

DATA DICTIONARY

How data was recorded:

By using the sensors(Gyroscope and accelerometer) in a smartphone, they have captured '3-axial linear acceleration'(*tAcc-XYZ*) from accelerometer and '3-axial angular velocity' (*tGyro-XYZ*) from Gyroscope with several variations.

1. prefix 't' in those metrics denotes time.
2. suffix 'XYZ' represents 3-axial signals in X , Y, and Z directions

Feature names

- 1) These sensor signals are preprocessed by applying noise filters and then sampled in fixed-width windows(sliding windows) of 2.56 seconds each with 50% overlap. ie., each window has 128 readings.
- 2) From Each window, a feature vector was obtained by calculating variables from the time and frequency domain.
- 3) The acceleration signal was saperated into Body and Gravity acceleration signals(___tBodyAcc-XYZ___ and ___tGravityAcc-XYZ___) using some low pass filter with corner frequency of 0.3Hz.
- 4) After that, the body linear acceleration and angular velocity were derived in time to obtian _jerk signals_ (___tBodyAccJerk-XYZ___ and ___tBodyGyroJerk-XYZ___).
- 5) The magnitude of these 3-dimensional signals were calculated using the Euclidian norm. This magnitudes are represented as features with names like _tBodyAccMag_, _tGravityAccMag_, _tBodyAccJerkMag_, _tBodyGyroMag_ and _tBodyGyroJerkMag_.
- 6) Finally, We've got frequency domain signals from some of the available signals by applying a FFT (Fast Fourier Transform). These signals obtained were labeled with ___prefix 'f'___ just like original signals with ___prefix 't'___ . These signals are labeled as ___fBodyAcc-XYZ___, ___fBodyGyroMag___ etc.,.
- 7) These are the signals that we got so far.
 - + tBodyAcc-XYZ
 - + tGravityAcc-XYZ
 - + tBodyAccJerk-XYZ
 - + tBodyGyro-XYZ

- + tBodyGyroJerk-XYZ
- + tBodyAccMag
- + tGravityAccMag
- + tBodyAccJerkMag
- + tBodyGyroMag
- + tBodyGyroJerkMag
- + fBodyAcc-XYZ
- + fBodyAccJerk-XYZ
- + fBodyGyro-XYZ
- + fBodyAccMag
- + fBodyAccJerkMag
- + fBodyGyroMag
- + fBodyGyroJerkMag

8) We can estimate some set of variables from the above signals. ie., We will estimate the following properties on each and every signal that we recorded so far.

- + `___mean()`: Mean value
- + `___std()`: Standard deviation
- + `___mad()`: Median absolute deviation
- + `___max()`: Largest value in array
- + `___min()`: Smallest value in array
- + `___sma()`: Signal magnitude area
- + `___energy()`: Energy measure. Sum of the squares divided by the number of values.
- + `___iqr()`: Interquartile range
- + `___entropy()`: Signal entropy
- + `___arCoeff()`: Autorregresion coefficients with Burg order equal to 4
- + `___correlation()`: correlation coefficient between two signals
- + `___maxInds()`: index of the frequency component with largest magnitude
- + `___meanFreq()`: Weighted average of the frequency components to obtain a mean frequency
- + `___skewness()`: skewness of the frequency domain signal
- + `___kurtosis()`: kurtosis of the frequency domain signal
- + `___bandsEnergy()`: Energy of a frequency interval within the 64 bins of the FFT of each window.

+ `angle()`: Angle between to vectors.

9) We can obtain some other vectors by taking the average of signals in a single window sample. These are used on the `angle()` variable'

- + `gravityMean`
- + `tBodyAccMean`
- + `tBodyAccJerkMean`
- + `tBodyGyroMean`
- + `tBodyGyroJerkMean`

`Y_Labels(Encoded)`

+ In the dataset, `Y_labels` are represented as numbers from 1 to 6 as their identifiers.

- WALKING as `1`
- WALKING_UPSTAIRS as `2`
- WALKING_DOWNSTAIRS as `3`
- SITTING as `4`
- STANDING as `5`
- LAYING as `6`

Data

All the data is present in 'UCI_HAR_dataset/' folder in present working directory.

- Feature names are present in 'UCI_HAR_dataset/features.txt'
- `Train Data`
 - 'UCI_HAR_dataset/train/X_train.txt'
 - 'UCI_HAR_dataset/train/subject_train.txt'
 - 'UCI_HAR_dataset/train/y_train.txt'
- `Test Data`
 - 'UCI_HAR_dataset/test/X_test.txt'
 - 'UCI_HAR_dataset/test/subject_test.txt'
 - 'UCI_HAR_dataset/test/y_test.txt'