Dr Holmes's notes on the Ruler Postulate

Randall Holmes

April 3, 2023

These are some notes on the axiomatics in Venema. Venema has a wonderful book, but some things I think benefit from a different approach.

Primitive notions that we start with. There are *points*. There are *lines*, which are sets of points (a line is a set of points, but of course not all sets of points are lines). We will refer to the set of all points as the plane.

We have a primitive d, the distance function, which sends any pair of points to a real number. Note that the distance from point P to point Q, which we write d(P,Q), is written just as PQ in Venema, which we find potentially confusing and so avoid.

More primitive notions will be introduced later.

The first two axioms are

Existence Postulate: There are at least two distinct points.

Incidence Postulate: For each pair of distinct points A, B there is exactly one line L such that $A \in L$ and $B \in L$: we denote this line by $\stackrel{\leftrightarrow}{AB}$.

The next axiom is best preceded by a definition.

Definition (coordinate function): Let L be a line. A coordinate function for L is defined as a function from L to the set \mathbb{R} of real numbers which is

- 1. one-to-one (for any points $P, Q, f(P) = f(Q) \rightarrow P = Q$),
- 2. onto (for any real number r, there is a point $P \in L$ such that f(P) = r; we can also write $P = f^{-1}(r)$),
- 3. and distance preserving: for any points $P, Q \in L$, d(P,Q) = |f(P) f(Q)|.

Ruler Postulate: For any line L, there is a coordinate function for L.

Semi-Metric Theorem: For any points $A, B, d(A, B) \ge 0, d(A, B) = d(B, A)$, and d(A, B) = 0 iff A = B.

Proof of Semi-Metric Theorem: Let A, B be points. Define a point P as B, in case B is distinct from A, and otherwise as some point distinct from A (there is such a point by the Existence Postulate).

Let L be the line $\stackrel{\smile}{AP}$. Note that both A and B are on L, because B is either A or P. Note the use of the Incidence Postulate.

Let f be a coordinate function for L.

$$d(A, B) = |f(A) - f(B)| = |f(B) - f(A)| = d(B, A).$$

 $d(A, B) = |f(A) - f(B)| \ge 0$. Further, |f(A) - f(B)| = 0 if and only if f(A) = f(B), and in turn this is true if and only if A = B, because f is one-to-one.

As we note briefly under one of the headings, a coordinate function f for L has an inverse f^{-1} such that for each real number r, $f^{-1}(r)$ is the unique point P on L such that f(P) = r.

The use of the Ruler Postulate depends on some facility with the notion of absolute value.

A line does not have a uniquely determined coordinate function. We give a complete account of what coordinate functions a line has.

Theorem: Let L be a line and let f be a coordinate function for L. For any real number c and any $\sigma = \pm 1$, the function g from L to \mathbb{R} defined by $g(P) = \sigma f(P) + c$ is a coordinate function.

Proof: g is one-to-one: suppose g(P) = g(Q). It follows by definition of g that $\sigma f(P) + c = \sigma f(Q) + c$, from which it follows by algebra that f(P) = f(Q) from which it follows by the fact that f is a coordinate function and so one-to-one that P = Q, so we have shown that g is one-to-one.

g is onto: Let r be a real number. We want to find a point P on L such that g(P) = r. That is, we want to find P such that $\sigma f(P) + c = r$, for which we need $f(P) = \sigma(r - c)$. So let $P = f^{-1}(\sigma(r - c))$.

 $g(P) = g(f^{-1}(\sigma(r-c))) = \sigma(f(f^{-1}(\sigma(r-c)))) + c = \sigma(\sigma(r-c)) + c = (r-c) + c = r$. Note the use of the fact that $\sigma = \pm 1$, so $\sigma^2 = 1$.

g is distance preserving: $|g(P) - g(Q)| = |(\sigma f(P) + c) - \sigma f(Q) + c| = |\sigma(f(P) - f(Q))| = |\sigma||f(P) - f(Q)| = |f(P) - f(Q)| = d(P, Q)$. Notice the use of the fact that $|\sigma| = 1$ and the fact that f is a coordinate function and so distance preserving.

- Observation about absolute values: For any real number x, there is $\sigma = \pm 1$ such that $|x| = \sigma x$, and for any τ , if $\tau = \pm 1$ and $\tau x \ge 0$, $\tau x = |x|$.
- **Lemma:** If r, s, x, y are real numbers, $r \neq s$, and |x r| = |y r| and |x s| = |y s| then x = y. In a geometric manner, we can say that if r and s are distinct real numbers, and x and y have the same distances from r and s respectively, then x = y: if we know the distance of a real number from both r and s, we have exactly determined that number.
- **Proof:** Let $r \neq s$. Let $|x r| = |y r| = d_1$ and let $|x s| = |y s| = d_2$. For any z, T and d, |z - t| = d implies that there is $\sigma = \pm 1$ such that $z = t + \sigma d$.

It follows from this that there is $\sigma_1 = \pm 1$ such that $x = r + \sigma_1 d_1$, and if $y \neq x$, it follows that $y = r - \sigma_1 d_1$. Similarly, there is $\sigma_2 = \pm 1$ such that $x = s + \sigma_2 d_2$ and if $y \neq x$, it follows that $y = s - \sigma_2 d_2$.

It then follows that $x+y=(r+\sigma_1d_1)+(r-\sigma_1d_1)=2r$ and $x+y=(s+\sigma_2d_2)+(s-\sigma_2d_2)=2s$, so 2r=2s, so r=s, which is a contradiction, so our assumption that $y\neq x$ is shown to be false.

I enjoy the elimination of case analysis by the use of variables equal to 1 or -1 in this presentation.

- **Corollary:** If f and g are coordinate functions for the same line L, and $P \neq Q$ are distinct points on L, and f(P) = g(P) and f(Q) = g(Q), we have f = g. Coordinate functions need only agree at two distinct points to be known to be equal.
- **Proof:** Let R be an arbitarily chosen point on L.

We have d(R, P) = |g(R) - g(P)| and d(R, P) = |f(R) - f(P)|. But also d(R, P) = |g(R) - g(P)| = |g(R) - f(P)|.

We have d(R,Q) = |g(R) - g(Q)| and d(R,P) = |f(R) - f(Q)|. But also d(R,Q) = |g(R) - g(Q)| = |g(R) - f(Q)|.

Now apply the previous lemma with x = f(R), y = g(R), r = f(P), s = f(Q) to conclude that f(R) = g(R) for every $R \in L$, so f = g.

Theorem: If L is a line with coordinate function f, and we use R as an independent variable ranging over L, every coordinate function g is if the form g(R) = c + sf(R) where c is a real number and $s = \pm 1$.

Proof: Let L be a line. Let f be a coordinate function for L. Let g be a coordinate function for L.

Let P,Q be two distinct points on L. Define h, a function from L to the real numbers, by $h(R) = g(P) + \frac{g(Q) - g(P)}{f(Q) - f(P)} (f(R) - f(P))$.

h is a coordinate function because h(R)=c+sf(R) where c is a real number and $s=\pm 1$. (c being $g(P)-\frac{g(Q)-g(P)}{f(Q)-f(P)}(f(P))$, and s being $\frac{g(Q)-g(P)}{f(Q)-f(P)}$)

$$h(P) = g(P) + \frac{g(Q) - g(P)}{f(Q) - f(P)} (f(P) - f(P)) = g(P)$$

$$h(Q) = g(P) + \frac{g(Q) - g(P)}{f(Q) - f(P)}(f(Q) - f(P)) = g(P) + g(Q) - g(P) = g(Q)$$

so by the previous corollary, h is the same coordinate function as g, since they agree at two distinct points, and h is of the form h(R) = c + sf(R) where c is a real number and $s = \pm 1$, establishing that g is of this form.

Now we introduce the notions of betweenness, segments, congruence, and rays.

Definition: We say that three points A, B, C are *collinear* iff $A \neq B, A \neq C$, $B \neq C$, and there is a line L such that $A \in L$, $B \in L$, and $C \in L$, i.e., the three points are distinct, and they all lie on the same line.

Definition: Let A, B, C be points. We define A * B * C, read "B is between A and C" as meaning "A, B, and C are collinear and

$$d(A,B) + d(B,C) = d(A,C).$$

- **Theorem:** Let L be a line and let A, B, C be three distinct points on L. Let f be a coordinate function for L. Then A * B * C holds if and only if either f(A) < f(B) < f(C) or f(C) < f(B) < f(A).
- **Proof:** $d(A, B) = \sigma_1(f(B) f(A))$, where $\sigma_1 = \pm 1$ and $\sigma_1(f(B) f(A)) = \sigma_1 f(B) \sigma_1 f(A) > 0$ (definition of absolute value).

 $d(B,C) = \sigma_2(f(C) - f(B))$, where $\sigma_2 = \pm 1$ and $\sigma_2(f(C) - f(B)) = \sigma_2 f(C) - \sigma_2 f(B) > 0$ (definition of absolute value).

There are two cases: either $\sigma_1 = \sigma_2$ or $\sigma_1 \neq \sigma_2$.

Case 1 ($\sigma_1 = \sigma_2$): If $\sigma_1 = \sigma_2$, then $d(A, B) + d(B, C) = \sigma_1 f(B) - \sigma_1 f(A) + \sigma_2 f(C) - \sigma_2 f(A) = \sigma_1 f(B) - \sigma_1 f(A) + \sigma_1 f(C) - \sigma_1 f(B) = \sigma_1 f(C) - \sigma_1 f(A) = \sigma_1 (f(C) - f(A)) = |f(C) - f(A)|$ (because $\sigma_1 = \pm 1$ and this is the sum of two nonnegative (in fact positive) quantities and so certainly nonnegative) = d(A, C), so A * B * C holds.

We also have $\sigma_1 f(A) < \sigma_1 f(B) < \sigma_1 f(C)$, so either f(A) < f(B) < f(C) or f(C) > f(B) > f(A), so in this case we have A * B * C if and only if either f(A) < f(B) < f(C) or f(C) < f(B) < f(A), because both are true.

Case 2 ($\sigma_1 \neq \sigma_2$): If $\sigma_1 \neq \sigma_2$ then $\sigma_2 = -\sigma_1$ and $d(A, B) + d(B, C) = \sigma_1 f(B) - \sigma_1 f(A) + \sigma_2 f(C) - \sigma_2 f(A) = \sigma_1 f(B) - \sigma_1 f(A) - \sigma_1 f(C) + \sigma_1 f(B) = 2\sigma_1 f(B) - \sigma_1 f(A) - \sigma_1 f(C)$. We show that this is greater than either $\sigma_1(f(C) - f(A))$ or $-\sigma_1(f(C) - f(A))$ and so is greater than d(A, C) (which is equal to whichever of these is positive).

 $(2\sigma_1 f(B) - \sigma_1 f(A) - \sigma_1 f(C)) - \sigma_1 (f(C) - f(A)) = 2\sigma_1(B) - 2\sigma_1(C) = 2\sigma_2(f(C) - f(B)) > 0$

$$(2\sigma_1 f(B) - \sigma_1 f(A) - \sigma_1 f(C)) - (-\sigma_1 (f(C) - f(A))) = 2\sigma_1(B) - 2\sigma_1(A) = 2\sigma_1 (f(B) - f(A)) > 0$$

This establishes the two inequalities. So if $\sigma_1 \neq \sigma_2$, we have d(A, B) + d(B, C) > d(A, C), so A * B * C does not hold.

We cannot have f(A) < f(B) < f(C) or f(C) < f(B) < f(A) in this case, because either of these inequalities implies $\sigma_1 = \sigma_2$ and forces us into the other case. So in this case we also have A * B * C if and only if we have either f(A) < f(B) < f(C) or f(C) < f(B) < f(A), because both are false.

- **Definition:** Let A and B be two distinct points. The segment from A to B, written \overline{AB} is defined as $\{P: P = A \lor P = B \lor A * P * B\}$.
- **Definition:** Let \overline{AB} be a segment. We say that the length of \overline{AB} is d(A, B). We say that segments $\overline{A}, \overline{B}$ and \overline{CD} are congruent, written $\overline{AB} \cong \overline{CD}$ iff they have the same length, that is, d(A, B) = d(C, D).

This definition requires verification. We need to establish that if $\overline{AB} = \overline{CD}$, we must have d(A, B) = d(C, D). This is proved as the following:

- **Lemma:** If $\overline{AB} = \overline{CD}$, we must have d(A, B) = d(C, D). In fact, we must have either $A = C \land B = D$ or $A = D \land B = C$.
- **Proof of Lemma:** Let A, B, C, D be points with $\overline{AB} = \overline{CD}$. Let f be a coordinate function for \overline{AB} . We may suppose without loss of generality that f(A) < f(B) (because otherwise we could use -f instead).

Since $C \in \overline{CD} = \overline{AB}$ we have either C = A or C = B or f(A) < f(C) < f(B) (by the betweenness theorem, with the alternative f(B) < f(C) < f(A) ruled out because f(A) < f(B)).

Suppose for the sake of a contradiction that f(A) < f(C) < f(B). We then observe further that since A and B belong to $\overline{AB} = \overline{CD}$, we have either $f(C) < f(A) < f(B) \le f(D)$ or $f(D) \le f(A) < f(B) < f(C)$, by the betweenness theorem and the known order fact f(A) < f(B). But both of these are incompatible with f(A) < f(C) < f(B), so this is false.

It follows that C = A or C = B. If C = A, then D = B, because C and D must be distinct (because there is a segment between them). If C = B then D = A, for the same reason. So d(A, B) = d(C, D) or d(D, C), but d(D, C) = d(C, D), so d(A, B) = d(C, D) holds in either case.