

Assignment Report

Problem 1: Perceptron

Q1. In how many steps perception learning algorithm will converge.

A1. The algorithm converged in 9 steps, assuming that we define steps as the number of times the model sees any data point.

Q2. What will be the final decision boundary? Show step-wise-step update of weight vector using computation as well as hand-drawn plot.

A2. The Weight vector of the final decision boundary is $W = [0.9, -0.5]$, step wise vector and the hand drawn plot is shown in the pdf document "Perceptron.pdf".

Assumptions while solving the problem:

It was assumed that the bias weight was not taken into consideration since the initial given weight vector had the same dimension(R^2) as the input vector $X(R^2)$. And bias wasn't mentioned.

But if we wanted to consider bias term very little modification is required i.e first we would have to initialize a bias, then in the algorithm while making a prediction instead of comparing $w \cdot x \geq 0$, we would have to change it to $w \cdot x \geq b$. And finally whenever a data point was misclassified, update the bias term along with the weight vector.

Problem 2 : Learning to implement Neural Network

Steps taken:

- **Division Of Data**
 - Provided Train Data - 1000 images
 - Used as Train Data - 800 images
 - Used as Validation Data - 200
 - Provided Validation Data - 178 images
 - Was used as Test data
 - These steps were initially used for selecting the model
 - Once the model was selected it was trained on the Provided Trained Data and evaluated on the Provided Validation Data
- **First Model** - A simple fully connected neural network was created and used.
- Experiments were conducted for different numbers of hidden layers(from 1 - 4) along with experiments with their respective number of neurons in the layers (within this list [32, 64, 128, 256, 512]) .
 - The model with the combination of (1024(Input Size) ->512->256->10) was chosen based on the validation loss.

Steps Taken to Improve Generalization:

- Experimented with Image Augmentation
- Saved Models with best validation loss
- Experimented with Batch Normalization and Dropout (together and individually) as both have regularization effects
- Experimented with L1 and L2 regularization for weights.

Observations:

- L2 Regularization performed better than L1.

- The combination of BatchNorm and Dropout were helpful for generalization.
- Image Augmentation did not help much
 - Possible Reasons could be
 - Very Few Augmentations possible so not much helpful variations (can't use big rotations or flips or shifting)

Results:

For Final Model :

Accuracy on Provided Training Dataset - 1.0

Accuracy on Provided Validation Dataset - 0.985

Steps For Running The Model on Test Set on Your End :

1. Run all the cells till the section “ Augmented Data Pipeline”
 - a. Change the value of the variables “train_dir” and “val_dir” with the paths of the directory containing training and validation images respectively.
2. Then jump to the last section of the notebook “For Evaluation On Test Side”
 - a. Here insert the path to the test directory
3. Then run the cell after that

Problem 3: Chart Image Classification using CNN

Steps taken:

- **Division of Data:**

- The Provided Training data was split into training and validation in the ratio of 80:20 for each class to maintain the balance.
- The Provided Test Data was not used because the labels were not provided for it.

- **Models**

- 2 Layer CNN Model and Accuracy and Loss were calculated and plotted
- Pretrained Network - A pre trained model of VGG16 network was used and Accuracy and Loss were calculated and plotted.
 - Model - (VGG16 -> 64 -> 5)

Results:

- 2 Layer CNN Model -
 - Training Accuracy - 1.0
 - Validation Accuracy - 0.985
- Pre Trained Model -
 - Training Accuracy - 1.0
 - Validation Accuracy - 1.0

Observations:

- The pretrained model reached a higher validation accuracy in fewer epochs compared to the 2 Layer CNN Model.