

4.3

$$\begin{aligned} (2) \quad & \bullet V(x) = \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2 \\ & \rightarrow \dot{V}(x) = -(x_1^2 + x_2^2)(1 - x_1^2 - x_2^2) \\ & D = \{x \mid x_1^2 + x_2^2 < 1\}, \quad \dot{V}(x) < 0, x \in D \end{aligned}$$

$$(4) \quad \bullet V(x) = x_1^2 + \frac{1}{2}x_2^2 \rightarrow \dot{V}(x) = -2x_1^2 - x_2^4$$

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(1)

$$\dot{x}_1 = x_1^3 + x_1^2 x_2$$

$$\dot{x}_2 = -x_2 + x_2^2 + x_1 x_2 - x_1^3$$

$$\text{set } V(x) = \frac{1}{2} x_1^2 - \frac{1}{2} x_2^2$$

(i)  $V(x)$  is continuous ly differenti able(ii)  $V(0) = 0$ (iii)  $V(x_0) > 0$  (i.e  $x_0 = (1,0)$ )Let  $B_r = \{x \in \mathbb{R}^2 \mid \|x\| < r\}$ ,  $U = \{x \in B_r \mid V(x) > 0\}$ 

$$\dot{V}(x) = x_1^4 + 2x_2 x_1^3 + x_2^2 (1 - x_1 - x_2)$$

For small  $r > 0$ ,  $\dot{V}(x) > 0$  in  $U$  $\therefore$  unstable

4.13

$$(2) \quad \begin{aligned} \dot{x}_1 &= -x_1^3 + x_2 \\ \dot{x}_2 &= x_1^6 - x_2^3 \end{aligned}$$

$$\text{set } V(x) = \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2$$

(i)  $V(x)$  is continuously differentiable

$$(ii) \quad V(0) = 0$$

$$(iii) \quad V(x_0) > 0 \text{ (i.e. } x_0 = (1,0))$$

$$\text{Let } B_r = \{x \in \mathbb{R}^2 \mid \|x\| < 1\},$$

$$\Gamma = \{0 \leq x_1 \leq 1\} \cap \{x_2 \geq x_1^3\} \cap \{x_2 \leq x_1^2\}$$

$$\dot{V}(x) = x_1(x_2 - x_1^3) + x_2(x_1^2 - x_2)(x_1^4 + x_1^2x_2 + x_2^2)$$

(a)  $\Gamma$  is nonempty

(b)  $\dot{V}(x) > 0$  in set  $\Gamma$  except at  $(0,0), (1,1)$

(c)  $V(x) > 0$  in set  $\Gamma$  except at  $(0,0)$

$$\text{Define } U = \{x \in B_r \mid V(x) > 0\} \subset \Gamma$$

$\therefore$  unstable

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(a) eq. pts  $\rightarrow (0,0), (2,6), (-2,-6)$

(b)  $(0,0) \rightarrow$  unstable

$(2,6) \rightarrow$  asym. stable

$(-2,-6) \rightarrow$  asym. stable

(c)

(i) Around eq. pt (2,6)

We use the direct Lyapunov method.

For simplicity, let  $z_1 = x_1 - 2$  and  $z_2 = x_2 - 6$ 

then system becomes

$$\dot{z}_1 = -11z_1 - 6z_1^2 - z_1^3 + z_2$$

$$\dot{z}_2 = 3z_1 - z_2$$

$$\text{Let } V(z) = \frac{1}{2} z_1^2 + \frac{1}{2} z_2^2 \rightarrow p.d \text{ on } \mathbb{R}^2$$

$$\begin{aligned} \dot{V}(z) &= -11z_1^2 - 6z_1^3 - z_1^4 + 4z_1z_2 - z_2^2 \\ &= -11z_1^2 - 6z_1^3 - z_1^4 + \frac{4}{\varepsilon^2} z_1^2 - \left(\frac{2}{\varepsilon} z_1 - \varepsilon z_2\right)^2 - (1 - \varepsilon^2) z_2^2 \end{aligned}$$

where  $0 < \varepsilon^2 < 1$ 

$$\dot{V}(z) \approx -7z_1^2 - 6z_1^3 - z_1^4 - (1 - \varepsilon^2) z_2^2 \quad (\text{for } \varepsilon^2 \approx 1)$$

 $\dot{V}(z)$  is n.d. on  $z_1 > -3 + \sqrt{2}$  and any  $z_2$ 

$$\text{Let } \Omega_c = \{z \mid V(z) \leq c\}$$

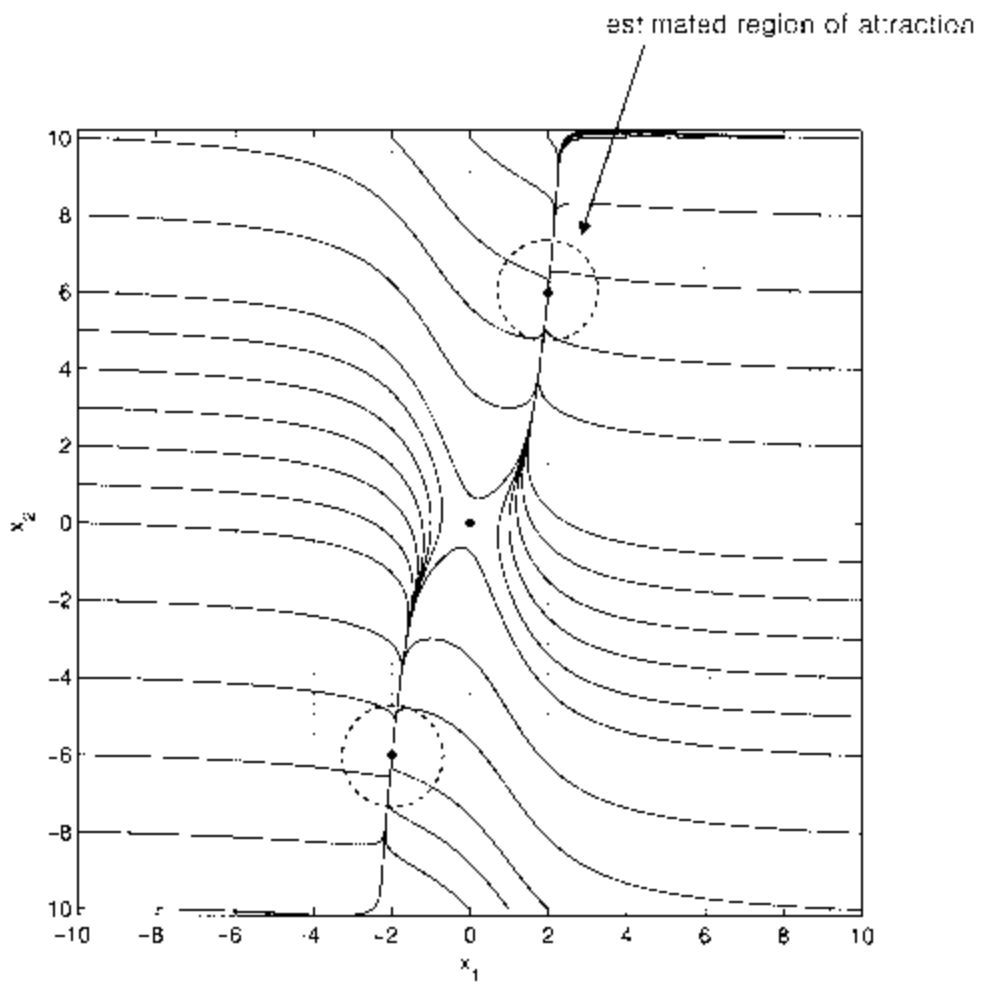
To make  $\Omega_c$  be inside the set  $D = \{z_1 > -3 + \sqrt{2}, \forall z_2\}$ 

$$\begin{aligned} \text{Let } c &= \min_{\partial D} V(z) = \frac{1}{2} (z_1^2 + z_2^2) \Big|_{z_1 = -3 + \sqrt{2}, z_2 = 0} \\ &= \frac{1}{2} (-3 + \sqrt{2})^2 \approx 1.2574 \end{aligned}$$

(ii) Around eq. pt (-2,-6), we get the similar result. [ $c \approx 1.2574$ ]

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(d)



4.32 We do the easiest approach:

i) Linearization:  $A = \left. \frac{\partial f}{\partial x} \right|_{x=0}$

ii) Check the eigenvalues of A

(2) *asym. stable*

(4) *asym. stable*

4.37

$$(2) \quad V(x) = x_1^2 + x_2^2$$

$$\begin{aligned} \dot{V}(x) &= 2x_1\{-x_1 + \alpha(t)x_2\} + 2x_2\{-\alpha(t)x_1 - 2x_2\} \\ &= -2x_1^2 - 4x_2^2 \leq -2x_1^2 - 2x_2^2 = -2\|x\|_2^2 \quad \therefore \text{exp. stable} \end{aligned}$$

$$(4) \quad V(x) = \frac{1}{2}x_1^2 + \frac{1}{2}ax_2^2$$

$$\text{Let } c_1 = \min\{1, a\}, c_2 = \max\{1, a\}$$

$$c_1 \|x\|_2^2 \leq V(x) \leq c_2 \|x\|_2^2$$

$$\dot{V}(x) = -x_1^2 - 2ax_2^2 + a\alpha(t)x_1x_2$$

$$\begin{aligned} &= -1/4x_1^2 + a\alpha(t)x_1x_2 - (a\alpha(t)x_2)^2 + (a\alpha(t)x_2)^2 \\ &\quad - 3/4x_1^2 - 2ax_2^2 \quad \rightarrow \quad -(1/2x_1^2 - a\alpha(t)x_2)^2 \\ &= -\cancel{(1/2x_1^2 - (a\alpha(t)x_2)^2)} - 3/4x_1^2 - (2a - (a\alpha(t))^2)x_2^2 \\ &\leq -3/4x_1^2 - a(2 - a\alpha(t)^2)x_2^2 \end{aligned}$$

Since  $\alpha(t)$  is bounded,  $\alpha(t)^2 \leq k$ .

If we choose  $a$  between  $0 < a < 2/k$ , then  $2 - a\alpha(t)^2 > 0$ .

$$\therefore \dot{V}(x) \leq -\min\{3/4, a(2 - a\alpha(t)^2)\} \|x\|_2^2$$

$\therefore$  exp. stable



4.45

(1)

$$V(x) = \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2 \rightarrow \frac{1}{4}(x_1^2 + x_2^2) \leq V(x) \leq (x_1^2 + x_2^2)$$

$$\dot{V}(x) = -g(t)(x_1^4 + x_2^4) \leq -k(x_1^4 + x_2^4)$$

$\therefore$  uniformly asymptotically stable

(2)

Let's find

$$\frac{\partial f}{\partial x}(t,0) = \begin{bmatrix} 0 & h(t) \\ -h(t) & 0 \end{bmatrix}$$

$$\text{Choose } V = \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2.$$

It means that the solutions staying on  $V(x) = C$  remain on  $V(x) = C, \forall t$ . Thus the origin is not exponentially stable.

Using Th.4.15, we conclude that the origin of the nonlinear system is not exponentially stable.

(3)

Yes

(4)

No