A Brief Introduction to MATLAB

MATLAB

- A high-level programming language
 - Graphics functions
 - Common operations are available as functions
 - Toolboxes for specific applications
- A development environment
 - Editor
 - Debugger
 - Variable browser
 - Profiler for optimization
 - GUI editor
 - On-line documentation with examples

MATLAB programs

- Programs are interpreted
 - Program development is fast
 - Program execution is slow (relative to C++)
 - Interaction with data is easy
 - Variables exist in a workspace
- Two kinds of programs
 - Scripts
 - Operate on variables in the base workspace
 - Functions
 - Input and output arguments--private workspace

Variables

• Floating point (double precision) by default a = 3.14

• Strings

• Names can begin in upper- or lower-case letters (and are case-sensitive)

Operators

- Arithmetic operators: +, -, *, /, ^
- Comparison operators: <, >, ==
- Type help func to get help on the function or operator "func" (or use the help browser)

Expressions

- Combinations of variables and operators
 a + pi*b/5
- Interpreter will display the value of the expression unless the line ends with a semicolon (;)
- Comments begin in %

Arrays

- Scalars: a = 3;
- One dimensional arrays:
 - Row array: b = [1, 2, 3];

$$b = (1 \ 2 \ 3)$$

- Column array: c = [1; 2; 3];

$$c = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

• Two dimensional arrays:

- Matrix:
$$d = [1, 2, 3; 4, 5, 6];$$

$$d = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$

Higher dimensional arrays

Naming conventions

• To remember dimensionality, I usually add a suffix:

```
c_1d, d_2d, f_3d, etc
```

Or more commonly

```
c_v for a vector (1D array)
```

d_m for a matrix (2D array)

Array indexing

• Accessing elements:

b_1d(3) is the third element

$$b_1d = (5 \ 7 \ 2)$$

d_2d(1, 3) is the element in row 1, column 3

$$d_2d = \begin{pmatrix} 1 & 2 & 4 \\ 6 & 9 & 0 \end{pmatrix}$$

Creating arrays

• Colon operator:

$$a = 1:5;$$

is the same as

$$a = [1, 2, 3, 4, 5];$$

• Create an array of zeros (2 rows, 3 columns) with

$$b = zeros(2, 3);$$

Higher dimensional arrays

• Elements of 3D arrays can be specified using three indices (row, column, and page):

```
image_3d(i, j, k) = 5;
```

For an image dataset, the 3rd dimension could represent slice number or time index

• Create 3D arrays with predefined arrays or concatenation:

```
image_3d = zeros(128, 128, 64);
image_3d = cat(3, image1_m, image2_m);
```



• Any number of dimensions is possible (given sufficient memory)

Array operations

- Element-by-element operations
- Usually much faster than using for loops
- Multiply with .*

$$c_{m} = a_{m} * b_{m}$$

$$= \begin{pmatrix} 1 & 4 \\ 2 & 0 \end{pmatrix} * \begin{pmatrix} 3 & 1 \\ 4 & 5 \end{pmatrix}$$

$$= \begin{pmatrix} 3 & 4 \\ 8 & 0 \end{pmatrix}$$

Array Division with ./

$$c_{m} = a_{m}/b_{m}$$

$$= \begin{pmatrix} 10 & 4 \\ 6 & 0 \end{pmatrix} \cdot / \begin{pmatrix} 5 & 1 \\ 2 & 5 \end{pmatrix}$$

$$= \begin{pmatrix} 2 & 4 \\ 3 & 0 \end{pmatrix}$$

Program control

• Loops: for j = 1:5For loop a = a+5;end j = 1;while (j<6) a = a + 5;While loop j = j + 1;

end

• Conditional execution:

If block

```
switch c
 case 1
      d = 26;
 case 2
      d = 77;
 case 3
      d = 103;
end
```

Switch statement

Using functions

• Functions take input arguments and return output variables

```
a = \sin(x);
```

- Functions are usually defined in an *M-file*
 - A text file named <function name>.m, for example myFunc.m
 - The file begins with the line
 function [output1, output2] = myFunc(input1, input2)
 and can have any number of input and output arguments
- *Subfunctions* are functions defined in another function's M-file
 - Can only be used within the defining M-file

Anonymous functions

A quick way to define a one-line function:
 fHandle = @(arg list) expr
 for example
 myMean = @(x,y,z) (x+y+z)/3

• The *function handle* fHandle is a variable that can be passed to another function

Model fitting

Fit a line (first order polynomial) to the data in x_v and y_v:

```
coeff_v = polyfit(x_v, y_v, 1);
where coeff_v = [slope, intercept].
```

• Fit the parameters p_v in more complicated models to the data in data v:

```
pFit_v = fminsearch(@(p_v) ...

sum((myFunc(p_v, const_v) - data_v).^2));
```

where

```
model_v = myFunc(p_v, const_v)
```

fminsearch uses an unconstrained search algorithm to find the value of p_v that minimizes the sum of squared errors between myFunc and data_v.

Plotting

- Open a new window for graphics with figure
- To plot elements of y_1d versus those of x_1d use plot(x_1d, y_1d)
- To put more than one plot in a figure, define subplots. For 3 rows and 4 columns of subplots (with the first as the current subplot), use

subplot(3, 4, 1)

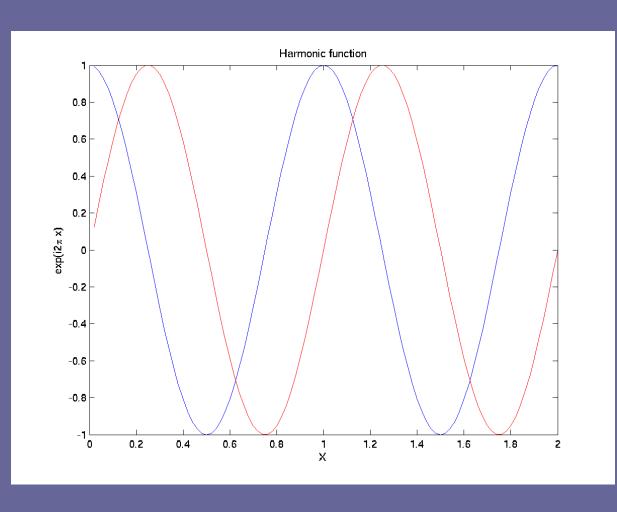
• Add the label 'time' to the x axis:

xlabel('time')

ylabel and title add labels to the y axis and plot box

Plotting example: e^{i2πx}

```
dx = 0.02;
x_v = (1:100)*dx;
y_v = exp(1i*2*pi*x_v);
plot(x_v, real(y_v), 'b', ...
    x_v, imag(y_v), 'r')
title('Harmonic function')
xlabel('X')
ylabel('exp(i2\pi x)')
```



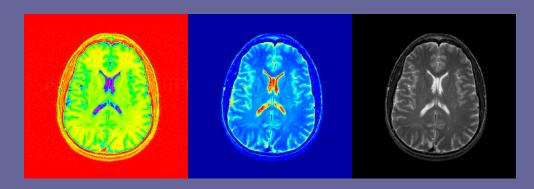
Summary

- MATLAB is a high-level programming environment
 - Optimized for array computation
 - Interaction with data
- Many similarities (but also some differences) to other languages
- Best way to learn MATLAB is to use it
- Next video:
 - A Brief Introduction to Image Analysis in MATLAB

A Brief Introduction to Image Analysis in MATLAB

Image display

- Display grayscale images with imagesc
- View in color by changing color map:
 - colormap(hsv)
 - colormap(jet)
 - colormap(gray)



- Show color image with image(color_3d)
 - Page 1: red values
 - Page 2: green values
 - Page 3: blue values

Finding image coordinates

• Define a region of interest (ROI):

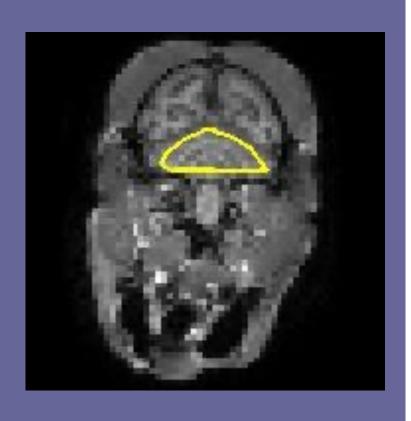
- Find coordinates of pixels in a mask with
 [row_v, col_v] = find(mask_m);
- Get coordinates of points selected with mouse clicks:

$$[x_v, y_v] = ginput(n);$$

• Find coordinates of all pixels:

$$[x_m, y_m] = meshgrid(1:nx, 1:ny);$$

The rows of x_m are all 1:nx, the columns of y_m are all 1:ny.

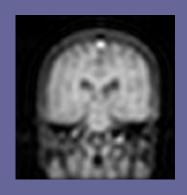


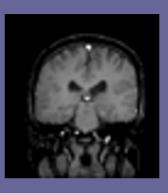
Operations on images

• Get the maximum or minimum value in an image array:

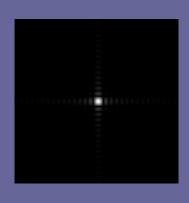
```
imageMax = max(image_m(:));
imageMin = min(image_m(:));
```

• Convolve an image with a blurring array: im2_m = conv2(im1_m, psf_m, 'same');





*



Array indexing

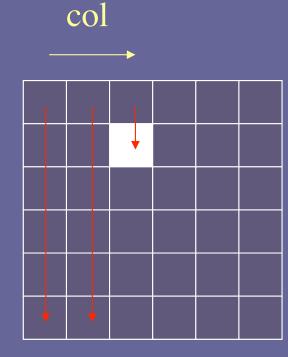
row

- Two ways to index a pixel in an image
 - Row, column indices
 - [row, col] = [2, 3]
 - Linear index
 - Index = 14
- Translate between these:

```
[row, col] = ind2sub(siz, index)
index = sub2ind(siz, row, col)
```

• Eliminate 'singleton' dimensions:

```
image_3d = zeros(64,64,1);
image_m = squeeze(image_3d);
```



Linear index

Making movies



Example: field mapping in MRI

• The problem:

- The magnetic field in the body is not uniform and this can distort an MRI image.
- If the field variation is known, it can be corrected or the images can be corrected

• Program steps

- Read image data
- Loop through all pixels
 - Find change in magnetization orientation with time
- Convert from frequency to magnetic field error

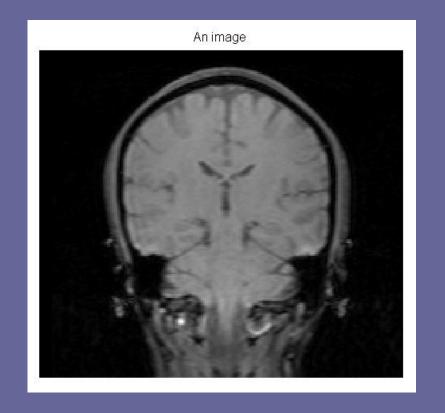
$$\delta B_z = -\omega/\gamma$$

Display

Read image data

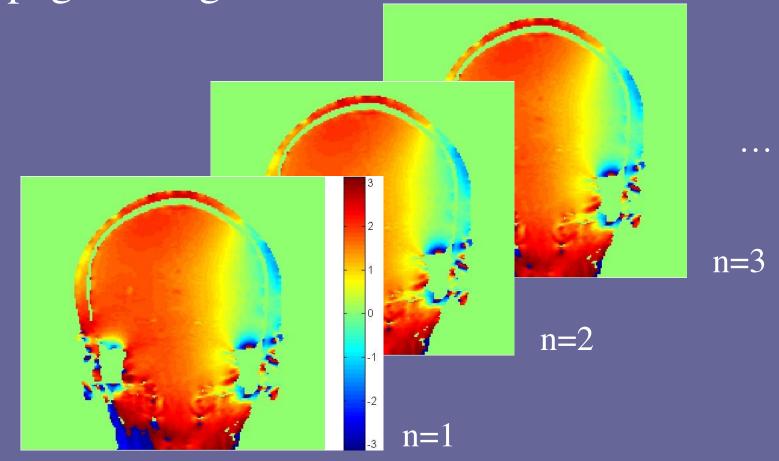
• Read and display the image matrix

load('myData.mat')
imagesc(image_m)
colormap(gray)
axis image
axis off
title('An image')



Orientation of magnetization

• Orientation angle at time *n* is stored in the *n*th page of angle_3d



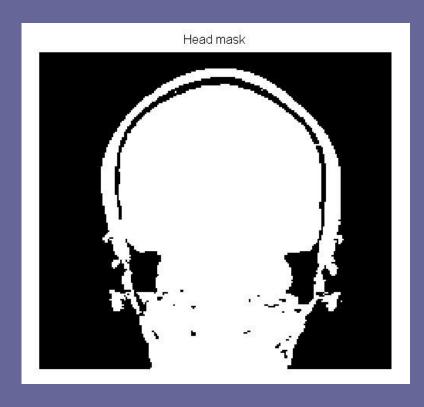
Ignore pixels outside the head

• Set intensity threshold at 10% of maximum:

 $mask_m = (image_m > 0.1*max(image_m(:)));$

figure
imagesc(mask_m)
colormap(gray)
axis image
axis off
title('Head mask')

• mask_m has 1's in head

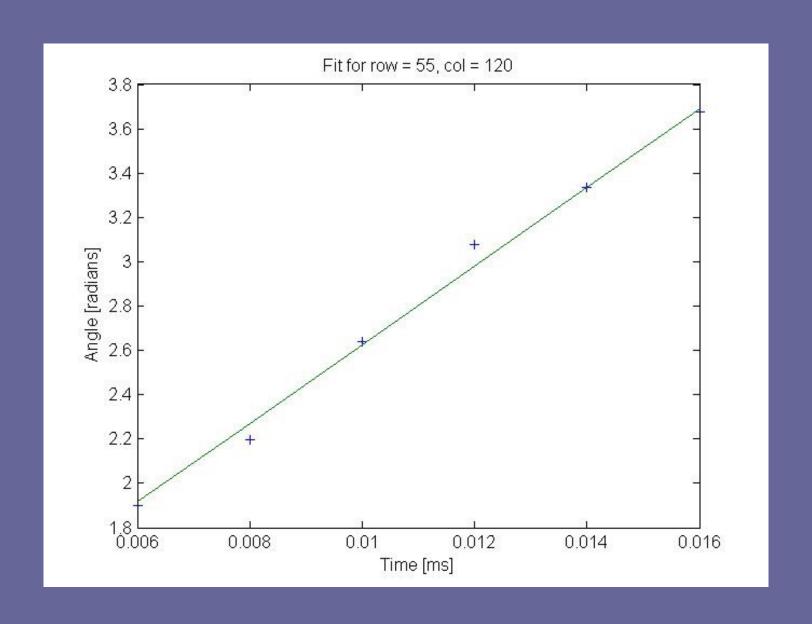


Loop through pixels in head

• Find the precession frequency for each pixel:

```
freq_m = zeros(nRows, nCols);
for row = 1:nRows
  for col = 1:nCols
    if (mask\_m(row, col) > 0)
       angle_v = angle_3d(row, col, :);
       uwAngle_v = unwrap(angle_v);
       a_v = polyfit(time_v, uwAngle_v, 1);
       slope = a_v(1);
       intercept = a_v(2);
       % Store frequency:
       freq_m(row, col) = slope;
    end
  end
end
```

Angle versus time for one pixel

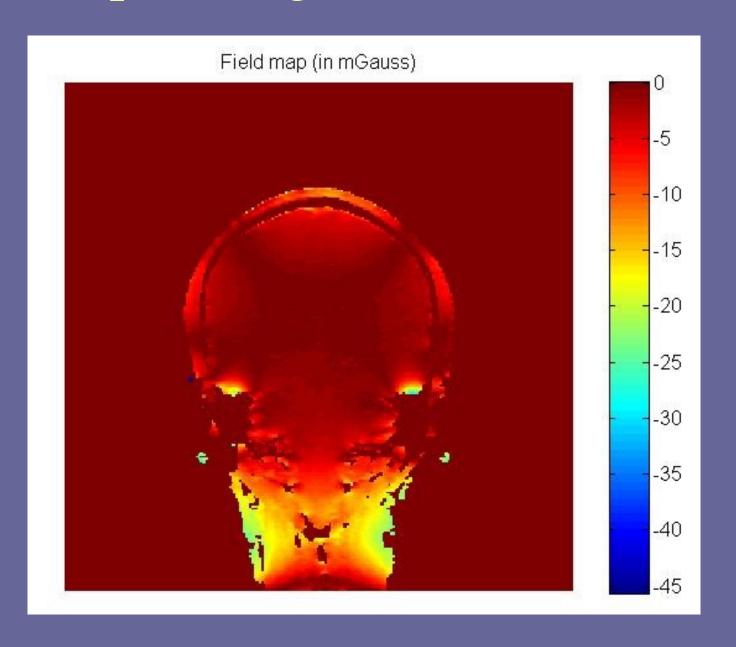


Convert frequencies to field errors

• Use Larmor relation: $\delta B_z = -\omega/\gamma$

```
field_m = -freq_m / (2*pi*4.26);
figure
imagesc(field_m)
axis image; axis off
colormap(jet)
colorbar
title('Field map (in mGauss)')
```

Map of magnetic field errors



Results of calculation

- Field errors, $B_z B_0$, are small in the center of the brain, larger near the edges
 - Why?
- How could the errors be reduced?

Summary

- MATLAB is a high-level language that facilitates interacting with data
 - Easy to view intermediate results
 - Test algorithms
- Provides many useful functions for data analysis and modeling
 - Image display
 - ROI definition
 - Mask generation
 - Data fitting functions
- Will be our main tool for data analysis projects