

Estimadores DFSA



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Implementação

- C++
- GNUPLOT

Parâmetros de entrada

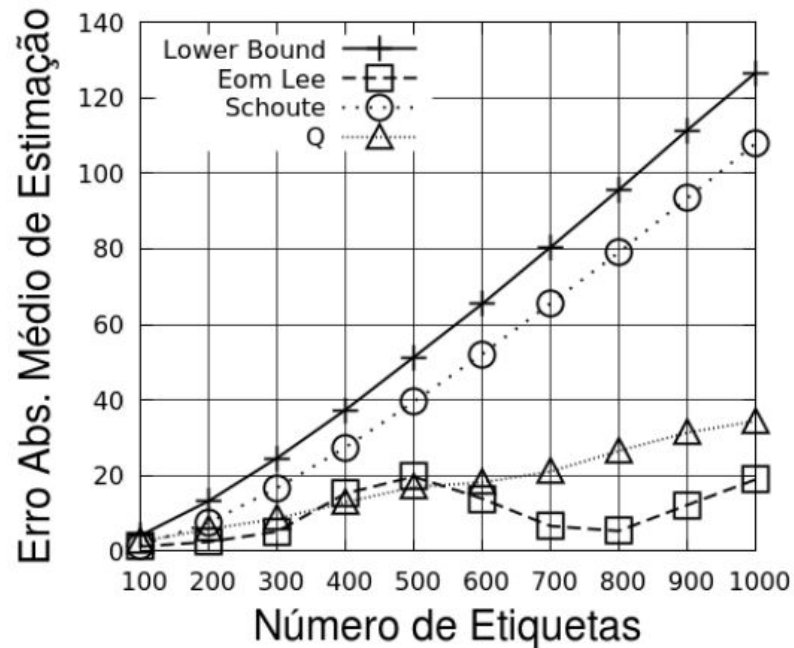
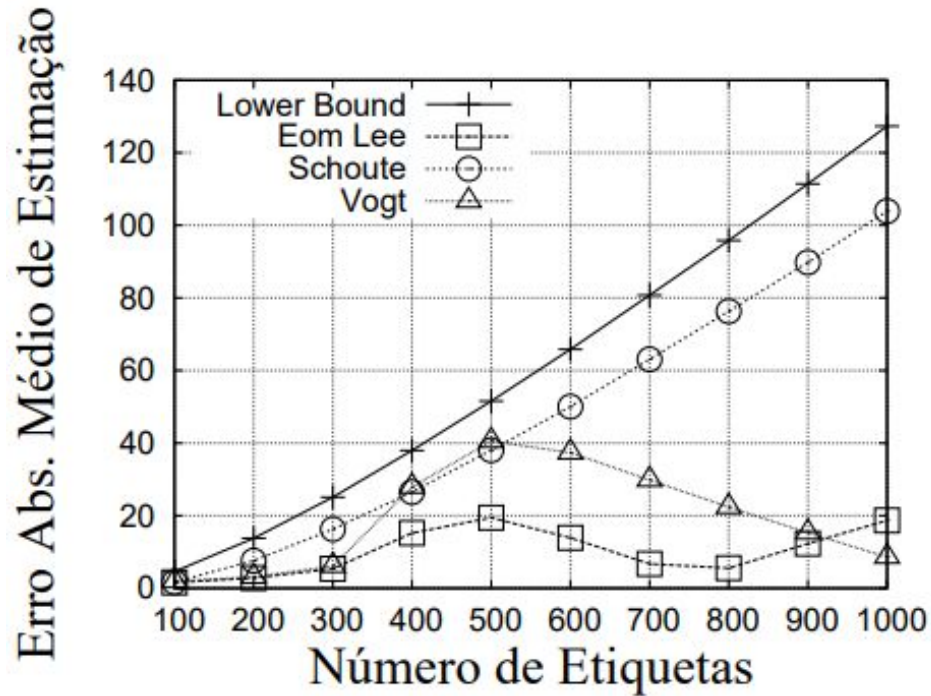
- st = quantidade inicial de tags
- iv = passo de incremento da quantidade de tags
- mt = quantidade máxima de tags
- s = quantidade de simulações
- if = quantidade inicial de slots na frame
- w = estimadores

Exemplo:

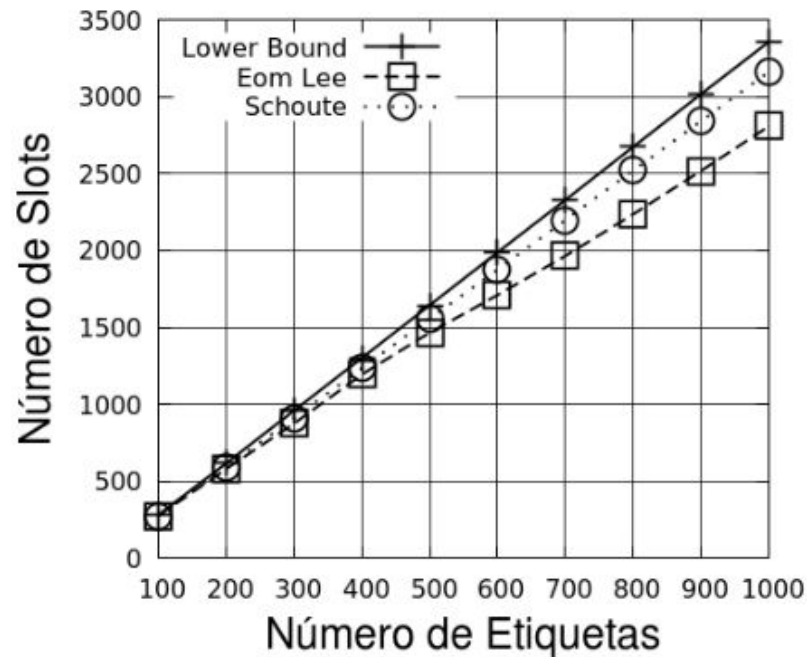
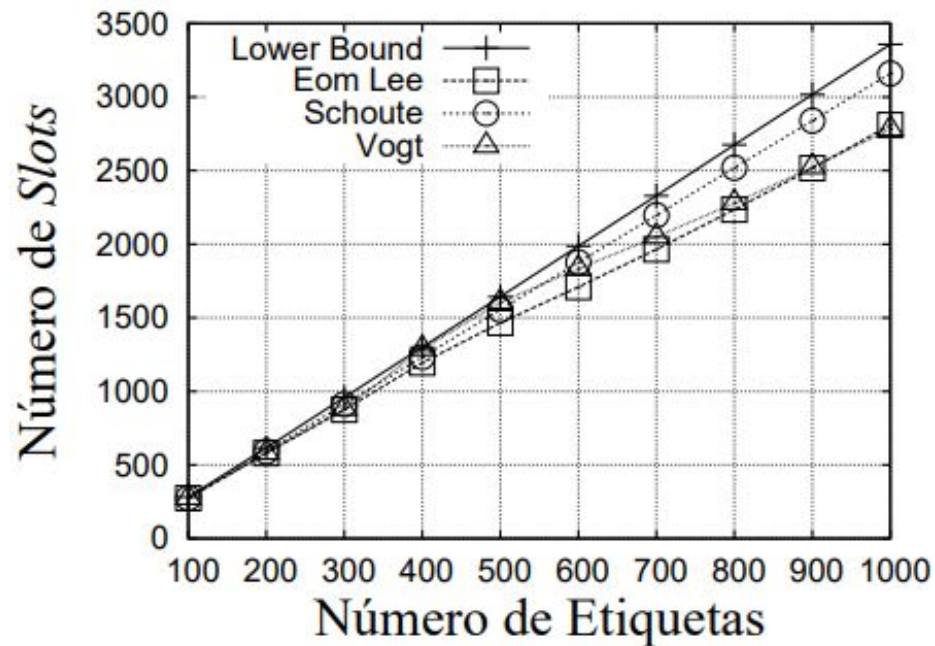
```
./estimator -st 100 -iv 100 -mt 1000 -s 2000 -if 64 -w lower-bound eom-lee
```



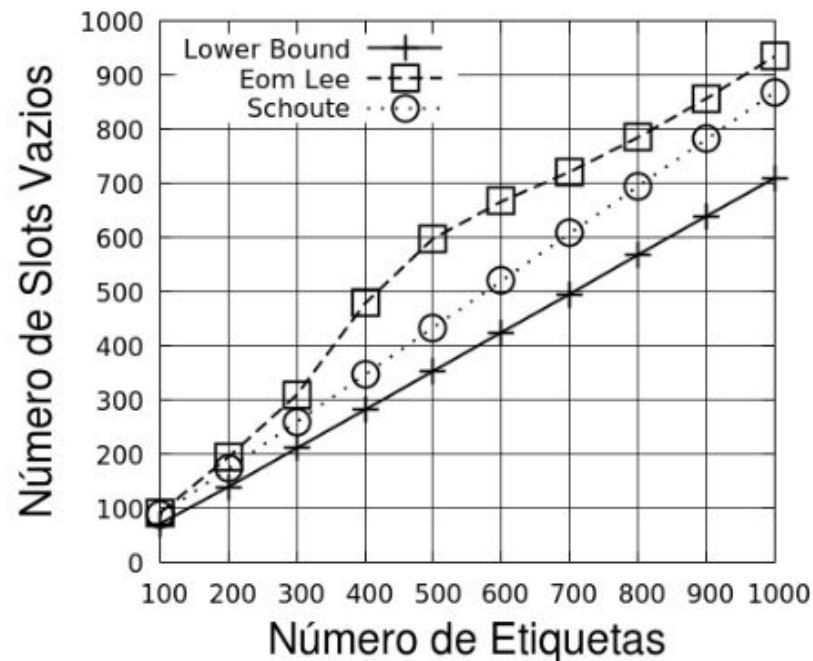
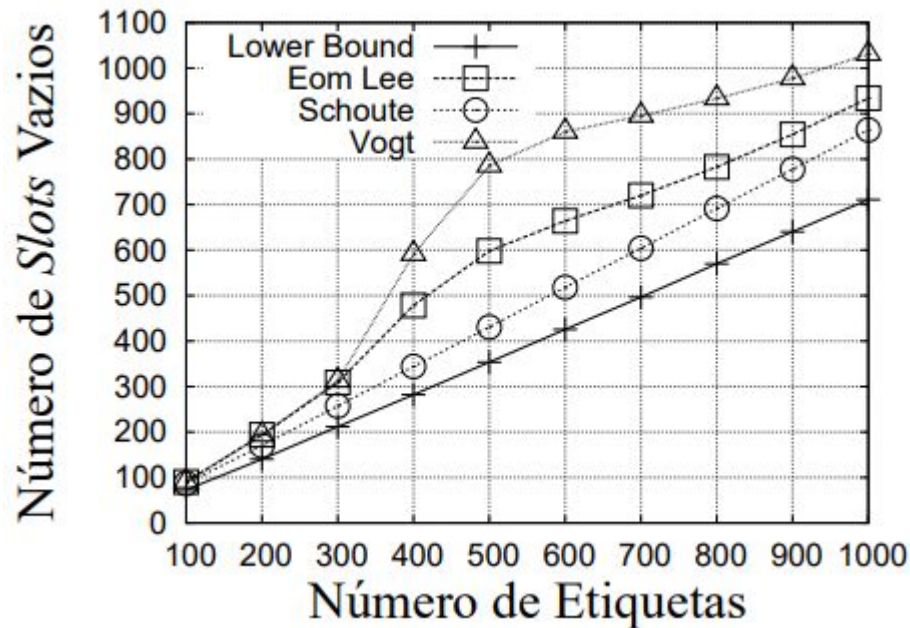
Erro absoluto médio de estimação



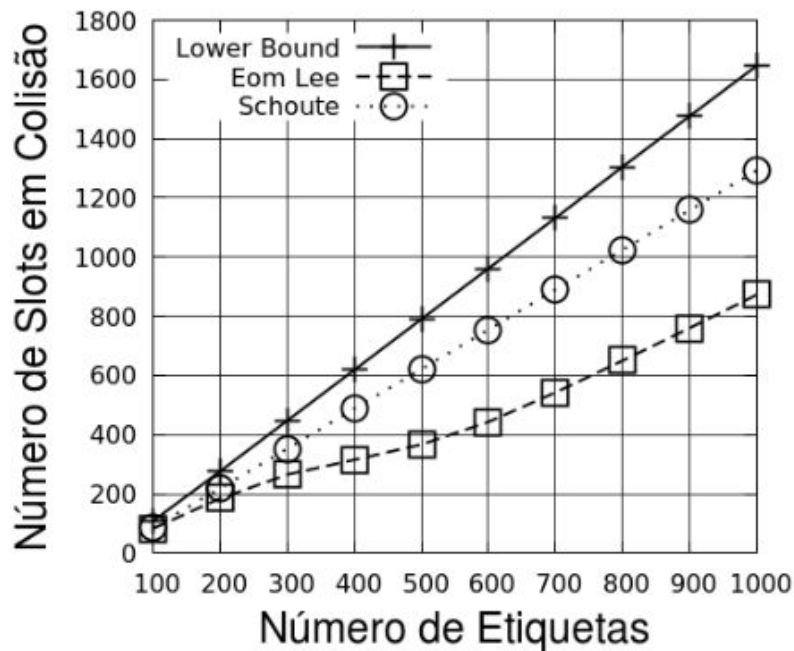
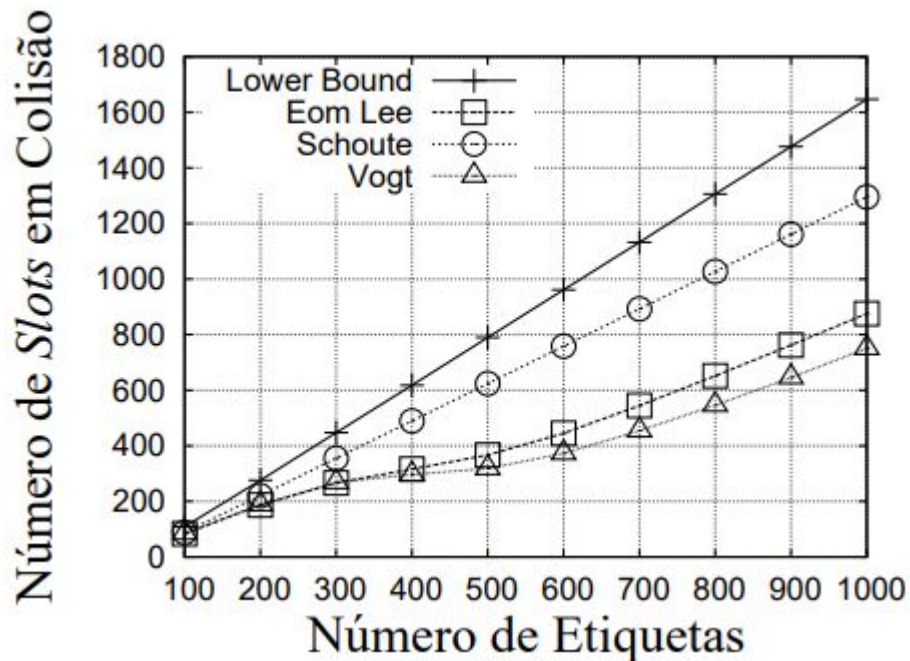
Número de slots



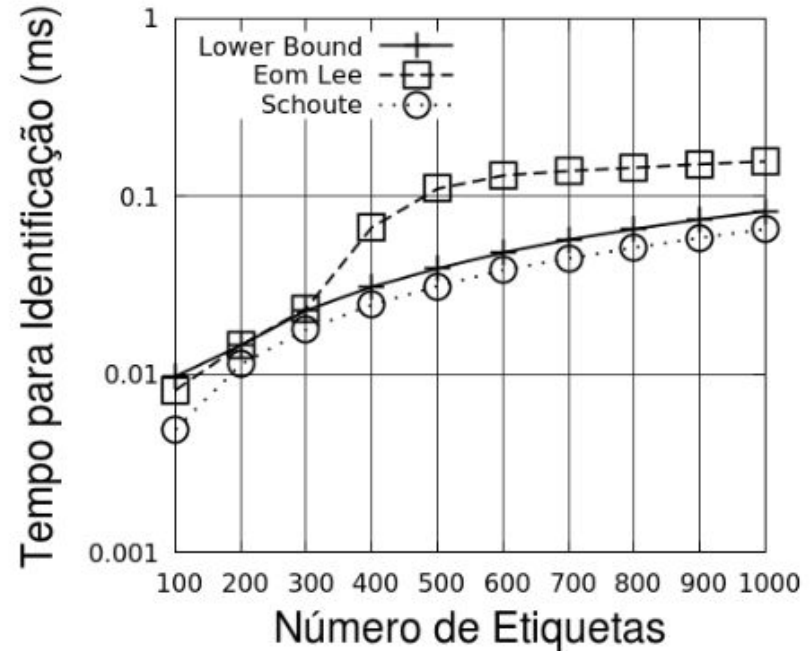
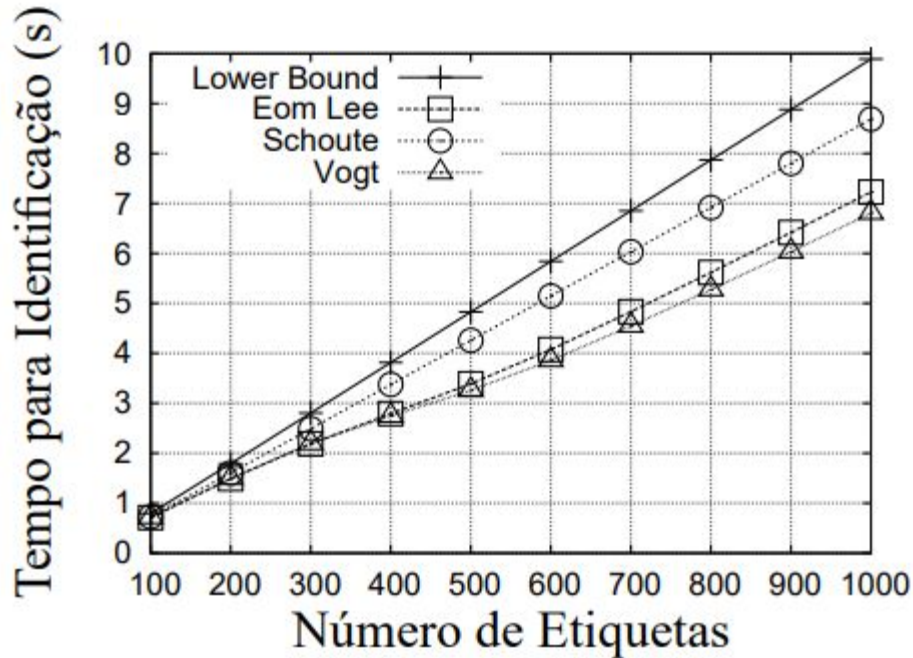
Número de slots vazios



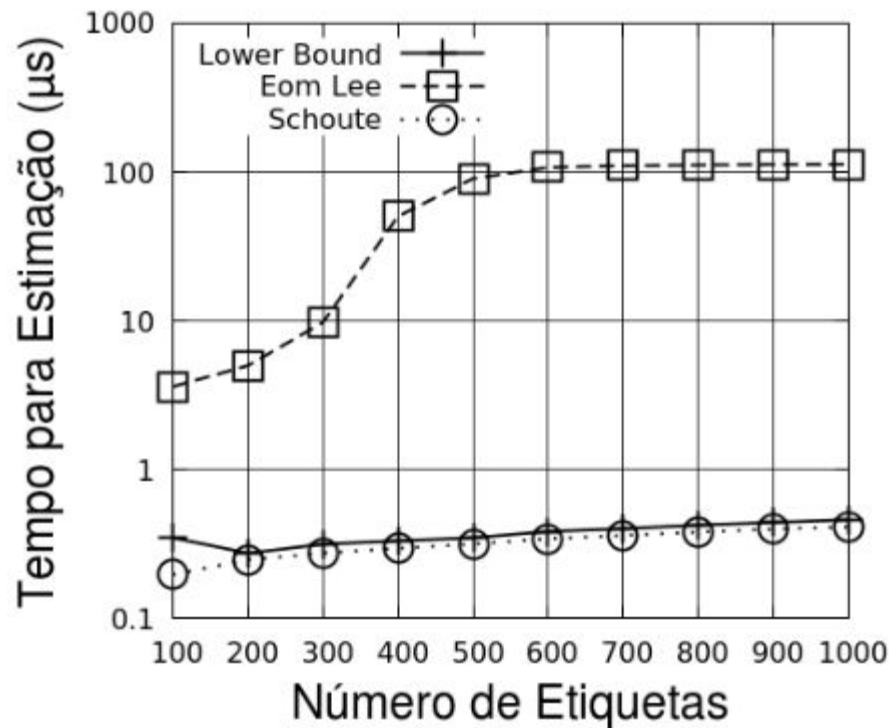
Número de slots em colisão



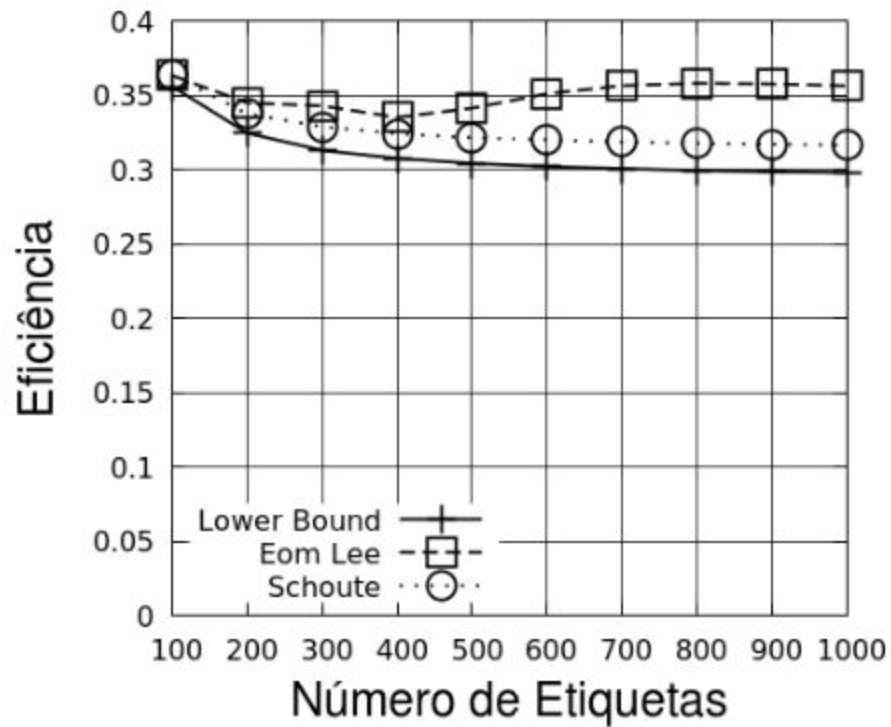
Tempo de identificação



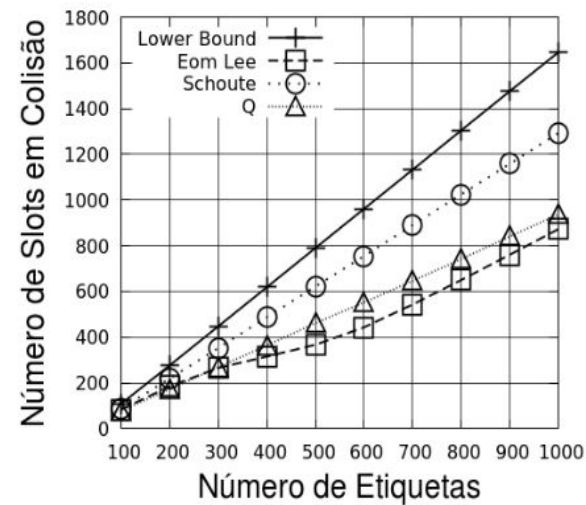
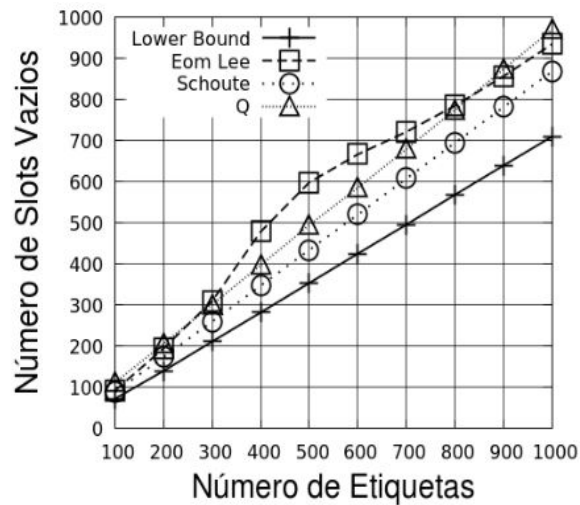
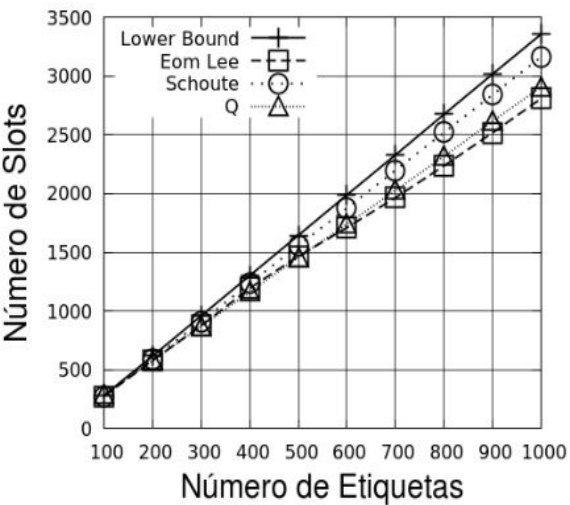
Tempo para estimação



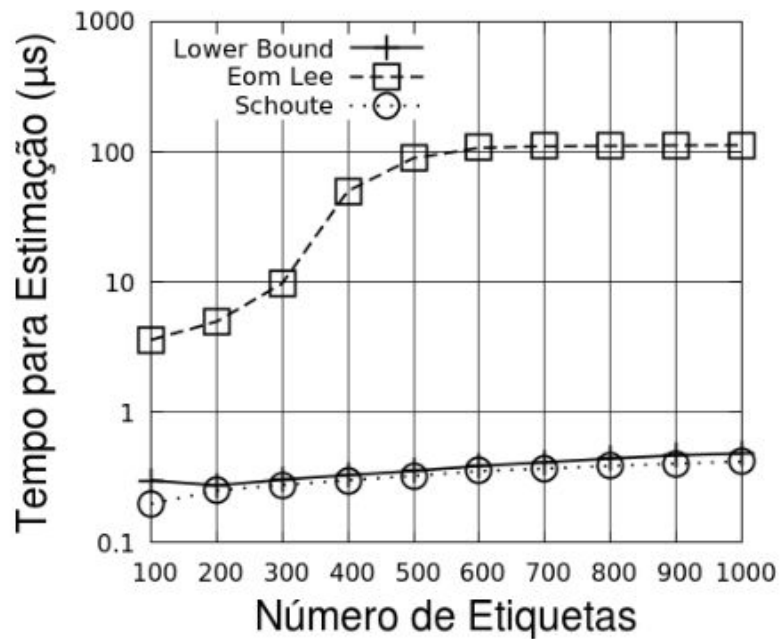
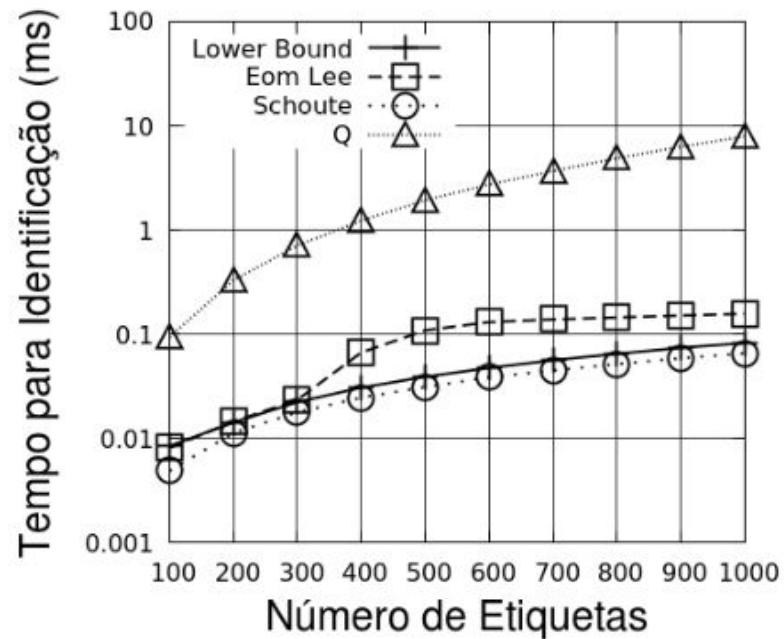
Eficiência



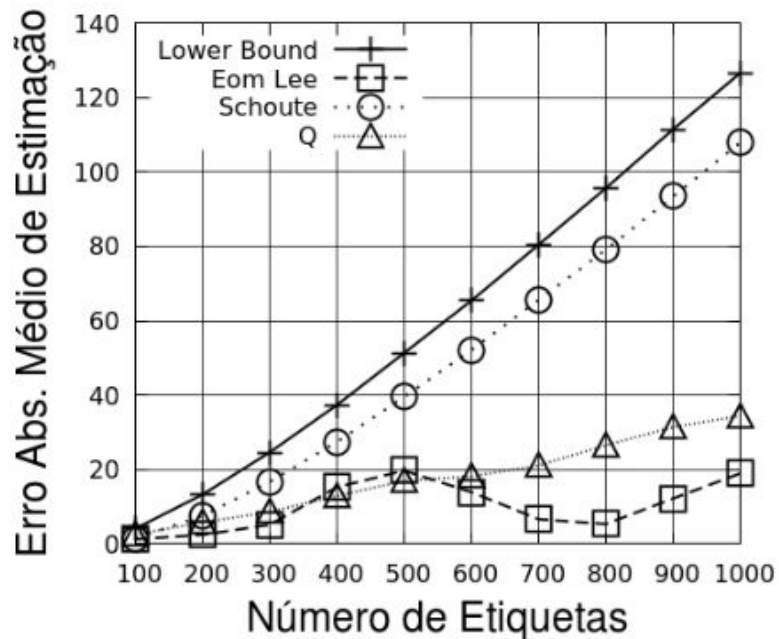
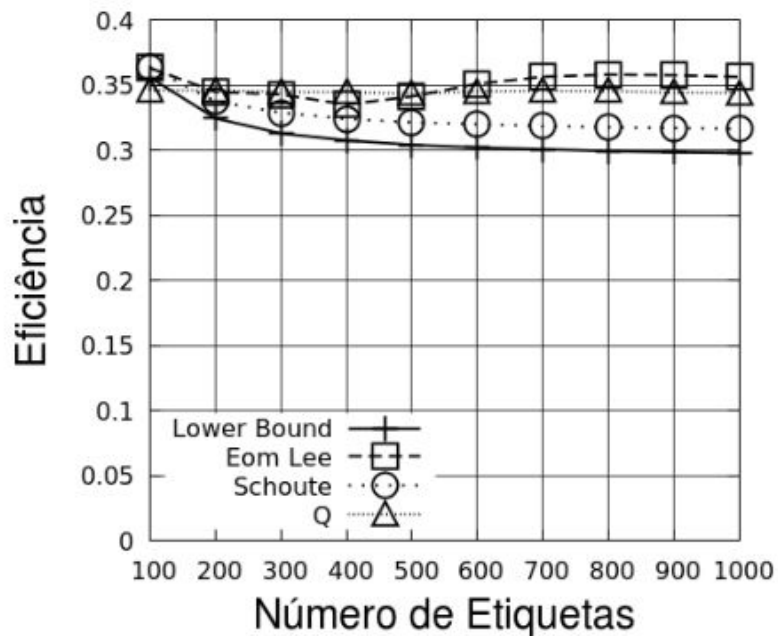
Algoritmo Q



Algoritmo Q



Algoritmo Q



Perguntas?



pRooFID

