

Applied Sciences and Humanities

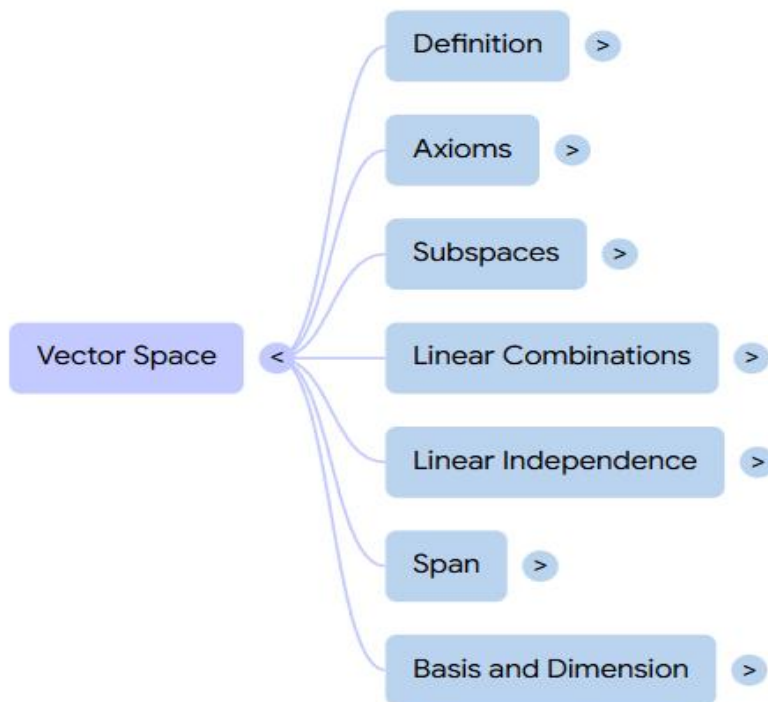
Unit 2 Vector Space

Study Guide

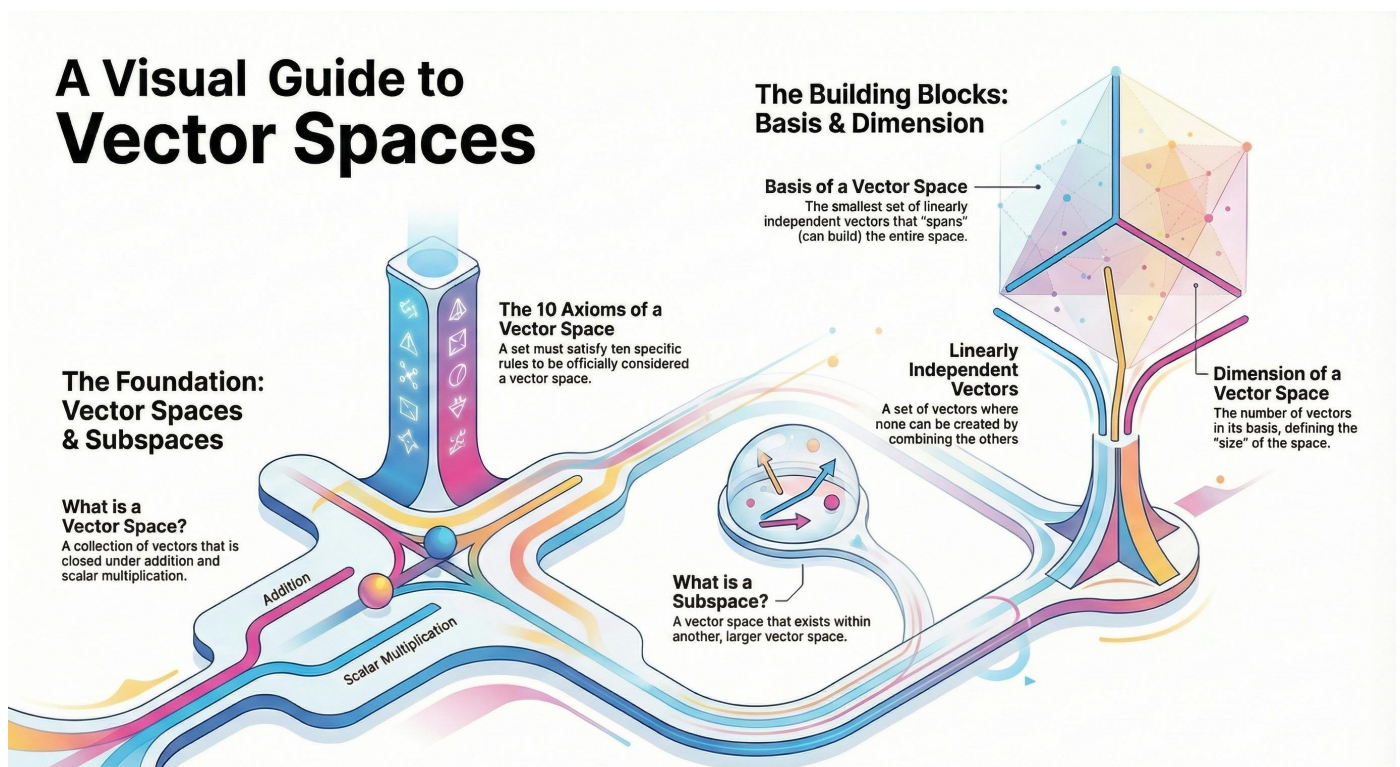
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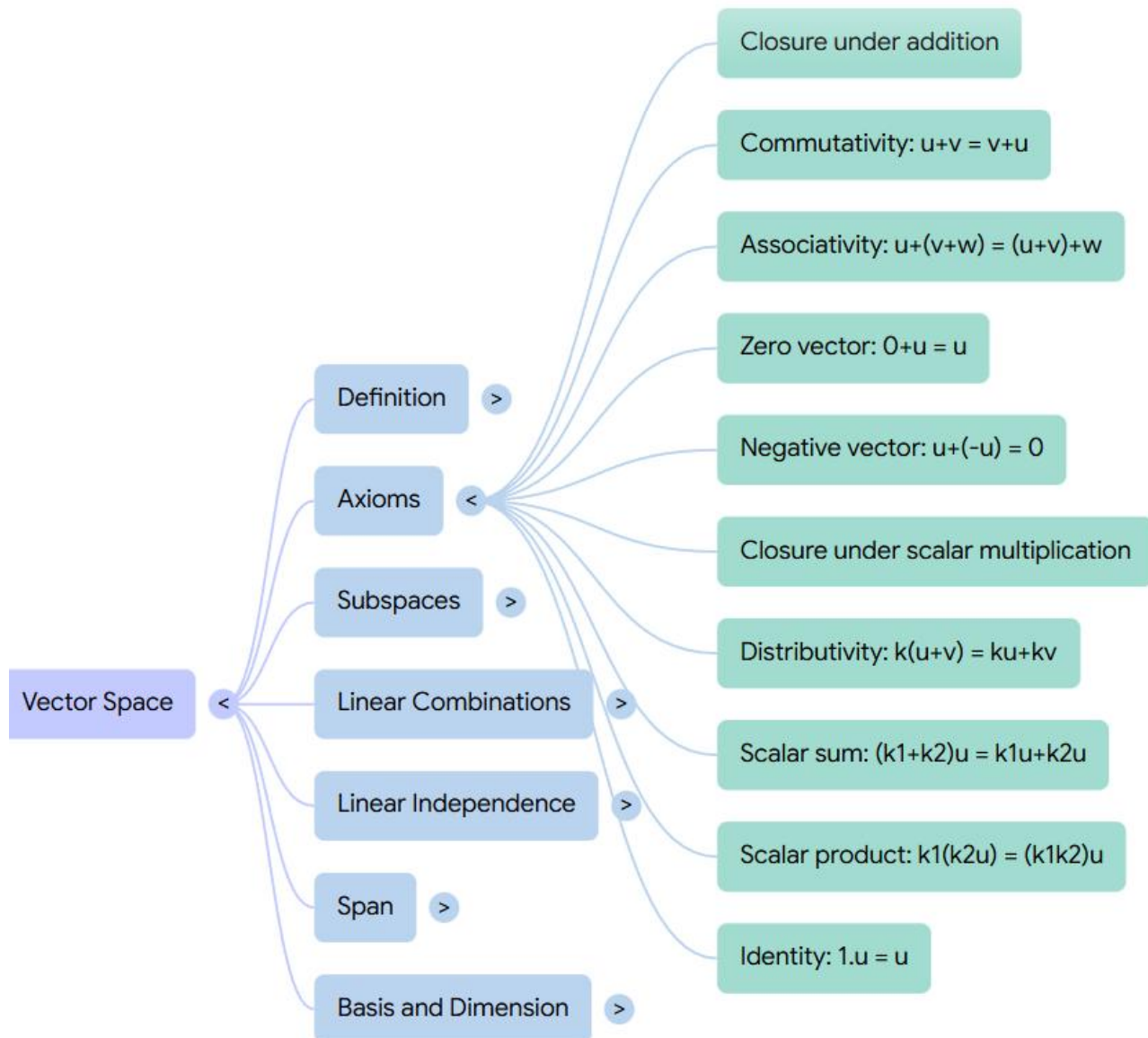
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2. VECTOR SPACE:

Let V be a non-empty set of vectors on which the operations of addition and multiplication by scalars are defined.

If the following axioms are satisfied by all vectors u, v, w in V and all scalars k_1, k_2 then V is called a vector space and elements in V are called vectors

1. If u and v are vectors in V then $u+v$ is in V .
2. $u+v=v+u$
3. $u+(v+w)=(u+v)+w$
4. There is an vector 0 in V , called Zero vector , such that $0+u = u+0=u$ for all u in V .

5. For each vector u in V , there exist an vector $-u$ in V is called a negative of u , such that
 $u + (-u) = (-u) + u = 0$.
6. If k_1 is any scalar and u is an vector in V ,
then $k_1 u$ is in V .
7. $k_1(u+v) = k_1 u + k_1 v$
8. If k_1, k_2 are scalars and u is an vector in V ,
then $(k_1 + k_2)u = k_1 u + k_2 u$.
9. $k_1(k_2 u) = (k_1 k_2)u$
10. $1.u = u$

Example 1: Determine whether the set V of all pairs of real numbers (x, y) with the operations
 $(x_1, y_1) + (x_2, y_2) = (x_1 + x_2 + 1, y_1 + y_2 + 1)$ and $k(x, y) = (kx, ky)$ is a vector space.

Solution:- Let $u = (x_1, y_1)$, $v = (x_2, y_2)$ and $w = (x_3, y_3)$ are vectors in V and k_1, k_2 are some scalars.

1. $u + v = (x_1, y_1) + (x_2, y_2) = (x_1 + x_2 + 1, y_1 + y_2 + 1) \in V$
2. $u + v = (x_1 + x_2 + 1, y_1 + y_2 + 1) = (x_2 + x_1 + 1, y_2 + y_1 + 1) = v + u$
3. $u + (v + w) = (x_1, y_1) + [(x_2, y_2) + (x_3, y_3)]$
 $= (x_1, y_1) + [(x_2 + x_3 + 1, y_2 + y_3 + 1)]$
 $= [x_1 + (x_2 + x_3 + 1) + 1, y_1 + (y_2 + y_3 + 1) + 1]$
 $= [(x_1 + x_2 + 1) + x_3 + 1, (y_1 + y_2 + 1) + y_3 + 1]$
 $= (x_1 + x_2 + 1, y_1 + y_2 + 1) + (x_3, y_3) = (u + v) + w$
4. Let (a, b) be an vector in V such that $(a, b) + u = u$
 $(a, b) + (x_1, y_1) = (x_1, y_1)$
 $(a + x_1 + 1, b + y_1 + 1) = (x_1, y_1) = a + x_1 + 1 = x_1, b + y_1 + 1 = y_1$
 $a = -1$ and $b = -1$, Hence $(-1, -1)$ is zero vector
5. Let (a, b) be an vector in V such that $u + (a, b) = (-1, -1)$
 $(x_1, y_1) + (a, b) = (-1, -1)$
 $(x_1 + a + 1, y_1 + b + 1) = (-1, -1) = x_1 + a + 1 = -1, y_1 + b + 1 = -1$
 $a = -x_1 - 2$ and $b = -y_1 - 2$,
Hence $(-x_1 - 2, -y_1 - 2)$ is the negative of u in V .
6. $k_1 u = k_1(x_1, y_1) = (k_1 x_1, k_1 y_1) \in V$
7. $k_1(u + v) = k_1(x_1 + x_2 + 1, y_1 + y_2 + 1)$
 $= (k_1 x_1 + k_1 x_2 + k_1, k_1 y_1 + k_1 y_2 + k_1)$
 $\neq k_1 u + k_1 v$

$\therefore V$ is not distributive under scalar multiplication, hence V is not a vector space.

Example 2:

Determine whether the set R^+ of all positive real number with operations
 $x + y = xy$ and $kx = x^k$ is a vector space.

Solution:-

Let x, y and z be positive real numbers in R^+ and k_1, k_2 are some scalars

1. $x + y = xy$, is also a positive real number.
2. $x + y = xy = yx = y + x$
3. $x + (y + z) = x(y + z) = x(yz) = (xy)z = (x + y)z = (x + y) + z$
4. Let a be a object in R^+ such that $a + x = x$, $ax = x$, $a = 1$, so 1 is zero vector in V
5. $x + a = 1$, $xa = 1$, $a = \frac{1}{x}$, so $\frac{1}{x}$ is the negative of x in R^+
6. If k_1 is real then $k_1 x = x^{k_1} \in R^+$
7. $k_1(x + y) = k_1(xy) = (xy)^{k_1} = x^{k_1} y^{k_1} = (k_1 x)(k_1 y) = k_1 x + k_1 y$

8. $(k_1 + k_2)x = x^{k_1 + k_2} = x^{k_1} x^{k_2} = k_1 x k_2 x = k_1 x + k_2 x$
 9. $k_1(k_2 x) = k_1 x^{k_2} = (x^{k_2})^{k_1} = x^{k_2 k_1} = x^{(k_1 k_2)} = (k_1 k_2)x$
 10. $1x = x^1 = x$

All axioms are satisfied by R^+ under operations.
 Hence, R^+ is a vector space under given operations.

Exercise:

1. Check whether following are vector space or not?

a. The set of all pairs of real number (x, y) with the function

$$(x_1, y_1) + (x_2, y_2) = (x_1 + x_2, y_1 + y_2) \text{ and } k(x, y) = (2kx, 2ky).$$

b. $(x_1, y_1, z_1) + (x_2, y_2, z_2) = (z_1 + z_2, y_1 + y_2, x_1 + x_2)$

2. Check whether $V = R^2$ is a vector space with respect to

$$(x_1, y_1) + (x_2, y_2) = (x_1 + x_2 - 2, y_1 + y_2 - 3) \text{ and } k(x, y) = (kx + 2k - 2, ky - 3k + 3), k \text{ is a real number.}$$

3. The set of all 2×2 matrices of the form

$$\begin{bmatrix} a & 1 \\ 1 & b \end{bmatrix} \text{ with standard matrix addition and scalar multiplication.}$$

4. The set of all 2×2 matrices of the form $\begin{bmatrix} a & 1 \\ b & 1 \end{bmatrix}$ with $\begin{bmatrix} a & 1 \\ b & 1 \end{bmatrix} + \begin{bmatrix} c & 1 \\ 1 & d \end{bmatrix} = \begin{bmatrix} a+c & 1 \\ 1 & b+d \end{bmatrix}$ and $k \begin{bmatrix} a & 1 \\ 1 & b \end{bmatrix} = \begin{bmatrix} ka & 1 \\ 1 & kb \end{bmatrix}$

5. The set of all ordered triples of real numbers of the form $(0, 0, z)$ with the operations $(0, 0, z_1) + (0, 0, z_2) = (0, 0, z_1 + z_2)$ and $k(0, 0, z) = (0, 0, kz)$

2.1.SUBSPACES:

A non-empty subset W of a vector space is called subspace of V if W is itself a vector space under the operation defined on V .

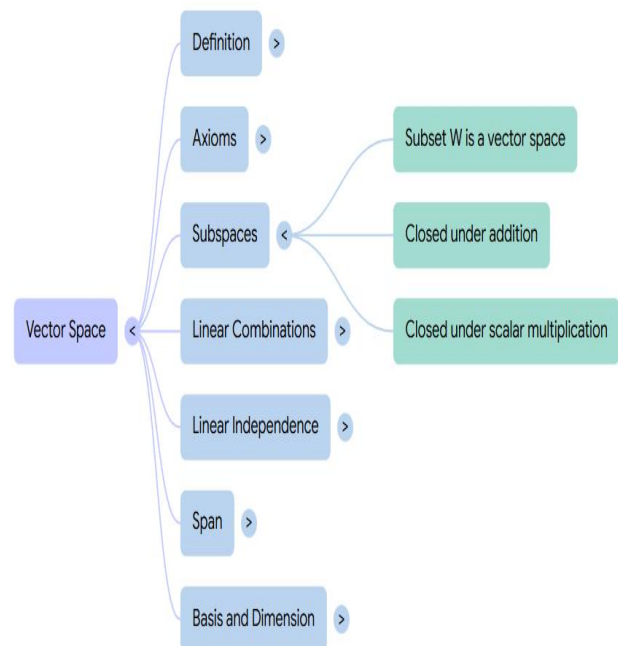
If W is a non-empty of vector space V , then W is a subspace of V if and only if following axioms hold.

Axiom 1:-

If u and v are vectors in W then $u + v$ is in W .

Axiom 2 :-

If k is a scalar and u is a vector in W , then ku is in W .



Example 3: Show that $W = \{(x, y) | x = 3y\}$ is a subspace of \mathbb{R}^2 .

Solution: Let $u = \{(x_1, y_1) | x_1 = 3y_1\}$ and $v = \{(x_2, y_2) | x_2 = 3y_2\}$ are in W and k is any scalar.

$$\begin{aligned} u + v &= (x_1, y_1) + (x_2, y_2) = (x_1 + x_2, y_1 + y_2) \quad x_1 = 3y_1 \\ &\quad \text{and } x_2 = 3y_2, \quad x_1 + x_2 = 3(y_1 + y_2), \\ u + v &= \{(x_1 + x_2, y_1 + y_2) | x_1 + x_2 = 3(y_1 + y_2)\} \quad \text{thus } u + v \text{ is in } W \\ ku &= k(x_1, y_1) = (kx_1, ky_1), \quad x_1 = 3y_1, \quad kx_1 = 3(ky_1), \\ ku &= \{(kx_1, ky_1) | kx_1 = 3(ky_1)\}, \end{aligned}$$

Thus ku is in W , so it's a subspace.

Example 4:- $W = \{(x, y, z) | x^2 + y^2 + z^2 \leq 1\}$

Solution:- Let $u = (1, 0, 0)$ and $v = (0, 0, 1)$ be two vectors of W satisfying $x^2 + y^2 + z^2 \leq 1$

$$u + v = (1, 0, 0) + (0, 0, 1) = (1, 0, 1),$$

Here $x^2 + y^2 + z^2 = 2 > 1$. Thus $u + v$ is not in W . So W is not closed under addition and hence is not a subspace of \mathbb{R}^3 .

Exercise:

(i) Show that the following sets are the subspaces of the respective real vector space V

under standard operation (i) $W = \{a_0 + a_1x + a_2x^2 + a_3x^3 | a_0 = 0\}$

(ii) $W = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mid a + b + c + d = 0 \right\}$

(iii) $W = \{(x, y) | x^2 = y^2\}$, (iv) $W = \{A_{nn} | AB = BA \text{ for a fixed } B_{nn}\}$

(iv) $W = \{f | f(x) = a_1 + a_2 \sin x, \text{ where } a_1 \text{ and } a_2 \text{ are real numbers}\}$,

(v) $W = \{(x, y) | xy \geq 0\}$

2.2.LINEAR COMBINATION:

If w is a vector in vector space V then w is said to be linear combination of the vectors

v_1, v_2, \dots, v_r if w can be expressed in the form,

$$w = k_1v_1 + k_2v_2 + \dots + k_rv_r$$

where k_1, k_2, \dots, k_r are scalars and known as coefficient of linear combination.

2.2.1.LINEAR DEPENDENCE AND INDEPENDENCE:

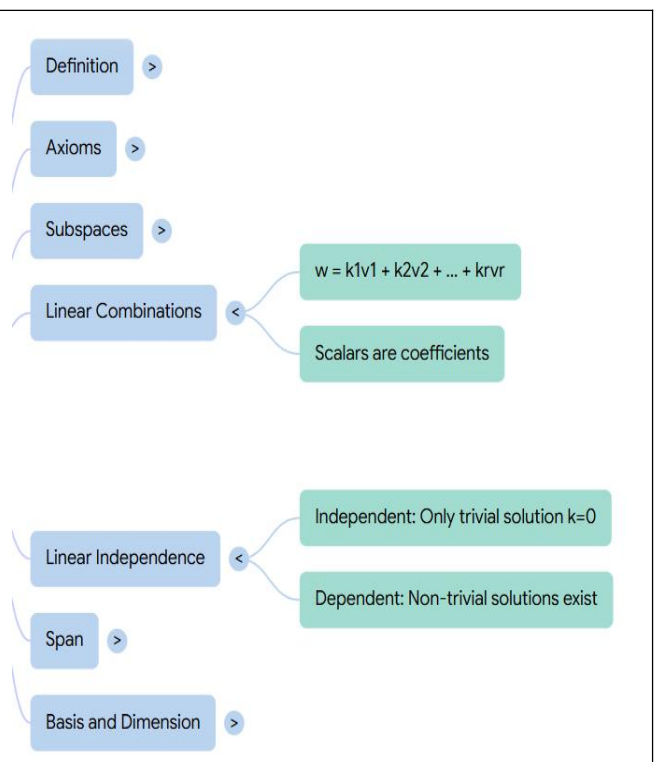
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Let $S = \{v_1, v_2, \dots, v_r\}$ is a nonempty set of vectors such that

$$k_1v_1 + k_2v_2 + \dots + k_rv_r = 0$$

If following homogeneous system obtained has trivial solution then S is called linearly independent.

If the system has a non-trivial solution then S is called linearly dependent.



Example 5:- Check following set in \mathbb{R}^3 is linearly dependent or independent?

(i) $(4, -1, 2), (-4, 10, 2), (4, 0, 1)$

Solution:

Let $v_1 = (4, -1, 2), v_2 = (-4, 10, 2), v_3 = (4, 0, 1)$
 $k_1 v_1 + k_2 v_2 + k_3 v_3 = 0$
 $k_1(4, -1, 2) + k_2(-4, 10, 2) + k_3(4, 0, 1) = (0, 0, 0)$

$$\left[\begin{array}{ccc|c} 4 & -4 & 4 & 0 \\ -1 & 10 & 0 & 0 \\ 2 & 2 & 1 & 0 \end{array} \right] \quad \left(\frac{1}{4} \right) R_1$$

$$\left[\begin{array}{ccc|c} - & -1 & 1 & 0 \\ -1 & 10 & 0 & 0 \\ 2 & 2 & 1 & 0 \end{array} \right] \quad R_2 + R_1, \quad R_3 - 2R_1$$

Solution is $v_1 = 0, v_2 = 0, v_3 = 0$
 They system has trivial solution so
 v_1, v_2, v_3 are linearly independent

$$\left[\begin{array}{ccc|c} - & -1 & 1 & 0 \\ 0 & 9 & 1 & 0 \\ 0 & 4 & -1 & 0 \end{array} \right] \quad \left(\frac{1}{9} \right) R_2$$

$$\left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 1 & \frac{1}{9} & 0 \\ 0 & 4 & -1 & 0 \end{array} \right] \quad R_3 - 4R_2$$

$$\left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 1 & \frac{1}{9} & 0 \\ 0 & 0 & -\frac{13}{9} & 0 \end{array} \right]$$

Example 6:- Let $v_1 = (-2, 0, 1), v_2 = (3, 2, 5), v_3 = (6, -1, 1), v_4 = (7, 0, -2)$

$$k_1 v_1 + k_2 v_2 + k_3 v_3 + k_4 v_4 = 0$$

$$k_1(-2, 0, 1) + k_2(3, 2, 5) + k_3(6, -1, 1) + k_4(7, 0, -2) = (0, 0, 0)$$

Equating corresponding components

$$-2k_1 + 3k_2 + 6k_3 + 7k_4 = 0$$

$$2k_2 - k_3 = 0$$

$$k_1 + 5k_2 + k_3 - 2k_4 = 0$$

The number of unknowns, $r=4$ and The number of equations, $n=3$,

Hence v_1, v_2, v_3, v_4 are linearly dependent

Exercise: Check L.D. OR L.I.

(i) $2-x+4x^2, 3+6x+2x^2, 2+10x-4x^2$

(ii) $A_1 = \begin{bmatrix} -3 & 4 \\ 2 & 0 \end{bmatrix}$ and $A_2 = \begin{bmatrix} 3 & -4 \\ -2 & 0 \end{bmatrix}$ in M_{22}

(iii) Show that vectors $v_1 = (0, 3, 1, -1), v_2 = (6, 0, 5, 1)$ and $v_3 = (4, -7, 1, 3)$ form linearly dependent in \mathbb{R}^4 .

(iv) For what value of λ are vectors $v_1 = \left(\lambda, -\frac{1}{2}, -\frac{1}{2} \right), v_2 = \left(-\frac{1}{2}, \lambda, -\frac{1}{2} \right), v_3 = \left(-\frac{1}{2}, -\frac{1}{2}, \lambda \right)$

is linearly dependent in \mathbb{R}^3

2.3. SPAN:

If $S = \{w_1, w_2, \dots, w_r\}$ is a non-empty set of vectors in a vector space V , then the subspace W of V that consists of all possible linear combinations of the vectors in S is called the subspace of V generated by S , and we say that the vectors w_1, w_2, \dots, w_r span W .

We denote this subspace as $W = \text{span}\{w_1, w_2, \dots, w_r\}$ or $W = \text{span}(S)$.

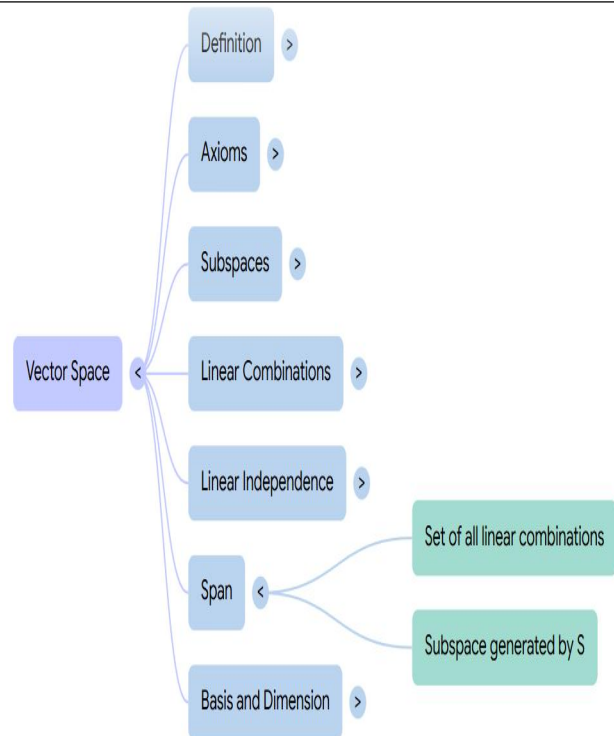
$$\text{Span}(S) = \{c_1 v_1 + c_2 v_2 + \dots + c_i v_i \mid \forall c_i \in \mathbb{R}\}$$

(the set of all linear combinations of vectors in S)

2.4. BASIS:

The set of vectors $S = \{v_1, v_2, v_3, \dots, v_n\}$ in a vector space V is called a basis for V if

- (i) S is linearly independent
- (ii) S spans V



2.5. A SPANNING SET OF VECTOR

If every vector in a given vector space can be written as a linear combination of vectors in a given set S , then S is called a spanning set of the vector space.

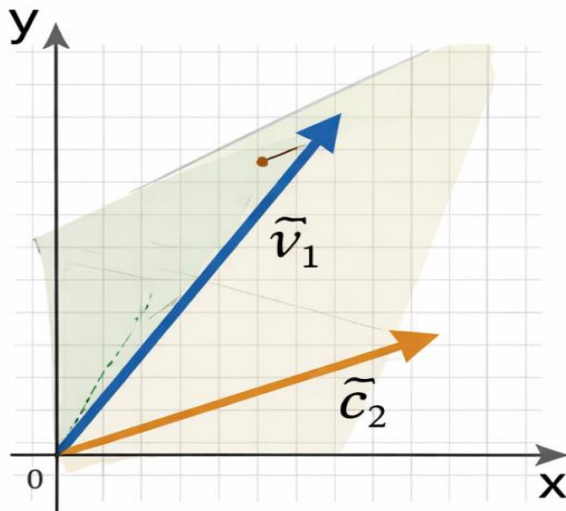
OR

A vector v in a vector space V is called a linear combination of the vectors u_1, u_2, \dots, u_k in V if v can be written in the form

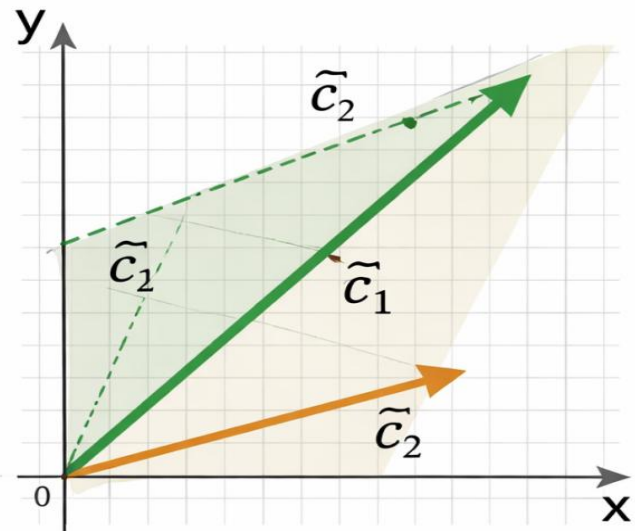
$$\text{Span}(S) = \{c_1 v_1 + c_2 v_2 + \dots + c_i v_i \mid \forall c_i \in \mathbb{R}\}$$

(the set of all linear combinations of vectors in S)

Spanning Set



$$\tilde{u} = c_1 \tilde{v}_1 + c_2 \tilde{v}_2$$



Example 7:- Show that vectors $e_1=i=(1,0,0)$, $e_2=j=(0,1,0)$ and $e_3=k=(0,0,1)$ form a basis for \mathbb{R}^3

Solution:- Let $b = (b_1, b_2, b_3)$ be an arbitrary vectors in \mathbb{R}^3 and

can be expressed as a linear combination of $b=k_1e_1+k_2e_2+k_3e_3$

$$(b_1, b_2, b_3) = k_1(1, 0, 0) + k_2(0, 1, 0) + k_3(0, 0, 1) = (k_1, k_2, k_3)$$

Equating we get $k_1=b_1, k_2=b_2, k_3=b_3$

Since for each choice of (b_1, b_2, b_3) some scalars k_1, k_2, k_3 exist the given vectors span \mathbb{R}^3 .

Now consider, $k_1e_1+k_2e_2+k_3e_3=0$

$$k_1(1, 0, 0) + k_2(0, 1, 0) + k_3(0, 0, 1) = (0, 0, 0), \text{ Equating we get } k_1=k_2=k_3=0$$

Thus e_1, e_2 and e_3 are linearly independent. Hence e_1, e_2 and e_3 form a basis for \mathbb{R}^3 .

Example 8: Let $v_1=(1,2,1)$, $v_2=(2,9,0)$ and $v_3=(3,3,4)$. Show that the set

$S=\{v_1, v_2, v_3\}$ is a basis for \mathbb{R}^3 .

Solution:- Let $b = (b_1, b_2, b_3)$ be an arbitrary vectors in \mathbb{R}^3 and can be expressed as a linear combination of

$$b = k_1v_1 + k_2v_2 + k_3v_3$$

$$(b_1, b_2, b_3) = k_1(1, 2, 1) + k_2(2, 9, 0) + k_3(3, 3, 4)$$

$$\text{Or } (b_1, b_2, b_3) = (k_1 + 2k_2 + 3k_3, 2k_1 + 9k_2 + 3k_3, k_1 + 4k_3)$$

$$\text{Or } k_1 + 2k_2 + 3k_3 = b_1, 2k_1 + 9k_2 + 3k_3 = b_2, k_1 + 4k_3 = b_3$$

We form the matrix with v_1, v_2, v_3 as a columns $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 9 & 3 \\ 1 & 0 & 4 \end{bmatrix}$

To check for linear independence, we determine if the determinant of A is nonzero.

$$\text{Here } \det(A) = \begin{vmatrix} 1 & 2 & 3 \\ 2 & 9 & 3 \\ 1 & 0 & 4 \end{vmatrix} \neq 0, \text{ therefore the vectors are linearly independent.}$$

Since S consists of three linearly independent vectors in R^3 , they must also span R^3 . Therefore, S is a **basis** for R^3 .

Exercise:-

(i) Show that the set $S = \{1, x, x^2, \dots, x^n\}$ is a basis for the vector space P_n .

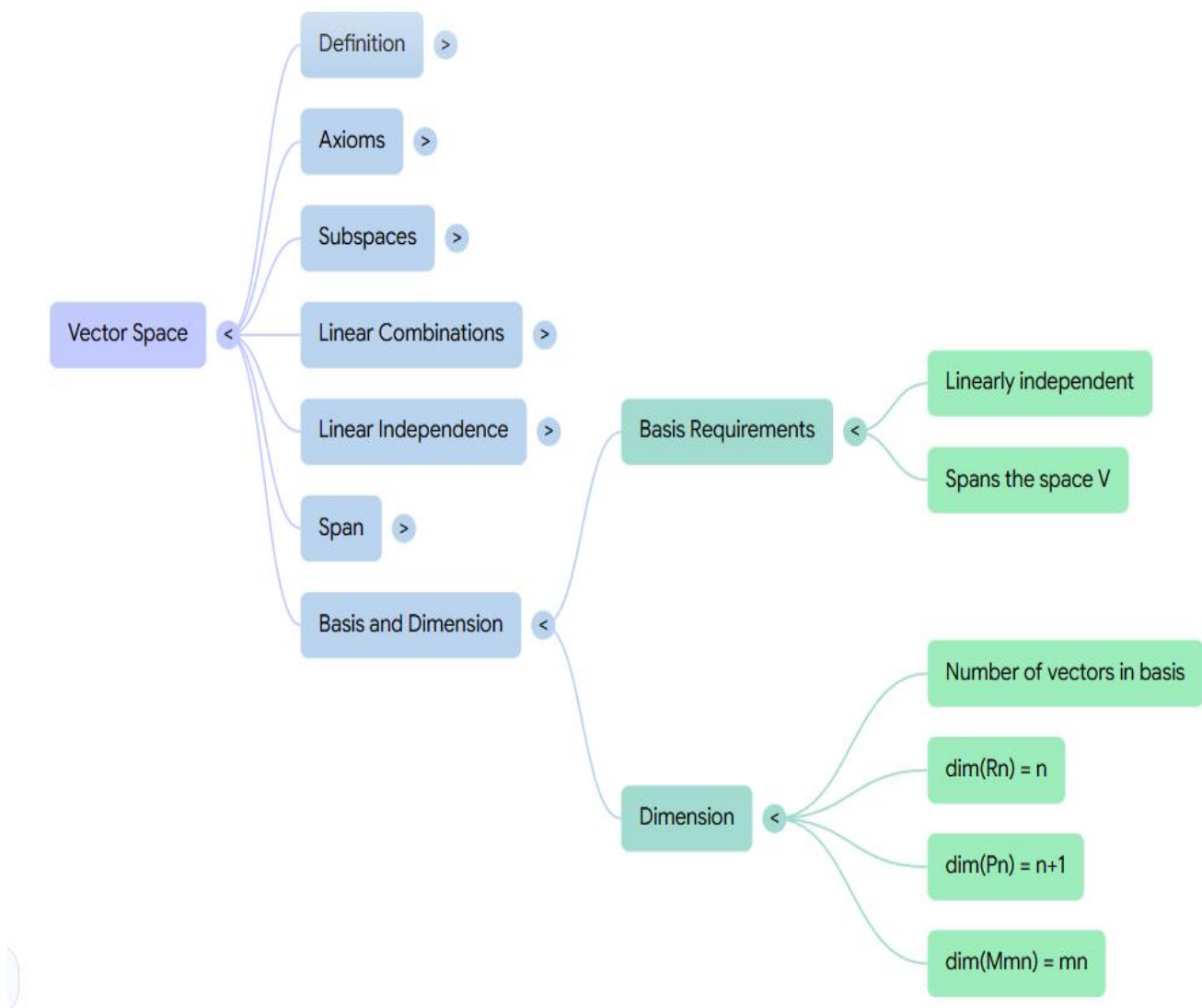
(ii) Show that the set $S = \{v_1, v_2, v_3, v_4\}$ is a basis for the vector space M_{22} where

$$v_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, v_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, v_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, v_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

(iii) Show that the set $S = \{v_1, v_2, v_3\}$ is a basis for R^3 , where $v_1(1,0,0)$, $v_2(2,2,0)$ and $v_3(3,3,3)$

(iv) Check which of following is basis for P_2 , $-4+x+3x^2$, $6+5x+2x^2$, $8+4x+x^2$

(v) Let V be the space spanned by $v_1 = \cos^2 x$, $v_2 = \sin^2 x$, $v_3 = \cos 2x$. Show that $S = \{v_1, v_2, v_3\}$ is not a basis



2.6.DIMENSIONS:

The number of vectors in basis of a non-zero finite dimensional vector space V is known as the dimension of V and is denoted by $\dim(V)$.

Remark :

(i) $\dim(R^n) = n$,

(ii) $\dim(P_n) = n+1$,

(iii) $\dim(M_{mn}) = mn$, (iv) $\dim\{0\} = 0$

Example9: Determine the dimension and a basis for the solution space of the system

$$x_1 + x_2 - 2x_3 = 0, -2x_1 - 2x_2 + 4x_3 = 0, -x_1 - x_2 + 2x_3 = 0$$

Solution:-

The matrix form of the system is,
$$\begin{bmatrix} 1 & 1 & -2 \\ -2 & -2 & 4 \\ -1 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The augmented matrix is
$$\left[\begin{array}{ccc|c} 1 & 1 & -2 & 0 \\ -2 & -2 & 4 & 0 \\ -1 & -1 & 2 & 0 \end{array} \right]$$

$R_2 + 2R_1, R_3 + R_1$

$$\left[\begin{array}{ccc|c} 1 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

The corresponding system of equation is $x_1 + x_2 - 2x_3 = 0$, solving for leading variables,

$$x_1 = -x_2 + 2x_3$$

Assigning the free variables x_2 and x_3 arbitrary values t_1 and t_2 respectively,

$x_1 = -t_1 + 2t_2, x_2 = t_1, x_3 = t_2$ is the solution of the system

The solution vector is
$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -t_1 + 2t_2 \\ t_1 \\ t_2 \end{bmatrix} = t_1 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + t_2 \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} = t_1 x_1 + t_2 x_2$$

$$\text{Basis} = \{x_1, x_2\} = \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \right\}, \text{Dimension} = 2$$

Exercise:-

(i) Find dimension and a basis for the solution space of the system

$$3x_1 + x_2 + x_3 + x_4 = 0, 5x_1 - x_2 + x_3 - x_4 = 0$$

(ii) Find a basis and dimension of $W = \{(a_1, a_2, a_3, a_4) \in \mathbb{R}^4 \mid a_1 + a_2 = 0, a_3 + a_4 = 0\}$

(iii) Find the dimension and a basis for the following subspaces of P_2 and P_3 , all polynomials of the form $ax^3 + bx^2 + cx + d$, where $b = 3a - 5d$ and $c = d + 4a$

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