TTK4150 Nonlinear Control Systems Department of Engineering Cybernetics Norwegian University of Science and Technology Fall 2015 - Assignment 5

Due date: Monday 20 November at 6.00.

- 1. Exercise 14.43 in Khalil (Hint: Theorem 14.4 in Khalil).
- 2. Exercise 13.1 in Khalil.
- 3. Exercise 13.2 in Khalil.
- 4. Given is the system

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} -x_1 + e^{x_2}u \\ x_1x_2 + u \\ x_2 \end{bmatrix}$$
$$y = x_3$$

- (a) Find the relative degree of the system and specify the region on which this relative degree holds.
- (b) Show that the system is input-output linearizable. Specify the region on which it is input-output linearizable.
- (c) Find a coordinate transformation z = T(x) that transforms the system into the normal form. (Note: T(x) must be a diffeomorphism¹ over the region of interest and T(0) = 0)
- (d) Express the system in normal form. Determine all functions and constants involved in the normal form. Which part of the normal form counts for the internal dynamics?
- (e) Find the zero dynamics and show that it has a globally asymptotically stable equilibrium at the origin.
- (f) Choose an input u to solve the stabilization problem for the entire system (asymptotically stable equilibrium in the origin).
- (g) Choose an input u to solve the tracking problem for the entire system (asymptotically stable equilibrium at the origin).
- 5. Exercise 13.25 in Khalil.

¹A function y = f(x) is a diffeomorphism over a domain \mathcal{D} if f(x) and $\frac{\partial f}{\partial x}(x)$ are continuous over D and there exist the inverse of f, $f^{-1}(y)$ such that $f^{-1}(y)$ and $\frac{\partial f^{-1}}{\partial y}(y)$ are continuous over $\bar{\mathcal{D}} = \{y = f(x) | x \in \mathcal{D}\}.$

⁽Example: $f(x) = x^3$ is a diffeomorphism over $\mathbb{R}_+ = \{x : x > 0\}$ since f(x) and $\frac{\partial f}{\partial x}(x) = 3x^2$ are continuous over \mathbb{R}_+ , $f^{-1}(y) = \sqrt[3]{y}$ and $\frac{\partial f^{-1}}{\partial y}(y) = \frac{1}{3}y^{-\frac{2}{3}}$) are continuous over \mathbb{R}_+).