# Continuous Mathematical Foundations: Introduction to Linear Algebra

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Introduction

2 Vectors

Matrices

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## Why linear?

Because we will treat linear objects.

## Why algebra?

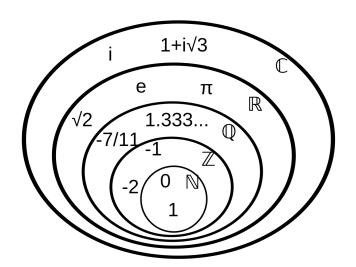
Because we discuss about operations in the objects.

#### **Vectors**

An x *n*-dimensional vector is written as,

$$\mathbf{x}=(x_1,x_2,x_3,\ldots,x_n).$$

### **Number Sets**



#### Vectors as elements of a Set

An **x** *n*-dimensional vector of real number elements is written as,

$$\mathbf{x} = (x_1, x_2, x_3, \dots, x_n).$$

Where  $x_1, x_2, x_3, \ldots, x_n \in \mathbb{R}$  and  $\mathbf{x} \in \mathbb{R}^n$ .

#### Vectors as elements of a Set

Obviously, the elements of the vector and subsequently the whole vector can be from any Set of choice.

Yet, in this class we care only about vectors in  $\mathbb{R}^n$ .

#### Sum of vectors

If 
$$\mathbf{x} \in \mathbb{R}^n$$
 is

$$\mathbf{x}=(x_1,x_2,x_3,\ldots,x_n)$$

and  $\mathbf{y} \in \mathbb{R}^n$  is

$$\mathbf{y}=(y_1,y_2,y_3,\ldots,y_n),$$

then

$$\mathbf{x} + \mathbf{y} = (x_1 + y_1, x_2 + y_2, x_3 + y_3, \dots, x_n + y_n).$$

## Multiplication on vectors

If 
$$\mathbf{x} \in \mathbb{R}^n$$
 is

$$\mathbf{x}=(x_1,x_2,x_3,\ldots,x_n)$$

and  $\lambda \in \mathbb{R}$ , then

$$\lambda \mathbf{x} = (\lambda x_1, \lambda x_2, \lambda x_3, \dots, \lambda x_n).$$

## Inner product

If  $\mathbf{x} \in \mathbb{R}^n$  is

$$\mathbf{x}=(x_1,x_2,x_3,\ldots,x_n)$$

and  $\mathbf{y} \in \mathbb{R}^n$  is

$$\mathbf{y}=(y_1,y_2,y_3,\ldots,y_n),$$

then

$$\mathbf{xy} = x_1y_1 + x_2y_2 + x_3y_3 + \ldots + x_ny_n = \sum_{i=1}^n x_iy_i.$$

#### Note

You can only sum and calculate inner products for vectors of equal dimension.

#### **Matrices**

An X m, n-dimensional matrix is written as,

$$\mathbf{X} = \begin{bmatrix} x_{11} & x_{12} & x_{13} & \dots & x_{1n} \\ x_{21} & x_{22} & x_{23} & \dots & x_{2n} \\ \vdots & \vdots & & & & \\ x_{m1} & x_{m2} & x_{m3} & \dots & x_{mn} \end{bmatrix}.$$

The number of rows of the matrix is equal to m and the number of columns to n.

#### Matrices as elements of a Set

An **X** m, n-dimensional matrix of real number elements has elements  $x_{11}, x_{12}, \ldots, x_{mn} \in \mathbb{R}$  and  $\mathbf{X} \in \mathbb{R}^{m \times n}$ .

#### Sum of Matrices

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$$\mathbf{X} = \begin{bmatrix} x_{11} & x_{12} & x_{13} & \dots & x_{1n} \\ x_{21} & x_{22} & x_{23} & \dots & x_{2n} \\ \dots & & & & & \\ x_{m1} & x_{m2} & x_{m3} & \dots & x_{mn} \end{bmatrix}$$

and

$$\mathbf{Y} = \begin{bmatrix} y_{11} & y_{12} & y_{13} & \cdots & y_{1n} \\ y_{21} & y_{22} & y_{23} & \cdots & y_{2n} \\ \vdots & \vdots & & & & \\ y_{m1} & y_{m2} & y_{m3} & \cdots & y_{mn} \end{bmatrix},$$

then

$$\mathbf{X} + \mathbf{Y} = \begin{bmatrix} x_{11} + y_{11} & x_{12} + y_{12} & x_{13} + y_{13} & \dots & x_{1n} + y_{1n} \\ x_{21} + y_{21} & x_{22} + y_{22} & x_{23} + y_{23} & \dots & x_{2n} + y_{2n} \\ \dots & & & & \\ x_{m1} + y_{m1} & x_{m2} + y_{m2} & x_{m3} + y_{m3} & \dots & x_{mn} + y_{mn} \end{bmatrix}.$$

## Multiplication on Matrices

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$$\mathbf{X} = \begin{bmatrix} x_{11} & x_{12} & x_{13} & \dots & x_{1n} \\ x_{21} & x_{22} & x_{23} & \dots & x_{2n} \\ \dots & & & & & \\ x_{m1} & x_{m2} & x_{m3} & \dots & x_{mn} \end{bmatrix}$$

and  $\lambda \in \mathbb{R}$  then

$$\lambda \mathbf{X} = \begin{bmatrix} \lambda x_{11} & \lambda x_{12} & \lambda x_{13} & \dots & \lambda x_{1n} \\ \lambda x_{21} & \lambda x_{22} & \lambda x_{23} & \dots & \lambda x_{2n} \\ \dots & & & & \\ \lambda x_{m1} & \lambda x_{m2} & \lambda x_{m3} & \dots & \lambda x_{mn} \end{bmatrix}$$

#### Matrix times Matrix

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$$\mathbf{X} = \begin{bmatrix} x_{11} & x_{12} & x_{13} & \dots & x_{1n} \\ x_{21} & x_{22} & x_{23} & \dots & x_{2n} \\ \dots & & & & & \\ x_{m1} & x_{m2} & x_{m3} & \dots & x_{mn} \end{bmatrix}$$

and

$$\mathbf{Y} = \begin{bmatrix} y_{11} & y_{12} & y_{13} & \cdots & y_{1m} \\ y_{21} & y_{22} & y_{23} & \cdots & y_{2m} \\ \vdots & \vdots & \vdots & \vdots \\ y_{n1} & y_{n2} & y_{n3} & \cdots & y_{nm} \end{bmatrix},$$

then

$$\mathbf{XY} = \left[\sum_{k=1}^{m} x_{ik} y_{kj}\right]_{\{i,j=1,2,...,n\}}.$$

#### Note

You can only sum matrices of equal dimension and multiply matrices with equality between rows and columns.

#### Vector times Matrix

Think of vectors as a matrix with dimension of rows or columns equal to 1, depending the case.

## Identity Matrix of dimension n

$$I_{nn} = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \dots & & & & & \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

## **Identity Matrix**

It is called Identity Matrix as for any matrix  $\mathbf{X}$  of respective dimensions,  $\mathbf{X}I = I\mathbf{X} = \mathbf{X}$ .

## Diagonal Matrix of dimension n

$$\mathbf{X}_{nn} = \begin{bmatrix} x_1 & 0 & 0 & \dots & 0 \\ 0 & x_2 & 0 & \dots & 0 \\ 0 & 0 & x_3 & \dots & 0 \\ \dots & & & & \\ 0 & 0 & 0 & \dots & x_n \end{bmatrix}$$

## Transpose Matrix

A Transpose Matrix  $\mathbf{X}^T$  is defined by an initial  $\mathbf{X}$  matrix, by changing places between rows and columns, i.e.

$$\mathbf{X} = \begin{bmatrix} x_{11} & x_{12} & x_{13} & \dots & x_{1n} \\ x_{21} & x_{22} & x_{23} & \dots & x_{2n} \\ \dots & & & & & \\ x_{m1} & x_{m2} & x_{m3} & \dots & x_{mn} \end{bmatrix}$$

and

$$\mathbf{X}^{T} = \begin{bmatrix} x_{11} & x_{21} & x_{31} & \dots & x_{m1} \\ x_{12} & x_{22} & x_{32} & \dots & x_{m2} \\ \dots & & & & \\ x_{1n} & x_{2n} & x_{3n} & \dots & x_{mn} \end{bmatrix}$$

#### Inverse Matrix

An inverse matrix  $\mathbf{X}^{-1}$  is is defined by an initial  $\mathbf{X}$  matrix when

$$\boldsymbol{X}\boldsymbol{X}^{-1}=\boldsymbol{X}^{-1}\boldsymbol{X}=\boldsymbol{I}.$$

#### Note

You can always calculate the transpose matrix, by an inverse matrix does not always exists.

### Linear Equation System

A linear equation system is of the form,

$$a_{11}x_1 + a_{11}x_2 + \dots + a_{1n}x_n = y_1$$
  
 $a_{21}x_1 + a_{21}x_2 + \dots + a_{2n}x_n = y_2$   
 $\dots$   
 $a_{n1}x_1 + a_{n1}x_2 + \dots + a_{nn}x_n = y_n$ 

## Linear System in Matrix form

Please note that you can write the system as

$$\mathbf{A}\mathbf{x}=\mathbf{y}.$$

## **Linear System Solution**

Please note that the previous relation is equivalent to

$$\mathbf{x} = \mathbf{A}^{-1}\mathbf{y}$$
.

## Determinant for 2, 2-matrix

$$det\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = a_{11}a_{22} - a_{12}a_{21}.$$

## Eigenvalues

Eigenvalues of an  ${\bf X}$  matrix are the  $\lambda$  values that solve the equation

$$det(\mathbf{X} - \lambda I) = 0.$$

## Eigenvectors

Eigenvectors of an  ${\bf X}$  matrix are the u vectors that solve the equation

$$\lambda \mathbf{X} = \lambda \mathbf{u},$$

where  $\lambda$  are the eigenvalues.

## Properties of Linear Equation Systems

- A system can have a unique solution, infinite solutions or no solution at all.
- If the A's rows are less than its columns then the system can't have unique solution.
- Determinants are only positive or 0.
- If **A** has eigenvalue equal to 0, **A** cannot be inverted.
- If the number of unique, positive eigenvalues of **A** is the same with the **x**'s dimensions, then the system has unique solution.

#### Goals of the Week

- Understand vectors and how to do operations with them.
- Understand matrices and how to do operations with them.
- Learn to solve linear systems.