systems and Control Engineering — *December 2020 — May 2021*
Used feedback linearization to achieve an upwind climb in gliding unmanned aerial vehicles with various wind gradient models, avoiding heavy computations from optimal control formulations.

Research Intern, Indian Space Research Organization — Bengaluru, India
Control and Digital Electronics Group — *June — July 2019*
Studied the properties of the Linear and Ensemble Kalman Filter, applied to a one– and three-dimensional motion estimation problem.

Peer Reviewer

American Control Conference — *2024 —*
IEEE Conference on Decision and Control — *2024 —*
Automatica — *2023 —*
IEEE Transactions on Systems, Man and Cybernetics — *2023 —*
IEEE Transactions on Industrial Electronics — *2024 —*

Other Presentations

Northwestern University, Midwest Workshop on Control and Game Theory — Evanston, IL, USA
How Much Reserve Fuel: Quantifying the Maximal Energy Cost of System Disturbances — *April 2024*

University of California, Berkeley — Berkeley, CA, USA
Analysis of Gradient Descent with Varying Step Sizes using IQCs [Online] — *February 2023*

PES University — Bengaluru, India
Discrete-Time Design and Applications of Uncertainty and Disturbance Estimator — *April 2021*

Memberships

Graduate Student Member: IEEE; IEEE Control Systems Society; IEEE Signal Processing Society