

# Cover Letter

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## 1 Introduction

My research interests lie in **human-centric computer vision** and **reinforcement learning from human feedback (RLHF)**. I am particularly interested in generative models for human-centric problems, such as pose estimation, motion prediction, eye tracking, etc. Additionally, further applications in human-AI interaction and related topics also attract me.

### 1.1 Alignment with Your Lab

My experiences and research interests align well with your excellent work in gaze estimation, motion prediction, and hand-object interaction (HOI). Previously, I conducted published works on 3D hand reconstruction. I also have experience in physics-based simulation (including robotic arm, dexterous hand and UAV) and multi-agent reinforcement learning (MARL). It could contribute to contact-rich HOI research and potential RLHF applications in human-centric tasks.

## 2 Related Experience

### 2.1 Opponent Modelling

I have explored the problem of cooperating with an unseen partner in the setting of mixed cooperative-competitive games[2], from the perspective of multi-agent reinforcement learning and game theory. Technically, we leverage contrastive learning to learn a consistent representation of the opponent's policy. This approach can be introduced in other tasks to enhance the zero-shot ability.

### 2.2 3D Hand Reconstruction from Blurry Monocular Images

Most current approaches focus on the blurriness problem in video, where the temporal information helps to reconstruct human motion. We recover hand motion from a single blurry image to utilise temporal information inherent in a single blurry image [1]. To overcome the ambiguity, we make multiple estimations for one image in a generative manner, and select the plausible ones with a learned selection module.

## 3 Future Plan

My proposed research directions include:

- generative model in 3D estimation and motion prediction.
- physics-based HOI estimation.
- self/weak/semi-supervised learning in human 3D estimation.

These ideas are preliminary, and I am eager to refine them to better align with the team. I am also open to any other related topics.

## References

- [1] Yuming Chen, Rongyu Chen, Zhongqun Zhang, Yihua Cheng, and Hyung Jin Chang. Multi-hypothesis 3d hand mesh recovering from a single blurry image. In *International Conference on Multimedia and Expo (ICME)*, 2025.
- [2] Yuming Chen and Yuanheng Zhu. Policy representation opponent shaping via contrastive learning. In *International Conference on Neural Information Processing (ICONIP)*, 2023.