

# Processes, Threads, Scheduling & Secure Execution

**Prof. Khushal Bhoyar**

Department of CSE (Cyber Security)  
PIET, Parul University

## 2.1 Process Management Fundamentals

- A process represents a program in execution.
- It consists of:
  - The executable code.
  - Current activity.
  - Associated system resources.
- Processes transition through various states:
  - New (creation).
  - Ready (awaiting CPU allocation).
  - Running (executing on CPU).
  - Waiting (awaiting event completion).
  - Terminated (finished execution).
- **The Process Control Block (PCB)** serves as the kernel data structure containing all information about a process.

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- **The PCB contains:**
- Process state.
- Program counter.
- CPU registers.
- Scheduling information.
- Memory management data.
- Accounting information.
- I/O status.
- **Context switching** involves saving the state of the current process and restoring the state of the next process to execute.
- **Context switching** requires careful management of:
- CPU registers.
- Program counters.
- Memory management data.

## 2.2 Thread Architecture and Implementation

- Threads represent the smallest unit of execution within a process.
- Threads share the process's:
  - Code.
  - Data.
  - Resources.
- Threads have independent execution streams.
- **User-level threads:**
  - Are managed by user-space libraries without kernel involvement.
  - Offer fast creation and switching.
  - Lack true parallelism on multiprocessors.
- **Kernel-level threads:**
  - Are managed directly by the OS kernel.
  - Enable true parallel execution across multiple CPUs.
  - Have higher management overhead.

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- **Multithreading benefits include:**
- Improved responsiveness (blocking one thread doesn't block entire process).
- Resource sharing (threads share memory and resources efficiently).
- Economy (thread creation cheaper than process creation).
- Scalability (better utilization of multiprocessor architectures).

Modern systems typically implement hybrid threading models combining advantages of both approaches.

## 2.3 CPU Scheduling Algorithms

- CPU scheduling determines which ready process receives CPU time.  
It is based on specific scheduling objectives:

- Maximizing CPU utilization.
- Ensuring fairness.
- Minimizing response time.
- Maintaining system balance.

### **First-Come-First-Served (FCFS):**

- Executes processes in arrival order.
- Simple but suffers from convoy effect.

### **Shortest Job First (SJF):**

- Selects the process with smallest next CPU burst.
- Optimal for minimizing average waiting time.
- Requires accurate burst time estimation.

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### **Round Robin (RR):**

Allocates fixed time quantum to each process in circular order.  
Ensures fairness with reasonable response times.

### **Priority scheduling:**

Assigns priority levels to processes.  
Executes highest priority ready process first.  
Potentially causes starvation of low-priority processes without aging mechanisms.

Modern systems typically implement multi-level feedback queues.  
These queues combine multiple algorithms with priority adjustments based on process behavior.

## 2.4 Security in Process Execution

**Process isolation** ensures that processes cannot interfere with each other's memory or execution.

It is implemented through:

Hardware memory protection.

Virtual address spaces.

**Sandboxing** creates restricted execution environments that limit system access for untrusted code.

Sandboxing uses techniques like:

System call filtering.

Resource quotas.

Namespace isolation.

**Privilege separation** divides programs into components with minimal necessary privileges.

This limits damage from compromised components.

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**Address Space Layout Randomization (ASLR)** randomizes memory locations of key data areas to thwart memory corruption attacks.

**Data Execution Prevention (DEP)** marks memory pages as non-executable unless explicitly containing code.

DEP prevents execution of injected malicious code.

These mechanisms collectively form a defense-in-depth approach to process security.

This approach makes successful exploitation increasingly difficult.

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