view_frames Result

Recorded at time: 17.679

odom

Broadcaster: /gazebo
Average rate: 50.202 Hz
Most recent transform: 17.661 (0.018 sec old)
Buffer length: 4.960 sec

base_footprint

Broadcaster: /xbot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (17.679 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /xbot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (17.679 sec old)
Buffer length: 0.000 sec

Broadcaster: /xbot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (17.679 sec old)
Buffer length: 0.000 sec

Broadcaster: /xbot/robot_state_publisher
Average rate: 16.870 Hz
Most recent transform: 17.657 (0.022 sec old)
Buffer length: 4.920 sec

imu_link

laser_mount_link

yaw_platform

Broadcaster: /xbot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (17.679 sec old)
Buffer length: 0.000 sec

Broadcaster: /xbot/robot_state_publisher
Average rate: 16.870 Hz
Most recent transform: 17.657 (0.022 sec old)
Buffer length: 4.920 sec

laser

pitch_platform

Broadcaster: /xbot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (17.679 sec old)
Buffer length: 0.000 sec

camera_link

Broadcaster: /xbot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (17.679 sec old)
Buffer length: 0.000 sec

camera_link_optical