

## 2.1

(1)

$$\cdot \frac{\partial f}{\partial x} = \begin{bmatrix} -1 + 6x_1^2 & 1 \\ -1 & -1 \end{bmatrix}$$

• equilibrium points :

$$x_s^1 = (0, 0) \rightarrow \text{stable focus}$$

$$x_s^2 = (1, -1) \rightarrow \text{saddle}$$

$$x_s^3 = (-1, 1) \rightarrow \text{saddle}$$

$$(3) \cdot \frac{\partial f}{\partial x} = \begin{bmatrix} 1 - x_1 - \frac{x_2}{1+x_1} + \left(-1 + \frac{2x_2}{(1+x_1)^2}\right) \cdot x_1 & -\frac{2x_1}{1+x_1} \\ \frac{x_2^2}{(1+x_1)^2} & 2 - \frac{x_2}{1+x_1} - \frac{x_2}{1+x_1} \end{bmatrix}$$

$$x_s^1 = (0, 0) \rightarrow \text{unstable node}$$

$$x_s^2 = (0, 2) \rightarrow \text{stable node}$$

$$x_s^3 = (1, 0) \rightarrow \text{saddle}$$

$$x_s^4 = (-1, -4) \rightarrow \text{saddle}$$

(5) ① Isolated equilibrium point

$$x_s = (0, 0) \rightarrow \text{unstable focus}$$

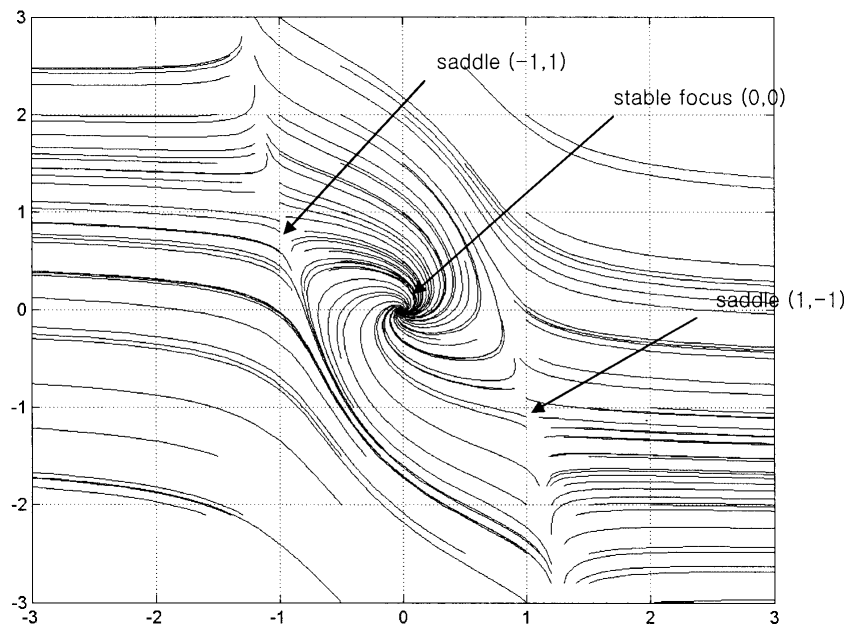
② Nonisolated equilibrium points

There are many nonisolated equilibrium points

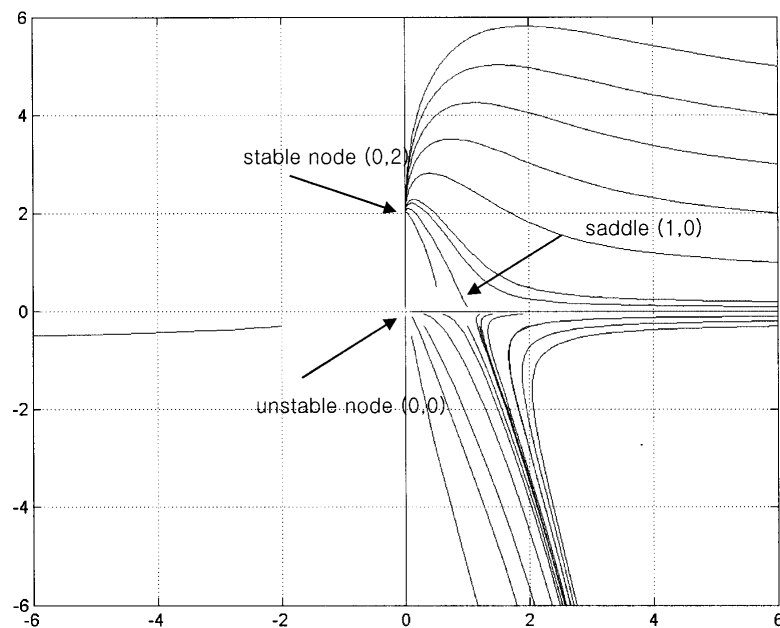
represented by  $S = \{(x_1, x_2) \mid x_1^2 + x_2^2 = 1\}$ .

## 2.3

(1)

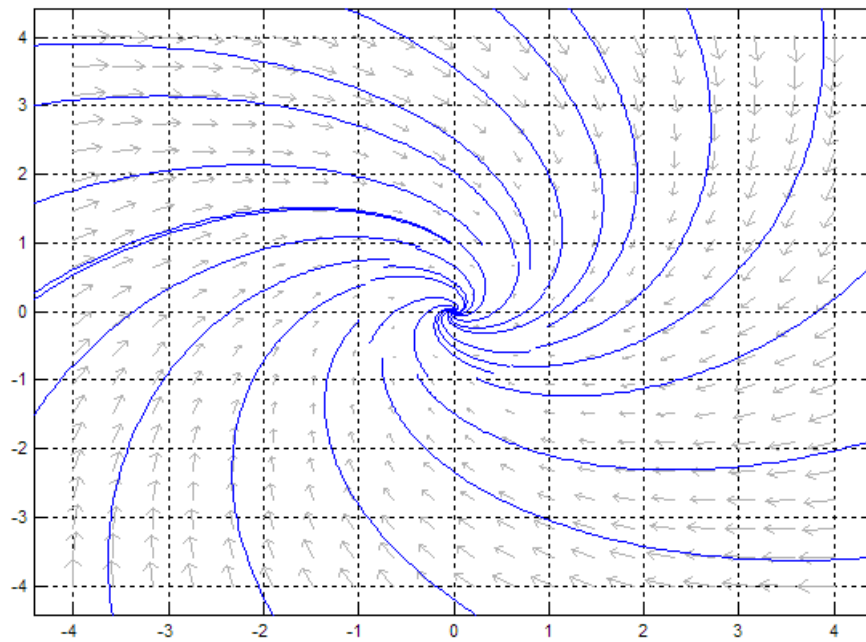


(3)

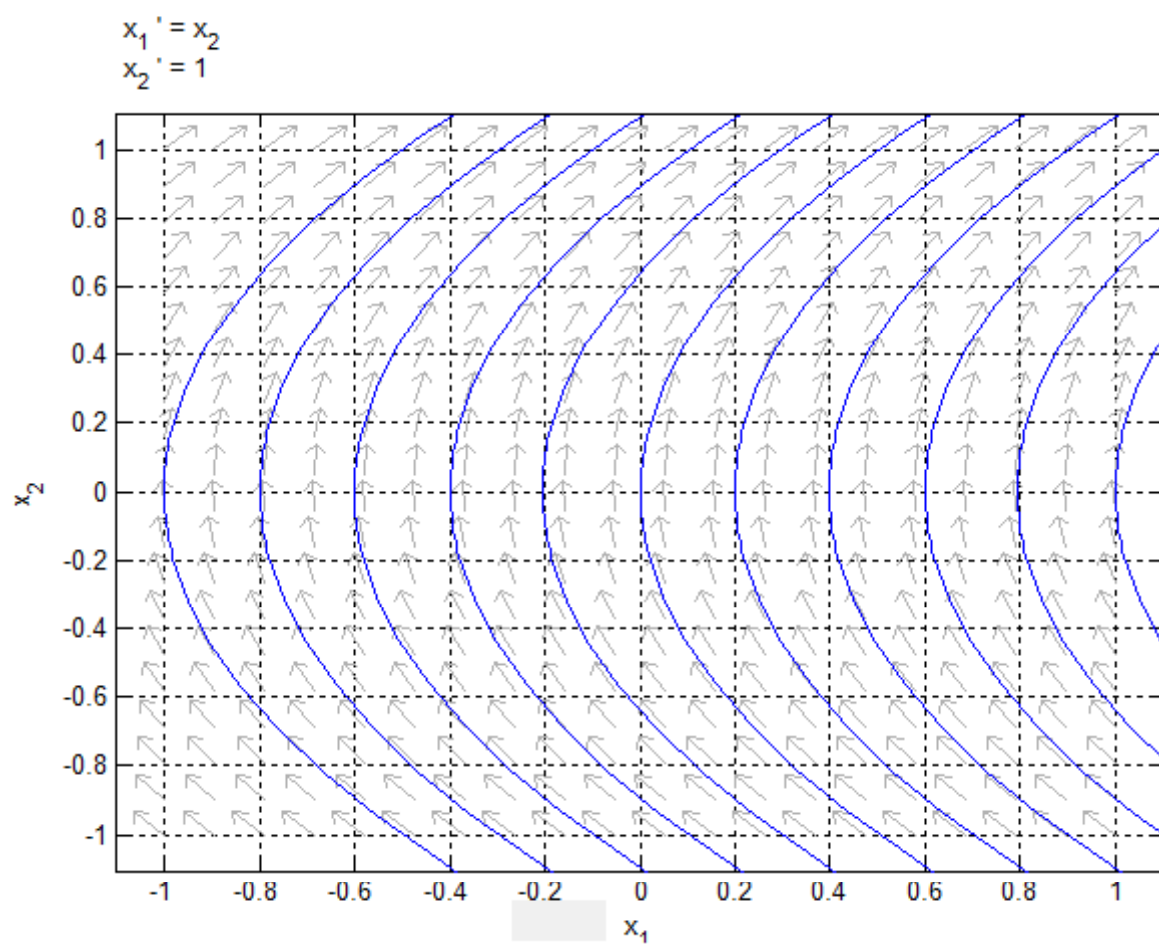


2.3

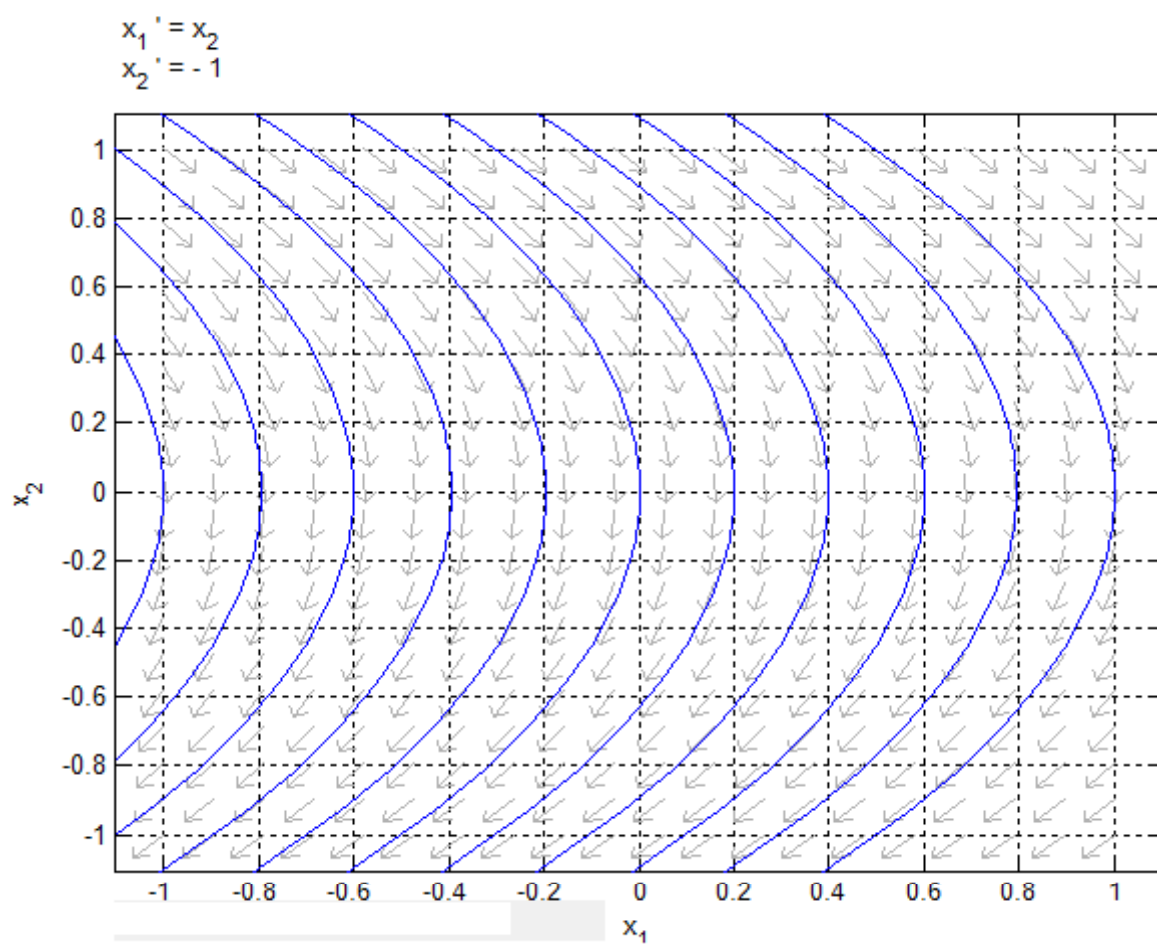
(5)



2.15 (a)

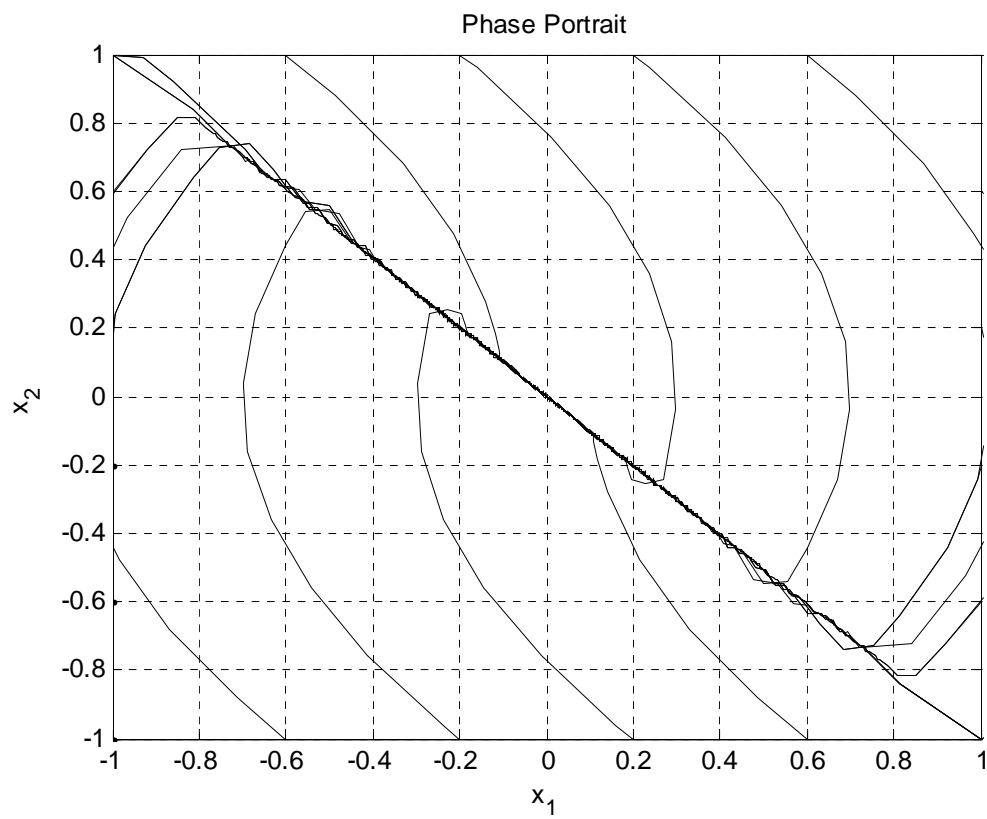


2.15 (b)



2.15 (c)

$$u = \begin{cases} -1 & \text{if } x_1 + x_2 \geq 0 \\ 1 & \text{if } x_1 + x_2 < 0 \end{cases}$$



2.17

(1)

$$\text{Let } x_1 = y, x_2 = \dot{x}_1, \begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -x_1 + \varepsilon x_2(1 - x_1^2 - x_2^2) \end{cases}$$

Let  $M = \{x \mid c_1 \leq V(x) \leq c_2\}$  where  $V(x) = x_1^2 + x_2^2$  and  $c_2 > c_1 > 0$

$$f(x)\nabla V(x) = 2\varepsilon x_2^2(1 - x_1^2 - x_2^2)$$

$$\text{By setting } c_1 = \frac{1}{2}, c_2 = \frac{3}{2}$$

$$\begin{cases} f(x)\nabla V(x) > 0 & \text{on } V(x) = c_1 \\ f(x)\nabla V(x) < 0 & \text{on } V(x) = c_2 \end{cases}$$

Moreover,  $M$  does not contain any equilibrium point.

$\therefore M$  contains a periodic orbit

2.17

(3)

We need to find a closed boundary set  $M$  so that  $M$  contains no equilibrium point and positively invariant.

Consider  $V = 3x_1^2 + 2x_1x_2 + 2x_2^2$ .

$$\begin{aligned}\dot{V} &= 6x_1x_2 + 2x_2^2 + 2(x_1 + 2x_2)(-x_1 + x_2) - 4(x_1 + 2x_2)^2x_2^2 \\ &= -2(x_1^2 + x_2^2) + 1 - (1 - 2x_2(x_1 + 2x_2))^2 \\ &\leq -2(x_1^2 + x_2^2) + 1 \leq 0\end{aligned}$$

$$\text{if } x_1^2 + x_2^2 \geq \frac{1}{2}.$$

Thus construct the surface  $V(x) = c$  so that this surface contains the circle  $\{x_1^2 + x_2^2 = \frac{1}{2}\}$  in it.

Then all trajectories starting in  $M = \{V(x) \leq c\}$  stay in  $M$ .

Moreover, linearization at 0 shows that the origin is unstable.

Therefore by P - B Theorem, there is a periodic solution.



2.20

(1) Using Bendixson criterion

$$\frac{\partial f_1}{\partial x_1} + \frac{\partial f_2}{\partial x_2} = -1 + a \neq 0$$

 $\Rightarrow$  no change of sign ( $\because a \neq 1$  and  $a$  : constant) $\therefore$  no limit cycle

(3) Using Bendixson criterion

$$\frac{\partial f_1}{\partial x_1} + \frac{\partial f_2}{\partial x_2} = -x_2^2 \neq 0$$

$$\text{i) } D_1 = \{(x_1, x_2) \mid x_2 < 0, (x_1, x_2) \in \mathbb{R}^2\}$$

$$\text{ii) } D_2 = \{(x_1, x_2) \mid x_2 > 0, (x_1, x_2) \in \mathbb{R}^2\}$$

 $\Rightarrow$  in  $D_1$  and  $D_2$ , no change of sign

$$(\because \frac{\partial f_1}{\partial x_1} + \frac{\partial f_2}{\partial x_2} \neq 0)$$

 $\therefore$  The system has no periodic orbits lying entirely in  $D_1$  or  $D_2$ .iii) across  $D_1$  and  $D_2$ 

$$x_1 = 0 \rightarrow \begin{cases} \dot{x}_1 = 1 \\ \dot{x}_2 = 0 \end{cases}, x_2 = 0 \rightarrow \begin{cases} \dot{x}_1 = 1 \\ \dot{x}_2 = x_1 \end{cases}$$

no closed curve  $\rightarrow$  no limit cycle

2.20

(5) We use Index theorem.

$$\text{eq. pts} \rightarrow \begin{bmatrix} x_1 = n\pi, (n = 0, \pm 1, \pm 2 \dots) \\ x_2 = 0 \end{bmatrix}$$

$$n = 2k (k = 0, 1, 2 \dots) \rightarrow \begin{bmatrix} 2kn \\ 0 \end{bmatrix} \rightarrow \lambda = \pm 1 : \text{saddle}$$

$$n = 2k + 1 (k = 0, 1, 2 \dots) \rightarrow \begin{bmatrix} 2(k+1)n \\ 0 \end{bmatrix} \rightarrow \lambda = \pm 1 : \text{saddle}$$

$\therefore$  no limit cycle

2.22

(a) Let  $V(x) = x_2$

Then  $V(x) > 0$  in  $\forall x \in D$  and  $V(x) = 0$  on  $\partial D$

$$\dot{V}(x) \Big|_{V(x)=0} = b x_1^2 \geq 0$$

Hence the trajectories on the boundary  $D$   
must move into  $D$

$\therefore D$  : positively invariant set

(b)

$$\nabla f(x) = a - c - x_2 < 0, \quad \forall x \in D$$

(no change of sign)

From (a),  $D$  is shown to be a positively  
invariant set.

$\therefore$  No periodic orbit through any point  $x \in D$ .