

# Exploring Circular Corner Regions as Seed Points for PDE-based Inpainting

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# What is inpainting...



[https://upload.wikimedia.org/wikipedia/commons/a/ae/Digital\\_Image\\_Restoration\\_and\\_Reconstruction.jpg](https://upload.wikimedia.org/wikipedia/commons/a/ae/Digital_Image_Restoration_and_Reconstruction.jpg)

- Restoration technique (antique paintings etc.)
- Used for decades
- Digital inpainting introduced in 2000

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Source: [Hoeltgen et al., 2017]

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- Many different approaches (semantic, tree-based, analytic, ...)
- **Semantic:** use image features as seeds (edges/corners)
- Edge-based methods successful
- Corners as seed points barely explored

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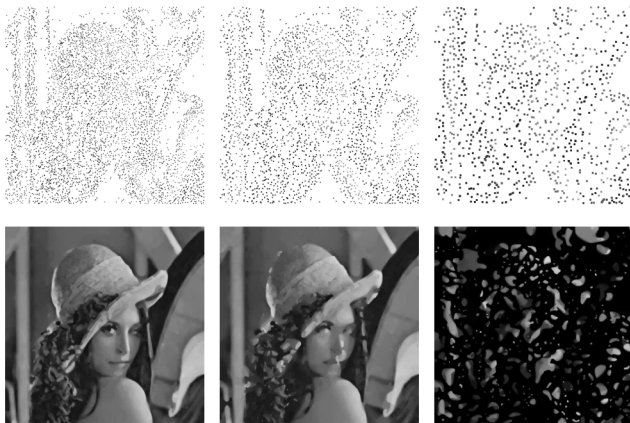
## Related Work

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- Masks as small neighbourhood around important corners
- Reconstruction using mean curvature motion (MCM) + edge-enhancing diffusion (EED)

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*PDE-based inpainting using corner information (Zimmer, 2007)*



Inpainting results from [Zimmer, 2007] for corner regions of different sizes

## Related Work

### *PDE-based inpainting using corner information (Zimmer, 2007)*

- Examined how well images can be compressed using only corners
- Masks as small neighbourhood around important corners
- Reconstruction using mean curvature motion (MCM) + edge-enhancing diffusion (EED)
- Open potential:
  - Corner detection very fuzzy (example results)
  - Corner regions not optimised properly
  - MCM not well suited for inpainting

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- Follow up on approach of Zimmer
- Förstner-Harris corner detection
- Introduce modifications
  - to better control mask size
  - to adapt detection to circular corner regions
- Pure EED inpainting
- Quantitative evaluation using **MSE/PSNR**



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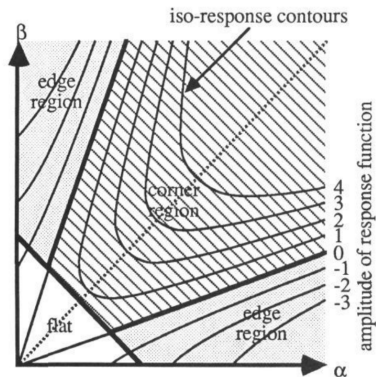
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$$J_\rho = K_\rho * (\nabla u \nabla u^\top)$$

- Corner detection based on eigenvalues
- Förstner-Harris measure:

$$\det(J)/\text{tr}(J) = \frac{\lambda_1 \lambda_2}{\lambda_1 + \lambda_2} > T$$

# Structure tensor based corner detection



Visualization of relation between eigenvalues of structure tensor. Source: [Harris and Stephens, 1988]

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- Local maxima of this measure are marked as corners

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Makes it hard to reliably produce masks of the same size

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## Alternative

Instead of filtering out percentage of corners, calculate upper bound for number of corners such that only a certain percentage of *pixels* is kept.



# Non-maximum Suppression

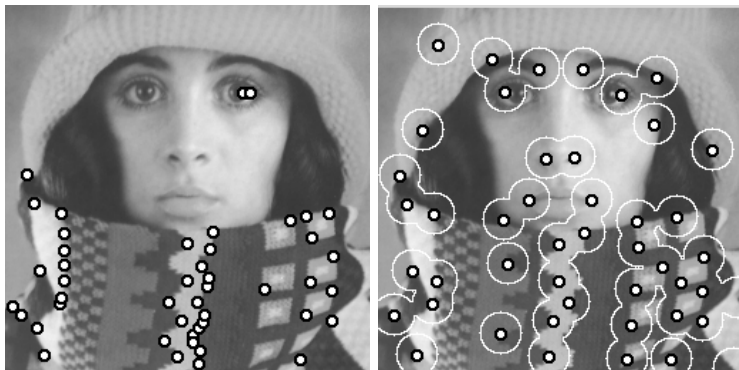
## Observation

Corner regions tend to overlap a lot, especially in textured regions  
Results in poorly distributed inpainting mask

## Possible Remedy

Discard corners already covered by a 'better' corner

# Non-maximum suppression



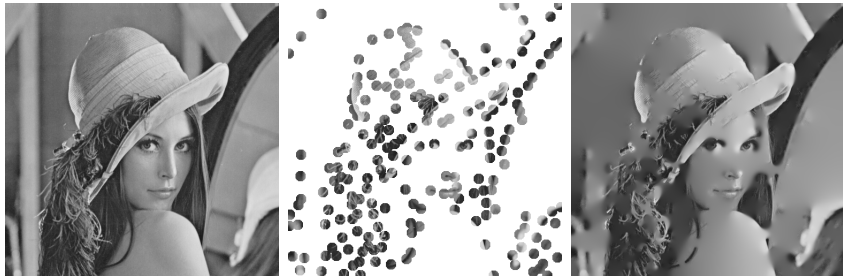
**Left:** Centre points of corner regions without suppression. **Right:** With suppression (boundary of each region highlighted). Corner detection using Förstner-Harris detector with identical parameters

# Expectations and Limitations



**Left:** Mask ( $\approx 5\%$  of all pixels). **Right:** Inpainting result ( $\sigma = 4$ ,  $\lambda = 0.03$ , stopped after 1000 iterations with  $\tau = 1000$ ) PSNR=32.04

# Expectations and Limitations



**Left:** Original image *lena512*. **Middle:** Mask (filled with white for visualisation,  $\approx 20\%$  of all pixels) **Right:** Inpainting result ( $\sigma = 2, \lambda = 0.4$ , stopped after 1000 iterations with  $\tau = 1000$ ) PSNR=21.56

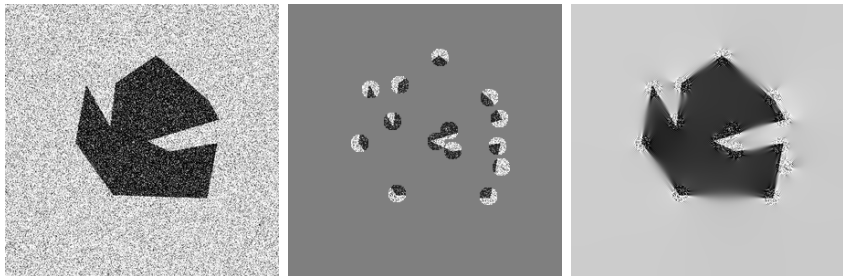
Any questions?

Thank you for your time!

# Bibliography

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## Examples (3)



**Left:** Original image. **Middle:** Mask ( $\approx 5\%$  of all pixels) **Right:** Inpainting result ( $\sigma = 4, \lambda = 0.3$ , stopped after 1000 iterations with  $\tau = 1000$ ) PSNR=16.72