

Assignment No: 2

1. Title of Assignment:

Implement A star Algorithm for 8 puzzle game search problems.

2. Prerequisite:

Basic knowledge of Graph, Tree , informed search, uninformed search, best first search etc.

3. Objective:

In this experiment, we will be able to do the following:

- To understand Informed Search Strategies.
- To make use of Graph and Tree Data Structure for implementation of Informed Search strategies.
- Study how A star Algorithm is useful for implementation of 8 puzzle game search problems.

4. Outcome: Successfully able to implement 8 puzzle game search problem using A star Algorithm

5. Software and Hardware Requirement:

Open Source C++ Programming tool like G++/GCC, python,java and Ubuntu.

6. Relevant Theory / Literature Survey:

Informed search

- Informed search algorithm contains an array of knowledge such as how far we are from the goal, path cost, how to reach the goal node, etc.
- This knowledge helps agents to explore less of the search space and find the goal node.
- The informed search algorithm is more useful for large search spaces.
- Informed search algorithms use the idea of heuristic, so it is also called Heuristic search

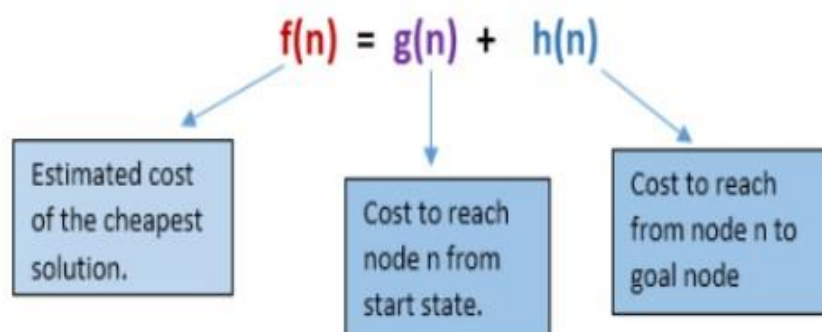
Heuristics function:

- Heuristic is a function which is used in Informed Search, and it finds the most promising path.
- It takes the current state of the agent as its input and produces the estimation of how close the agent is from the goal.
- The heuristic method, however, might not always give the best solution, but it guaranteed to find a good solution in reasonable time.
- Heuristic function estimates how close a state is to the goal. It is represented by $h(n)$, and it calculates the cost of an optimal path between the pair of states.
- The value of the heuristic function is always positive.

A* Search Algorithm:

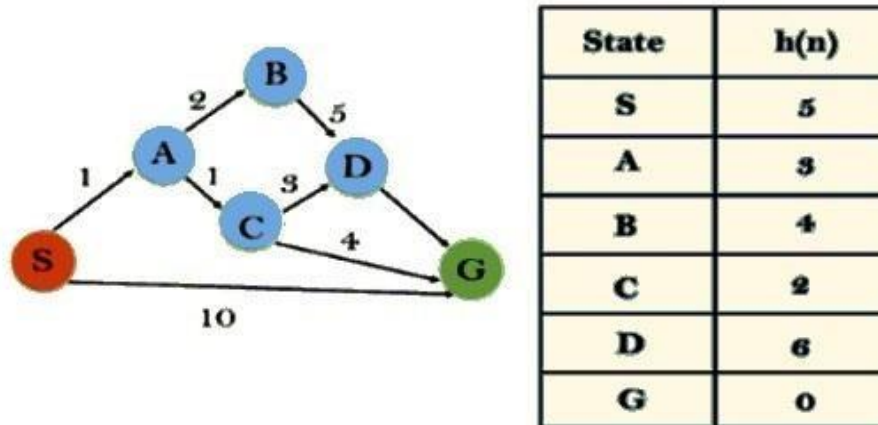
- A* search is the most commonly known form of best-first search.
- It uses the heuristic function $h(n)$, and costs to reach the node n from the start state $g(n)$.
- It has combined features of UCS and greedy best-first search, by which it solves the problem efficiently.
- A* search algorithm finds the shortest path through the search space using the heuristic function.
- This search algorithm expands less search tree and provides optimal results faster.
- A* algorithm is similar to UCS except that it uses $g(n)+h(n)$ instead of $g(n)$.

In A* search algorithm, we use search heuristic as well as the cost to reach the node. Hence we can combine both costs as following, and this sum is called as a **fitness number**.



In this example, we will traverse the given graph using the A* algorithm. The heuristic value of all states is given in the below table so we will calculate the $f(n)$ of each state using the formula $f(n) = g(n) + h(n)$, where $g(n)$ is the cost to reach any node from start state.

Here we will use OPEN and CLOSED list.



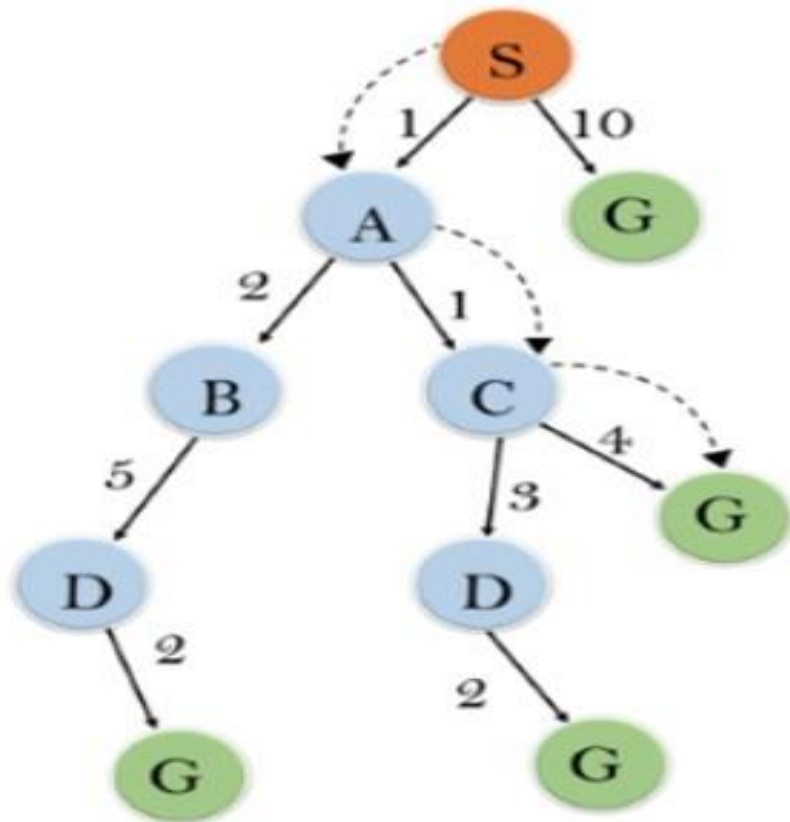
Initialization: $\{(S, 5)\}$

Iteration1: $\{(S \rightarrow A, 4), (S \rightarrow G, 10)\}$

Iteration2: $\{(S \rightarrow A \rightarrow C, 4), (S \rightarrow A \rightarrow B, 7), (S \rightarrow G, 10)\}$

Iteration3: $\{(S \rightarrow A \rightarrow C \rightarrow G, 6), (S \rightarrow A \rightarrow C \rightarrow D, 11), (S \rightarrow A \rightarrow B, 7), (S \rightarrow G, 10)\}$

Iteration 4 will give the final result, as $S \rightarrow A \rightarrow C \rightarrow G$ it provides the optimal path with cost 6.

Solution:**A* search Algorithm Advantages:**

- A* search algorithm is the best algorithm than other search algorithms.
- A* search algorithm is optimal and complete.
- This algorithm can solve very complex problems.

A* search Algorithm Disadvantages:

- A* search algorithm has some complexity issues.
- The main drawback of A* is memory requirement as it keeps all generated nodes in the memory, so it is not practical for various large-scale problems.

Complete: A* algorithm is complete as long as:

- Branching factor is finite.
- Cost at every action is fixed.

Optimal: A* search algorithm is optimal if it follows below two conditions:

- **Admissible:** the first condition requires for optimality is that $h(n)$ should be an admissible heuristic for A* tree search. An admissible heuristic is optimistic in nature.
- **Consistency:** Second required condition is consistency for only A* graph-search.

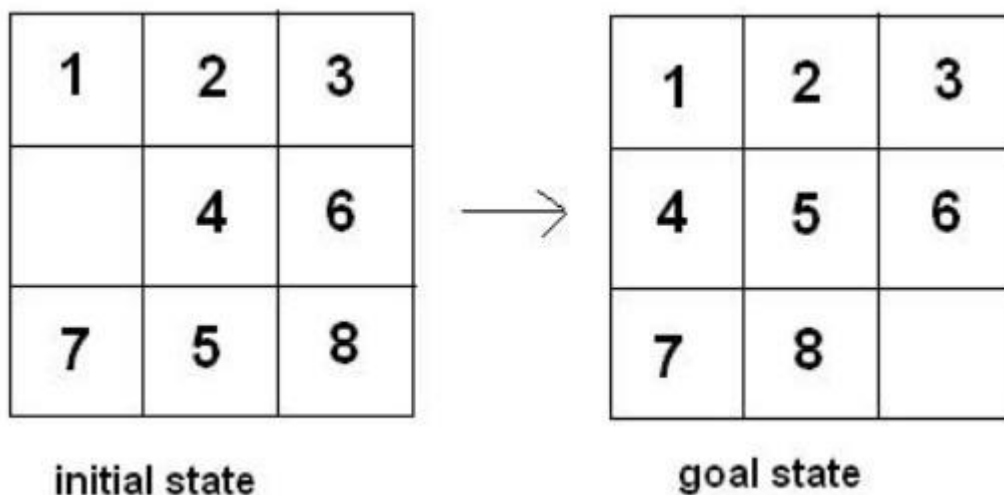
If the heuristic function is admissible, then A* tree search will always find the least cost path.

Time Complexity: The time complexity of A* search algorithm depends on heuristic function, and the number of nodes expanded is exponential to the depth of solution d . So the time complexity is $O(b^d)$, where b is the branching factor.

Space Complexity: The space complexity of A* search algorithm is $O(b^d)$

8 Puzzle Algorithm:-

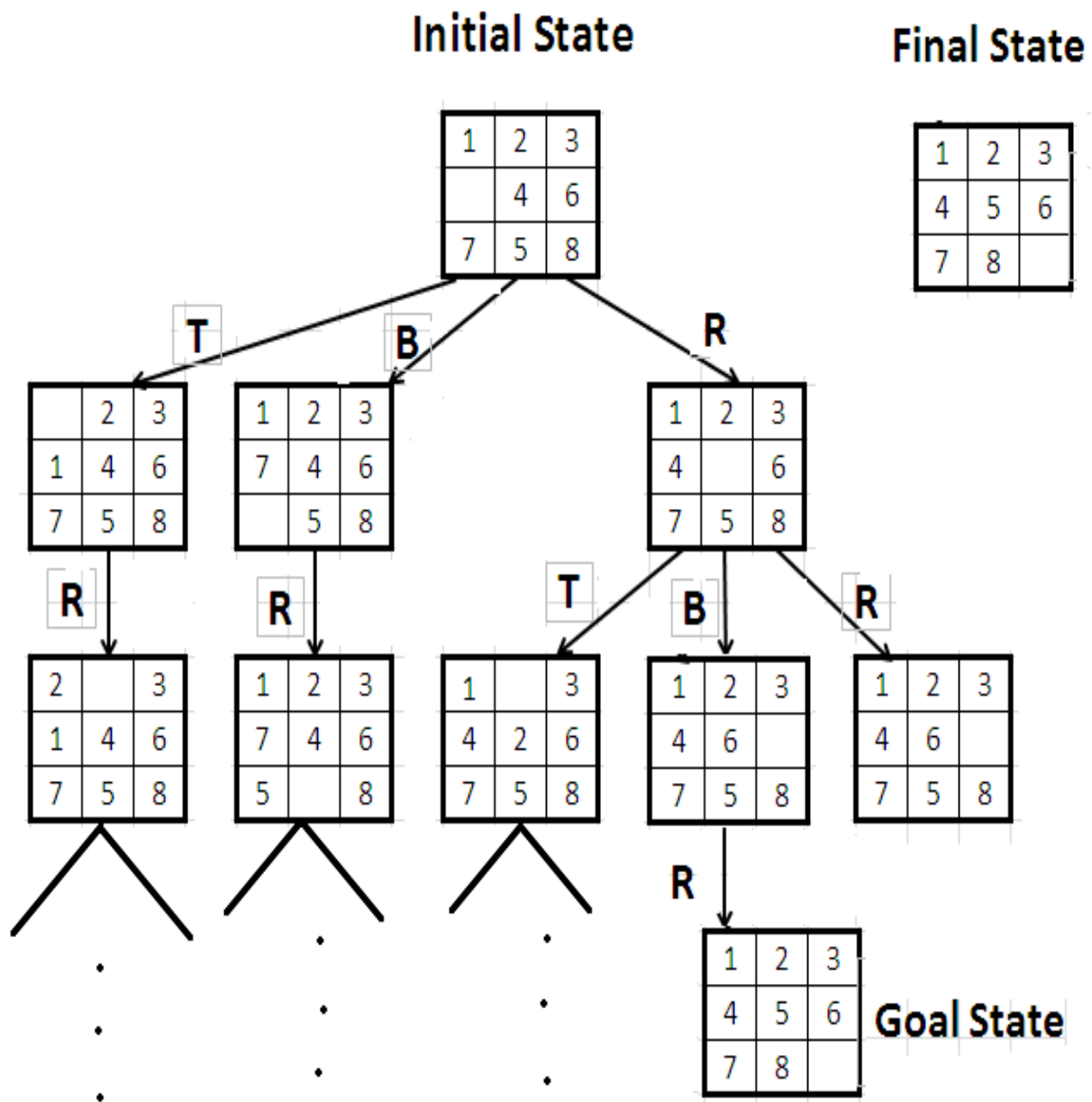
The 8-puzzle problem is a puzzle invented and popularized by Noyes Palmer Chapman in the 1870s. It is played on a 3-by-3 grid with 8 square blocks labeled 1 through 8 and a blank square. Your goal is to rearrange the blocks so that they are in order. You are permitted to slide blocks horizontally or vertically into the blank square.



There are a number of ways by which we can solve 8 puzzle problems.

- Solution without Heuristic Function
- Solution A* Algorithm

Solution without Heuristic Function



Disadvantages

need to explore each node and in case of failure need to generate its child which is a very time consuming as well as space consuming process.

Solution A* Algorithm

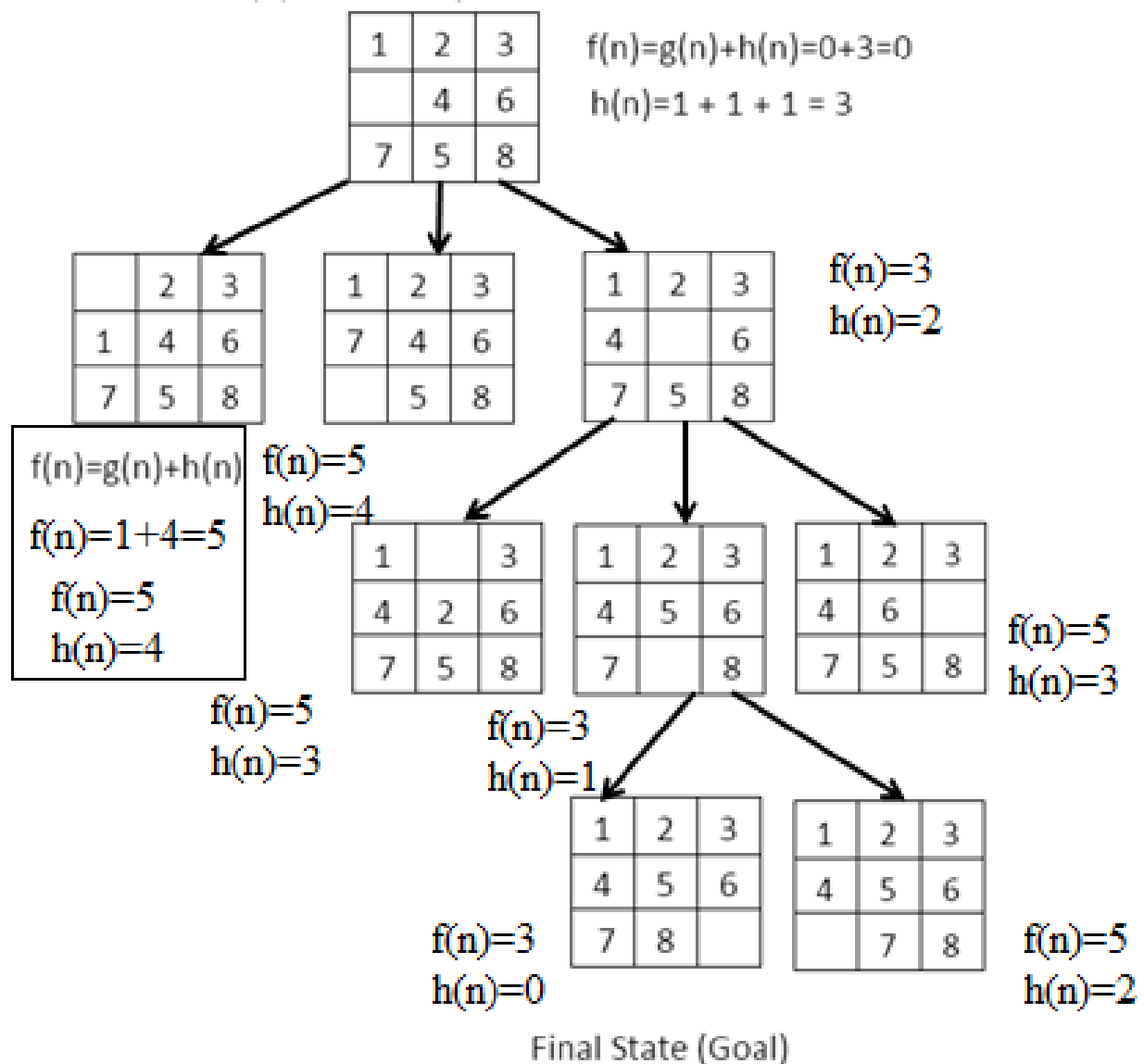
1	2	3
	4	6
7	5	8

Initial State

1	2	3
4	5	6
7	8	

Final State (Goal)

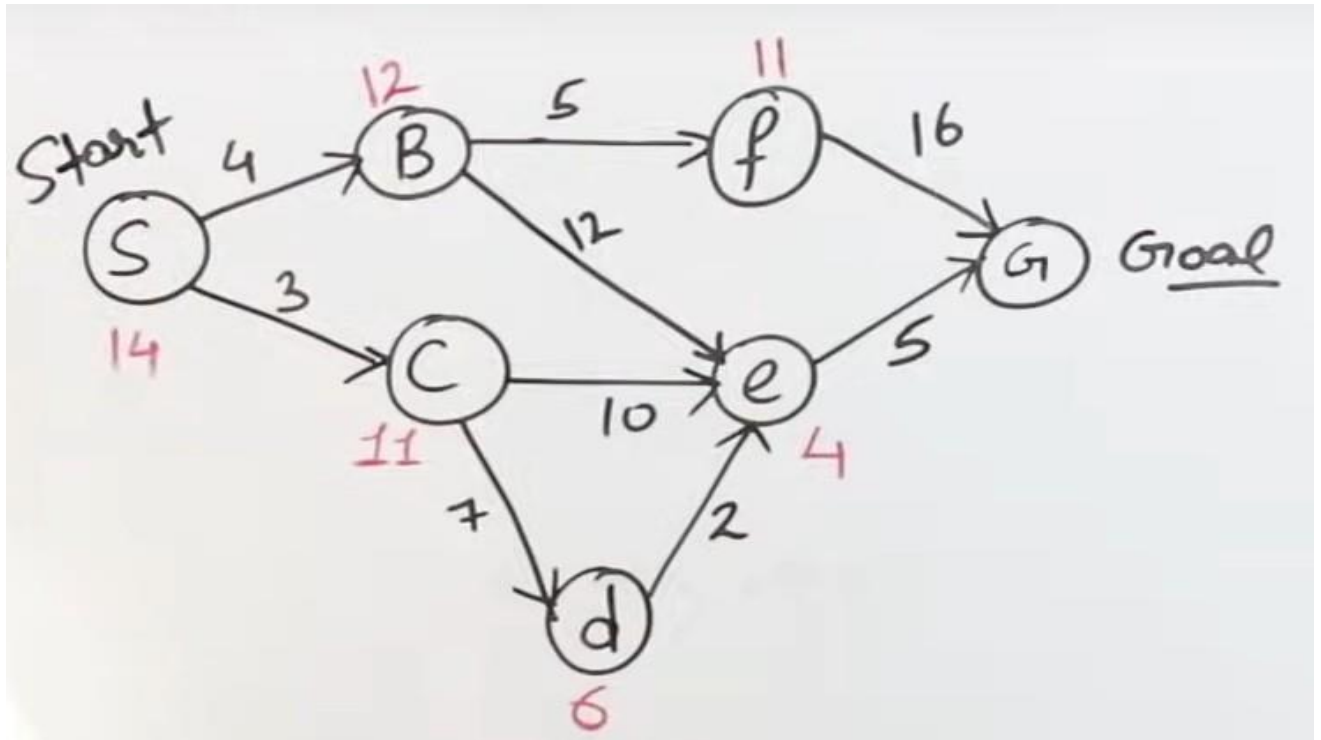
$h(n)$ = No of misplaced tiles



7. Questions:

Q 1: Differentiate between Best first search and A star algorithm.

Q 2: Solve this problem using A star algorithm



Q 3: What is the drawback to solve 8 Puzzle problem with a non heuristic method ?

8. Conclusion:

In This way we have studied informed search strategy, how to calculate heuristic function and implementation of 8 puzzle game search problems using A star Algorithm.