Yuming Chen

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EDUCATION BACKGROUND

University of Birmingham, Birmingham, U.K.

Sept. 2023 - Jun. 2024

Project: MSc. AI & ML School: School of Engineering and Physical Sciences Overall GPA: 73.6 /100 (Distinct)

Dissertation: Multi-Hypothesis 3D Hand Mesh Sequence Estimation from Blurry Image

University of Chinese Academy of Social Sciences, Beijing, China

Sept. 2017 - Jun. 2022

Major: Economics School: School of Economics Overall GPA: 3.59 /4.0

Thesis: Approximability of Equilibria in Pure Exchange Economy with Atomic Traders

RESEARCH EXPERIENCES

Research Internship Mar. 2022 - Jul. 2023

Deep Reinforcement Learning Research Group, the State Key Laboratory for Management and Control of Complex Systems, Institute of Automation, Chinese Academy of Sciences.

- ❖ Designed a module to represent opponent's policy in Multi-Agent System (MAS) via contrastive learning. Agents with such a module reached the equilibria with higher social welfare in social dilemmas, such as Iterated Prisoner's Dilemma (IPD). It is accepted by 2023 International Conference on Neural Information Processing (ICONIP2023).
- Assisted to design an algorithm for decentralized rescue drones to collaborate with each other. Such drones were totally controlled via Reinforcement Learning. I used reward shaping to avoid shifting from the original high-level goal, and reward randomization to learn diversified policies.

Research Internship Feb. 2024 - Nov. 2024

Intelligent Robotics Lab, the University of Birmingham

❖ Developed a generative 3D hand pose estimation model from a blurry image. To address the multi-hypothesis issue, the model generates multiple plausible candidates and selects the best via a trained reward model. It is aiming at ICCV2025.

Research Interests

Reinforcement Learning:

- Human-AI collaboration
- Imitation Learning
- Preference Learning

Multi-Agent System & Game Theory:

- Opponent Modelling & Reasoning
- Game Dynamics Analysis

Publications

<u>Yuming C.</u>, Yuanheng, Z. "Policy Representation Opponent Shaping via Contrastive Learning" Accepted by the International Conference on Neural Information Processing (ICONIP2023).

Dapei Z., Ying K., <u>Yuming C.</u> "Research on Duopoly Non-cooperative Game Model under the Conditions of Supply Surplus"

Published in Contemporary Economic Research (indexed by CSSCI) in Jul. 2021 [Link (in Chinese)]