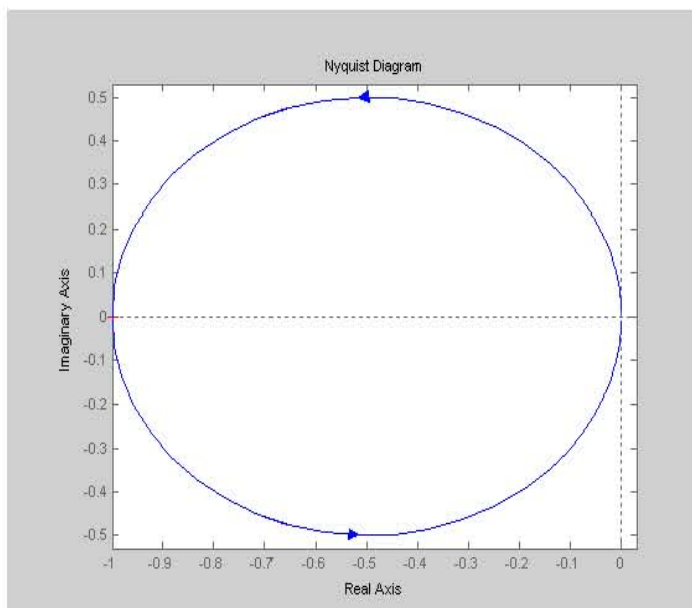
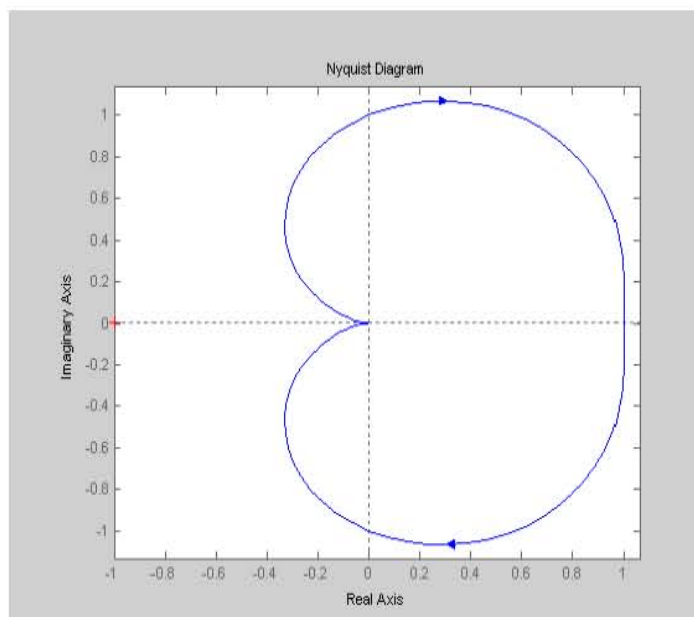


7.1 Apply Theorem 7.2 and use example 7.2~4

(1)

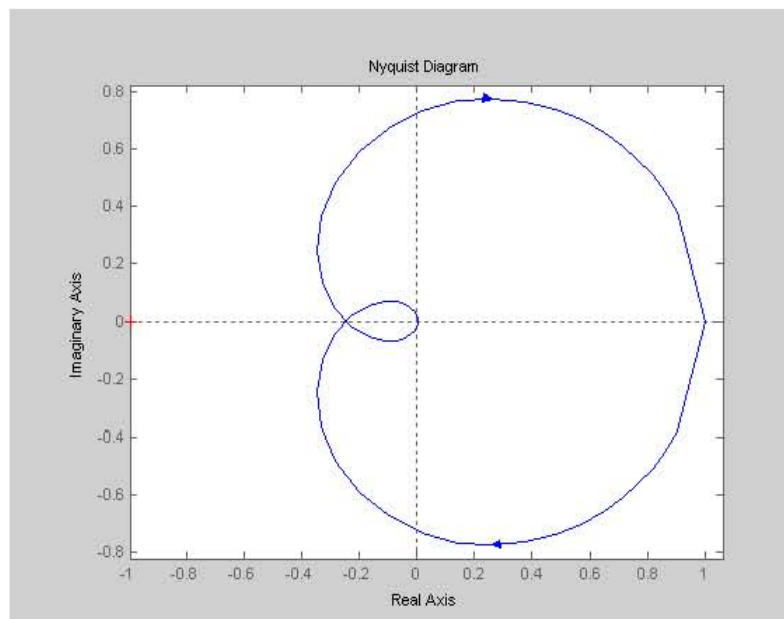


(3)



7.1

(7) Apply Theorem 7.2



7.2

$$(1) z(s) = 1 + G(s) = \frac{s^2 + 3s + 1}{s^2 + s + 1}$$

$$\operatorname{Re}(z(j\omega)) = \frac{(1 - \omega^2)^2 + 3\omega^2}{(1 - \omega^2)^2 + \omega^2} > 0$$

(2) $\psi(y) = \operatorname{sat}(y)$ has nonlinearities in the sector $[0, 1]$.

\Rightarrow eq. point is globally uniformly asymptotically stable.

\Rightarrow no limit cycle.

7.11

$$(3) \quad \psi(a) = \frac{4}{\pi a}$$

$$G(j\omega) = \frac{-(\omega^2 - 1)(\omega^4 - 14\omega^2 + 1)}{\omega^2 + 6\omega^{10} + 15\omega^8 + 20\omega^6 + 15\omega^4 + 6\omega^2 + 1} - j \frac{6\omega(\omega^4 - 3.333\omega^2 + 1)}{\sim}$$

$$\Rightarrow \omega = 1.73205 \text{ or } 0.577735$$

$$\psi(a) = \frac{4}{\pi a} = -\frac{1}{\operatorname{Re}[G(j\omega)]} = -64 \text{ or } 2.37$$

\therefore periodic solution with $a \approx 0.54$, $\omega = 0.577$

$$(5) \quad \psi(a) = \frac{5}{8}a^4$$

$$G(j\omega) = \frac{-\omega^2}{\omega^4 - \omega^2 + 1} - j \frac{\omega(\omega^2 - 1)}{\omega^4 - \omega^2 + 1}$$

$$\Rightarrow \omega = 1$$

$$\psi(a) = \frac{5}{8}a^4 = -\frac{1}{\operatorname{Re}[G(j\omega)]} = 1 \Rightarrow a = \left(\frac{8}{5}\right)^{1/4}$$

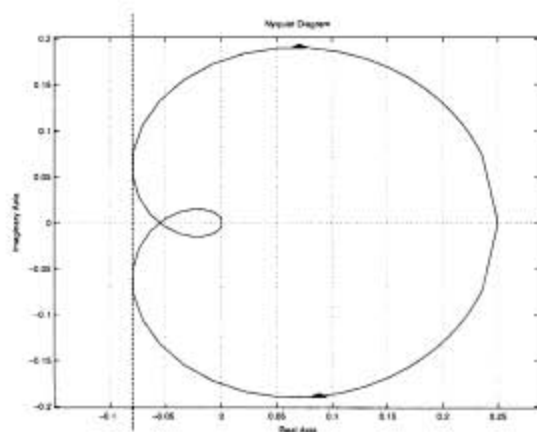
\therefore periodic solution with $a = \left(\frac{8}{5}\right)^{1/4}$, $\omega = 1$

(9)

The same method above problems

7.14

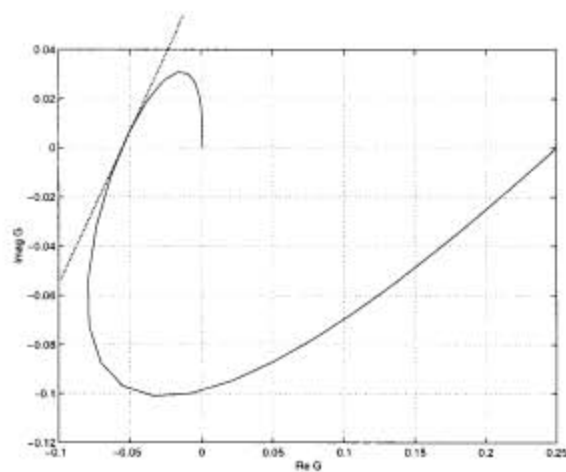
(a)



case 2 of Theorem 7.2

$$-\frac{1}{\beta} = -0.08 \Rightarrow b \approx 12.5$$

(b)



$$-\frac{1}{b} \approx -0.055 \Rightarrow b \approx 18$$

7.14

(c)

$$\psi(a) = \begin{cases} b & \text{if } 0 \leq a \leq \frac{1}{b} \\ \frac{2b}{\pi} \left[\sin^{-1}\left(\frac{1}{ab}\right) + \frac{1}{ab} \sqrt{1 - \left(\frac{1}{ab}\right)^2} \right] & \text{if } 1 < ab \end{cases}$$

$$\begin{cases} \operatorname{Im} G(j\omega) = 0 \rightarrow \omega = \sqrt{2} \\ \operatorname{Re} G(j\omega)|_{\omega=\sqrt{2}} = -\frac{1}{18} \end{cases}$$

$$1 + \psi(a) \operatorname{Re} G(j\omega)|_{\omega=\sqrt{2}} = 1 - \frac{1}{18} \psi(a) = 0 \Rightarrow \psi(a) = 18$$

$$\text{if } 0 \leq a \leq \frac{1}{b} \rightarrow b = 18$$

$$\text{if } \frac{1}{ab} < 1 \rightarrow \frac{2b}{\pi} \left[\sin^{-1}\left(\frac{1}{ab}\right) + \frac{1}{ab} \sqrt{1 - \left(\frac{1}{ab}\right)^2} \right] = 18$$

$$\frac{1}{ab} = 1 \rightarrow b = 18, \quad a = \frac{1}{18}$$

System oscillates for $b \geq 18$ with $\omega = \sqrt{2}$, $a = \frac{1}{18}$.

7.15

Refer to the solution of 7.14.

10.10

$$(1) \quad \dot{x}_1 = \varepsilon x_2$$

$$\dot{x}_2 = -\varepsilon(1 + 2\sin t)x_2 - \varepsilon(1 + \cos t)\sin x_1, \quad \text{where } \varepsilon \ll 1$$

$$f_{av}(x) = \frac{1}{2\pi} \int_0^{2\pi} \begin{bmatrix} x_2 \\ -(1 + 2\sin t)x_2 - (1 + \cos t)\sin x_1 \end{bmatrix} dt = \begin{bmatrix} x_2 \\ -x_2 - \sin x_1 \end{bmatrix}$$

$$\dot{\bar{x}} = \varepsilon \begin{bmatrix} \bar{x}_2 \\ -\bar{x}_2 - \sin \bar{x}_1 \end{bmatrix}$$

The averaged system has an equilibrium point at the origin.

The linearization yields

$$\left. \frac{\partial f_{av}}{\partial \bar{x}} \right|_{\bar{x}=0} = \begin{bmatrix} 0 & 1 \\ -1 & -1 \end{bmatrix} \quad \text{which is Hurwitz.}$$

\Rightarrow the origin is exponentially stable.

$$(3) \quad f_{av1} = \frac{1}{2\pi} \int_0^{2\pi} (-x \sin^2 t + x^2 \sin t) dt = -\frac{1}{2} x$$

$$f_{av2} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T x e^{-t} dt = 0$$

$$\therefore \dot{\bar{x}} = -\frac{1}{2} \bar{x} \rightarrow \text{Hurwitz}$$

\therefore exponentially stable

11.10

(a) • Set $\varepsilon = 0$ $(z + xt)(z - 2)(z - 4) = 0$

$$\begin{cases} z = -xt \\ z = 2 \\ z = 4 \end{cases} \quad \therefore \text{possible three}$$

(b) i) $h(t, x) = -xt$ ($t = t_0$ (0 for convenience), $x(0) = \xi_0$)

$$\frac{\partial y}{\partial \tau} = -y(y - 2)(y - 4)$$

$$V(y) = \frac{1}{2}y^2 \quad \frac{\partial V}{\partial y}g = -y^2(y - 2)(y - 4) \rightarrow \text{exp. stable}$$

$$(\text{RoA} : y < 2)$$

ii) $h(t, x) = 2$

$$\frac{\partial y}{\partial \tau} = -y(y + 2)(y - 2) \rightarrow \text{unstable}$$

iii) $h(t, x) = 4$

$$\frac{\partial y}{\partial \tau} = -y(y + 2)(y + 4)$$

$$V(y) = \frac{1}{2}y^2 \quad \frac{\partial V}{\partial y}g = -y^2(y + 2)(y + 4) \rightarrow \text{exp. stable}$$

$$(\text{RoA} : y > -2)$$

11.10

(c) i) $h(t, x) = -xt$

$$\dot{x} = -x, \quad x(0) = 1 \Rightarrow \bar{x}(t) = e^{-t}$$

Since RoA: $y < 2$ and $y(0) = z(0) - h(0, x(0)) = a$

$$\begin{cases} x(t, \varepsilon) = e^{-t} + O(\varepsilon) \\ z(t, \varepsilon) = -te^{-t} + \hat{y}\left(\frac{t}{\varepsilon}\right) + O(\varepsilon) \end{cases} \quad a \in [-2, 2)$$

ii) unstable

iii) $h(t, x) = 4$

$$\dot{x} = \frac{x^2 t}{4}, \quad x(0) = 1$$

Since RoA: $y > -2$ and $y(0) = z(0) - h(0, x(0)) = a - 4$

$$\begin{cases} x(t, \varepsilon) = \bar{x}(t) + O(\varepsilon) \\ z(t, \varepsilon) = 4 + \hat{y}\left(\frac{t}{\varepsilon}\right) + O(\varepsilon) \end{cases} \quad a \in (2, 6]$$