

Advanced Algorithms Analysis and Design

By

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Lecture No 18

2-Line Assembly Scheduling Problem

Today Covered

- 2-Line Assembly Scheduling Algorithm using Dynamic Programming
- Time Complexity
- n-Line Assembly Problem
- Brute Force Analysis
- n-Line Assembly Scheduling Algorithm using Dynamic Programming
- Time Complexity
- Generalization and Applications
- Conclusion

Assembly-Line Scheduling Problem

- There are two assembly lines each with n stations
- The j th station on line i is denoted by $S_{i,j}$
- The assembly time at that station is $a_{i,j}$.
- An auto enters factory, goes into line i taking time e_i
- After going through the j th station on a line i , the auto goes on to the $(j+1)$ st station on either line
- There is no transfer cost if it stays on the same line
- It takes time $t_{i,j}$ to transfer to other line after station $S_{i,j}$
- After exiting the n th station on a line, it takes time x_i for the completed auto to exit the factory.
- Problem is to determine which stations to choose from lines 1 and 2 to minimize total time through the factory.

Mathematical Model Defining Objective Function

Base Cases

- $f_1[1] = e_1 + a_{1,1}$
- $f_2[1] = e_2 + a_{2,1}$

Two possible ways of computing $f_1[j]$

- $f_1[j] = f_2[j-1] + t_{2,j-1} + a_{1,j}$ OR $f_1[j] = f_1[j-1] + a_{1,j}$
For $j = 2, 3, \dots, n$
$$f_1[j] = \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j})$$

Symmetrically

For $j = 2, 3, \dots, n$

$$f_2[j] = \min(f_2[j-1] + a_{2,j}, f_1[j-1] + t_{1,j-1} + a_{2,j})$$

Objective function = $f^* = \min(f_1[n] + x_1, f_2[n] + x_2)$

Dynamic Algorithm

FAATEST-WAY(a, t, e, x, n)

```
1    $f_1[1] \leftarrow e_1 + a_{1,1}$ 
2    $f_2[1] \leftarrow e_2 + a_{2,1}$ 
3   for  $j \leftarrow 2$  to  $n$ 
4       do if  $f_1[j - 1] + a_{1,j} \leq f_2[j - 1] + t_{2,j-1} + a_{1,j}$ 
5           then  $f_1[j] \leftarrow f_1[j - 1] + a_{1,j}$ 
6            $l_1[j] \leftarrow 1$ 
7           else  $f_1[j] \leftarrow f_2[j - 1] + t_{2,j-1} + a_{1,j}$ 
8            $l_1[j] \leftarrow 2$ 
9           if  $f_2[j - 1] + a_{2,j} \leq f_1[j - 1] + t_{1,j-1} + a_{2,j}$ 
```

Contd..

10. **then** $f_2[j] \leftarrow f_2[j - 1] + a_{2,j}$

11. $l_2[j] \leftarrow 2$

12. **else** $f_2[j] \leftarrow f_1[j - 1] + t_{1,j-1} + a_{2,j}$

13. $l_2[j] \leftarrow 1$

14. **if** $f_1[n] + x_1 \leq f_2[n] + x_2$

15. **then** $f^* = f_1[n] + x_1$

16. $l^* = 1$

17. **else** $f^* = f_2[n] + x_2$

18. $l^* = 2$

Optimal Solution: Constructing The Fastest Way

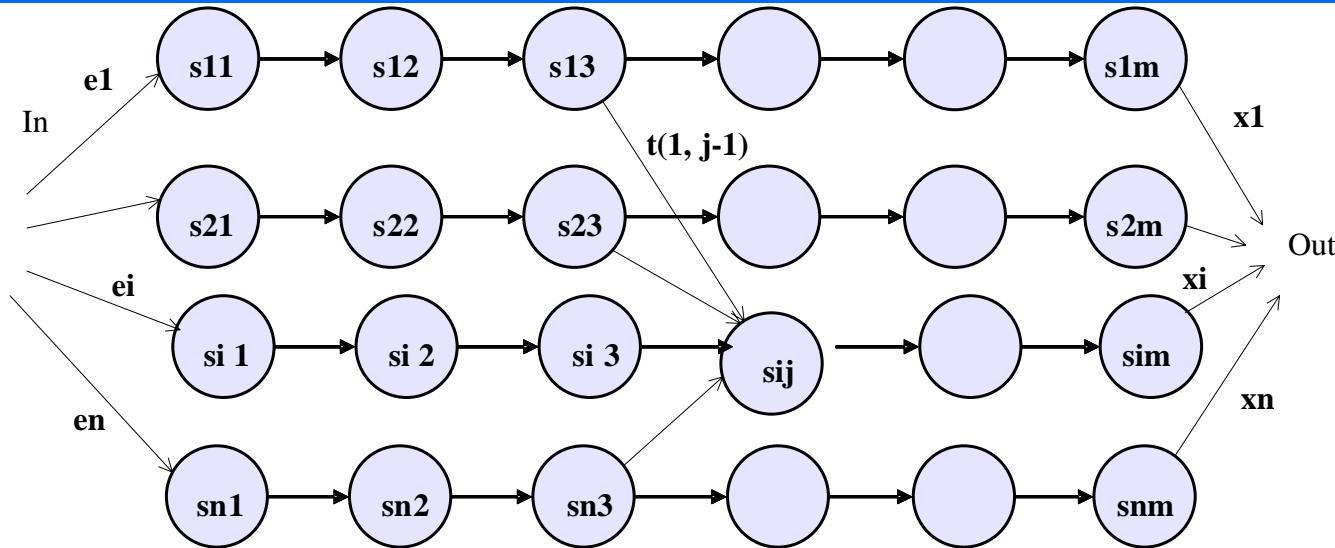
1. Print-Stations (l , n)
2. $i \leftarrow l^*$
3. print “line” i “, station” n
4. **for** $j \leftarrow n$ **downto** 2
5. **do** $i \leftarrow l_i[j]$
6. print “line” i “, station” $j - 1$

n-Line Assembly Problem

n-Assembly Line Scheduling Problem

- There are n assembly lines each with m stations
- The jth station on line i is denoted by $S_{i,j}$
- The assembly time at that station is $a_{i,j}$.
- An auto enters factory, goes into line i taking time e_i
- After going through the jth station on a line i, the auto goes on to the $(j+1)$ st station on either line
- It takes time $t_{i,j}$ to transfer from line i, station j to line i' and station $j+1$
- After exiting the nth station on a line i, it takes time x_i for the completed auto to exit the factory.
- Problem is to determine which stations to choose from lines 1 to n to minimize total time through the factory.

n-Line: Brute Force Solution



Total Computational Time

= possible ways to enter in stations at level n x one way Cost

Possible ways to enter in stations at level 1 = n^1

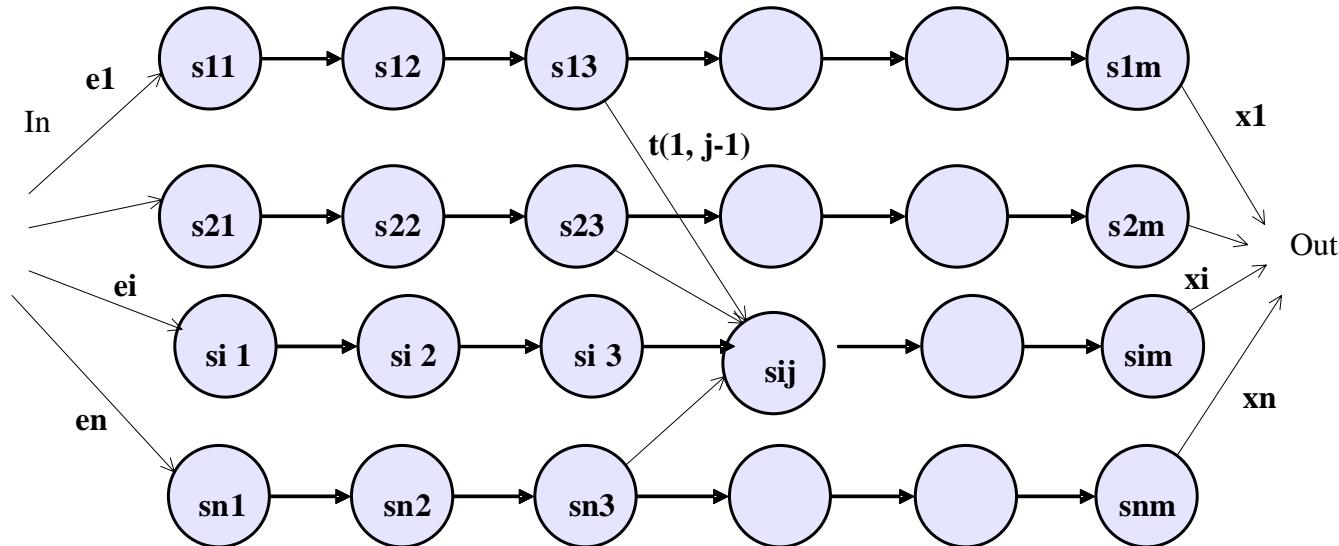
Possible ways to enter in stations at level 2 = $n^2 \dots$

Possible ways to enter in stations at level m = n^m

Total Computational Time = $\Theta(m \cdot m^n)$

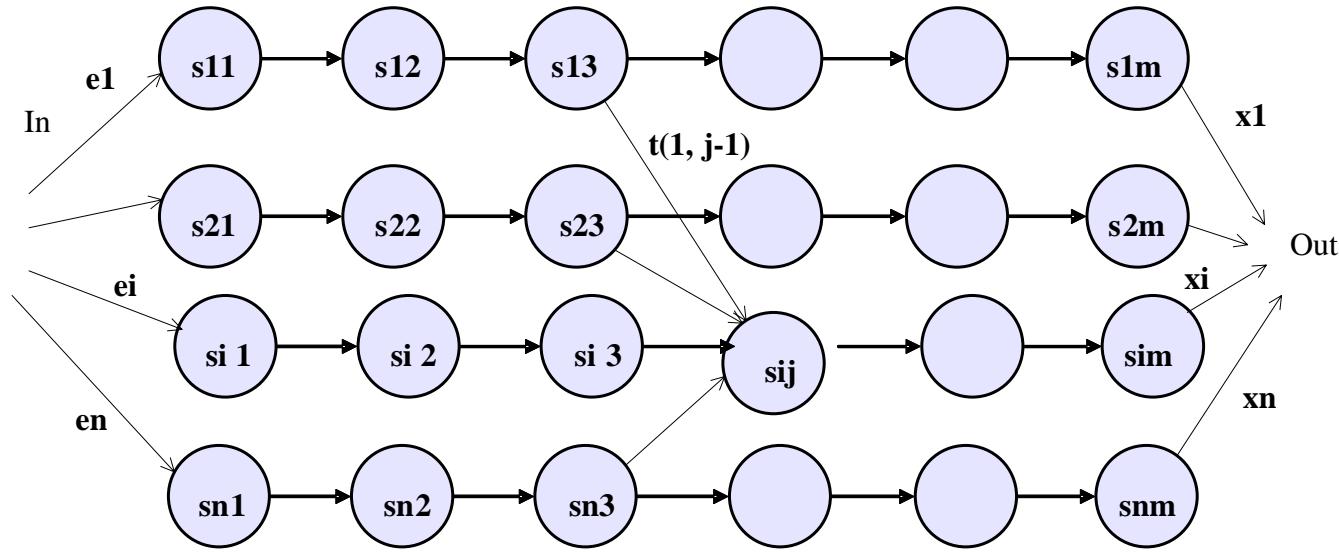
Dynamic Solution

Notations : n-Line Assembly



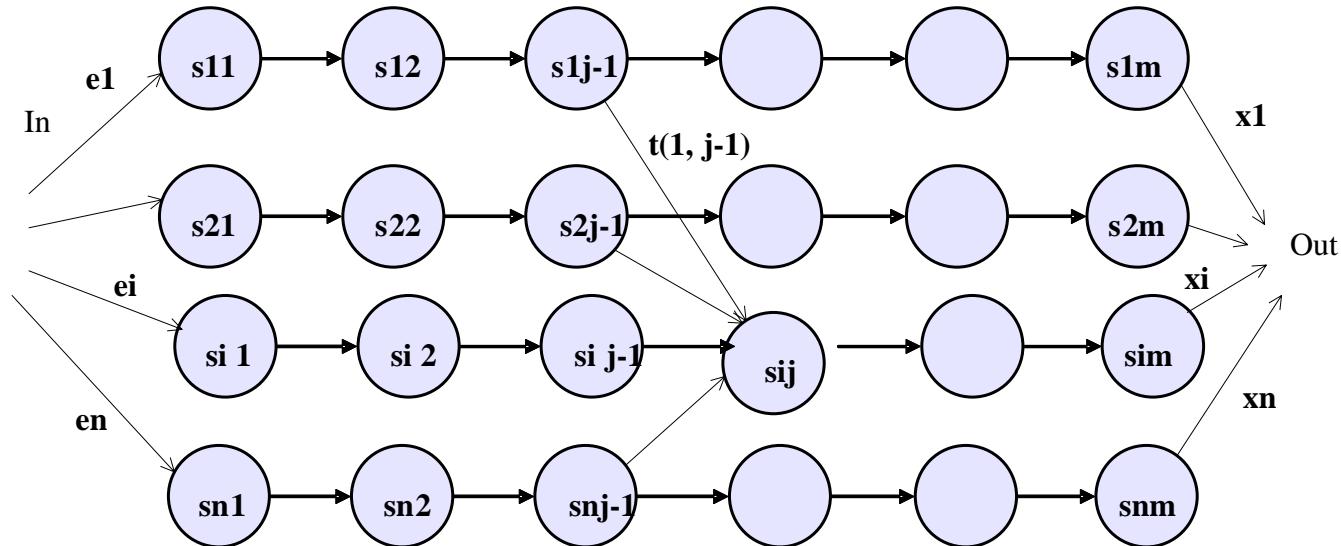
- Let $f_i[j]$ = fastest time from starting point to station $S_{i,j}$
- $f_1[m]$ = fastest time from starting point to station $S_{1,m}$
- $f_2[m]$ = fastest time from starting point to station $S_{2,m}$
- $f_n[m]$ = fastest time from starting point to station $S_{n,m}$
- $I_i[j]$ = The line number, 1 to n, whose station $j-1$ is used in a fastest way through station $S_{i,j}$

Notations : n-Line Assembly



- $t_i[j-1]$ = transfer time from station $S_{i, j-1}$ to station $S_{i, j}$
- $a[i, j]$ = time of assembling at station $S_{i, j}$
- f^* = is minimum time through any way
- I^* = the line no. whose m^{th} station is used in a fastest way

Possible Lines to reach Station S(i, j)



Time from Line 1, $f[1, j-1] + t[1, j-1] + a[i, j]$

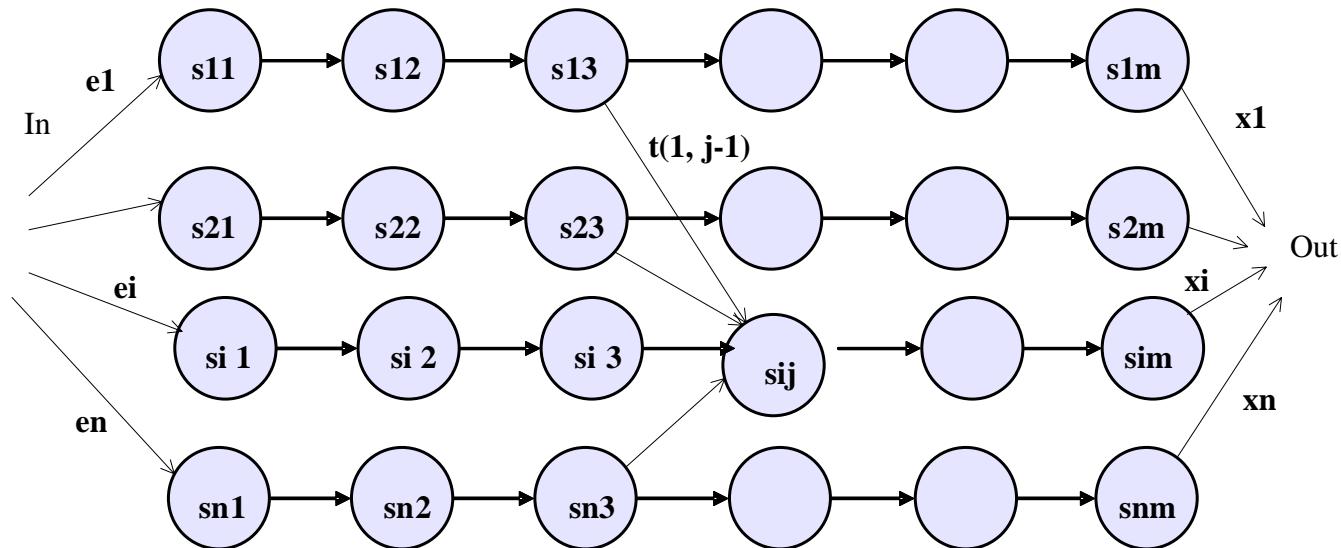
Time from Line 2, $f[2, j-1] + t[2, j-1] + a[i, j]$

Time from Line 3, $f[3, j-1] + t[3, j-1] + a[i, j]$

...

Time from Line n, $f[n, j-1] + t[n, j-1] + a[i, j]$

Values of $f(i, j)$ and l^* at Station $S(i, j)$



$f[i, j] = \min\{f[1, j-1] + t[1, j-1] + a[i, j], f[2, j-1] + t[2, j-1] + a[i, j], \dots, f[n, j-1] + t[n, j-1] + a[i, j]\}$

$f[1, 1] = e_1 + a[1, 1]; f[2, 1] = e_2 + a[2, 1], \dots, f[n, 1] = e_n + a[n, 1]$

$f^* = \min\{f[1, n] + x_1, f[2, n] + x_2, \dots, f[n, m] + x_n\}$

$l^* = \text{line number of } m^{\text{th}} \text{ station used}$

n-Line Assembly: Dynamic Algorithm

FASTEST-WAY(a, t, e, x, n, m)

```
1  for i  $\leftarrow$  1 to n
2     $f[i,1] \leftarrow e[i] + a[i,1]$ 
3  for j  $\leftarrow$  2 to m
4    for i  $\leftarrow$  1 to n
5       $f[i, j] \leftarrow f[1, j-1] + t[1, j-1] + a[i, j]$ 
6       $L[1, j] = 1$ 
7    for k  $\leftarrow$  2 to n
8      if  $f[i,j] > f[k, j-1] + t[2, j-1] + a[i, j]$ 
9      then  $f[i,j] \leftarrow f[k, j-1] + t[2, j-1] + a[i, j]$ 
           $L[i, j] = k$ 
10     end if
```

n-Line Assembly: Dynamic Algorithm

```
11  $f^* \leftarrow f[1, m] + x[1]$ 
12  $l^* = 1$ 
13 for  $k \leftarrow 2$  to  $n$ 
14     if  $f^* > f[k, m] + x[k]$ 
    15 then  $f^* \leftarrow f[k, m] + x[k]$ 
    16  $l^* = k$ 
```

Constructing the Fastest Way: n-Line

1. Print-Stations (l^* , m)
2. $i \leftarrow l^*$
3. print “line” i “, station” m
4. **for** $j \leftarrow m$ **downto** 2
5. **do** $i \leftarrow l_i[j]$
6. print “line” i “, station” $j - 1$

Generalization: Cyclic Assembly Line Scheduling

Title: Moving policies in cyclic assembly line scheduling

Source: Theoretical Computer Science, Volume 351, Issue (February 2006)

Summary: Assembly line problem occurs in various kinds of production automation. In this paper, originality lies in the automated manufacturing of PC boards.

- In this case, the assembly line has to process number of identical work pieces in a cyclic fashion. In contrast to common variant of assembly line scheduling.
- Each station may process parts of several work-pieces at the same time, and parts of a work-piece may be processed by several stations at the same time.

Application: Multiprocessor Scheduling

- The assembly line problem is well known in the area of multiprocessor scheduling.
- In this problem, we are given a set of tasks to be executed by a system with n identical processors.
- Each task, T_i , requires a fixed, known time p_i to execute.
- Tasks are indivisible, so that at most one processor may be executing a given task at any time
- They are un-interruptible, i.e., once assigned a task, may not leave it until task is complete.
- The precedence ordering restrictions between tasks may be represented by a tree or forest of trees

Conclusion

- Assembly line problem is discussed
- Generalization is made
- Mathematical Model of generalized problem is described
- Algorithm is proposed
- Applications are observed in various domains
- Some research issues are identified