

Ram Padmanabhan

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EDUCATION

University of Illinois Urbana-Champaign
Ph.D. Electrical and Computer Engineering
Advisor: Prof. Melkior Ornik

Urbana, IL, USA
August 2023 — Present

University of Michigan
M.S. Electrical and Computer Engineering
Advisor: Prof. Peter Seiler

Ann Arbor, MI, USA
August 2021 — April 2023

PES University
B. Tech Electronics and Communication Engineering
Advisors: Prof. Rajini Makam and Prof. Koshy George
Capstone Project: *Adaptive Iterative Learning Control*

Bengaluru, India
August 2017 — June 2021

PUBLICATIONS

Journal Articles:

- [1] **R. Padmanabhan** and P. Seiler, "Analysis of Gradient Descent with Varying Step Sizes using Integral Quadratic Constraints," accepted to *IEEE Transactions on Automatic Control*, 2024.
- [2] **R. Padmanabhan**, R. Makam, and K. George, "[Multiple Estimation Models for Discrete-time Adaptive Iterative Learning Control](#)," *International Journal of Systems Science*, 55(10), pp. 2154–2171, 2024.
- [3] **R. Padmanabhan**, M. Shetty, and T. S. Chandar, "[Discrete Robust Control of Robot Manipulators using an Uncertainty and Disturbance Estimator](#)," *Journal of Dynamic Systems, Measurement and Control*, 145(5): 051022, May 2023.
- [4] **R. Padmanabhan**, M. Shetty, and T. S. Chandar, "[Discrete-Time Design and Applications of Uncertainty and Disturbance Estimator](#)," *International Journal of Robust and Nonlinear Control*, 31(10), pp. 4994–5015, Jul. 2021.

Conference Papers:

- [5] **R. Padmanabhan**, C. Bakker, S. A. Dinkar, and M. Ornik, "How Much Reserve Fuel: Quantifying the Maximal Energy Cost of System Disturbances," in *2024 63rd IEEE Conference on Decision and Control (CDC)*, Milan, Italy, Dec. 2024.
- [6] **R. Padmanabhan**, M. Bhushan, K. K. Hebbar, R. Makam, and K. George, "[Second-Level Adaptation and Optimization for Multiple Model Adaptive Iterative Learning Control](#)," in *2021 Seventh Indian Control Conference*, Mumbai, India, Dec. 2021, pp. 289–294.
- [7] S. Damodaran, **R. Padmanabhan**, R. Maahin, and S. Gurugopinath, "[A Copula-Driven Unsupervised Learning Framework for Anomaly Detection with Multivariate Heterogeneous Data](#)," in *2021 IEEE 31st International Workshop on Machine Learning for Signal Processing*, Gold Coast, Queensland, Australia, Oct. 2021.
- [8] **R. Padmanabhan**, M. Bhushan, K. K. Hebbar, R. Makam, and K. George, "[A Novel Strategy with Multiple Models to Improve Performance of Adaptive Iterative Learning Control](#)," in *2021 IEEE International Conference on Electronics, Computing and Communication Technologies (CONECCT)*, Bengaluru, India, Jul. 2021.
- [9] **R. Padmanabhan**, S. Damodaran, V. N. Batra, and S. Gurugopinath, "[A Convolutional Neural Network Architecture for Camera Model Identification with Small Datasets](#)," in *2020 IEEE International*

Conference on Electronics, Computing and Communication Technologies (CONECCT), Bengaluru, India, Jul. 2020.

AWARDS AND FELLOWSHIPS

Joan and Lalit Bahl Fellowship	<i>August 2024 — May 2025</i>
Prof. CNR Rao Merit Scholarship	<i>August 2017 — May 2020</i>
Prof. MRD Merit Scholarship	<i>August 2017 — May 2020</i>

TEACHING

Graduate Student Instructor, University of Michigan	Ann Arbor, MI, USA
<i>EECS 460 — Control System Analysis and Design</i>	<i>January — April 2023</i>
Held two discussion sessions each week, with teaching evaluations among the University's highest.	

Graduate Student Instructor, University of Michigan	Ann Arbor, MI, USA
<i>EECS 301 — Probabilistic Methods in Engineering</i>	<i>August — December 2022</i>
Held two discussion sessions each week, with teaching evaluations among the University's highest.	

MENTORING

Undergraduate Research Apprenticeship Program (URAP)	<i>August 2024 — May 2025</i>
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Promoting Undergraduate Research in Engineering (PURE)	<i>August — December 2023</i>
Mentored a group of three undergraduates at UIUC in investigating the performance of different nonlinear Kalman filters on the problem of battery state-of-charge estimation. (One student subsequently joined our primary research group.)	

EXPERIENCE

Research Intern, Indian Institute of Technology, Bombay	Mumbai, India
<i>Systems and Control Engineering</i>	<i>December 2020 — May 2021</i>
Used feedback linearization to achieve an upwind climb in gliding unmanned aerial vehicles with various wind gradient models, avoiding heavy computations from optimal control formulations.	

Research Intern, Indian Space Research Organization	Bengaluru, India
<i>Control and Digital Electronics Group</i>	<i>June — July 2019</i>
Studied the properties of the Linear and Ensemble Kalman Filter, applied to a one- and three-dimensional motion estimation problem.	

PEER REVIEWER

IEEE Conference on Decision and Control	<i>2024 —</i>
Automatica	<i>2023 —</i>
IEEE Transactions on Systems, Man and Cybernetics	<i>2023 —</i>
IEEE Transactions on Industrial Electronics	<i>2024 —</i>

OTHER PRESENTATIONS

Northwestern University, Midwest Workshop on Control and Game Theory	Evanston, IL, USA
<i>How Much Reserve Fuel: Quantifying the Maximal Energy Cost of System Disturbances</i>	<i>April 2024</i>

University of California, Berkeley	Berkeley, CA, USA
<i>Analysis of Gradient Descent with Varying Step Sizes using IQCs [Online]</i>	<i>February 2023</i>

PES University	Bengaluru, India
<i>Discrete-Time Design and Applications of Uncertainty and Disturbance Estimator</i>	<i>April 2021</i>

MEMBERSHIPS

Graduate Student Member: IEEE; IEEE Control Systems Society; IEEE Signal Processing Society