

MLPR four notes

linear regression

total square error: $E(w, b) = (y - f)^T (y - f)$

can add bias as extra column of 1's to x and a w_0 to w

RBS form: $\exp\left(-\frac{(x - \underbrace{c}_{\text{center}})^T (x - c) / h^2}{\underbrace{\quad}_{\text{width } (h)}}\right)$

regularization:

$$E_\lambda(w; y, \Phi) = (y - \Phi w)^T (y - \Phi w) + \lambda w^T w$$

$$= (y' - \Phi' w)^T (y' - \Phi' w) \quad \text{where } y' = \begin{bmatrix} y \\ 0_k \end{bmatrix}, \Phi' = \begin{bmatrix} \Phi \\ \sqrt{\lambda} I_k \end{bmatrix}$$

model evaluation:

gen. error $E = \mathbb{E}_{p(x, y)} [L(y, f(x))] = \int L(y, f(x)) p(x, y) dx dy$

use mean test error: $\frac{1}{M} \sum_{m=1}^M L(y^{(m)}, f(x^{(m)})) \quad x^{(m)}, y^{(m)} \sim p(x, y)$

univariate Gaussian: $p(z) = N(z, \mu, \sigma^2) = \frac{1}{\sigma \sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma^2} (z - \mu)^2\right)$

error bars: $\text{var}[\bar{x}] = \frac{\sigma^2}{N}$

typical deviation: $\mu \pm \frac{\hat{\sigma}}{\sqrt{N}} \Rightarrow$ can apply this to errors in test set

multivariate Gaussian

$$\begin{aligned} \text{cov}[y] &= \mathbb{E}[yy^T] - \mathbb{E}[y] \mathbb{E}[y]^T \\ &= \mathbb{E}[Axx^T A] - \mathbb{E}[Ax] \mathbb{E}[Ax]^T \quad \text{if } y = Ax \text{ and } x \sim N(0, I) \\ &= A \mathbb{E}[xx^T] A^T \\ &= AA^T \\ &= \Sigma \end{aligned}$$

note on determinants: $|\Sigma| = |AA^T| = |A| |A^T| = |A|^2$

$$p(z) = N(z; \mu, \Sigma) = \frac{1}{|\Sigma|^{1/2} (2\pi)^{D/2}} \exp\left(-\frac{1}{2} (z - \mu)^T \Sigma^{-1} (z - \mu)\right)$$

classification

Bayes classifier: $P(y=k|x) \propto p(x|y) P(y=k)$
 $\propto N(x; \mu_k, \Sigma_k) \pi_k \quad \text{where } \pi_k = \frac{\sum_n I(y^{(n)}=k)}{N}$
 $= S_k$

$$P(y=k|x, \theta) = \frac{S_k}{\sum_{k'} S_{k'}}$$

"Naive Bayes": features are independent, i.e., Σ_k is diagonal for all k
 natural when features x are binary.

$$P(x|y=k, \theta) = \prod_d P(x_d|y=k, \theta) = \prod_d \theta_{d,k}^{x_d} (1 - \theta_{d,k})^{1-x_d}$$

regression and gradients:

calculate square error: $\underline{r} = (\underline{y} - \underline{X}\underline{w})$

then take deriv: $\nabla_{\underline{w}} \underline{r}^T \underline{r} = -2 \underline{X}^T \underline{r} + 2 \underline{X}^T \underline{X} \underline{w}$

now can do:

closed form: $\underline{w} = (\underline{X}^T \underline{X})^{-1} \underline{X}^T \underline{y}$ (after setting $\nabla_{\underline{w}} \underline{r}^T \underline{r}$ to zero)

iterative: $\underline{w} \leftarrow \underline{w} - \eta \nabla_{\underline{w}} [\underline{r}^T \underline{r}]$

logistic regression:

$$NLL = - \sum_{n=1}^N \log \left[\sigma(\underline{w}^T \underline{x}^{(n)})^{y^{(n)}} (1 - \sigma(\underline{w}^T \underline{x}^{(n)}))^{1-y^{(n)}} \right]$$

$$= - \sum_{n=1}^N \log \sigma(\underline{z}^{(n)} \underline{w}^T \underline{x}^{(n)})$$

$$\frac{\partial \sigma(a)}{\partial a} = \sigma(a)(1 - \sigma(a))$$

$$\nabla_{\underline{w}} NLL = - \sum_{n=1}^N (1 - \sigma_n) \underline{z}^{(n)} \underline{x}^{(n)}$$

approx grad: $\frac{\partial f(\underline{w})}{\partial \underline{w}} \approx \frac{f(\underline{w} + \frac{\underline{\epsilon}}{2}) - f(\underline{w} - \frac{\underline{\epsilon}}{2})}{\underline{\epsilon}}$ (i.e., $\frac{\Delta y}{\Delta x}$)

softmax / robust solutions:

$$f_k = \frac{\exp(\underline{w}^{(k)T} \underline{x})}{\sum_{k'} \exp(\underline{w}^{(k')T} \underline{x})}$$

$$\nabla_{\underline{w}^{(k)}} \log f_k = (\underline{y}_k - f_k) \underline{x}$$

a robust model randomly sets y to $\frac{1}{2}$ w/ probability ϵ

$$\begin{cases} \text{exp:} & \text{real} \rightarrow \text{pos} \\ \text{log:} & \text{pos} \rightarrow \text{real} \\ \text{sigmoid:} & \text{real} \rightarrow (0,1) \\ \text{logit:} & (0,1) \rightarrow \text{real} \end{cases}$$

neural nets

don't set weights to zero or to $\chi(0,1) \Rightarrow$ set as $\frac{0.1}{\sqrt{K}} N(0,1)$

chain rule: $\frac{\partial f}{\partial r} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial r}$

$$\frac{\partial f}{\partial u_i} = \sum_{d=1}^D \frac{\partial f}{\partial x_d} \frac{\partial x_d}{\partial u_i} \quad (\text{generalized})$$

$$\frac{\partial f}{\partial \underline{X}_{ab}} = \underline{X}_{ab}$$

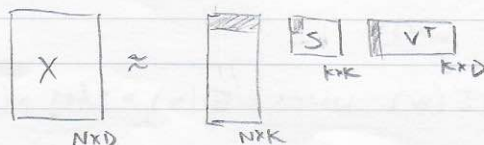
automatic differentiation: $\underline{z} = \underline{X} \underline{y} \Rightarrow \overline{\underline{X}} = \overline{\underline{z}} \underline{y}^T$ and $\overline{\underline{y}} = \underline{X}^T \overline{\underline{z}}$ (ordinary matrix operations: not $O(N^4)$!)

backprop the error signals: $\delta_i^{(2)} = \frac{\partial E}{\partial a_i^{(1)}} = \overline{a}_i^{(1)}$

PCA

denoising autoencoder: essentially dropout

$$X \approx USV^T$$



~~U~~ = operations for 1st PC

$US \approx XV$ is data projected down to k dims

$USV^T \approx XVV^T$ is data projected back up (but it's low-rank k)

Bayesian regression:

conjugate prior is one where the product of the prior and the likelihood combines to give a dist w/ the same functional form as the prior

$$p(w|D) \propto p(D|w) p(w)$$

$$\propto \prod_n N(y^{(n)}; \mathbf{x}^{(n)T} \mathbf{w}, \sigma^2) N(\mathbf{w}; \mathbf{0}, \sigma_{\text{prior}}^2)$$

assuming we're updating a Gaussian and have a Gaussian prior

Bayesian inference and prediction:

$$\text{prediction: } p(y|x, D) = \int p(y, w|x, D) dw$$

$$= \int p(y|x, w) \underbrace{p(w|D)}_{\text{see last section}} dw$$

(posterior)

$$p(w|D) = N(w; w_N, V_N) \text{ if Gaussian}$$

linear and Gaussian models can be solved in closed form

$$\text{for linear: } \mu_f = E_w[\mathbf{x}^T \mathbf{w}] = \mathbf{x}^T \mathbf{w}_N$$

$$\text{var}[f] = \mathbf{x}^T V_N \mathbf{x}$$

$$f = \mu_f \quad f = \mu_f$$

$$= E[(\mathbf{x}^T \mathbf{w} - \mathbf{x}^T \mathbf{w}_N)^T (\mathbf{x}^T \mathbf{w} - \mathbf{x}^T \mathbf{w}_N)]$$

$$p(y|D, \mathbf{x}) = N(y; \mathbf{x}^T \mathbf{w}_N, \mathbf{x}^T V_N \mathbf{x} + \sigma^2)$$

add this for noise going from f to y

Bayesian model selection:

small for overly complex models

$$p(y|x, M) = \int p(y|x, w, M) p(w|M) dw$$

can do marginal likelihood to estimate hyperparameters (e.g., σ_{prior}^2 and σ_y^2)

$$p(y|x, \alpha, \sigma) = \int p(y|x, w, \sigma) p(w|\alpha) dw$$

maximize this to find α and σ

GPs:

$$\text{joint dist: } p\left(\begin{bmatrix} y \\ \mathbf{f}_* \end{bmatrix}\right) = N\left(\begin{bmatrix} y \\ \mathbf{f}_* \end{bmatrix}; \mathbf{0}, \begin{bmatrix} K + \sigma_y^2 \mathbf{I} & K_* \\ K_* & K_{**} \end{bmatrix}\right)$$

$$k(\mathbf{x}^{(i)}, \mathbf{x}^{(j)}) = \sigma_f^2 \exp\left(-\frac{1}{2} \sum_{d=1}^D (\mathbf{x}_d^{(i)} - \mathbf{x}_d^{(j)})^2 / \ell_d^2\right)$$

σ_f^2 typical vertical height

"typical dist. b/w turning points"

can compute hyperparameters by max likelihood

max $\log(p(y|x, \theta)) = \max \log N(\cdot)$
or by integrating out θ ...

Bayesian logistic regression and Laplace approx

$$\text{MAP: } \underline{w}^* = \arg \max_{\underline{w}} [\log p(\underline{w} | \mathcal{D})] = \arg \max_{\underline{w}} [\underbrace{\log \tilde{p}(\mathcal{D} | \underline{w})}_{\text{likelihood}} - \underbrace{\frac{1}{2\alpha} \underline{w}^T \underline{w}}_{\lambda}]$$

↳ basically regularized MLE

Laplace approx

1. find \underline{w}^* : $\underline{w}^* = \arg \min_{\underline{w}} E(\underline{w})$ where $E(\underline{w}) = -\log p(\underline{w} | \mathcal{D})$
2. calculate $H_{ij} = \frac{\partial^2 E(\underline{w})}{\partial w_i \partial w_j} \bigg|_{\underline{w} = \underline{w}^*}$

$$3. \text{ set } p(\underline{w} | \mathcal{D}) \approx \mathcal{N}(\underline{w}; \underline{w}^*, H^{-1})$$



sometimes not so great

variational inference:

$$D_{KL}(p \| q) = \int p(z) \log \frac{p(z)}{q(z)} dz$$

usually want $D_{KL}(q \| p)$ where q approximates p

$$\begin{aligned} D_{KL}(q(\underline{w}; \alpha) \| p(\underline{w} | \mathcal{D})) &= \int q(\underline{w}; \alpha) \log \frac{q(\underline{w}; \alpha)}{p(\underline{w} | \mathcal{D})} d\underline{w} \quad \rightarrow \quad = \frac{p(\mathcal{D} | \underline{w}) p(\underline{w})}{p(\mathcal{D})} \\ &= \underbrace{- \int q(\underline{w}; \alpha) \log p(\underline{w} | \mathcal{D}) d\underline{w}}_{\text{cross-entropy ... small = good}} + \underbrace{\int q(\underline{w}; \alpha) \log q(\underline{w}; \alpha) d\underline{w}}_{\text{(neg) entropy: want entropy to be large (spread out)}} \\ &= \underbrace{\mathbb{E}_q [\log p(\mathcal{D} | \underline{w})]}_{J(q)} + \dots + \log p(\mathcal{D}) \end{aligned}$$

only the neg log likelihood term can't be computed in closed form

so use MC

Gaussian mixture models:

$$\begin{aligned} p(\underline{x}^{(n)} | \theta) &= \sum_k p(\underline{x}^{(n)}, z^{(n)} = k | \theta) \quad \pi_k \\ &= \sum_k p(\underline{x}^{(n)} | z^{(n)} = k, \theta) p(z^{(n)} = k | \theta) \\ &= \sum_k \pi_k \mathcal{N}(\underline{x}^{(n)}; \mu^{(k)}, \Sigma^{(k)}) \end{aligned}$$

use EM to take NLL of $p(\mathcal{D} | \theta)$

$$\begin{aligned} E: \text{ set soft responsibilities: } r_k^{(n)} &= p(z^{(n)} = k | \underline{x}^{(n)}, \theta) = \frac{\pi_k \mathcal{N}(\underline{x}^{(n)}; \mu^{(k)}, \Sigma^{(k)})}{\sum_l \pi_l \mathcal{N}(\underline{x}^{(n)}; \mu^{(l)}, \Sigma^{(l)})} \\ M: \text{ update params } \theta &= \{\pi, \{\mu^{(k)}, \Sigma^{(k)}\}\} \end{aligned}$$

$$\mu^{(k)} = \frac{1}{r_k} \sum_{n=1}^N r_k^{(n)} \underline{x}^{(n)}$$

$$\Sigma^{(k)} = \dots$$